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Modelling of shear behaviour of interfaces involving smooth geomembrane and nonwoven geotextile under static and dynamic loading conditions

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Modelling of shear behaviour of interfaces involving smooth geomembrane and nonwoven geotextile under static and dynamic loading conditions

Abstract

The constitutive modelling of geosynthetic-geosynthetic interfaces is essential to predict the performance of the engineering structures such as landfills, flood control dykes and geotextile encapsulated-sand systems for the protection of shore. This article presents a model to simulate the shear stress/force-displacement behaviour of the interfaces involving smooth geomembrane and nonwoven geotextile under static and dynamic loading conditions. The model is the extension of an existing model developed for predicting the soil-structure interface shear behaviour under static loading conditions. The model is capable of predicting the non-linear pre-peak and the post-peak strain softening/hardening behaviour of the interfaces observed during the laboratory testing. The shear stress/force-displacement response of the interfaces has been modelled by dividing it into three parts: pre-peak, peak and post-peak behaviour. Subsequently, the modelling parameters have been obtained using the results from the laboratory direct shear tests and fixed block type shake table tests conducted on these interfaces. Finally, the modelling parameters have been used to obtain the back-fitted shear stress/force-displacement response of the interfaces (which is compared with the experimental results). The predicted shear stress/force-displacement response of the interfaces is found to be in good agreement with the experimental data for both static and dynamic loading conditions.

Keywords: Geosynthetics; Interface behaviour; Modelling; Dynamic loading.

1 Introduction

1 The geosynthetic-geosynthetic interface shear behaviour plays a crucial role in the design
2 of geotechnical engineering structures such as landfills, flood control dykes and
3
4 geotextile encapsulated-sand systems for the protection of shore (Bergado et al. 2006;
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6 Lohani et al. 2006; Krahn et al. 2007; Mariappan et al. 2011; Moreira et al. 2013, 2016;
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8 Guo and Chu 2016). The geosynthetic-geosynthetic interface [involving smooth
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10 geomembrane (GMB) and geotextile (GTX)] usually acts as a weak zone in these
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12 structures due to very low interface shear strength (with interface friction angles ranging
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14 between 5-20°). However, on the contrary, the low interface shear strength might prove
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16 beneficial in some cases. The studies by Hushmand and Martin (1991), Kavazanjian et
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18 al. (1991), Yegian and Lahlaf (1992), Yegian and Kadakal (1998, 2004), Yegian and
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20 Catan (2004) and Georgarakos et al. (2005) have explored the use of these low friction
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22 geosynthetic-geosynthetic interfaces in achieving seismic isolation. Therefore, it is
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24 imperative to understand the shear behaviour of the different interfaces involving
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26 geosynthetics.
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36 Numerous experimental investigations have been conducted in the past to study
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38 the behaviour of geosynthetic-geosynthetic interfaces under static as well as dynamic
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40 loading conditions (e.g. Bacas et al. 2011, 2015; Stark et al. 2015; Punetha et al. 2019).
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42 Furthermore, a significant amount of work has been reported on the constitutive
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44 modelling of geosynthetic-geosynthetic interfaces under static loading conditions,
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46 however, in contrast, very little has been reported regarding the constitutive modelling
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48 under cyclic or dynamic loading condition (Gilbert and Byrne 1996; Reddy et al. 1996;
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50 Esterhuizen et al. 2001; Seo et al. 2003; Liu and Ling 2006; Bacas et al. 2011; Arab et al.
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52 2012). The constitutive modelling of the geosynthetic-geosynthetic interfaces is very
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1 important to predict the response of the structures involving geosynthetic-geosynthetic
2 interface and assess their long-term performance.
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5 In the present article, an attempt has been made to simulate the shear stress/force-
6 displacement response of the GMB-GTX, GMB-GMB and GTX-GTX interfaces under
7 both static as well as dynamic loading conditions. The model used in the present study is
8 an extension of a model originally developed for predicting the soil-structure interface
9 shear behaviour under static loading conditions. Initially, large size direct shear box tests
10 and fixed block type shake table tests have been conducted on GMB-GTX, GMB-GMB
11 and GTX-GTX interfaces. Subsequently, the results of the experimental investigation
12 have been used to derive the modelling parameters. Finally, the back-fitted shear
13 stress/force-displacement response of the interfaces is obtained using the modelling
14 parameters, and the response is compared with the experimental results. The present study
15 on GMB-GTX, GMB-GMB and GTX-GTX interfaces is essential for the design and
16 prediction of long-term performance of landfills, flood control dykes and geotextile
17 encapsulated-sand systems for the protection of shore.
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38 **2 Experimental Study**

39 **2.1 Materials Used**

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41 Two types of geosynthetics have been used in the present study, nonwoven needle-
42 punched geotextile and smooth High Density Poly Ethylene (HDPE) geomembrane.
43 Tables 1 and 2 show the properties of the geotextile and geomembrane, respectively. Both
44 geotextile and geomembrane are 1.5 mm thick. The geotextile is made up of
45 polypropylene staple fibres and has a mass per unit area, apparent opening size (O_{95}) and
46 wide-width tensile strength of 200 g/m², 0.085 mm and 14 kN/m, respectively. The
47 geomembrane possesses a density and yield strength of 940 kg/m³ and 25 kN/m,
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2.2 Static Interface Shear Test

2.2.1 Test Apparatus and Procedure

The static interface shear tests have been conducted using a large size direct shear box with 300 mm × 300 mm plan dimensions. The dimensions of the direct shear box meet the minimum requirements specified in ASTM D5321 (ASTM, 2014). Several researchers have employed direct shear tests to study the interface behaviour of geosynthetics with other materials owing to the simplicity and economy (e.g. Lopes and Silvano, 2010; Punetha et al. 2016, 2017; Punetha and Samanta 2017). Fig. 1 shows the schematic diagram of the large size direct shear box test assembly. The shear box comprises two halves of the same size with fixed upper half, while the lower half is movable. A rigid block is placed in the lower half to prevent the sagging of geosynthetics during the shear test. One geosynthetic is attached to the top of this block while the other geosynthetic is attached to a steel plate (300 mm × 300 mm × 5 mm), placed at the bottom portion of the upper half. The remaining portion of the upper half is backfilled using sand. A pressure pad is then placed on the top of the backfilled sand. Subsequently, the desired normal load is applied using a loading yoke which rests on the top of the pressure pad. The driving unit generates the horizontal movement in the lower half of the shear box while the motion of the upper half is prevented using a reaction wall. A proving ring is placed between the upper half and the reaction wall to monitor the shear force. Moreover, the horizontal displacement of the box is recorded using a dial gauge.

The geosynthetic specimens are sampled as per ASTM D4354 (ASTM, 2012). The size of the geomembrane and geotextile specimens is 300 mm × 300 mm and 500 mm × 300 mm, respectively. To prevent slippage during the tests, the geomembrane specimens are firmly glued to the rigid block/ steel plate, while the edges of geotextile specimens are clamped. All the tests have been performed under a constant shearing rate

1 of 0.314 mm/min and over a normal stress range of 50-200 kPa. Each test is repeated
2 three times to ensure the repeatability of the test results.
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6 2.2.2 Test Results 7

8 Fig. 2 shows the stress-displacement curves for the GMB-GTX, GMB-GMB and GTX-
9 GTX interfaces at 200 kPa normal stress. It can be observed that the shear stress increases
10 with an increase in horizontal displacement up to a peak value beyond which it decreases
11 with further increase in horizontal displacement and finally, becomes constant for the
12 GMB-GTX and GMB-GMB interfaces. However, for the GTX-GTX interface, the shear
13 stress increases with an increase in horizontal displacement up to a peak value beyond
14 which it becomes constant. Moreover, the horizontal displacement corresponding to the
15 peak is minimum for the GMB-GTX interface followed by the GMB-GMB and the GTX-
16 GTX interfaces. The secant slope of the stress-displacement curves at 50% of the peak
17 shear stress for the GMB-GTX, GMB-GMB and GTX-GTX interfaces are 69.23 MN/m³,
18 80.03 MN/m³ and 57.62 MN/m³, respectively. The secant slope is highest for the GMB-
19 GMB interface, whereas the slope of GMB-GTX interface is intermediate of the GMB-
20 GMB and GTX-GTX interfaces.
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40 Fig. 3 shows the peak (P) and residual (R) strength envelopes for the three
41 interfaces. It can be observed that the shear strength increases linearly with an increase in
42 normal stress for all the interfaces tested. The peak interface friction angles for the GMB-
43 GTX, GMB-GMB and GTX-GTX interfaces are 14.6°, 19.8° and 20.3°, respectively.
44 Furthermore, the residual interface friction angles for the GMB-GTX, GMB-GMB and
45 GTX-GTX interfaces are 13°, 17.2° and 20.3°, respectively. The friction angle of the
46 GMB-GMB interface is higher than the GMB-GTX interface due to a large real contact
47 area between the upper and lower geomembrane. As shown in Fig. 4, the geomembrane
48 surface usually possesses minute irregularities/asperities. Therefore, the real contact area
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1 at the interface is usually smaller than the gross/apparent contact area, which is calculated
2 using actual dimensions of the geosynthetic specimens (Stachowiak and Batchelor,
3 2013). The peak interface shear strength depends on the magnitude of the real contact
4 area (Dove and Frost, 1999). An increase in the real contact area increases the peak
5 interface shear strength. In the case of GMB-GTX interface, the real contact area may be
6 much smaller due to the inherent fabric structure of the non-woven geotextile, which
7 comprises randomly distributed fibres. Thus, the friction angle for the GMB-GTX
8 interface is small. Whereas, for the GMB-GMB interface, the real contact area may be
9 large (refer to Fig. 4). Therefore, the interface friction angle for the GMB-GMB interface
10 is high. Nevertheless, further investigation is required to understand this behaviour.
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26 2.3 Dynamic Interface Shear Test

