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Individually Frequency Tunable Dual- and Triple-band Filters in a Single Cavity

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ABSTRACT This paper presents a new class of second-order individually and continuously tunable dual- and triple-band bandpass filters in a single metal cavity. Each passband is realized by two identical metal posts. These dual- and triple-band tunable filters are achieved by putting two or three identical sets of metal-post pair in a single metal cavity. Metal screws are co-designed as a part of the metal posts to control their insertion depth inside the cavity. In this way, the resonant frequencies can be continuously controlled and designed at the desired frequency bands. Moreover, the distance between the two metal posts in a post pair can be freely tuned. Thus, the external quality factor (Q_e) and coupling coefficient (k) between the adjacent modes can be easily adjusted to meet the specified requirement in synthesis design. At the bottom of the cavity, some grooves are used to extend the tunable frequency of each passband can be independently tuned with a frequency range of 0.8–3.2 GHz and tunable ratio of 4. Finally, the continuously tunable dual- and triple-band bandpass filters prototypes with second order response are designed and fabricated, of which each passband can be individually tuned with a large tuning range.

INDEX TERMS Tunable bandpass filter, dual- and triple-band, individual tunable cavity filter, single cavity, groove.

I. INTRODUCTION

Microwave filters are one of indispensable components in many types of radio frequency (RF) communication, radar and spectrum measurement systems. In particular, cavity filters are widely used in the base station of wireless communication systems due to their inherently adopted high power handling capacity and low in-band insertion loss [1]. With the rapid development of multiple services in recent years, the usage of multiple frequency bands has triggered the demand for multiple-band filters. Recently, some multipleband filters [2]–[7] have been reported with the capability of performance enhancement in wireless communication systems, where the multi-channel services front-ends are expected. In communication systems, reconfigurable or tunable filters are one of the most essential microwave components due to the merits of reconfigurability and multifunction capability. In recent years, many types of tunable bandpass filters have been proposed using different tuning devices, such as MEMS [8]-[11], varactors [12]-[14], mechanical tuners [15]–[17] and ferrite-loaded [18]. In general, MEMS devices have a large insertion loss but fast tuning speed. Varactors have a better insertion loss than MEMS but the tuning range is relatively narrow. By mechanically adjusting the positions of the capacitive components of the tuner, mechanical tuning devices in cavity filters can achieve small insertion loss. However, this method has the challenges from device miniaturization and sensitive passband performance due to the critically specified coupling coefficients. As a desirable performance, flexible passband tunability turns to be an attractive feature in modern communication systems due to its potential benefits in size and cost reduction at system level by replacing multiple filters using one.

It is a common technology by using a planar integrated structure to build up these multiple-band tunable or reconfigurable filters [19]–[24]. However, in general, the planar multiple-band tunable filters present two drawbacks: large insertion losses and narrow tunable frequency range. As discussed in [19]-[24], the in-band insertion loss of these tunable filters are usually larger than 3 dB. In particular, the work in [24] shows that its insertion loss is as large as 7 dB in the tunable frequency range. Undoubtedly, the desirable performance of wide frequency tuning range and multipleband ability is quite challenging by using planar structure due to the inherent limitation as a 2-dimensional structure. The reported literature reveals that the highest and lowest tunable frequency range ratio $(f_{\rm H}/f_{\rm L})$ of a tunable multiple-band planar filter is usually smaller than 2.0 [23], [24]. To achieve a wider tuning range, it is expected to effectively control the intra-resonator coupling [19]. However, it is difficult to control the coupling coefficient (k) during the process of frequency tuning because of the restricted freedom of structural movement of the filter.

Therefore, a novel and efficient inner-resonator coupling technique is needed for multiple passband filters with wide tuning range without deteriorating effect on the passband performance over the entire tuning frequency range.

