

Robust Sensor Technologies Combined with Smart Predictive Analytics for Hostile Sewer Infrastructures

by

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at the

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 $25^{\rm th}$ July 2018

Declaration of Authorship

I certify that the work in this dissertation has not previously been submitted for a degree

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within the text.

I also certify that the dissertation has been written by me. Any help that I have received

in my research work and the preparation of the dissertation itself has been acknowledged.

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i

UNIVERSITY OF TECHNOLOGY SYDNEY

Abstract

Faculty of Engineering and Information Technology

Centre for Autonomous Systems

Doctor of Philosophy

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Underground sewer systems are an important national infrastructure requirement of any country. In most cities, they are old and have been exposed to significant levels of microbial induced concrete corrosion, which is widely regarded as a serious global problem as they pose threats to public health and cause economic repercussions to water utilities. In order to maintain those underground assets efficaciously, it is pivotal for water utilities to estimate the amount of intact concrete left to rebar by predicting the rate of corrosion throughout the sewer network. Existing predictive models incorporate concrete surface temperature and surface moisture conditions as observations. However, researchers and water utilities often use indirect measures like ambient temperature and humidity data as inputs to their models. This is primarily due to unavailability of proven technologies in the state-of-the-art systems and sensing limitations predominantly attributed to the corrosive nature of the sewer environment. Hence, the focus of this dissertation is to provide reliable measures of surface temperature and moisture conditions by developing robust sensor technologies that can facilitate measurements under the hostile sewer conditions.

This dissertation encompasses three main parts:

In the first part, a robust sensor technology using an infrared radiometer sensor for quantifying surface temperature dynamics inside concrete sewer pipes is proposed. In this regard, the sensor was comprehensively evaluated in the laboratory conditions to study the effects of optical window fogging, incident angle, limit of detection, distance, lighting conditions, reproducibility, humidity and increased surface temperature conditions. Thereafter, the sensor was deployed in sewer pipe for real-time continuous measurements. The field study revealed the suitability of the proposed sensor technology for non-contact surface temperature measurements under the hostile sewer environment. Further, the accuracy of the sensor measurements was improved by calibrating the sensor with emissivity coefficient of the sewer concrete.

In the second part of the dissertation, a non-invasive sensing technique to determine the concrete surface moisture conditions is proposed. In this context, laboratory experiments were conducted to study the behaviour of concrete moisture to electrical resistance variations and different pH concentrations. This study led to utilize the Wenner array method to determine the surface moisture conditions based on concrete surface electrical resistivity measurements. Then, the sensor suite was deployed in concrete sewer pipe to measure the surface resistivity for about three months. Upon on-site calibration, surface moisture conditions were determined and thereof, the field campaign exhibited the feasibility of the proposed sensing method. Further investigations were conducted to locate the reinforcing bar embedded in concrete for optimal sensor installation in order to minimize the effects of reinforcing bar during measurements.

In the third part, sensor technologies were combined with smart predictive analytics to develop a diagnostic toolkit that can digitally monitor the health conditions of the sensors is proposed. This toolkit embraces a seasonal autoregressive integrated moving average model with statistical hypothesis testing technique to enable temporal forecasting of sensor data; identify and isolate anomalies in a continuous stream of sensor data; detect early sensor failure and finally to provide reliable estimates of sensor data in the event of sensor failure or during the scheduled maintenance period of sewer monitoring systems.

Overall, this dissertation significantly contributes to ameliorating the way sewer assets are monitored and maintained in Australia and globally by providing information-rich new data to the predictive models for better corrosion prediction.

Acknowledgements

This dissertation is the result of the research conducted by me during the last four years at the Centre for Autonomous Systems of The University of Technology Sydney, Australia. The presented work is part of a water industry led collaborative project, "Data Analytics on Sewers", funded by Sydney Water Corporation, Melbourne Water Corporation, Water Corporation (WA) and South Australian Water Corporation. The research participants are Data61-Commonwealth Scientific and Industrial Research Organization (CSIRO), University of Technology Sydney (UTS) and University of Newcastle (UoN).