27 2.3.1 Test Apparatus and Procedure

28 Fixed block type shake table tests have been conducted to study the shear behaviour of
29 the GMB-GTX, GMB-GMB and GTX-GTX interfaces under dynamic loading
30 conditions. Fig. 5 shows the schematic diagram of the fixed block type testing assembly
31 for the dynamic interface shear tests. The test setup comprises three units: shearing unit,
32 normal load unit and reaction unit. The shearing unit consists of a uniaxial shake table
33 and a 10 mm thick steel plate (bottom steel plate). The shake table is a 2 m × 2 m, servo-
34 controlled shake table with a horizontal and vertical load-carrying capacity of 50 kN and
35 30 kN respectively. The bottom steel plate is mounted over the shake table using 16 mm
36 diameter bolts. One layer of the geosynthetic is fixed [glued (for geomembrane) and
37 clamped (for geotextile)] to the bottom plate. The movement of the shake table generates
38 the desired horizontal displacement at the geosynthetic-geosynthetic interface. The
39 normal load unit consists of a 30 mm thick steel plate (upper steel plate), threaded steel
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1 rod and dead weights. To control the normal stress at the interface, a 115 mm × 115 mm
2 × 30 mm steel block is attached to the bottom of the upper steel plate. The size of the steel
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4 block was fixed to achieve the normal stress in the range of 51-148 kPa. The second
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6 geosynthetic is attached [glued (for geomembrane) and clamped (for geotextile)] to the
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8 bottom of the steel block. The reaction unit consists of a connecting rod and a reaction
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10 frame. The reaction unit restricts the movement of the normal load unit (the portion above
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12 the geosynthetic-geosynthetic interface) and a dynamic load cell measures the total force
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14 required to prevent the movement of the normal load unit. A linear variable displacement
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16 transducer (LVDT) measured the table displacement.
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21 Tests have been conducted on three interfaces: GMB-GTX, GMB-GMB and
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23 GTX-GTX. The size of the geomembrane specimens is fixed at 100 mm × 100 mm and
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25 400 mm × 300 mm for the upper and lower portion, respectively. Moreover, the size of
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27 geotextile specimens is fixed at 200 mm × 200 mm and 500 mm × 500 mm for the upper
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29 and lower portion, respectively. The use of large-sized geosynthetic specimens for the
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31 lower portion ensures a uniform contact area (between the two geosynthetics) during the
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33 shearing. Furthermore, the size of the geotextile specimens is larger than the
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35 geomembrane specimens to fulfil the clamping requirements.
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41 After the attachment of geosynthetics, a normal load is applied using a set of dead
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43 weights. Subsequently, the interface is subjected to a sinusoidal loading with a
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45 displacement amplitude and frequency of 15.91 mm and 1 Hz, respectively, over a normal
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47 stress range of 51-148 kPa. The sinusoidal loading is useful to study the force-
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49 displacement behaviour of the dynamic systems and interfaces (De and Zimmie 1998;
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51 Yegian and Kadakal 1998; Park et al. 2004; Kotake and Kamon 2016). The companion
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53 paper by Punetha et al. (2019) provides a detailed description of the test setup and the
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1 procedure used to study the geosynthetic-geosynthetic interface shear behaviour under
2 dynamic loading conditions.
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6 *2.3.2 Dynamic Interface Test Results*

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8 This section presents the results of the fixed block type shake table tests on geosynthetic-
9 geosynthetic interfaces (GMB-GTX, GMB-GMB and GTX-GTX). Figs. 6(a) and 6(b)
10 show the shear force-time history and the shear force-horizontal displacement curve,
11 respectively, for the GMB-GTX interface at 97 kPa normal stress. As can be seen, the
12 shear force increases with an increase in horizontal displacement up to a peak value and
13 becomes constant thereafter. The value of shear force remains constant till the half cycle
14 is completed. In the next half cycle, the shear force again increases with an increase in
15 horizontal displacement, but in an opposite direction. The shear force again reaches a
16 peak value and becomes constant thereafter. This process continues till the end of the
17 cycle. Thus, two plateau regions form during each cycle with a sustained value of shear
18 force. The ratio of the sustained value of shear force to the normal load at the interface
19 gives the dynamic coefficient of friction for the interface (Nanda et al. 2010).
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37 The GTX-GTX interface, on the other hand, showed a post-peak strain hardening
38 behaviour. Therefore, for GTX-GTX interface, the ratio of the maximum value of shear
39 force to the normal load is taken as the dynamic coefficient of friction. Table 3 gives the
40 values of the dynamic coefficient of friction for the three interfaces tested. The dynamic
41 coefficient of friction for the GMB-GTX interface increases marginally from 0.22 to 0.24,
42 with an increase in normal stress from 51 to 112 kPa. The increase in the dynamic
43 coefficient of friction may be attributed to the plastic deformation of the geomembrane
44 surface below the geotextile fibres at high normal stress. Since, a high magnitude of shear
45 force is required to push the fibres through the asperities formed due to plastic
46 deformation of the geomembrane surface, the coefficient of friction increases.
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2 For the GMB-GMB interface, the dynamic coefficient of friction decreases from
3 0.24 at 68 kPa normal stress to 0.21 at 148 kPa normal stress. The reduction may be
4 ascribed to the fact that the real contact area between the lower and upper geomembrane
5 may increase at a lower rate as compared to the applied normal stress (Dove and Frost,
6 1999). Consequently, the dynamic coefficient of friction decreases with an increase in the
7 normal stress. Moreover, for the GTX-GTX interface, the dynamic coefficient of friction
8 decreases from 0.29 to 0.21, with an increase in normal stress from 51 to 112 kPa. This
9 reduction may be due to an increase in the number of fibre to fibre contacts with a rise in
10 normal stress. The increase in the number of contacts reduces the contact stress and
11 consequently, the coefficient of friction decreases.
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24 The secant stiffness of the GMB-GTX, GMB-GMB and GTX-GTX interface at
25 50 % of the peak shear force also increases with an increase in normal stress. For GMB-
26 GTX and GTX-GTX interface, the secant stiffness increases from 790 to 1026 kN/m and
27 379 to 1169 kN/m, respectively, with an increase in normal stress from 51 to 112 kPa.
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29 The secant stiffness of GMB-GMB interface is the highest among all the interfaces, and
30 its magnitude varies from 2852 to 3700 kN/m with an increase in normal stress from 68
31 to 148 kPa.
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43 **3. Constitutive Modelling**

44 **3.1 Static Case**

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46 For modelling the static case, the stress-displacement response of the interface is divided
47 into three zones, namely, pre-peak, peak and post-peak zone.
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53 *3.1.1 Pre-peak Zone*

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55 Figs. 7(a), 7(b) and 7(c) show the predicted vs. the experimental shear stress-displacement
56 curves for GMB-GTX, GMB-GMB and GTX-GTX interfaces, respectively. It is clear
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1 from the experimental stress-displacement curves that all the three interfaces show a non-
 2 linear pre-peak behaviour. The hyperbolic model given by Kondner (1963) has been used
 3
 4 to model the non-linear pre-peak behaviour of the interfaces.
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$$7 \quad \tau = \frac{\delta}{\frac{1}{K_s} + \frac{\delta}{\tau_{ult}}} \quad (1)$$

8 where τ = shear stress; δ = horizontal displacement; K_s = initial slope of shear stress vs.
 9 horizontal displacement curve; τ_{ult} = ultimate shear stress. In Equation (1), K_s and τ_{ult} are
 10 the two unknown parameters which are determined using the experimental data. In some
 11 interfaces, the initial slope of the stress-displacement curves depends on the normal stress.
 12 From Fig. 7(c), it can be observed that for the GTX-GTX interface, the initial slope
 13 increases with an increase in the normal stress. The expression given by Reddy et al.
 14 (1996) [Equation (2)] has been used to model this pressure-dependent behaviour.
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$$29 \quad K_s = K\gamma_w \left(\frac{\sigma_n}{P_a} \right)^N \quad (2)$$

30 To account for the non-linear behaviour in the model, instantaneous slope has
 31 been calculated using the expression given by Reddy et al. (1996):
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$$38 \quad K_t = K\gamma_w \left(\frac{\sigma_n}{P_a} \right)^N \left[1 - R_f \left(\frac{\tau}{\tau_p} \right) \right]^2 \quad (3)$$

39 where K_t = instantaneous slope of the stress-displacement curve; K = modulus number;
 40 γ_w = unit weight of water; σ_n = normal stress; P_a = atmospheric pressure; N = modulus
 41 exponent; R_f = failure ratio; τ_p = peak shear strength. The parameter N depicts the
 42 dependency of the initial slope on the normal stress. A small value of N (equal to 0) shows
 43 pressure-independent behaviour, while a large value (about 1) represents the pressure-
 44 dependent behaviour. The failure ratio is the ratio of the peak shear strength to the
 45 ultimate shear stress, and its value is always less than one.
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$$R_f = \frac{\tau_p}{\tau_{ult}} \quad (4)$$

3.1.2 Peak Zone

To model the peak shear strength, the Mohr-Coulomb's criterion has been used.

$$\tau_p = c_p + \sigma_n \tan \varphi_p \quad (5)$$

where c_p = peak adhesion intercept; φ_p = peak interface friction angle.