In this paper, we present a new approach of designing the individually and continuously tunable cavity bandpass filters for dual- and triple-band applications. The proposed multiple-band tunable filters have a wide tuning frequency range from 0.8 to 3.2 GHz with a tuning ratio $f_{\rm H}/f_{\rm L}$ of 4. Within the tunable frequency range, the intra-resonator coupling coefficient (k) can be effectively controlled by freely tuning the distance between the two metal posts in a post pair. As a highlight of this design, each passband can be controlled independently without affecting its neighboring passband(s). Notably, all the resonators are designed in a single metal cavity without using additional coupling windows, metallic walls or coupling screws in between neighboring resonators, leading to a very simple tuning mechanism. To verify the proposed design approach and predicted the frequency responses, two prototypes of dual- and triple-band tunable filters are designed, fabricated and measured. The measured results demonstrate the individually and continuously tuning capability of the dual- and triple-band cavity filters in a wide frequency range.

II. CONTINUOUSLY TUNABLE SINGLE-BAND FILTER

This section introduces a single resonator with three types of configured resonant cavities. The proposed resonator is selected based on the comparative studies, which is used as a basic unit for single band bandpass filter design. All filter simulations are used CST.

A. WIDE TUNING RANGE OF COAXIAL RESONATOR

Fig. 1(a) depicts the basic configuration of a coaxial cavity resonator. It consists of one resonant metallic post with diameter $D_2 = 4$ mm, which is loaded with a thin disc at its bottom



FIGURE 1. Configuration of the proposed three types of resonant cavities. (a) Case-A: resonant posts with $D_2 = 4$, $D_3 = 7$. (b) Case-B: added metal sleeves with $D_1 = 8$ and h = 14 in length. (c) Case-C: added grooves. All in mm.

to produce an extra capacitance value, namely, Case-A. The principle of frequency tuning in Case-A can be easily understood by following explanation. According to the capacitance equation $C = \varepsilon * \text{Area/distance}$, the capacitance C is inversely proprotional to the distance between the disc and the bottom of the cavity. Thus, the resonant frequency can be tuned by the insertion depth of the posts, namely h in Case-A. When the parameter D_2 is selected as 4.0 mm, the resonant frequency of Case-A varies as a function of h as displayed by the blackrhombus curve in Fig. 2. When the disc is moved far away from the bottom metellic wall, the capacitance value becomes too weak to dominate the resonant frequency. In contrast, the inductance component of the resonant mode becomes much influential to resonant frequency. According to (1) from [25], the inductance value per unit length depends on the ratio of r_2/r_1 , where r_1 and r_2 are the inner and outer conductor radii of a coaxial resonator. Obviously, a high resonant frequency can be obtained by decreasing the ratio of r_2/r_1 . Hence, a large diameter sleeve with $D_1 = 8$ mm is embedded in the top wall, as shown in Fig. 1(b), namely, Case-B. The simulated results of the resonant frequency against h are plotted by the red-triangle curve in Fig. 2. Compared with Case-A in Fig. 2, Case-B is found to achieve a wider tuning frequency. Thus, the tuning frequency range can be expanded by embedding these sleeves in the resonant post.

$$L \propto \left(ln \frac{r_2}{r_1} + \frac{1}{4} \right) \tag{1}$$

In order to achieve a better tuning capability in practical application, a cylindrical groove is implemented under the resonant post to improve the linearity of frequency-tuning curve, namely, Case-C. Fig. 1(c) shows the designed groove engineered at the bottom of the cavity which has the same dimensions as Case-B. As shown in Fig. 2, the lower band frequency is less sensitive in Case-C than the other two cases. The reason is that in case- B when the disc is very close to the bottom metallic wall, the distance between the two metal faces is very small leading to a large variation of capacitance value when h is slightly changed. With the groove, the capacitance is produced by both the edge of the disc and the edge of the groove. This edge-to-edge capacitance is less sensitive



FIGURE 2. Resonant frequency as a function of *h*.



FIGURE 3. Resonant frequency versus *d* under different *h* (mm).

to the face-to-face capacitance. For this reason, the edge-toedge capacitance provides a smooth transition before the disc reaches the bottom of the metallic wall. Thus, the variation of the capacitance in terms of h is less sensitive using the proposed groove. The parameter d is designed to control the intra-coupling and the external quality factor. From Fig. 3, the resonant frequency is almost unchanged throughout the entire frequency-tuning band (with less than 0.4% variation) when the distance d tunes from 37 to 41 mm. This shows that the parameter d has almost no impact on resonant frequency.