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I truly appreciate the support offered by the industrial partners of "Data Analytics on Sewers" project in successful completion of this dissertation. Specially, I would like to acknowledge the support of Mr. Dammika Vitanage, Mr. Gino Iori, Mr. Craig Earl, Mr. Jeremy Hearfield, Mr. Derek Cunningham and Mr. Steve Barclay from Sydney Water Corporation. Technical discussions with Dr. Fang Chen, Dr. Yang Wang and Dr. Bin Li from Data61-CSIRO during Technical Committee Meeting for Sewer Corrosion project were valuable in gaining insights about corrosion modelling. In addition, Prof. Robert Melchers and Prof. Tony Wells helped me to gain domain knowledge on concrete corrosion.

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Contents

De	eclar	ation of Authorship	i
Al	ostra	$\operatorname{\mathbf{ct}}$	ii
A	cknov	wledgements	iv
Li	st of	Figures	x
Li	st of	Tables	xiii
No	omen	nclature x	vii
$\mathbf{G}^{\mathbf{I}}$	lossa	ry of Terms	xxi
1	Intr 1.1 1.2 1.3 1.4 1.5	Hostile Sewer Infrastructures Research Motivation Statement of the Problem Principal Contributions First Published Appearances of the Described Contributions 1.5.1 Journals 1.5.2 Conference Proceedings 1.5.3 Technical Reports The Structure of the Dissertation	1 3 5 7 9 10 10 11 11 12
2	Rob Sew 2.1 2.2	8	13 13 16 16 17 17 18 19

Contents vii

		2.2.1.5	Thermistors	19	
		2.2.1.6	Infrared Temperature Measurement Devices	21	
		2.2.1.7	Fiber Optic Type Temperature Measurement Device	24	
		2.2.1.8	Distributed Temperature Sensing	26	
	2.2.2	Feasibili	ty	26	
		2.2.2.1	Temperature Conditions Inside Australian Sewers	27	
		2.2.2.2	Comparative Analysis	28	
	2.2.3	Conclud	ing Remarks	29	
2.3	Sensor	Characte	erization and Development for Measuring Surface Temperature	29	
	2.3.1	Assessm	ent of Infrared Radiometer (IRR) Sensor's Optical Window		
		in Varie	d Humidity Conditions	30	
	2.3.2	The Effe	ects of Incident Angle on the IRR Sensor Performance and		
		their Lin	mit of Detection	30	
	2.3.3	Distance	e, Lighting Condition and Reproducibility	31	
	2.3.4		ance of IRR Sensor in Higher Humidity Conditions	31	
	2.3.5	IRR Sen	asor Performance with Varying Surface Temperatures	31	
	2.3.6		Development and Packaging	32	
2.4			ent for Real-time Continuous Measurements Inside Hostile		
			cture	35	
2.5			at Validations of the IRR Sensor After Long Exposure to		
2.0			Conditions	38	
2.6	Improving Surface Temperature Measurements of IRR Sensor based on On-				
				38	
0.7	2.6.1		ical Considerations and On-site Calibration	38	
2.7	•		Results	40	
	2.7.1 Pre-deployment Evaluation: Sensor Characterization and Development				
		2.7.1.1		41	
		2.7.1.1 $2.7.1.2$	Evaluating the Effects of Incident Angle and Limit of	41	
		2.1.1.2	Detection	42	
		2.7.1.3	Evaluating the Effects of Distance, Lighting Condition and	12	
		2.1.1.0	Reproducibility	43	
		2.7.1.4	Evaluating the Performance of IRR Sensor in Higher		
			Humidity Conditions	44	
		2.7.1.5	Evaluating the IRR Sensor Performance with Varying		
			Surface Temperatures	45	
		2.7.1.6	Sensor Development and Packaging Prior to Sewer		
			Deployment	46	
	2.7.2	Field De	eployment Experimentation: Data Collection and Analysis .	47	
		2.7.2.1	Real-time Sensor Data Showing Temporal Dynamics of		
			Surface Temperature Measurements from the Sewer Pipe .	47	
		2.7.2.2	Comparative Analysis of Temperature Variables Data	48	
	2.7.3		ployment Validations	49	
	2.7.4	-	d Measurements of IRR Sensor with Post Calibration Analysis	50	
2.8	Summ	ary		51	