3.1.3 Post-peak Zone

Some interfaces show post-peak strain hardening/ softening behaviour while for others, the shear stress becomes constant after the peak. In the present study, the GMB-GTX and GMB-GMB interfaces show a strain-softening behaviour, while for the GTX-GTX interface, the shear stress became constant after the peak. The strain-softening behaviour has been modelled using the method given by Anubhav and Basudhar (2010). Initially, the relationship between the reduction factor and the horizontal displacement is established. The reduction factor is the post-peak reduction in shear stress normalised by the shear stress reduction from peak to the residual value.

$$R = \frac{\tau_p - \tau}{\tau_p - \tau_r} \quad (6)$$

where τ_p = peak shear strength; τ_r = residual shear strength. τ_r can be evaluated using Equation (5) by replacing c_p and φ_p with c_r (residual adhesion intercept) and φ_r (residual interface friction angle), respectively. For the present case, the reduction factor varies with the horizontal displacement as:

$$R = x + ye^{-z\delta^{-n}} \quad (7)$$

where R is the reduction factor; δ is the horizontal displacement; x , y , z and n are constants. For interfaces showing a constant value of shear stress after the peak, the previously described method is slightly modified. The modified method involves the use of the

1 hyperbolic function to model the pre-peak behaviour (similar to the method described
2 above). However, after the peak, the shear stress is assumed to be constant and equal to
3 the peak value. In other words, the reduction factor is assumed to be equal to zero. Table
4 4 shows the values of the modelling parameters and the constants of the Equation (7) used
5 in the present study. A code was developed in MATLAB to evaluate the magnitude of
6 shear stress corresponding to a particular value of horizontal displacement using
7 Equations (1-7).
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10 11 12 13 14 15 16 17 18 *3.1.4 Results*

19 From Fig. 7, it can be observed that the back-fitted stress-displacement response of the
20 three interfaces matches quite well with the experimental results, with an average
21 variation of about 15%, 24% and 11% for GMB-GTX, GMB-GMB and GTX-GTX
22 interfaces, respectively. The model is able to reproduce the shear behaviour of the
23 geosynthetic-geosynthetic interfaces involving smooth geomembrane and nonwoven
24 geotextile over the range of normal stresses used in experiments. Moreover, the model
25 can also be used to interpolate the response at the normal stresses which are difficult to
26 generate in the laboratory. Similarly, by varying the modelling parameters, the response
27 of the interface can also be predicted at different testing conditions.
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44 *3.2 Dynamic Case*

45 For modelling the interface behaviour under dynamic loading conditions, the method
46 used in the static case has been modified.
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52 *3.2.1 Pre-peak Zone*

53 A close observation of the experimental shear force vs. horizontal displacement curve for
54 GMB-GTX interface in Fig. 8(a) reveals that the behaviour is non-linear in the initial
55 portion of the first half cycle. Therefore, to simulate this portion, the hyperbolic model
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1 given by Kondner (1963) has been used. As shown in Equation (8), the only difference
 2 in the two cases (static and dynamic) is that the shear force has replaced the shear stress
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 4 in the dynamic case.
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$$7 \quad S = \frac{\delta}{\frac{1}{K_s'} + \frac{\delta}{S_{ult}}} \quad (8)$$

8 where S = shear force; δ = horizontal displacement; K_s' = initial slope of shear force vs.
 9 horizontal displacement curve; S_{ult} = ultimate shear force. The values of K_s' and S_{ult} are
 10 calculated using the experimental data (by back analysis). For determination of the
 11 instantaneous slope of the shear force-displacement curve, the Equations (2) and (3)
 12 described above have been modified as:
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$$24 \quad K_s' = Ka \left(\frac{F}{b} \right)^N \quad (9)$$

$$25 \quad K_t' = Ka \left(\frac{F}{b} \right)^N \left[1 - R_f \left(\frac{S}{S_p} \right) \right]^2 \quad (10)$$

26 where K_t' = instantaneous slope of the shear force-displacement curve; K = modulus
 27 number; F = normal force; N = modulus exponent; R_f = failure ratio; S_p = peak shear
 28 force; a and b are constants. The parameter ' b ' is used to make the term F/b dimensionless
 29 and ' a ' is used to make the equation dimensionally stable. The values of the parameters
 30 ' a ' and ' b ' are taken as 1 kN/m and 1 kN respectively in the present study. The parameters
 31 K and N are determined using Equation (10) and the experimental data.
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48 3.2.2 Peak Zone

49 The peak value of the shear force (S_p) is modelled using the Equation (11):
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$$52 \quad S_p = F\mu_d \quad (11)$$

53 where μ_d is the dynamic coefficient of friction.
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3.2.3 Post-peak Zone

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2 After attaining a peak value, the shear force remains constant throughout the rest of the
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4 half cycle irrespective of the displacement. With the change in direction of sliding, the
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6 shear force increases in the opposite direction up to a peak value. The change of direction
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8 is predicted by calculating the value of sliding velocity (by differentiating the horizontal
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10 displacement). The negative value of velocity indicates a change in sliding direction. A
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12 similar procedure is used to predict the value of shear force for the rest of the half cycle.
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16 The experimental results show isometric hardening behaviour of the interfaces and
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18 therefore similar behaviour is assumed in modelling.
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21 Fig. 8(a) shows the predicted vs. experimental force-displacement curves for the
22
23 GMB-GTX interface at 51 kPa normal stress. It can be observed that the back-fitted force-
24
25 displacement curves are in good agreement with the experimental results. Fig. 8(b) shows
26
27 the predicted vs. experimental shear force-time history for GMB-GTX interface at 51 kPa
28
29 normal stress. It can be observed that the back-fitted force-time history matches well with
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31 the experimental results. Similarly, for GMB-GMB interface, the back-fitted results
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33 match well with the experimental results as shown in Figs. 9(a-b).
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38 Figs. 10(a) and 10(b) show the force-displacement curve and the shear force-time
39
40 history for the GTX-GTX interface at 66 kPa normal stress. It is evident that the GTX-
41
42 GTX interface shows a post-peak strain hardening behaviour. The shear force increases
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44 continuously with an increase in horizontal displacement throughout the rest of the half
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46 cycle at a low rate, after attaining an initial peak value. A similar behaviour i.e. a
47
48 continuous increment in shear force at a low rate is observed in the opposite direction
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50 with the change in the direction of sliding after the half cycle. The strain hardening
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52 behaviour could be due to the stretching of fibres of the lower geotextile during shear, in
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54 the contact region. As the shearing progresses, the fibres of the bottom geotextile in the
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1 contact zone get stretched and produce wrinkles in the portion adjacent to the edge of the
2 contact zone (in the direction of shear). The wrinkles present near the edge of the contact
3 zone oppose the motion as the shearing progresses and therefore, results in post-peak
4 strain hardening. For modelling this post-peak strain hardening behaviour, the residual
5 factor method (similar to the one used in static case) has been used. This method involves
6 the establishment of a relationship between the reduction factor and the horizontal
7 displacement. This relationship is used to calculate the shear force at any horizontal
8 displacement using Equation (12).
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$$19 \quad R = \frac{S_p - S}{S_p - S_r} \quad (12)$$

20 where S_p = peak shear force; S_r = residual shear force. Fig. 10(c) shows the relationship
21 between the reduction factor and the horizontal displacement. This relationship has been
22 evaluated using a non-linear regression analysis in MATLAB and the expression is given
23 in Equation (13).
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$$33 \quad R = xe^{y\delta} + ze^{n\delta} \quad (13)$$

34 The value of the constants (x , y , n and z) of the best fit curve and the value of other
35 modelling parameters is given in Table 5. It can be seen from Figs. 10(a-b) that the back-
36 fitted results are in good agreement with the experimental ones. Thus, the back-fitted
37 stress displacement curves for the three interfaces match quite well with the
38 corresponding experimental curves, with an average variation of 25 %. It must be noted
39 that the scope of the present study is limited to the development of the constitutive model
40 for the geosynthetic-geosynthetic interfaces under static and dynamic loading conditions.
41 The future scope of the work includes the implementation of the proposed model in the
42 commercially available finite element/ finite difference based software and subsequent
43 prediction of the response of geosynthetic-geosynthetic interfaces.
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4. Conclusions

The present study deals with the constitutive modelling of the GMB-GTX, GMB-GMB and GTX-GTX interfaces under static and dynamic loading conditions. The results of the laboratory direct shear tests and fixed block type shake table tests on the three interfaces revealed that the stress/force-displacement behaviour of the interfaces could be divided into three zones: non-linear pre-peak zone, peak and post-peak zone (involving strain softening/hardening or perfectly plastic behaviour). The models originally developed for predicting the soil-structure interface shear behaviour under static loading conditions were extended to reproduce the force/stress-displacement response of the three interfaces under static and dynamic loading conditions. The results of the experimental investigation were used to obtain the modelling parameters by back analysing the experimental data.

Using the parameters (derived from the experimental data), the back-fitted stress/force-displacement response of the interfaces showed excellent agreement with the experimental data over the range of normal stresses used in the present study. The interface shear behaviour of all the interfaces under static and dynamic loading conditions was simulated using the same model with slight modifications.

The present study provides a constitutive model for predicting the response of geosynthetic-geosynthetic interfaces involving smooth geomembrane and nonwoven geotextile under static and dynamic loading conditions. The constitutive modelling is particularly useful for the interpolation of interface behaviour for the testing conditions which are difficult to generate at the laboratory level. This study is essential to predict the response of the structures involving geosynthetic-geosynthetic interface and assess their long-term performance.