B. SINGLE-BAND TUNABLE FILTER AND SIMULATED RESULTS

Fig. 4 shows the structure of a tunable single-band bandpass filter with a second order filter response. To meet the demand in good tunable filtering performance, an appropriate feeding method becomes critical to achieve a wide frequency tuning range. Three methods have been commonly used to design



FIGURE 4. Structure of tunable single-band filter. All in mm.

the input/output coupling structure in a coaxial cavity filter, namely, direct coupling, loop coupling and disc capacitive coupling. The direct coupling arouses the strongest coupling, but the probes need to be physically contacted with the resonant posts, which is difficult to be applied in this scenario as the resonator posts are moving during the tuning process. The disc capacitive coupling brings out the weakest coupling among these three methods. It cannot support a wide frequency tuning range. The loop coupling can not only support a wide frequency tuning range, but also provide a strong coupling from input/output ports without a physical contact on the tuning posts. Therefore, the loop coupling is used as the input/output structure in the design of this tunable filter. As shown in Fig. 4, two ports are placed in the symmetrical sidewall of the metal cavity through a standard 50 ohm coaxial line as a feeder. Two L-shaped conductors of the probes are extended into the cavity as the magnetic coupling probes for excitation of the resonant modes. One end of the L-shaped conductor is shorted to the top wall of the metal cavity, while the other end is connected to the input/output port. In order to have enough space to tune the distance between the two metal posts in a post pair, the height and length of L-shaped conductor are set as 12.0 mm and 15.5 mm, respectively, to provide sufficient input/output coupling to the first resonator. Once the probes are fixed, d can be freely changed by tuning the posts within a sliding slot. In practice, there is a screw in each post for vertically tuning of the disc.



FIGURE 5. Variation of coupling coefficient (k) and external quality factor (Q_E) as a function of *h* under different *d*. All in mm.



FIGURE 6. Calculated and Simulated k and Q_F over tuning range.



FIGURE 7. Simulated results of the proposed continuously tunable single-band filter under different tuned frequencies. (a) |S21| and (b) |S11|.

After designing the input/output coupling structure, the study of the coupling coefficient (k) and the external quality factor (Q_E) is the next critical task for achieving the desired filter performance. During the process of frequency tuning, the controllable intra-resonator coupling is important to achieve a good passband. In this work, the coupling coefficient (k) is determined by the distance d between the two resonant posts. The variation of coupling coefficient as a function of frequency under different d is plotted in Fig. 5. It can be seen that the intra-resonant coupling becomes stronger with a reduced d. Thus, a mechanism of controlling the coupling coefficient (k) is realized by moving the position of the two resonant posts. Because the magnetic coupling turns to the electric coupling at the frequency around 2 GHz, the k values appear a decreasing and an increasing tendency before and after 2 GHz. Fig. 5 also plots the external quality factors, Q_E , against the frequency under various d (Note: the resonant frequency is directly related to *h* as shown in Fig.2). The curves show that, when the frequency is tuning, Q_E is stable with d = 37, 38 and 39 mm. In contrast, when d is set to be more than 40 mm and the frequency is higher than 2.2 GHz, Q_E has larger variation. Thus, when the tunable frequency is tuned to higher than 2.2 GHz, d should not be larger than 40 mm because of unstable Q_E . In addition, Q_E reduces with the increment of d. This inspires us that we can compensate for the variation of Q_E by changing the d during the tuning process. This can be done by moving the posts within the sliding slot along the y-axis. Furthermore, the distance d can be employed to control the coupling between two resonators. Thus, by appropriately tuning the d and h, two resonant frequencies can form a passband in the desired frequency range.

$$Q_E = \frac{g_0 g_1}{FBW} \tag{2}$$

$$k = \frac{FBW}{\sqrt{g_1g_2}} \tag{3}$$

We all know that if the realized k and Q_E satisfy the element values of the filter synthesis method, a good passband will be formed. According to (2) and (3) from [26], a fractional bandwidth more than 3.3% and a passband ripple between 0.2 and 0.5 dB are chosen for theoretical calculations of k and Q_E , of which the frequency response curves