Contents viii

3 Ro 3.1		ensor Technology for Measuring Surface Moisture in Sewers 5 duction		
3.2	ng Study: Sensors for Surface Moisture Measurements 5			
	3.2.1	Sensors for Moisture Sensing		
	0.2.	3.2.1.1 Gravimetric Method		
		3.2.1.2 Gamma Densitometry Method 5		
		3.2.1.3 Electrical Resistivity Method 5		
		3.2.1.4 Capacitance Sensor		
		3.2.1.5 Resonator Based Methods 6		
		3.2.1.6 Time Domain Reflectometry based Sensors 6		
		3.2.1.7 Frequency Domain Reflectometry based Sensors 6		
		3.2.1.8 Fibre Optic Sensors		
		3.2.1.9 Micro Electro Mechanical Systems Sensors 6		
		3.2.1.10 Hyperspectral Sensing		
	3.2.2	Feasibility		
	3.2.3	Concluding Remarks		
3.3	Exper	rimental Evaluation to Study the Behaviour of Concrete Moisture with		
	_	rical Resistance and pH Conditions		
	3.3.1	Experimental Approach		
		3.3.1.1 Concrete Sample Preparation 6		
		3.3.1.2 pH Measurements		
		3.3.1.3 Moisture Measurements 6		
		3.3.1.4 Electrical Resistance Based Sensor System		
	3.3.2	Data-driven Approach for Predicting Moisture Content		
3.4	Senso	r Development and Pre-deployment Evaluation		
3.5	Field	Application for Real-time Measurements of Surface Moisture Conditions 7		
	3.5.1	Sensor Suite Deployment		
3.5.2 $$ Field Data Collection and On-site Calibration		Field Data Collection and On-site Calibration 8		
3.6	1 v			
	to Ho	stile Sewer Condition		
3.7	Locat	ing the Rebar Orientation using Electrical Resistivity Measurements . $$ 8		
	3.7.1	Data Collection		
	3.7.2	Spatial Estimation using Gaussian Markov Random Fields 8		
		3.7.2.1 Gaussian Markov Random Fields 8		
		3.7.2.2 Spatial Field Model by way of Gaussian Markov Random		
		Fields		
		3.7.2.3 $$ Sensor Data Modelled by GMRF Using SPDE Approach $$. $$ 8		
3.8	Exper	rimental Results		
	3.8.1	Experimental Evaluation to Study the Effects of Concrete Moisture		
		with Electrical Resistance and pH		
	3.8.2	Sensor Development and Pre-deployment Evaluation 9		
	3.8.3	Field Deployment Application		
		3.8.3.1 Real-time Sensor Data Showing Temporal Dynamics of		
		Surface Resistivity Measurements from the Sewer Pipe 9		

Contents

On-site Calibration and Surface Moisture Interpretations .

Spatial Estimation of Rebar Using GMRF

92

92

95

97

151

3.8.3.2

3.8.3.3

3.8.4

3.9

Bibliography

Sma	art Predictive Analytics for Detecting Sensor Failure 104
4.1	Introduction
4.2	Related Works
4.3	Forecasting Temporal Dynamics of Quantified Variables from the Sensing
	Suite
	4.3.1 Surface Temperature and Surface Resistivity Data From the Sensing
	Suite
	4.3.2 Formulation of Seasonal Autoregressive Integrated Moving Average
	(SARIMA) Model
	4.3.3 Automatic Selection of SARIMA Model Parameters
	4.3.4 Computing Prediction Intervals of the Forecasts at Any Lead Time 114
4.4	SFDA Algorithm
4.5	Experimental Evaluation Results
	4.5.1 Comparative Analysis of Forecasting Models
	4.5.2 SFDA Algorithm Evaluation: Anomalies and Sensor Failure Detection 127
	4.5.3 SFDA Algorithm Evaluation: Forecasting Performance
	4.5.4 SFDA Algorithm Evaluation: Data Accommodation Process 138
4.6	Summary
Con	clusions 144
5.1	Summary of Contributions
5.2	Discussion of Limitations
5.3	Implications for the Water Industry
5.4	Future Research
	4.1 4.2 4.3 4.4 4.5 4.6 Con 5.1 5.2 5.3