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Table Captions

Table 1 Properties of nonwoven needle-punched geotextile

Table 2 Properties of smooth HDPE geomembrane

Table 3 Results of the dynamic interface shear tests

Table 4 Values of the parameters used for constitutive modelling of static interface behaviour

Table 5 Values of the parameters used for constitutive modelling of dynamic interface behaviour

Figure Captions

Fig. 1 Schematic diagram of modified large-size direct shear box test assembly

Fig. 2 Shear stress vs. horizontal displacement curves for GMB-GTX, GMB-GMB and GTX-GTX interfaces at 200 kPa normal stress

Fig. 3 Peak and residual strength envelopes for GMB-GTX, GMB-GMB and GTX-GTX interfaces for static loading condition

Fig. 4 Real contact area for GMB-GTX and GMB-GMB interfaces

Fig. 5 Schematic illustration of the fixed block type testing assembly for the dynamic interface shear tests

Fig. 6 (a) Shear force-time history for the GMB-GTX interface at 97 kPa normal stress; **(b)** force-displacement curve for the GMB-GTX interface at 97 kPa normal stress

Fig. 7 Experimental vs. predicted stress-displacement curves for **(a)** GMB-GTX interface; **(b)** GMB-GMB interface; **(c)** GTX-GTX interface

Fig. 8 Experimental vs. predicted behaviour of GMB-GTX interface at 51 kPa normal stress **(a)** force-displacement curve; **(b)** shear force-time history

Fig. 9 Experimental vs. predicted behaviour of GMB-GMB interface at 88 kPa normal stress **(a)** force-displacement curve; **(b)** shear force-time history

Fig. 10 Experimental vs. predicted behaviour of GTX-GTX interface at 66 kPa normal stress: **(a)** force-displacement curve; **(b)** shear force-time history; **(c)** variation of reduction factor with horizontal displacement

Figure 1

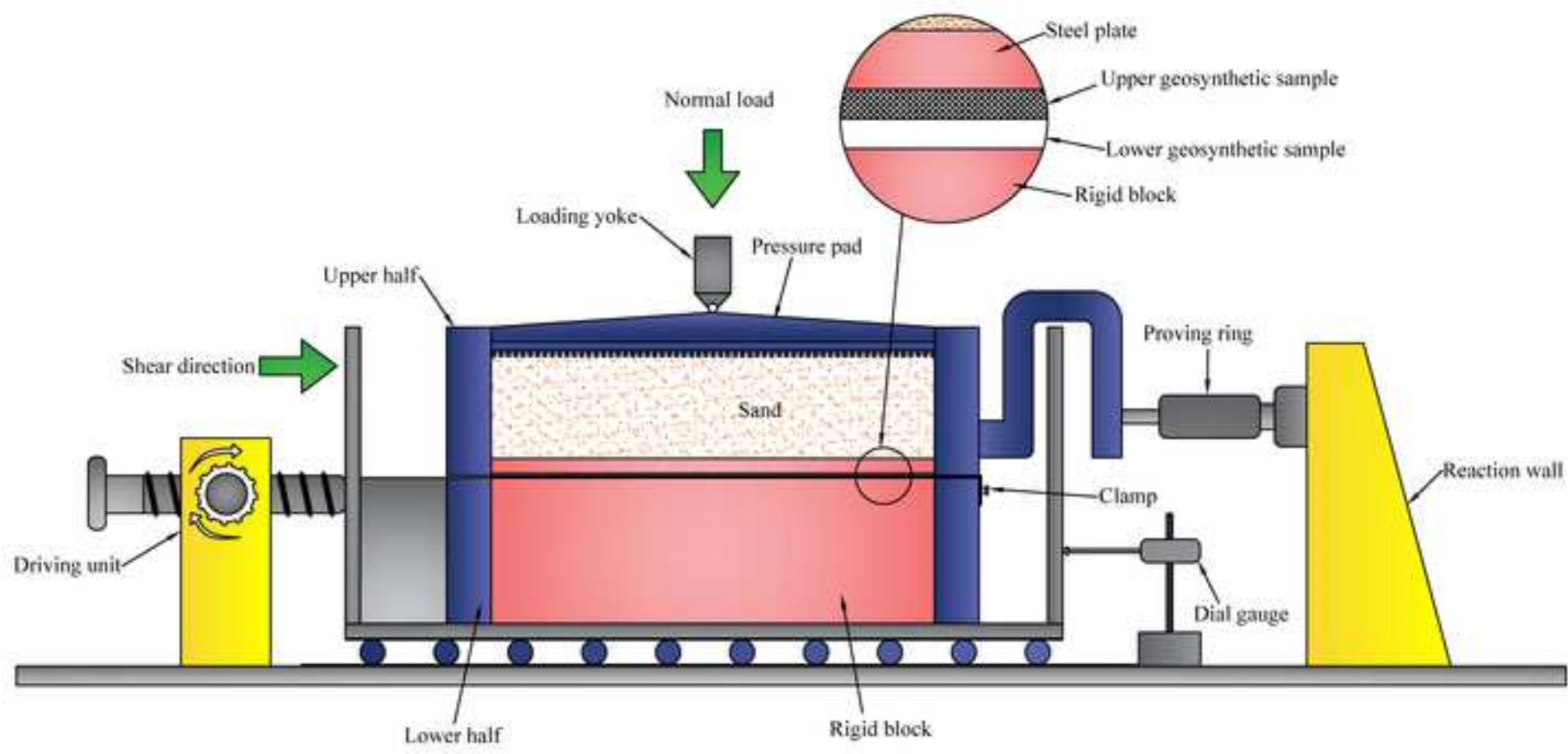


Figure 2

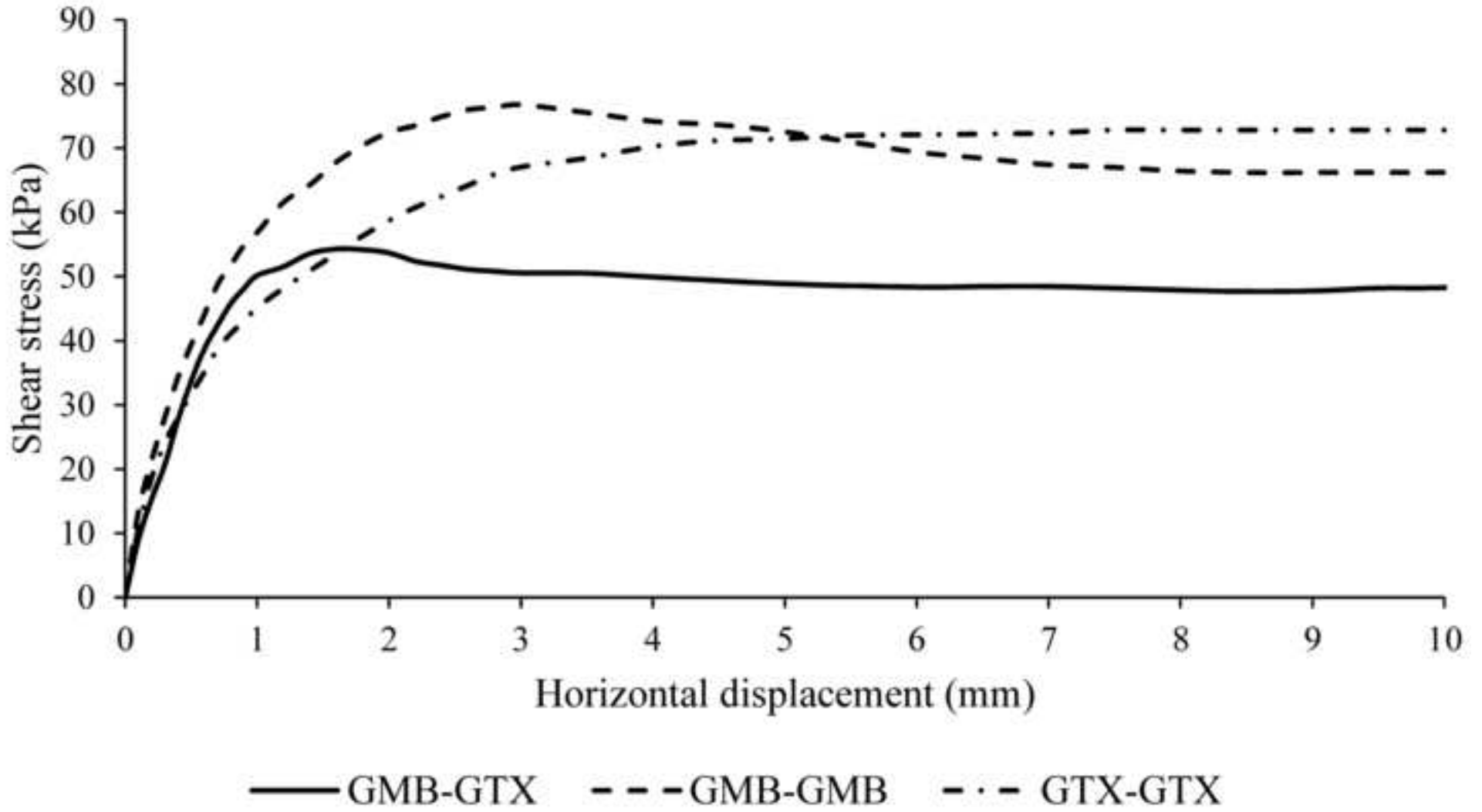
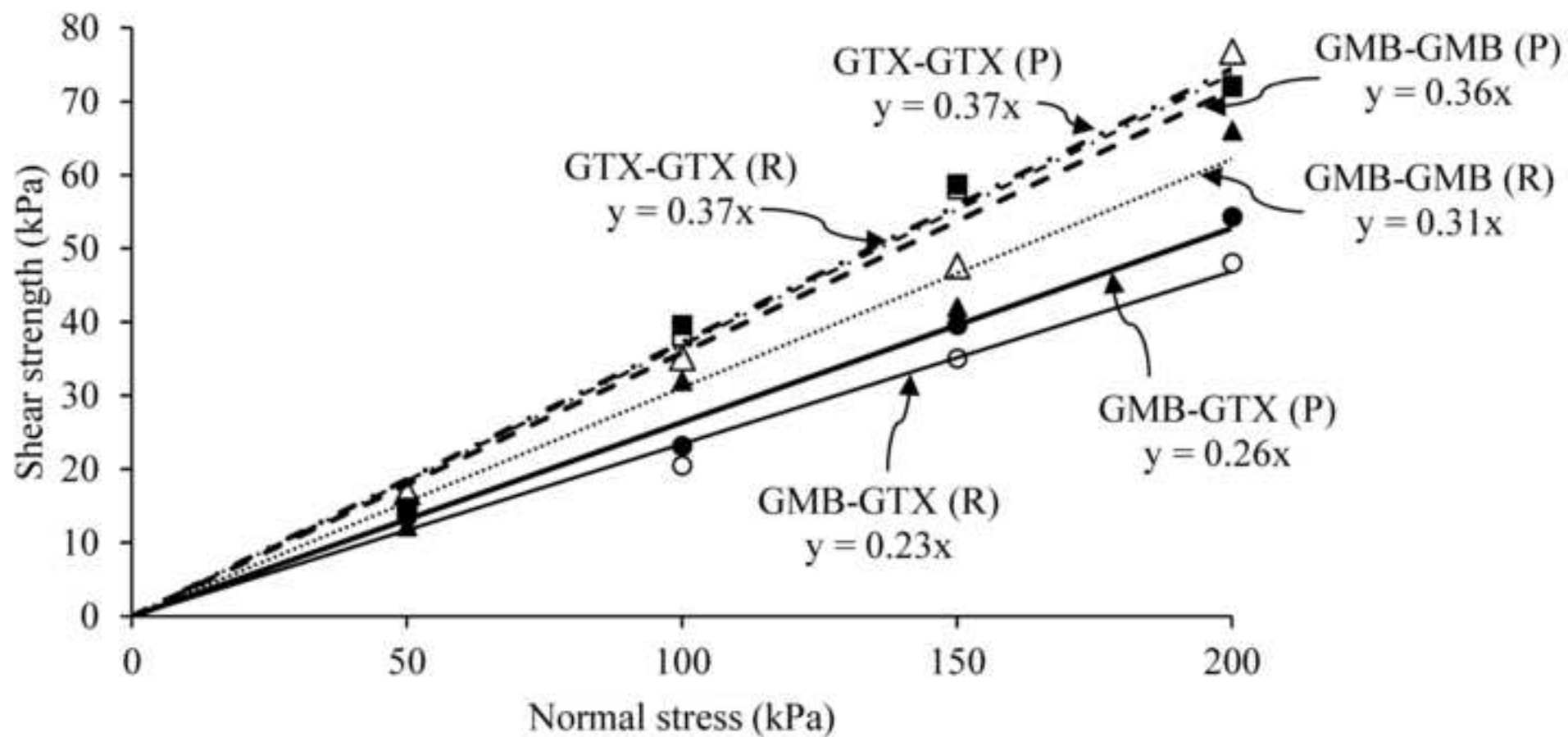