FIGURE 8. Configuration of the individual continuously tunable dual-band filter. (a) 3D-view. (b) Top-view. All in mm.

are plotted in Fig. 6. The extracted values of the simulated k and Q_E from the circuit model are also plotted in Fig. 6 for comparison. The two sets of curves are reasonably matched over the entire frequency tuning band. This shows that the passbands of our proposed tunable filter satisfy the filter synthesis method over the entire frequency band. Thus, Fig. 6 can be used as the design guidelines to determine the values of d and h with satisfactory passband performance.

The basic design procedure has been summarized as the following:

• Step 1: If the passband frequency is determined, according to Fig. 2, the value of h is determined. For example, a passband is designed at 2 GHz, h = 24 mm must be chosen from Fig. 2.



FIGURE 9. Simulated results for demonstration of tuning performance, (a) tuning of |S₂₁| with fixed Passband II, (b) tuning of |S₁₁| with fixed Passband II, (c) tuning of |S₂₁| with fixed Passband I, (d) tuning of |S₁₁| with fixed Passband I.

- Step 2: Find the calculated *k* and *Q_E* from Fig. 6 according to the chosen frequency, e.g. at 2 GHz, *k* is 0.026 and *Q_E* is 55 from Fig. 6.
- Step 3: Find the value of d in Fig. 5 according to the chosen value of k and Q_E in Step 2, e.g. k = 0.026, and $Q_E = 55.2$ at 2 GHz, the d = 38 mm is determined in Fig. 5.

Following the steps above, a second order bandpass filter response can be realized throughout the entire frequency band with the particular value of d from Fig. 5. Fig. 7 shows the simulated S-parameters of a continuously tunable singleband cavity filter. The example, demonstrated in Steps 1-3, with the passband center frequency at 2 GHz is marked in Fig. 7(a). A good passband is formed with h = 24 mm and d = 38 mm in the circuit model. This example proves that the method proposed is useful to design a good passband within the proposed frequency range. The filter can be continuously tuned from 0.8 GHz to as high as 3.2 GHz with a 3-dB fractional bandwidth (FBW) of $4.5 \pm 1.2\%$, and an unloaded Q value varies from 4250 to 6527. Meanwhile, it is seen that the return loss is better than 10 dB and the insertion loss is less than 0.3 dB. Particularly, there is only a single passband over the entire tuning frequency range without the emergence of any parasitic passband in the upperband. Taking the advantage of the grooves, the process of tuning becomes more accurate and linear.

III. TUNABLE DUAL- AND TRIPLE-BAND CAVITY FILTERS

A. DUAL-BAND FILTER

In this section, the individually and continuously tunable dual- and triple-band cavity filters are presented based on Section II. All the components are employed in a single cavity. Figs. 8(a) and 8(b) show the physical configuration of 3-D view and top-view of the tunable dual-band cavity filter, respectively. There is no coupling window and no intra-



FIGURE 10. Configuration of the individual continuously tunable triple-band filter. (a) 3D- view. (b) Top-view. The parameters are: m = 20, and l = 7. All in mm.



FIGURE 11. Simulated S-parameter with tuning performance, (a) tuning of $|S_{21}|$ with fixed Passband I and II, (b) tuning of $|S_{11}|$ with fixed Passband I and II, (c) tuning of $|S_{21}|$ with fixed Passband I and III, (e) tuning of $|S_{21}|$ with fixed Passband I and III, (e) tuning of $|S_{21}|$ with fixed Passband II and III, (f) tuning of $|S_{11}|$ with fixed Passband II and III, (f) tuning of $|S_{11}|$ with fixed Passband II and III.

cavity metallic wall inside the cavity. Fig. 8(b) indicates two post pairs (each pair contains two metal posts) corresponding to two independently and continuously tunable passbands inside a single cavity, namely, Passband I and Passband II.