List of Figures

1.1	Multi-sensor robot for condition assessment of sewer infrastructures [1]	2
1.2	Microbial induced corrosion process in concrete sewer assets	4
2.1	Surface Temperature Sensors (A) Infrared Radiometer Sensor (B) Epoxy coated thermistor sensor	33
2.2	Enclosure testing in sewers. (A) Deploying mechanism of the enclosure (B) Enclosure inside sewer having Hydrogen Sulphide (H_2S) around 5ppm	34
2.3	Field deployment of a sensor suite at a sewer site for real-time measurements of temperature variables. (A) Installations of the sensing unit at the crown of the sewer pipe for monitoring surface temperature variations (B) Construction of the monitoring unit outside the sewer pipe (C) Housing the monitoring unit using an electrical pillar box having	36
2.4	Assessment of the optical window exposed to different relative humidity conditions inside the humidity chamber. (A) 80% RH (B) 90% RH (C)	41
2.5	100% RH	41
		42
2.6	Statistical comparative analysis of IRR sensor measurements obtained in illuminated and dark ambient conditions by positioning the sensor in	49
2.7	Computed measures of RMSE and MAPE illustrating the IRR sensor	43
2.8	Computed measures of RMSE and MAPE illustrating the IRR sensor with	45
2.9	Sensor enclosure. (A) New enclosure CAD Model (B) Top-view of the sensor	46
2.10	·	47
2.11		48
2.12	Comparison of daily average surface temperature profile from IRR sensor with the daily average of ambient temperature outside the sewer pipe	49
2.13	Sensor enclosure after exposure to hostile sewer conditions. (A) Front view of the sensor enclosure (B) Picture showing the degradation on the	
	germanium optical window (C) Top view of the sensor enclosure	50

List of Figures xi

2.14	Improving surface temperature measurements of the IRR sensor between November 2016 and January 2017	51
3.1	Functional block diagram of the sensor system	72
3.2	Resistance sensor circuit.	72
3.3	Surface resistivity measurement. (A) Commercial resistivity meter from	
	Proceq (B) Wenner method to measure surface resistivity	76
3.4	Moisture sensor deployment. (A) Sensing unit near the crown of the	
	concrete sewer pipe (B) Monitoring unit of the access station constructed	
	outside the sewer pipe	79
3.5	Electrical Resistance vs. Volumetric Moisture Content	88
3.6	Learned GP model with training data	88
3.7	GP predictions in 3D	89
3.8	The behaviour of predicted values corresponding to training data	89
3.9	The behaviour of predictions vs. measured values (testing data)	90
3.10	(A) Accommodation of resistivity meter inside sensor enclosure CAD model and (B) Sensor enclosure displaying the electrodes of the resistivity meter.	91
2 11	Surface resistivity profiles obtained from the concrete sewer pipe	93
	Profiles of surface resistivity, surface temperature and ambient temperature.	94
	Surface moisture profiles obtained from the concrete sewer pipe	96
	Moisture sensor measurements after long exposure to sewer conditions	97
	Sensor enclosure after exposure to hostile sewer conditions for about three	0.
0.20	months. (A) Top view of the sensor enclosure displaying the sensor	
	electrodes and (B) Side view of the enclosure displaying the de-colouration	
	occurred during the field evaluation	98
3.16	Spatial estimation using GMRF by taking resistivity measurements at 0° .	98
	Spatial estimation using GMRF by taking resistivity measurements at 30°.	99
	Spatial estimation using GMRF by taking resistivity measurements at 45°.	99
		100
3.20	Spatial estimation using GMRF by taking resistivity measurements at 90°.	100
4.1	Block diagram of hardware redundancy	107
4.2	Block diagram of analytical redundancy	
4.3	Illustration of the sliding window mechanism at time period t	
4.4	Illustration of the chi square	
4.5	Profile of the training data	
4.6	Forecast data profile resulting from the Exponential Smoothing (ETS) model.	
4.7	Forecast data profile resulting from the TBATS model	
4.8	Forecast data profile resulting from the SARIMA model	125
4.9	Comparison of time series forecasting of sensor data using SARIMA,	105
1.10	TBATS and ETS models with the measured sensor data profile	
	IRR Sensor: Short-term Evaluation-1 of SFDA algorithm	
	Long-term evaluation of SFDA algorithm	
	Moisture Sensor: Short-term Evaluation-1 of SFDA algorithm	

