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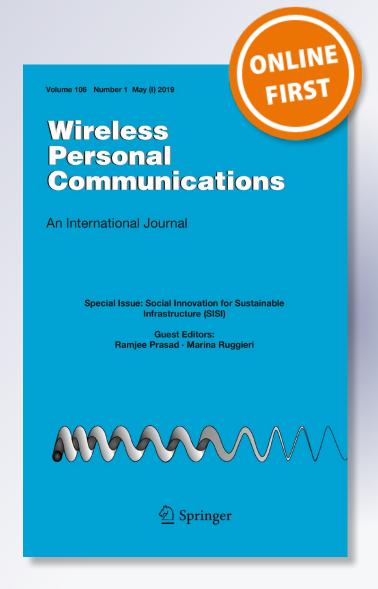
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A Model Based Poisson Point Process for Downlink Cellular Networks Using Joint Scheduling

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Abstract

This paper proposes a model based on a random cellular network to analyse performance of Joint Scheduling in which a typical user measures signal-to-interference-plus-noise ratio (SINR) on different resource blocks from K nearest BSs in order to find out the BS with the highest SINR to establish communication. The paper derives the general form of average coverage probability of a typical user in the case of K > 2 and its close-form expression in the case of K = 2. The analytical results which are verified by Monte Carlo simulation indicates that (1) using the Joint Scheduling can improve the user's performance up to 34.88% in the case of the path loss exponent $\alpha = 3$; (2) the effect of the density of BSs on the user association probability is infinitesimal.

Keywords Poisson point process · Joint scheduling · Coverage probability

1 Introduction

In a LongTerm Evolution-Advanced (LTE-A) cellular network, coordinated multipoint (CoMP) transmission and reception such as Joint Scheduling [1] is a promising technique that can enhance the quality of the received signals as well as mitigate the effects of interference.

In a Joint Scheduling network with a cluster size of K, every K adjacent BSs are grouped into a cluster in which the Channel State Information (CSI) is exchanged within this cluster. Conventionally, a typical user measures SINR from K nearest BSs and selects the BSs with the highest SINR as the serving BS. Hence, the downlink SINR of the typical user is given by $\max(SINR_1, \ldots, SINR_K)$. Fig. 1 is an example of Joint Scheduling with the number of coorinated BSs K = 3.

In the literature, there was an association approach that allows the user connect to the strongest BS which is called flexible user association [2, 3]. In these works, the user measures the downlink SINR from all BSs and select the BS with highest average

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received-signal strength as the serving BSs. The main differences between Joint Scheduling and flexible association approach are as follows: (1) the flexible association approach only considers the transmit power of BSs and the path loss. Thus, the user only connects to the nearest BS when all BSs transmit at the same power. (2) the Joint Scheduling takes the instantaneous transmission conditions such as fading, intercell interference in the association solution.

In the literature, a lot of research works have been conducted to evaluate the performance of Joint Scheduling in a hexagonal network layout only, which were surveyed in [4]. To the best of our knowledge, work on performance analysis of Joint Scheduling in Poisson point process (PPP) network layout [5] was only conducted in [6]. In this paper, the worst case user with equal distances to three nearest BSs was studied. In addition, the paper assumed that the worst case user measures SINR on the same resource block (RB), which causes all measured signals at the typical user to have the same interference. Thus, the serving BS was selected according to fading channels between the typical user and BSs only. This assumption may be infeasible in practical networks since it may be impossible to find a RB which is free in two adjacent cells at the same time.

In this paper, the performance of the typical user who is located randomly in the cellular network using Joint Scheduling is investigated. Instead of assuming that the user measures SINR on the same RB, the typical user in this work observes K values of SINRs on K different RBs from K BSs. Take K=2 for example, SINR from the BS 1 on RB m and BS 2 on RB m ($m \ne m$) are observed. Since fading channels vary between RBs, the interference power of the measured SINR from these BSs are different though all signals are affected by interference originating from the same BSs. Thus, the selection of a serving BS depends on various network parameters such as the fading channels, transmit power of BSs, and distance from the typical user to BSs.