In order to achieve the function of individual tuning, the intra cavity coupling between two frequency bands must be small enough, which requires a certain distance between the post pairs. However, the dimension of the cavity needs to be as small as possible for miniaturization purpose. Considering the tradeoff between the isolation and size of the filter, the distance m is selected as $\lambda/4$ with respect to the upper-frequency band 3.2 GHz. Based on the design of a single-band filter, n = 15.5 mm is selected. As shown in Figs. 8(a) and 8(b), the insertion depth of the posts (h_1 and h_2) of the Passband I and Passband II can be differently selected to achieve different resonant frequencies and perform dual-band behavior. It is obvious that the structure is symmetrical in the x-z plane for both Passband I and Passband II structure. For example, the posts, discs and sliding windows are identical along the symmetrical x-z plane. In addition, four identical grooves are employed under the metallic discs, and their depths are all selected to be 10 mm. A T-shaped feeding structure is used to provide



FIGURE 12. External photography of the proposed tunable filters, (a) the dual-band filter, (b) the triple-band filter.

two coupling paths to Passband I and Passband II structures with n = 15.5 mm and the center-to-center distance between Passband I and Passband II structures is selected to be m = 20 mm.

The tuning mechanism of this dual-band filter is similar to that of its single-band counterpart as discussed in Section II. To demonstrate the continuously individual-tuning capability of this dual-band filter, we fix one passband at an arbitrary chosen frequency and tune the frequency of other passband. Fig. 9 indicates the simulated results of the dual-band tunable



FIGURE 13. Internal photography of the proposed tunable filter, (a) top-cover of the dual-band filter, (b) top-cover of the triple-band filter, (c) bottom cavity of the dual-band filter (left) and bottom cavity of the triple-band filter (right).

filter. We tune the length of two posts to change the passband frequency and adjust the two posts along the sliding slots to control the value of Q_E and k to perform a required passband performance. Fig. 8(a) shows that when we fixed Passband II at 2.59 GHz with $h_2 = 19$ mm and $d_2 = 42.2$ mm, Passband I can be continuously tuned from 0.78 to 2.3 GHz by changing h_1 from 21 to 43.5 mm and d_1 from 40 to 42.8 mm. The fractional bandwidth (FBW) of Passband I varies from 1.25% to 2%. Fig. 9(c) illustrates that when Passband I is fixed at 1.58 GHz with $h_1 = 34.2$ mm and $d_1 = 41.6$ mm, Passband II exhibits a tuning frequency range from 2 to 3.24 GHz with h_2 tuned from 14.9 to 24.5 mm and

 d_2 tuned from 41.0 to 43.6 mm. The FBW varies from 0.8% to 2.3%. It is noteworthy that the tuning elements of Passband I and Passband II are identical and they can be tuned in the entire frequency range from 0.8 GHz to 3.2 GHz. In this case, the unloaded Q of dual-band filter varies from 2751 to 3562.

B. TRIPLE-BAND FILTER

The final configuration of the individually and continuously tunable triple-band filter is depicted in Figs. 10(a) and 10(b). Again, the three sets of tuning elements of the triple-band filter are identical. In order to achieve a triple-band performance, the size of the cavity needs to be larger than previous tunable single- and dual-band cavity filters. Its volume becomes 80 mm \times 60 mm \times 50 mm. Next, the number of resonators needs to be properly modified for accommodating three identical pairs of metal posts. Meanwhile, each of input/output feeding networks in the triple-band filter has three branches instead of two in contrast to the dual-band filter. The distance m between the neighboring post pairs of the proposed filter is set as 20 mm, and the length of feeding structure *l* is set as 7 mm. Fig. 11 plots the simulated results of continuously individual-tunable triple-band filter. For clear demonstration, three tuning cases are displayed in Fig. 11 to verify the individually and continuously tuning capability. Fig. 11(a) shows that, when Passband II and Passband III are fixed at 2 and 2.8 GHz with $h_2 = 23.75$ mm, $h_3 =$ 43 mm, $d_2 = 53.4$ mm and $d_3 = 54$ mm, Passband I can be tuned continuously from 0.8 to 1.65 GHz corresponding to a tuning h_1 from 15.57 to 19.0 mm. Fig. 11(c) shows that the center frequencies of Passband I and Passband III are fixed at 1.1 and 2.8 GHz, respectively, with $h_1 = 46.4$ mm, $h_3 = 16 \text{ mm}, d_1 = 54.6 \text{ mm}$ and $d_3 = 54.6 \text{ mm}.$



FIGURE 14. Measured S-parameter of the individually and continuously tunable dual-band filter, (a) tuning of $|S_{21}|$ with fixed Passband II, (b) tuning of $|S_{11}|$ with fixed Passband II, (c) tuning of $|S_{21}|$ with fixed Passband I. (d) tuning of $|S_{11}|$ with fixed Passband I.