List of Figures xii

4.14	Moisture Sensor: Short-term Evaluation-2 of SFDA algorithm	133
4.15	Illustration of SARIMA model forecasting performance of surface	
	temperature data	135
4.16	Illustration of SARIMA model forecasting performance of surface resistivity	
	data	136
4.17	Illustration of the data accommodation during IRR sensor failure	139
4.18	Illustration of the data accommodation during moisture sensor failure	140

List of Tables

2.1	Gas-phase temperatures inside confined sewer system	27
2.2	Feasibility Analysis: Comparison of surface temperature measurement	
	modalities	28
2.3	Specifications of the surface temperature sensors used in this study	33
3.1	Feasibility: Comparison of surface moisture measurement modalities	66
3.2	Mass of concrete samples in dry condition	68
3.3	Mass of concrete samples in wet condition	68
3.4	Concrete samples in different pH value of solutions	69
3.5	Depth profile of moisture penetration inside concrete	70
3.6	Density of concrete samples in dry condition	70
3.7	Density of pH solution	71
3.8	Specifications of the resistivity meter	
4.1	Statistical Performance Evaluation of Time Series Models	127
4.2	IRR Sensor: Statistical Evaluation of SFDA Model's Forecasting Performance.137	
4.3 Moisture Sensor: Statistical Evaluation of SFDA Model's Foreca		
	Performance	138
4.4	Evaluation of SFDA Model's Data Accommodation Process for IRR Sensor.	141
4.5	Evaluation of SFDA Model's Data Accommodation Process for Moisture	
	Sensor	141

Acronyms & Abbreviations

1D One-dimensional

2D Two-dimensional

3D Three-dimensional

AC Alternating Current

AIC Akaike Information Criterion

AR Autoregressive

ARMA Autoregressive Moving Average

ARIMA Autoregressive Integrated Moving Average

CAS Centre for Autonomous Systems

CCTV Closed-circuit television

CW Critical Wavelength

DC Direct Current

DTS Distributed Temperature Sensing

ETS Exponential Smoothing

FBG Fiber Bragg Gratings

FDR Frequency Domain Reflectometry

FG Fiber Grating

GMRF Gaussian Markov Random Fields

GP Gaussian Process

GPR Gaussian Process Regression

 $\mathbf{H}_2\mathbf{S}$ Hydrogen Sulphide

 $\mathbf{H}_2\mathbf{SO}_4$ Sulphuric acid

IRR Infrared Radiometer

IRT Infrared Thermography

MA Moving Average

MAE Mean Absolute Error

MAPD Mean Absolute Percentage Deviation

MAPE Mean Absolute Percentage Error

MPE Mean Percentage Error

NTC Negative Temperature Coefficient

RF Radio Frequency

RFs Radio Frequencies

RH Relative Humidity

RMSE Root Mean Square Error

RTD Resistance Temperature Detector

RW Random Walk

SARIMA Seasonal Autoregressive Integrated Moving Average

SDR Successful Detection Rate

SES Simple Exponential Smoothing

SFA Sensor Failure Accommodation

SFDA Sensor Failure Detection and Accommodation

SPDE Stochastic Partial Differential Equations

TDR Time Domain Reflectometry

UTS University of Technology Sydney

Nomenclature

General Notations

cm Centimetre (unit).

Dt Time interval between the two sensor measurements.

df Degrees of freedom.

mm Millimetre (unit).

g Gram (unit).

 m_d Mass of the concrete sample in a dry condition. m_w Mass of the concrete sample in a wet condition.

n Number of Samples.

ppm Parts per Million (unit).

t Time (continuous).

V Voltage (unit). $^{\circ}C$ Degree Celsius.

 μ Mean.

 σ Standard deviation.

 σ^2 Variance.

 ρ_d Density of concrete sample in a dry condition.

 ρ_w Density of pH solution.

 $heta_G$ Wet basis moisture content of a material. Volumetric moisture content of a material.