2 Network Model

2.1 Network Topology

We consider the cellular network using Joint Scheduling with a cluster size of K in which the BSs are distributed according to a PPP with density λ .

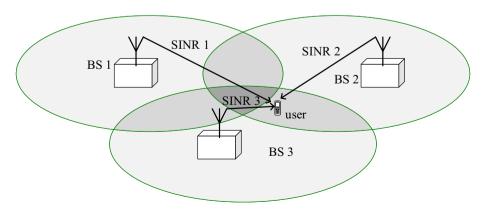


Fig. 1 An example of joint scheduling with K = 3



The typical user is assumed to be located at the origin. We denote r_k as the distance from the typical user to the BS k which is a random variable whose the probability density function (PDF) is given by

$$f_{R_k}(r_k) = \frac{2(\pi\lambda)^k}{(k-1)!} r_k^{2k-1} e^{-\pi\lambda r_k^2}$$
 (1)

The joint PDF of R_1, R_2, \ldots , and R_K in which $R_1 < R_2 < \cdots < R_K$ is defined by $f_{R_1, \ldots, R_K}(r_1, \ldots, r_K)$ which is given by [7]

$$f_{R_1,\dots,R_K}(r_1,\dots,r_K) = (2\pi\lambda)^K e^{-\pi\lambda r_K^2} \prod_{m=1}^K r_m$$
 (2)

Therefore, the joint PDF of any N random variables in S which is a subset of $\{1, 2, ..., K\}$ is denoted by $f_S(S)$ and obtained by integrating K - N integrals of $f_{R_1,...,R_K}(r_1,...,r_K)$ with respect to $r_i(r_i \in S^c)$ by the following equation

$$f_S(S) = (2\pi\lambda)^K \int \cdots \int e^{-\pi\lambda r_K^2} \prod_{m=1}^K r_m \prod_{i \in S^c} dr_i$$
 (3)

in which S^c is the complementary set of S, $S^c = \{1, 2, ..., K\} \setminus \{S\}$, the bounds of integrations satisfy the following rule: $0 < r_1 < \cdots < r_K < \infty$.

2.2 The Downlink Model

In a LTE-Advanced network using Joint Scheduling, the typical user experiences interference from all active BSs which can be separated into: (1) Intra-Cluster BSs which includes the BSs within the associated cluster, and (2) Inter-Cluster BSs which includes BSs belonging to other clusters. Hence, the downlink interference at the typical user associated with BS k can be stated as

$$I_{k} = \sum_{j=1, j \neq k}^{K} P_{j} g_{j}^{(k)} r_{j}^{-\alpha} + \sum_{j \in \theta^{c}} P_{j} g_{j}^{(k)} r_{j}^{-\alpha}$$

$$Intra-Cluster Interference \qquad Inter-Cluster Interference \qquad (4)$$

in which $g_j^{(k)}$ and r_j are the power channel gain and distance from the typical user to interfering BS j whose transmit power is P_j ; α is the path-loss exponent; θ^c is the set of interfering BSs which belong to adjacent clusters. We denote θ is the set of BSs in the network, then $\theta = \theta^c \bigcup \{1, 2, ..., K\}$.

Since the BSs in a given cluster fully exchange the channel state information, the Intra-Cell Interference can be controlled by the scheduling mechanism. Meanwhile the Inter-Cluster Interference may not be controlled. For simplicity, we assume that the typical user only experiences Inter-Cluster Interference. Furthermore, the transmit power of the BS in the cellular network is usually much greater than Gaussian noise, then Gaussian noise can be neglected. Thus, the downlink signal-interference-ratio (SIR) from BS k is given by

$$SIR_{k} = \frac{P_{k}g_{k}^{(k)}r_{k}^{-\alpha}}{\sum_{j \in \theta^{c}} P_{j}g_{j}^{(k)}r_{j}^{-\alpha}}$$
(5)

We assume that all BSs transmit at the same power, thus the serving signal of the typical user is given by

$$SIR = \max_{1 \le k \le K} \left(\frac{g_k^{(k)} r_k^{-\alpha}}{\sum_{j \in \theta^c} g_j^{(k)} r_j^{-\alpha}} \right)$$
 (6)

In this paper, each fading channel has a unit power and follows a Rayleigh fading distribution, thus the channel power gain $g_j^{(k)}$ is an exponential distribution with PDF $\gamma(g) = \exp(-g)$.