TABLE 1. Comparison among tunable cavity filters.

	f_1	hable range (GF f_2	Hz) f3	Number of Passband	Tuning ratio	Size $(\lambda_c^2/\lambda_c^3)$	Controllable intra-coupling	IL (dB)	Tuning device
[6]	0.9	1.8	N.A.	2	N.A.	0.416*0.13.3*0.239	No	1-1.9	N.A.
[11]	4.07-5.58	N.A.	N.A.	1	1.37	0.152*0.152*0.152	No	3.2-4.9	MEMS
[14]	1.15-1.74	2.24-3.64	N.A.	2	1.65	0.15*0.115 (planar)	No	1.1-7.5	Varactors
[18]	0.37-1.03	N.A.	N.A.	1	2.76	0.56*0.22 *0.22	No	0.1-0.3	Ferrite Loaded
[23]	1.48-1.8	2.48-2.88	N.A.	2	1.21	0.25*0.25 (planar)	Yes	2.8-4.8	Varactors
[24]	1.1-1.7	2.04-2.4	N.A.	2	1.7	0.173*0.092 (planar)	No	6.4-11	Varactors
This work	0.8-3.2	0.8-3.2	0.8-3.2	3	4	0.21*0.16*0.133	Yes	0.6-2.6	Screws

 λ_c : The wavelength at the center frequency of the tuning frequency range. IL: Insertion loss.



FIGURE 15. Measured S-parameters of the individually and continuously tunable triple-band filter, (a) tuning of $|S_{21}|$ with fixed Passband I and II, (b) tuning of S_{11} with fixed Passband I and II, (c) tuning of $|S_{21}|$ with fixed Passband I and II, (d) tuning of $|S_{11}|$ with fixed Passband I and II, (e) tuning of $|S_{21}|$ with fixed Passband I and II, (e) tuning of $|S_{21}|$ with fixed Passband I and II, (c) tuning of $|S_{11}|$ with fixed Passband I and II, (b) tuning of $|S_{21}|$ with fixed Passband I and III, (c) tuning of $|S_{11}|$ with fixed Passband I and III, (c) tuning of $|S_{21}|$ with fixed Passband I and III, (c) tuning of $|S_{11}|$ with fixed Passband I and III, (c) tuning of $|S_{11}|$ with fixed Passband I and III, (c) tuning of $|S_{11}|$ with fixed Passband I and III, (c) tuning of $|S_{11}|$ with fixed Passband I and III, (c) tuning of $|S_{11}|$ with fixed Passband I and III, (c) tuning of $|S_{11}|$ with fixed Passband I and III, (c) tuning of $|S_{11}|$ with fixed Passband I and III, (c) tuning of $|S_{11}|$ with fixed Passband I and III, (c) tuning of $|S_{11}|$ with fixed Passband I and III, (c) tuning of $|S_{11}|$ with fixed Passband I and III, (c) tuning of $|S_{11}|$ with fixed Passband I and III.

Passband II can be tuned from 1.2 to 2.3? GHz with h_2 being tuned from 5 to 26 mm. Fig. 11(e) shows that, when Passband I and Passband II are fixed at 1 and 2 GHz with their tunable parameters $h_1 = 46.4$ mm, $h_2 = 24.3$ mm, $d_1 = 54.6$ mm and $d_2 = 53.4$ mm, the Passband III can be individually tuned from 2.4 to 3 GHz corresponding to a varying h_3 from 14 to 20 mm. As shown in Figs. 11(b), (d) and (f), the designed filters have the return loss better than -10 dB for all the passbands, which implies a good impedance matching. Meanwhile, the unloaded quality factor Q is obtained from 2000 to 3151.