Nomenclature xviii

	Sensors
T_{IRR}	Surface temperature measurements from the infrared radiometer
	sensor.
T_{RIT}	Surface temperature measurements from the reference instrument
	thermistor sensor.
	On-site Calibration of Sensors
E	Measurement error.
E_{ir}	Radiant energy detected by the infrared surface temperature sensor.
E_{tr}	Radiant energy detected by the contact-type surface temperature
	sensor.
SM	Surface moisture conditions.
SR_S	Surface resistivity value measured from the resistivity meter.
SR_W	Surface resistivity value measured at wet area of the concrete sewer
	pipe.
SR_D	Surface resistivity value measured at dry area of the concrete sewer
	pipe.
T_{is}	Temperature measured by the infrared surface temperature sensor.
T_{tr}	Temperature measured by the contact-type surface temperature
	sensor.
ϵ_{is}	Set emissivity of the infrared sensor.
ϵ_t	True emissivity of the measured surface.
ϵ_{IR}	Set emissivity of the infrared radiometer sensor.
ϵ_T	Estimated emissivity of the surface.
μ	Mean value of ϵ_T .
	SFDA Algorithm
AR(p)	Autoreggressive model of order p .
$AR(p)_t$	Actual value of $AR(p)$ at time t .
ARMA(p,q)	Autoreggressive Moving Average model of order p and q .

 $ARMA(p,q)_t$ Actual value of ARMA(p,q) at time t.