Figure 3



- GMB-GTX (P)
- GMB-GTX (R)
- △ GMB-GMB (P)
- ▲ GMB-GMB (R)
- GTX-GTX (P)
- GTX-GTX (R)

Figure 4

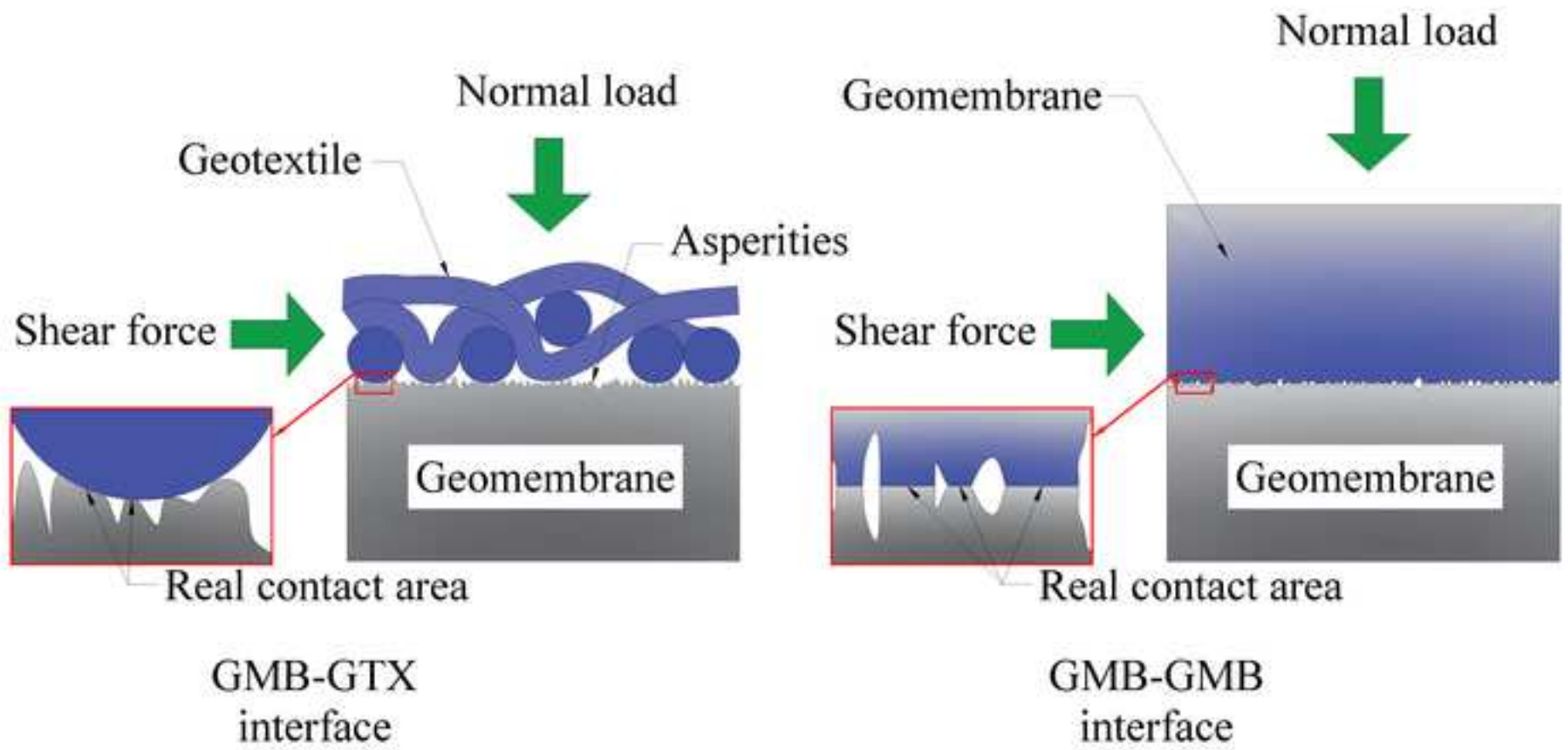


Figure 5

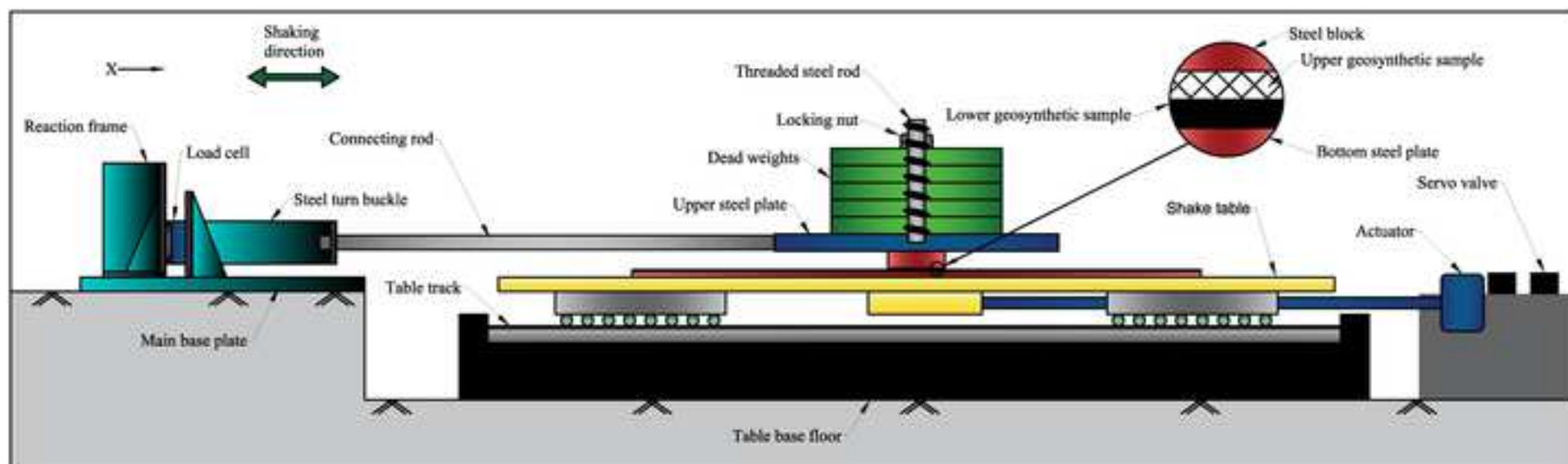