IV. EXPERIMENTAL RESULTS

Following the discussion in Sections II and III, two individually and continuously tunable dual- and triple-band filters are fabricated and measured. Figs. 12(a) and 12(b) shows components, the fabricated filter cavity is divided into the two detached parts: the top-cover and the bottom cavities. Figs. 13(a) external view of the photography of dual- and triple-band filters, respectively. In order to facilitate the assembly of tuning and 13(b) shows the top-cover internal view of dual- and triple-band filters, respectively. Fig. 13(c) shows the bottom cavity internal view of the two filters. All of the components and the filter cavities are silver-plated to maintain a low the in-band insertion loss from the metal. The top cover of the filter cavity has slots embedded for sliding the posts horizontally. For structural support of the tunable posts, metal plates are implemented on the top surface of the sliding slots of the tunable posts.

In Fig. 14, there is a good agreement between the simulated and measured results of tunable dual-band filter. Fig. 14(a) shows the results in the case that the Passband II is fixed and the Passband I is tuned. The return loss is better than 10 dB in the tuning frequency passbands as shown in Fig. 14 (b). Fig. 14(c) displays the results in the case that the Passband I is fixed and the Passband II is tuning. The return loss in Fig. 14(d) is better than 10 dB in the tunable frequency passbands. This satisfies with the results in Fig. 9 and experimentally proves the continuously and individually tuning capability of the proposed dual-band cavity filter over a wide frequency range. From the simulated results, the proposed filters are designed to have the in-band insertion loss less than 0.5 dB. But the measured insertion loss varies from 0.86 dB to 2.7 dB over tuning range. The difference between the simulated and measured results is mainly due to the screws-based mechanical tuning approach. The nonideal contact between the tuning screws and the conductors may result in extra insertion losses. Due to the limitation of metal fabrication, the thread cannot cover the entire body of the screw leading to a shortened the tuning range (0.8 to 2.6 GHz) in measurement, which is about 600 MHz shorter than the simulated one. Fig. 15 shows three sets of simulated and measured results of the triple-band filter: 1) Set One, Fig. 15(a) and (b), the Passband I and II are fixed, while the Passband III is tuning, 2) Set Two, Fig. 15(c) and (d), the Passband I and III are fixed, while the Passband II is tuning, 3) Set Three, Fig. 15(e) and (f), the Passband II and III are fixed, while the Passband I is tuning. This experiment proves that the proposed triple-band filter can achieve individually and continuously frequency-tuning capability over a wide frequency range. Meanwhile, the triple-band filter provides better than 10 dB return loss as illustrated in Figs. 15(b), (d), and (f). The simulated and the measured results agree well with each other in FBW. Similar to the case in dual-band filter, the measured frequency-tuning range covers 0.8 to 2.8 GHz, which is 400 MHz shorter than the simulated one, due to the limitation of metal screws fabrication. The measured in-band insertion loss varies from 0.6 to 2.6 dB. Table I shows that, among the reported single-band and multiband frequency-tunable cavity filters, the mechnism generally applied for dual- and triple-band tuanable filters have not yet been reported, according to the authors' knowledge. Compared to those single-band tunable filters, our proposed filter has achieved the highest tuning ratio of 4, almost two times better than the reported ones. Moreover, our filter is very compact comparing with the counterparts, especially for the triple-band case. It is noteworthy that only a single metal cavity is implemented for the realization of the dual- and triple-band filters.

In this paper, a class of individually and continuously tunable dual- and triple-band filters have been presented. According to the authors' best knowledge, it is the first time that the mechanical-tuning approach is applied to achieve the dualand triple-band tunable filters with a tunable ratio of 4. This is almost 2 times better than the reported counterparts. Furthermore, all the components and resonators installed in a single metal cavity without any intra-cavity metallic wall, which significantly reduces the fabrication complexity. As experimentally verified, the proposed approach can be used for multiple-band filter designs with individually and continuously tunable capability over a wide frequency range of 0.8-3.2 GHz.

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