Nomenclature xix

$\begin{array}{lll} ARIMA(p,d,q)_t & \text{Actual value of }ARIMA(p,d,q) \text{ at time }t. \\ B & \text{Backshift operator.} \\ d & \text{Parameter governs the level of differencing.} \\ D & \text{Degree of seasonal differencing parameter.} \\ k & \text{Backward observation of the time series.} \\ K_n & \text{Number of parameters estimated to compute one-step ahead forecasts.} \\ L & \text{Maximized likelihood of the }SARIMA(p,d,q)(P,D,Q)_{S_p} \text{ model.} \\ MA(q) & \text{Moving Average model of order }q. \\ MA(q)_t & \text{Actual value of }MA(q) \text{ at time }t. \\ p & \text{Autoregressive model order.} \\ P & \text{Seasonal Autoregressive model order.} \\ Q & \text{Seasonal Moving Average model order.} \\ Q_t & \text{Seasonal Moving Average model order.} \\ SARIMA & SARIMA(p,d,q)(P,D,Q)_{S_p} \text{ model with parameters }p,d,q,P,D \text{ and }Q. \\ S_p & \text{Seasonal period of the stochastic model.} \\ S_{t+f} & \text{Future observable variable.} \\ \tilde{S}_{t-n} & \text{Previous deviations from the mean value of the time series data.} \\ \hat{S}_{t+f}(+) & \text{Forecast value resulting from the SARIMA model.} \\ \hat{S}_{t+f}(-) & \text{Lower limit of the forecast.} \\ \hat{S}_{t+f}(-) & \text{Lower limit of the forecast.} \\ W_L & \text{Size of sliding window} \\ \phi_n & \text{Finite set of weight parameters of the }AR(p).} \\ \theta_n & \text{Finite set of weight parameters of the }MA(q).} \\ \varepsilon_t & \text{Random shock.} \\ \mu_{\lambda/2} & \text{Percentiles of the standard normal distribution.} \\ \end{array}$	ARIMA(p,d,q)	Autoreg gressive Integrated Moving Average model of order p,d and
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$K_n \qquad \text{Number of parameters estimated to compute one-step ahead forecasts.} \\ L \qquad \text{Maximized likelihood of the } SARIMA(p,d,q)(P,D,Q)_{S_p} \text{ model.} \\ MA(q) \qquad \text{Moving Average model of order } q. \\ MA(q)_t \qquad \text{Actual value of } MA(q) \text{ at time } t. \\ p \qquad \text{Autoregressive model order.} \\ P \qquad \text{Seasonal Autoregressive model order.} \\ q \qquad \text{Moving Average model order.} \\ Q \qquad \text{Seasonal Moving Average model order.} \\ R_t \qquad \text{Observe red sensor data coming from the sewer.} \\ SARIMA \qquad SARIMA(p,d,q)(P,D,Q)_{S_p} \text{ model with parameters } p,d,q,P,D \text{ and } Q. \\ S_p \qquad \text{Seasonal period of the stochastic model.} \\ S_{t+f} \qquad \text{Future observable variable.} \\ \tilde{S}_{t-n} \qquad \text{Previous deviations from the mean value of the time series data.} \\ \hat{S}_{t+f}(+) \qquad \text{Upper limit of the forecast.} \\ \hat{S}_{t+f}(-) \qquad \text{Lower limit of the forecast.} \\ \hat{S}_{t+f}(-) \qquad \text{Lower limit of the forecast.} \\ W_L \qquad \text{Size of sliding window} \\ \phi_n \qquad \text{Finite set of weight parameters of the } AR(p). \\ \theta_n \qquad \text{Finite set of weight parameters of the } MA(q). \\ \varepsilon_t \qquad \text{Random shock.} \\ Previous the stable to the limit of the interval of the limit of limit o$	D	Degree of seasonal differencing parameter.
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	k	Backward observation of the time series.
$\begin{array}{lll} L & \text{Maximized likelihood of the } SARIMA(p,d,q)(P,D,Q)_{S_p} \text{ model.} \\ MA(q) & \text{Moving Average model of order } q. \\ MA(q)_t & \text{Actual value of } MA(q) \text{ at time } t. \\ p & \text{Autoregressive model order.} \\ P & \text{Seasonal Autoregressive model order.} \\ q & \text{Moving Average model order.} \\ Q & \text{Seasonal Moving Average model order.} \\ R_t & \text{Observe red sensor data coming from the sewer.} \\ SARIMA & SARIMA(p,d,q)(P,D,Q)_{S_p} \text{ model with parameters } p,d,q,P,D \text{ and } Q. \\ S_p & \text{Seasonal period of the stochastic model.} \\ S_{t+f} & \text{Future observable variable.} \\ \tilde{S}_{t-n} & \text{Previous deviations from the mean value of the time series data.} \\ \hat{S}_{t+f}(+) & \text{Forecast value resulting from the SARIMA model.} \\ \hat{S}_{t+f}(+) & \text{Upper limit of the forecast.} \\ \hat{S}_{t+f}(-) & \text{Lower limit of the forecast.} \\ W_L & \text{Size of sliding window} \\ \phi_n & \text{Finite set of weight parameters of the } AR(p).} \\ \theta_n & \text{Finite set of weight parameters of the } MA(q).} \\ \varepsilon_t & \text{Random shock.} \\ \end{array}$	K_n	Number of parameters estimated to compute one-step ahead
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$\begin{array}{lll} p & \text{Autoregressive model order.} \\ P & \text{Seasonal Autoregressive model order.} \\ q & \text{Moving Average model order.} \\ Q & \text{Seasonal Moving Average model order.} \\ R_t & \text{Observe red sensor data coming from the sewer.} \\ SARIMA & SARIMA(p,d,q)(P,D,Q)_{Sp} \operatorname{model with parameters} p,d,q,P,D \operatorname{and} Q. \\ S_p & \text{Seasonal period of the stochastic model.} \\ S_{t+f} & \text{Future observable variable.} \\ \tilde{S}_{t-n} & \text{Previous deviations from the mean value of the time series data.} \\ \hat{S}_{t+f}(+) & \text{Forecast value resulting from the SARIMA model.} \\ \hat{S}_{t+f}(-) & \text{Upper limit of the forecast.} \\ \hat{S}_{t+f}(-) & \text{Lower limit of the forecast.} \\ W_L & \text{Size of sliding window} \\ \phi_n & \text{Finite set of weight parameters of the } AR(p).} \\ \theta_n & \text{Finite set of weight parameters of the } MA(q).} \\ \varepsilon_t & \text{Random shock.} \\ \end{array}$	MA(q)	Moving Average model of order q .
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$\begin{array}{lll} q & \text{Moving Average model order.} \\ Q & \text{Seasonal Moving Average model order.} \\ R_t & \text{Observe red sensor data coming from the sewer.} \\ SARIMA & SARIMA(p,d,q)(P,D,Q)_{Sp} \operatorname{model with parameters } p,d,q,P,D \operatorname{and } Q. \\ S_p & \text{Seasonal period of the stochastic model.} \\ S_{t+f} & \text{Future observable variable.} \\ \tilde{S}_{t-n} & \text{Previous deviations from the mean value of the time series data.} \\ \hat{S}_{t+f}(+) & \text{Forecast value resulting from the SARIMA model.} \\ \hat{S}_{t+f}(-) & \text{Upper limit of the forecast.} \\ \hat{S}_{t+f}(-) & \text{Lower limit of the forecast.} \\ W_L & \text{Size of sliding window} \\ \phi_n & \text{Finite set of weight parameters of the } AR(p).} \\ \theta_n & \text{Finite set of weight parameters of the } MA(q).} \\ \varepsilon_t & \text{Random shock.} \\ \end{array}$	p	Autoregressive model order.
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$SARIMA \qquad SARIMA(p,d,q)(P,D,Q)_{Sp} \ \text{model with parameters } p,d,q,P,D \ \text{and} \ Q.$ $S_p \qquad \text{Seasonal period of the stochastic model.}$ $S_{t+f} \qquad \text{Future observable variable.}$ $\tilde{S}_{t-n} \qquad \text{Previous deviations from the mean value of the time series data.}$ $\hat{S}_{t+f}(+) \qquad \text{Forecast value resulting from the SARIMA model.}$ $\hat{S}_{t+f}(+) \qquad \text{Upper limit of the forecast.}$ $\hat{S}_{t+f}(-) \qquad \text{Lower limit of the forecast.}$ $W_L \qquad \text{Size of sliding window}$ $\phi_n \qquad \text{Finite set of weight parameters of the } AR(p).$ $\theta_n \qquad \text{Finite set of weight parameters of the } MA(q).$ $\varepsilon_t \qquad \text{Random shock.}$	Q	Seasonal Moving Average model order.
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ϕ_n Finite set of weight parameters of the $AR(p)$. θ_n Finite set of weight parameters of the $MA(q)$. ε_t Random shock.	$\hat{S}_{t+f}(-)$	Lower limit of the forecast.
$ heta_n$ Finite set of weight parameters of the $MA(q)$. Random shock.	W_L	Size of sliding window
$arepsilon_t$ Random shock.	ϕ_n	Finite set of weight parameters of the $AR(p)$.
	$ heta_n$	Finite set of weight parameters of the $MA(q)$.
$\mu_{\lambda/2}$ Percentiles of the standard normal distribution.	$arepsilon_t$	Random shock.
	$\mu_{\lambda/2}$	Percentiles of the standard normal distribution.