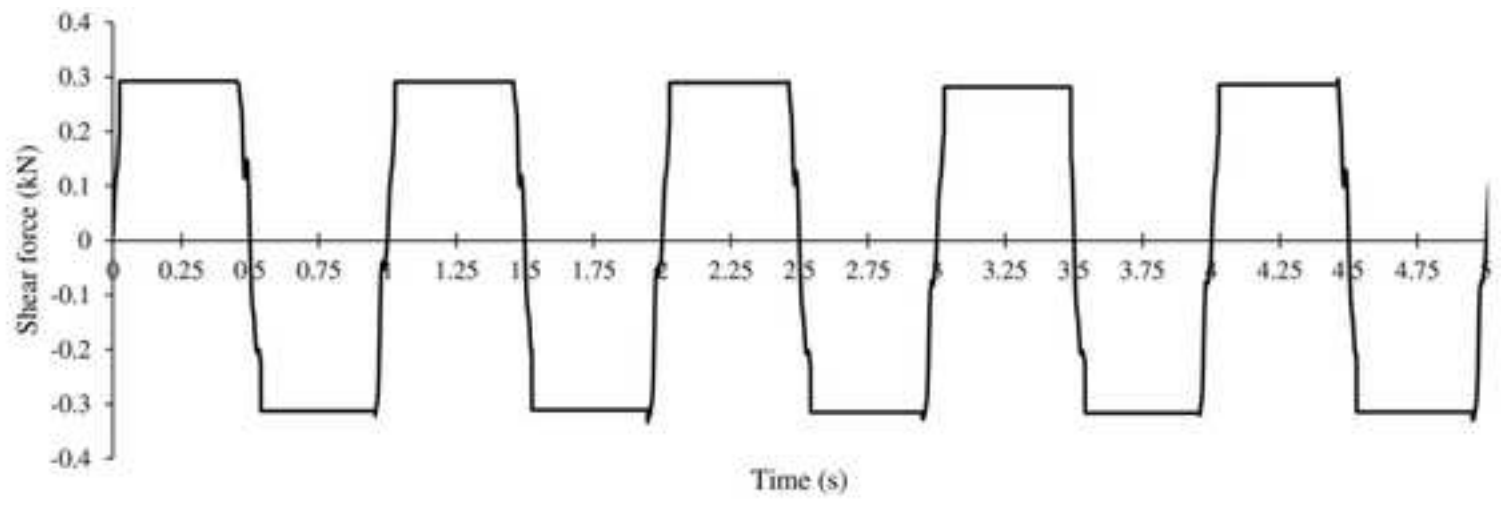
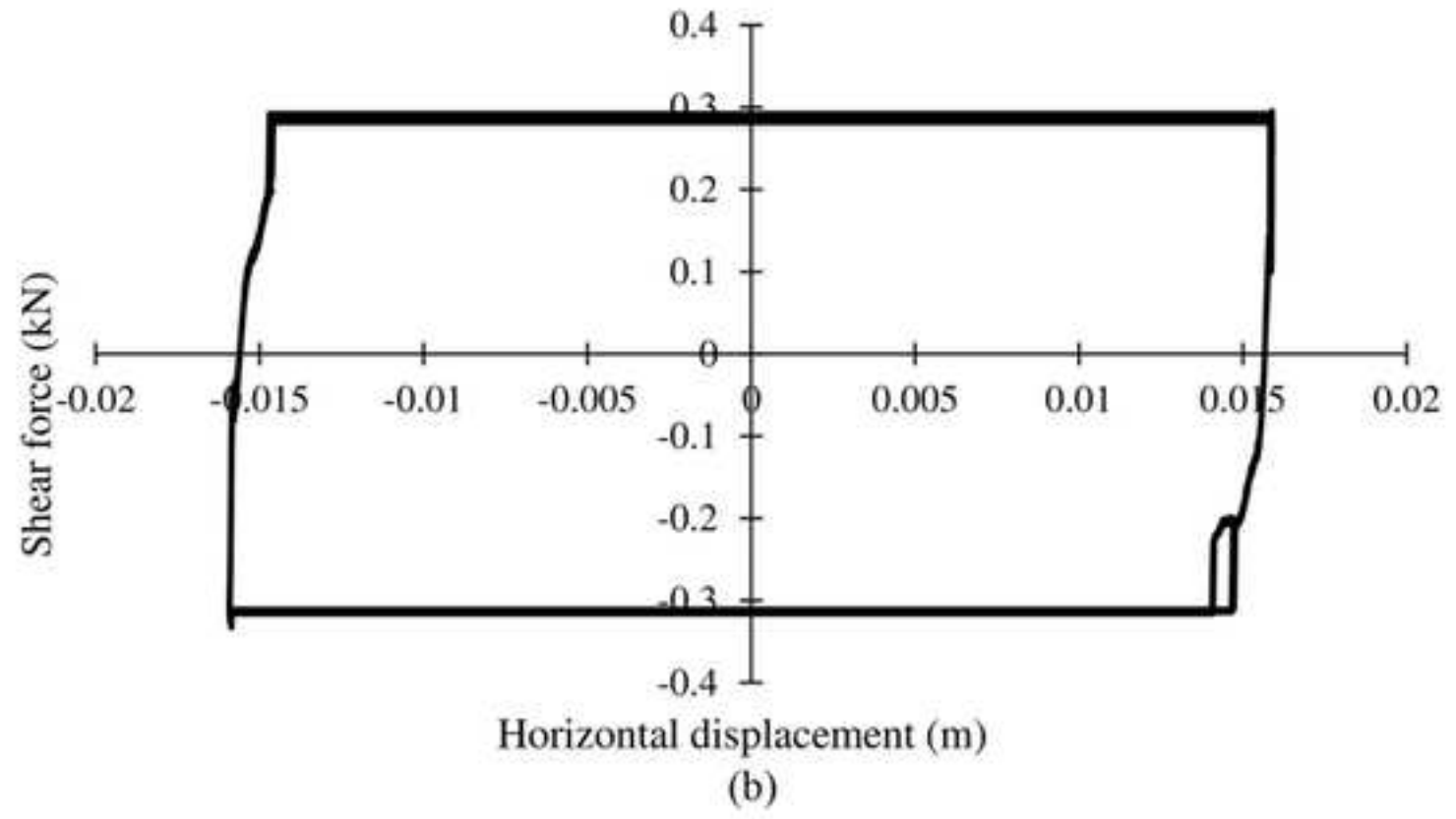


Figure 6

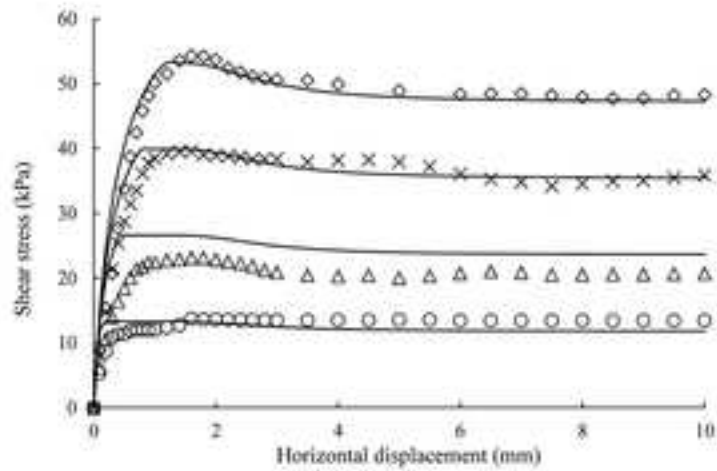


(a)

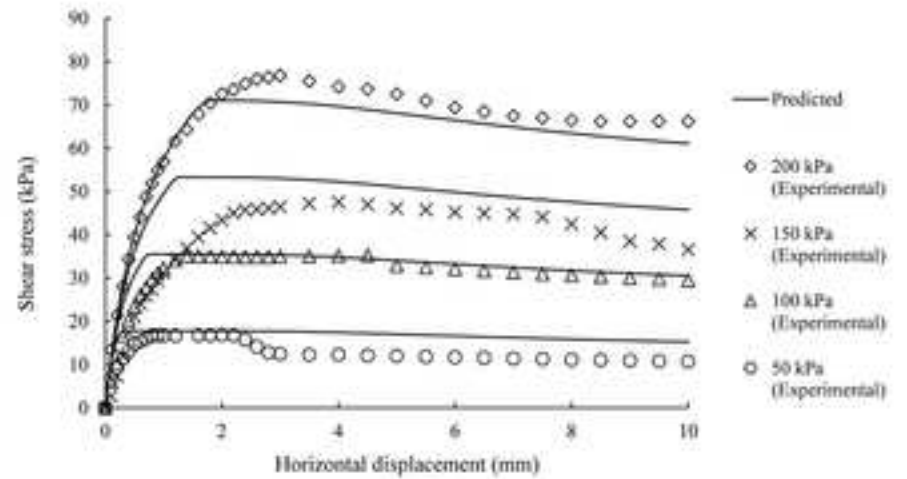


(b)