3 Average Coverage Probability

The average coverage probability of the typical user for a given coverage threshold T is defined as the probability in which the received SIR is greater than the coverage threshold T.

$$P(T) = \mathbb{P}(SIR > T) \tag{7}$$

The average coverage probability can be evaluated by the following steps

$$\begin{split} P(T) &= \mathbb{P}\!\!\left(\max_{1 \leq k \leq K} \left(\frac{g_k^{(k)} r_k^{-\alpha}}{\sum_{j \in \theta^c} g_j^{(k)} r_j^{-\alpha}} \right) > T \right) \\ &= 1 - \mathbb{P}\!\!\left(\max_{1 \leq k \leq K} \left(\frac{g_k^{(k)} r_k^{-\alpha}}{\sum_{j \in \theta^c} g_j^{(k)} r_j^{-\alpha}} \right) < T \right) \\ &= 1 - \mathbb{E}\!\!\left[\prod_{1 \leq k \leq K} P\!\!\left(\frac{g_k^{(k)} r_k^{-\alpha}}{\sum_{j \in \theta^c} g_j^{(k)} r_j^{-\alpha}} < T \right) \right] \end{split}$$

With the assumption that all fading channels are independent Rayleigh random variables, the average coverage probability is given by

$$P(T) = 1 - \mathbb{E}\left[\prod_{1 \le k \le K} \left(1 - \prod_{j \in \theta^c} e^{-Tr_k^\alpha r_j^{-\alpha} g_j^{(k)}}\right)\right]$$
$$= \mathbb{E}\left[\sum_{S} (-1)^{N+1} \prod_{k \in S} \prod_{j \in \theta^c} e^{-Tr_k^\alpha r_j^{-\alpha} g_j^{(k)}}\right]$$



in which S is the subset of $\{1, 2, ..., K\}$ and $S \neq \emptyset$, N is the number of elements of S. Thus, the average coverage probability can be re-written as the following equations

$$\begin{split} P(T) &= \mathbb{E}\left[\sum_{S} (-1)^{N+1} \prod_{j \in \theta^c} \prod_{k \in S} \mathbb{E}_{G_j^{(k)}} \left[e^{-Tr_k^{\alpha} r_j^{-\alpha} g_j^{(k)}} \right] \right] \\ &= \mathbb{E}\left[\sum_{S} (-1)^{N+1} \mathbb{E}_{\theta^c} \left[\prod_{j \in \theta^c} \prod_{k \in S} \frac{1}{1 + Tr_k^{\alpha} r_j^{-\alpha}} \right] \right] \end{split}$$

By employing the properties of probability generating function (PGF) and reminding that the distance from any interfering BS to the typical user must be greater than r_K , we obtain

$$P(T) = \mathbb{E}\left[\sum_{S} (-1)^{N+1} e^{-2\pi\lambda \int_{r_{K}}^{\infty} t \left[1 - \prod_{k \in S} \frac{1}{1 + Tr_{k}^{\alpha} r^{-\alpha}}\right] dt}\right]$$

$$= (2\pi\lambda)^{K} \sum_{S} (-1)^{N+1} \int_{0}^{\infty} \int_{r_{1}}^{\infty} \cdots \int_{r_{K-1}}^{\infty} e^{-\pi\lambda r_{K}^{2} - 2\pi\lambda \int_{r_{K}}^{\infty} t \left[1 - \prod_{k \in S} \frac{1}{1 + Tr_{k}^{\alpha} r^{-\alpha}}\right] dt}$$

$$\times \prod_{j=1}^{K} r_{j} dr_{K-j+1}$$
(8)

in which Eq. (8) is the result of taking the expected values of N random variables, $(R_1, R_2, ..., R_K)$, whose joint PDF is defined in Eq. (3).