Standard deviation of the Gaussian distribution.

 σ_g

Nomenclature

χ^2	Pearson's chi-squared test.
χ^2_{df}	Chi-squared distribution.
α	Critical value.

Glossary of Terms

Ambient Pertains to the immediate surroundings.

Anomalies Data that deviates from the standard, normal, or expected.

Autonomous Without human intervention.

Data Utilizing the data coming from the reliable measure, prediction

Accommodation or estimation.

Field Deployment The transportation of equipment to a place or position for

desired operations.

Forecasting Predict or estimate the future trends or unknown events.

Infrared Radiometer An instrument for detecting or measuring the intensity of

radiation using infrared signals.

Measurements The action of measuring the physical quantities.

Modelling A description of a system using mathematical concepts and

language. The process of developing a mathematical model is

termed mathematical modelling.

Predictive Analytics A variety of statistical techniques from predictive modelling,

machine learning and data mining to predict future trends or

unknown events by using historical and transactional data.

Real-time Relating to a system in which input data is processed within

milliseconds so that it is available virtually immediately as

feedback to the process from which it is coming.

Relative Humidity The amount of water vapour present in air expressed as a

percentage of the amount needed for saturation at the same

temperature.

Resistance The measure of the degree to which a conductor opposes an

electric current through that conductor.

Resistivity It is a fundamental property that quantifies how strongly a

material under test is opposing the flow of electric current.

Robust Able to withstand or overcome adverse conditions.

Sensing Suite A set of sensors enclosed in a housing to perform measurements

of interest.

Sensor A device that detects or measures a physical property, indicates

or otherwise responds to it.

Sensor A description of the distinctive nature or features of the sensor

Characterization under different condition.

Sensor Failure The state of improper functioning of a sensor.

Sewers An underground conduit for carrying off drainage water and

waste matter.

Smart Device programmed so as to be capable of some independent

action.

Study A detailed investigation and analysis of a subject or situation.

Technology Device or equipment developed from the application of

scientific knowledge.

Temporal Dynamics The properties that changes within a system or process relating

to or denoting time.

Quantification The measurement of the variable of interest.