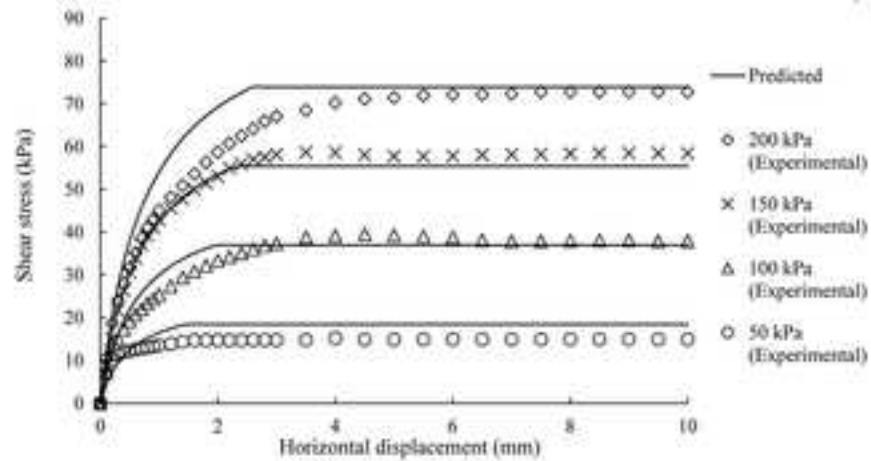
Figure 7



(a)

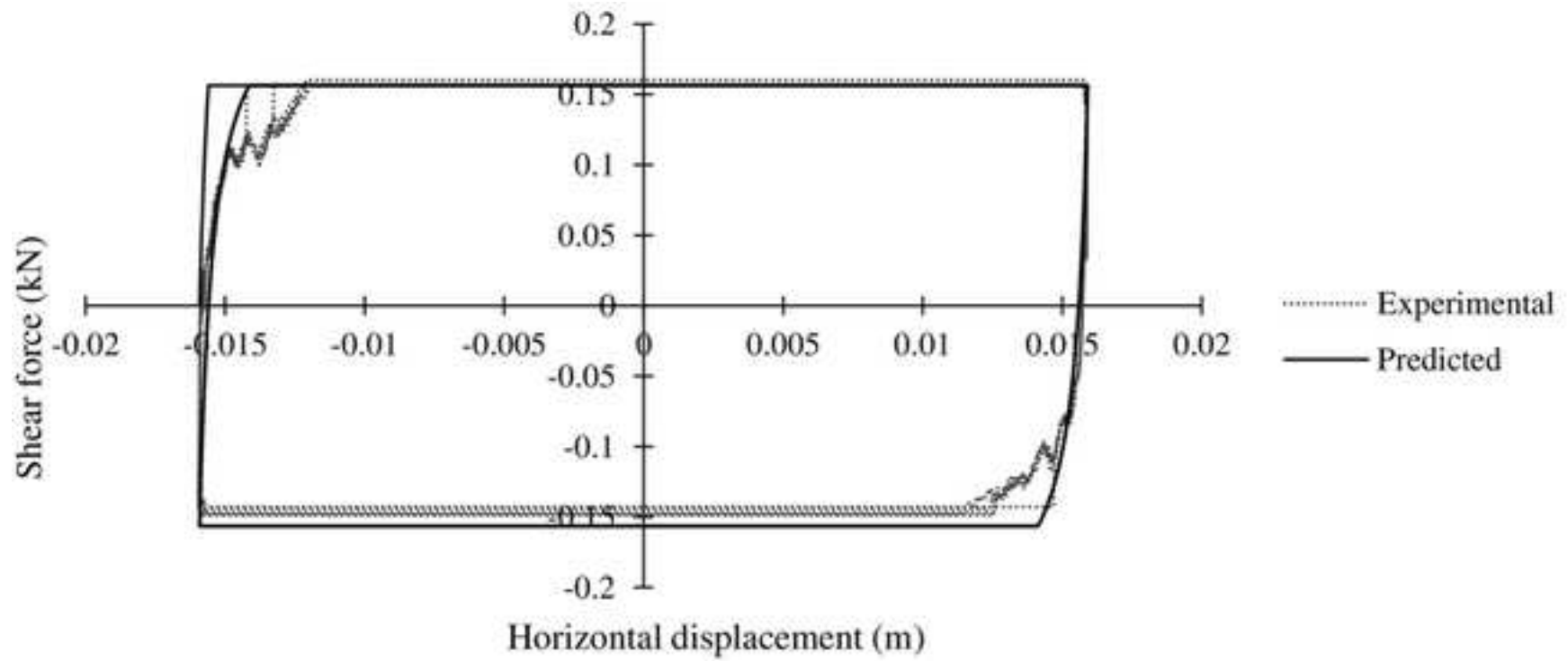


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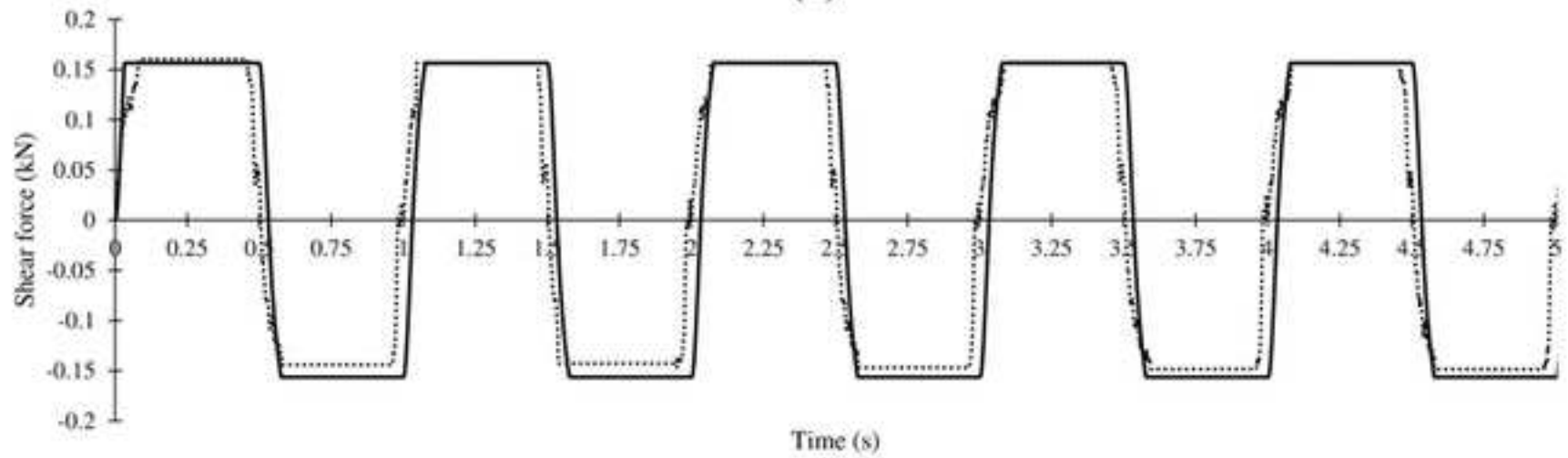


(c)

Figure 8



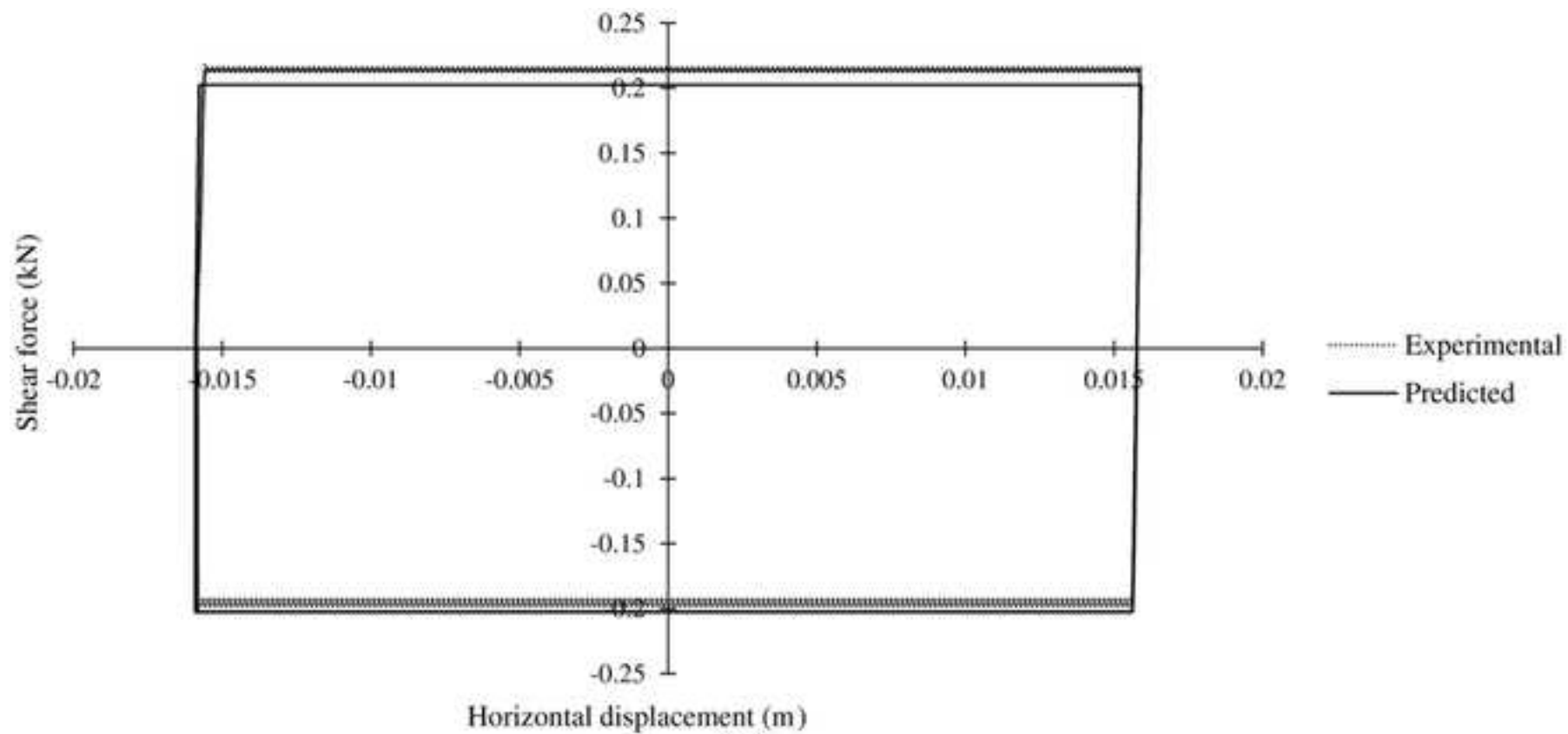
(a)