By employing changes of variable $t^2 = r_K y$ and $x_j = \pi \lambda r_j^2$, $(1 \le j \le K)$, we obtain

$$P(T) = \sum_{S} (-1)^{N+1} \int_{0}^{\infty} \int_{x_{1}}^{\infty} \cdots \int_{x_{K-1}}^{\infty} e^{-x_{K} - x_{K} \int_{1}^{\infty} \left[1 - \prod_{k \in S} \frac{1}{1 + T x_{K}^{\alpha/2}(x_{K}))^{-\alpha/2}} \right] dy} \prod_{j=1}^{K} dx_{K-j+1}$$
(9)

Equation (9) provides the most important result of this paper which derives the average coverage probability of the typical user. It is interesting that the average coverage probability does not depend on the density of BS, which is consistent with the conclusion for the cellular network without Joint Scheduling [8].

A special case of Joint Scheduling with K = 2, $S \subset \{1,2\}$ and $S \neq \emptyset$ By employing a change of variable $t = \frac{r_1}{r_2}$, the average coverage probability is obtained by the following equation

$$P(T) = \int_0^\infty r_2 e^{-r_2} \left[\int_0^1 e^{-r_2 v(T,t)} dt + e^{-r_2 v(T,1)} - \int_0^1 e^{-r_2 \frac{t^{\alpha/2} v(T,t) - \nu(T,1)}{t^{\alpha/2} - 1}} dt \right] dr_2$$
 (10)

in which $v(T,t) = \int_1^\infty \frac{Tt^{\alpha/2}y^{-\alpha/2}}{1+Tt^{\alpha/2}y^{-\alpha/2}}dy$.

In Eq. 10, the infinite integral has a suitable form of Gauss-Legendre Quadrature while the integral defined from [0, 1] can be approximated by using Gauss-Laguerre Quadrature. Hence, the average coverage probability can be approximated by



$$P(T) \approx \sum_{j=1}^{N_{GL}} w_{j} t_{i} \left[\sum_{i=1}^{N_{G}} \frac{c_{i}}{2} e^{-t_{j} \upsilon \left(T, \eta_{i}\right)} + e^{-t_{j} \upsilon \left(T, 1\right)} \right] - \sum_{i=1}^{N_{GL}} w_{j} t_{j} \sum_{i=1}^{N_{G}} \frac{c_{i}}{2} e^{-\zeta_{j} \left[\frac{\eta_{i}^{a/2} \upsilon \left(T, \eta_{i}\right) - \upsilon \left(T, 1\right)}{\eta_{i}^{a/2} - 1} \right]}$$

$$(11)$$

where N_{GL} and N_G are the degrees of the Laguerre and Legendre polynomial, t_i and w_i , c_i and x_i are the *i*-th node and weight, abscissas and weight of the corresponding quadratures; $\eta_i = \frac{x_i + 1}{2}$.

Furthermore, the integral v(T,t) can be presented as the difference of two integrals I_0 and I_1 which are defined on intervals $[0,\infty]$ and [0,1], respectively. While the first one, I_0 , is evaluated by employing changes of variables $\gamma = Tt^{\alpha/2}y^{-\alpha/2}$ and using the properties of Gamma function, the second one I_1 is approximated by Gauss–Legendre rule. Hence, v(T,t) can be approximated by [9]

$$v(T,t) \approx \frac{2tT^{2/\alpha}}{\alpha} \frac{\pi}{\sin\left(\frac{2\pi}{\alpha}\right)} - \sum_{i=1}^{N_G} \frac{c_i}{2} \frac{Tt^{\alpha/2}}{\left(\frac{x_i+1}{2}\right)^{\alpha/2} + Tt^{\alpha/2}}$$
(12)