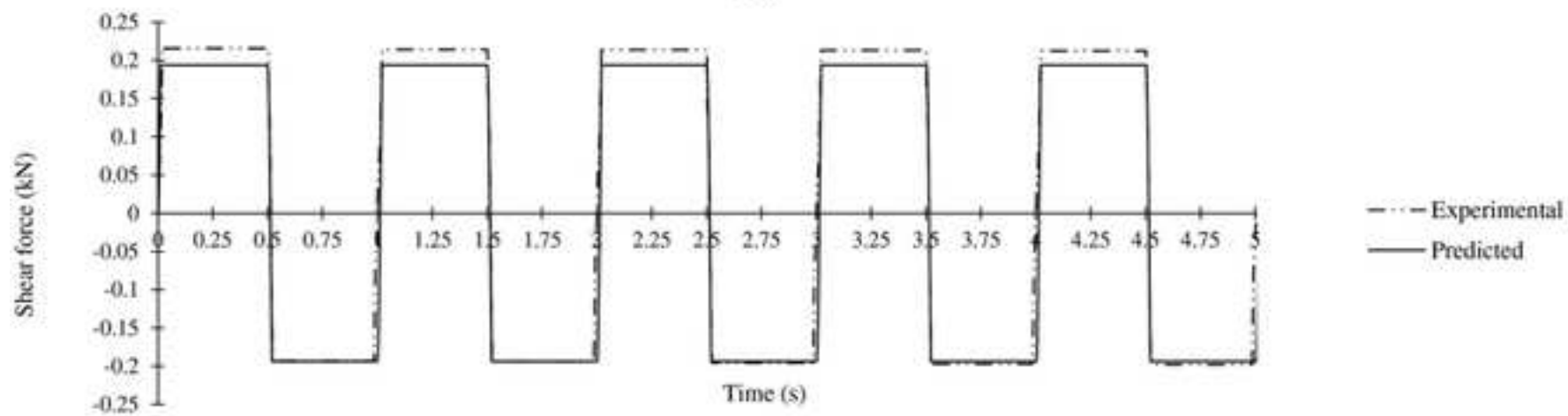
..... Experimental — Predicted

(b)

Figure 9



(a)



(b)

Figure 10

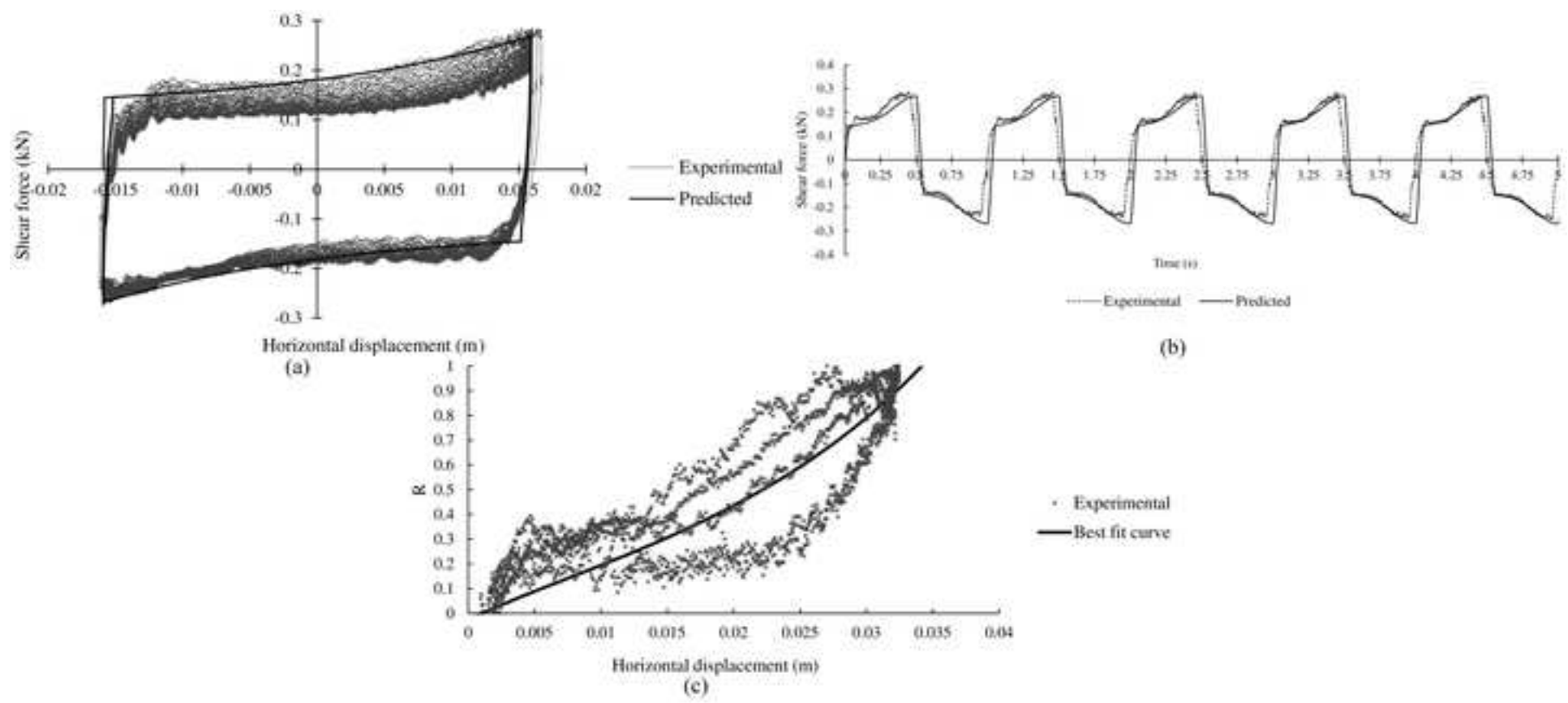


Table 1 Properties of nonwoven needle-punched geotextile

Property	Value
Thickness (mm)	1.5
Mass/unit area (g/m ²)	200
Wide width tensile strength (machine direction) (kN/m)	14
Wide width tensile strength (cross-machine direction) (kN/m)	12
Elongation (%)	55
Apparent opening size (O ₉₅) (mm)	0.085
Permittivity (s ⁻¹)	1.34
Flow rate (10 cm head) (L/m ² /s)	95
Permeability (m/s)	0.0036

Table 2 Properties of smooth HDPE geomembrane

Property	Value
Thickness (mm)	1.5
Density (kg/m ³)	940
Strength at yield (kN/m)	25
Strength at break (kN/m)	52
Elongation at yield (%)	15
Elongation at break (%)	800
Puncture resistance (N)	400
Tear resistance (N)	222

Table 3 Results of the dynamic interface shear tests

Interface	Normal stress (kPa)	Maximum shear force (kN)	Coefficient of friction (dynamic)
GMB-GTX	51	0.15	0.22
	66	0.2	0.23
	81	0.24	0.22
	97	0.3	0.23
	112	0.36	0.24
GMB-GMB	68	0.16	0.24
	88	0.2	0.23
	108	0.28	0.26
	128	0.27	0.21
	148	0.31	0.21
GTX-GTX	51	0.2	0.29
	66	0.27	0.31
	81	0.31	0.29
	97	0.3	0.23
	112	0.31	0.21

Table 4 Values of parameters used for constitutive modelling of static interface behaviour

Parameters	R_f	N	K	$\tan \phi_p$	$\tan \phi_r$	x	y	z	n
GMB-GTX	0.85	0.17	13274	0.26	0.23	-0.0023	0.9414	17.6	3.07
GMB-GMB	0.74	0.05	11218	0.36	0.31	0.0321	1.735	20.23	1.463
GTX-GTX	0.84	0.7	6957	0.37	0.37	–	–	–	–

Table 5 Values of parameters used for constitutive modelling of dynamic interface behaviour

Parameters	R_f	N	K	x	y	z	n
GMB-GTX	0.4	0.6	1012	–	–	–	–
GMB-GMB	0.2	0	5000	–	–	–	–
GTX-GTX	0.2	1.37	1720	0.1511	55.39	-0.85	-1121