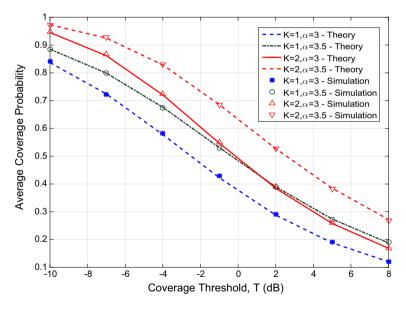


Fig. 2 A comparison between analytical and Monte Carlo simulation results



4 Simulation

4.1 Validation of the Analytical Results

In this section, the Monte Carlo simulation results are used to verify the analytical results in Eq. (9) in the cases of $\alpha = 3, 3.5$ and K = 1, 2. The simulation scenario is set up as follows

- The network cover a globular area with a radius of R in which $R \to \infty$
- The density of BSs is 0.5 BS/km².
- The fading channel has an exponential distribution with the expected value of 1.
- The user prefer a connection with two nearest BSs.

As shown in Fig. 2, the analytical result curves perfectly match with the points which represent the simulation results. This can verify the accuracy of the analytical results. Furthermore, the simulation results also indicates the density of BSs does not impose any impact on the network performance. This trend was discussed in Eq. 9. Take K = 2, $\alpha = 3$ for example, the average coverage probability is at when 0.7237 when T = -4 dB and reduces by 24.1% to 0.5493 when T = -2 dB.

It is reminded that the coverage threshold *T* represents the required SINR of the mobile user to successfully perform communication with its associated BS. Thus, when the coverage threshold increases, the average coverage probability significantly reduces as shown in Fig. 2.

It is observed from Fig. 2 that Joint Scheduling technique can significantly improve the average coverage probability of the typical user. Take $\alpha = 3$ for example, when coverage threshold T = 2 dB, the average coverage probability increases by 34.88% from 0.3908 to 0.5271.

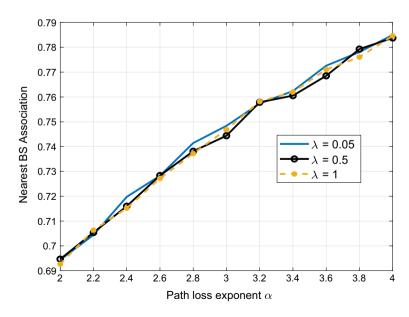


Fig. 3 Effects of path-loss exponent on the user association



4.2 User Association Analysis

In this section, the effects of path loss exponent and the density of BSs on the user association is investigated. Figure 3 is obtained by Monte Carlo simulation. In this figure, the nearest BS association represents the probability in which the user connects to the nearest BSs.

It is observed from Fig. 3 that the user association probability is independent to the density of BSs. For example, when the density of BSs λ increases from $\lambda=0.005$ to $\lambda=0.5$ then to $\lambda=1$ the nearest user association probability has a slight change between 0.7414, 0.7381 and 0.7372 respectively. These numbers also show that the number of users associated with the second nearest BS are significant, up to around 25%. This finding contradicts the conclusions in previous works [2] which stated that in the case of single-tier networks and the strongest association procedure is applied, all user will associate with the nearest BS when BSs transmit at the same power.

Figure 3 also indicates that the nearest user association increases with the path loss exponent. Take $\lambda = 0.5$ for example, the user association probability increases by around 4% from 0.7283 to 0.7581 when the path loss exponent increases from 2.6 to 3.2. This phenomenon can be explained as follows: (1) The path loss of the signal is proportional to the distance from the user to its associated BS. (2) From the user perspective, the second nearest BS is farther than the nearest BS. Thus, the signal from the second nearest BS experiences a higher path loss than that from the nearest BS. Consequently, the user tends to associate with the nearest BS when the path loss exponent increases.

5 Conclusion

We investigated the average coverage probability of the typical user in the random cellular network using Joint Scheduling under Rayleigh fading condition. The general analytical results were conducted for Joint Scheduling network with the cluster of K. In the case of Joint Scheduling with the cluster size of K=2, the closed-form expression of user's average coverage probability is presented. The paper derived two important conclusions: (1) the probability in which the user connects to the nearest BS and the second nearest BS independents to the density of BSs. (2) The user connects to the nearest BS with a higher probability in the environment with high path loss exponent than that in the environment with low path loss exponent.

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