

**Climate change impacts on potential evapotranspiration, drought,
and runoff in eastern Australia**

Submitted by

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Certificate of Original Authorship

I, Lijie Shi declare that this thesis, is submitted in fulfilment of the requirements for the award of Doctor of Philosophy, in the School of Life Science/Faculty of Sciences at the University of Technology Sydney.

This thesis is wholly my own work unless otherwise referenced or acknowledged. In addition, I certify that all information sources and literature used are indicated in the thesis.

This document has not been submitted for qualifications at any other academic institution.

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Abbreviations

BoM	Bureau of Meteorology
CR	Capillary rise
DP	Deep percolation
ET	Evapotranspiration
ETa	Actual evapotranspiration
ETp	Potential evapotranspiration
ET0	Reference evapotranspiration
H	Sensible heat of water
I	Irrigation water
G	Soil heat flux
GCMs	Global Climate Models
P	Precipitation
XAJ	Xinjiang model
RCPs	Representative Concentration Pathways
Rn	Net radiation
RO	Runoff
R	Surface runoff
SILO	Science
SPEI	Standardized precipitation evapotranspiration index
λ	Latent heat of vaporization
Δ SF	Horizontal surface flow
Δ SW	Change in soil moisture

Abstract

As one of the most arid continents, Australia is exposed to drought and water scarcity. The changing climate is likely to intrigue more drought occurrence and make water scarcity more severe. In this context, it is important to investigate the influence of climate change on drought and water availability in Australia.

This study aimed to investigate the possible change of potential evapotranspiration (ET_p), drought occurrence, and runoff under future climate scenarios, thus providing useful information to mitigate the adverse impacts of climate change on crop production and water resource management. In specific, four inter-related studies were carried out based on widely used empirical ET_p models, random forest method, statistical indices, standardized precipitation evapotranspiration index (SPEI), Xinanjiang model, and a three-way analysis of variance. Findings from these studies suggested that: (1) radiation based models including Jensen-Haise, Abtew, modified Makkink, and Turc and temperature-based model Hargreaves were able to reasonably estimate ET_p rates, capture its temporal evolution, and periodically oscillation; (2) random forest-based ET_p models generally outperformed empirical ET_p models which required the same climatic inputs; (2) ET_p was likely to increase in the future and the increase could be mostly explained by the increase in temperature and solar radiation; (3) Droughts, especially for moderate and severe droughts were also likely to increase and the increases in spring and winter were larger than that in summer and autumn. The increase in ET_p explained more of the change in drought than the decrease in rainfall did; (4) There were obvious decreases in spring and winter runoff whereas the mean changes in summer and autumn runoff were subtle. The changes in runoff were consistent with the pattern of changes in rainfall and the difference in ET_p inputs barely influenced runoff projection; (5) GCMs, RCPs, or their interaction generally were the dominant factors resulting in uncertainty in the projections of ET_p, drought, and runoff in future climate scenarios.

This study confirmed the increase in air evaporative demand, drought occurrence, and water scarcity in eastern Australia and highlighted the necessary to for farmers and policy makers take measures to adapt to the changing climate. The possible measures include cultivating drought-resistant varieties, adjusting the planting structure, improving the capability of drought forecast, and changing the seeding windows accordingly.

Keywords: climate change; potential evapotranspiration; random forest, drought; runoff; uncertainty; eastern Australia

Chapter 1. Introduction

1.1 Brief research background

1.1.1 Evapotranspiration response to climate change in Australia

Climate change has been verified in the last century in Australia and it is going to continue in the following decades (CSIRO and BOM, 2015). In specific, temperature has increased by 0.9°C in Australia in the past hundred years (CSIRO and BOM, 2015); wind speed has decreased over 90% of Australia (McVicar et al., 2008) while rainfall did not show uniform trend across Australia.

Companied with climate change, evapotranspiration (ET) inevitably showed temporal evolution. As an illustration, Kirono et al. (2009) analyzed the temporal evolution of Pan-evaporation and point potential evaporation in Australia from 1970 to 2004, claiming that both pan evaporation and point potential evaporation showed general increasing trend. Similarly, CSIRO and BOM (2015) also demonstrated that Morton point potential evaporations has increased in the last hundred years and will keep increasing in the future based on the output from global climate models (GCMs). Another example is that Kirono and Kent (2011) reported that most regions in Australia are going to experience increasing evapotranspiration. Consequently, the areas influenced by drought is going to increase by 1.4% to 16.8% to 2070 over the Eastern NSW region. In addition to increasing trend in evaporation, negative trend has also been found across Australia since 1970 (Jovanovic et al., 2008; Kirono and Jones, 2007; McVicar et al., 2008; Roderick and Farquhar, 2004; Roderick et al., 2007).

The obvious discrepancy will have impact on the confidence in model projections. Meanwhile, in spite of the fact that evapotranspiration could be estimated based on pan evaporation, evapotranspiration by which 90% of rainfall returns back to atmosphere in Australia (Rayner, 2007) is different with pan evaporation to some extent (Johnson and Sharma, 2010). However, research directly focusing on evapotranspiration response to climate change in Australia is still scare. Thus, both the discrepancy and the gap highlight the importance to do further research on evapotranspiration impact of climate change to reconcile the differences between estimation from models or instrumental records.

1.1.2 Drought and aridity in Australia

Drought is a recurring climate event in Australia (Bond et al., 2008). For instance, the most recent one,

known as “millennium” drought has lasted more than ten years from 1996 to 2010 (Steffen, 2015). Similar to other natural disaster, drought has remarkably influence on ecosystem, agricultural production, economic and social activities and so on (Mishra and Singh, 2010). As reported, drought happened in Australia resulted in a 36% reduction in winter cereal crop, thus leaving many framers in financial crisis in 2006 (Wong et al., 2009). The damage caused by drought in Australia can also be referred to Steffen (2015) and Mpelasoka et al. (2008), as shown in Figure 1-1.

Figure 1-1. Examples of damage caused by major drought happened in Australia. The figure is extracted from Mpelasoka et al. (2008)

Period	Areal coverage	Losses
1864–1866	All States except Tasmania	50% of sheep population 40% of cattle population 19 million sheep
1911–1916	Widespread	2 million cattle
1918–1920	All States except Western Australia	Not available
1939–1945	Widespread	30 million sheep 40% drop in wheat production 20 million sheep
1963–1968	Widespread	\$300–500 million farm income
1972–1973	Mainly eastern Australia	Not available Billions of farm income
1982–1983	The most intense, widespread	\$590 million in terms of relief \$10 billion farm income
2002–2003	Widespread	70 000 jobs

Aridity is changing with the most possibility in expansion in eastern Australia (Steffen, 2015) and droughts tend to occur more frequently since the possible increase in rainfall is likely to be lower than the increase of moisture demand (Nicholls, 2004). For instance, compared with drought in 1951-2000, Mpelasoka et al. (2007) found an increase trend in drought frequency, severity and duration for 2051 to 2100 based on Palmer Drought Severity Index driven by CSRIO MK3 GCM under SRES A2 scenario.

In drought assessment, Australia generally adopts Rainfall Decile which only takes water supply (precipitation) into consideration to assess drought (Gibbs Maher, 1967). However, a lot scientists found that

the increasing frequency of drought occurrence is due to the increase in evapotranspiration instead of the decrease in precipitation. In this case, the index only involving precipitation in assessing drought might lead to misunderstanding on the cause of drought and may underestimate the possible increase of drought frequency. For example, Mpelasoka et al. (2008) compared Rainfall Deciles and Soil Moisture Deciles (considering both precipitation and evapotranspiration) in assessing drought in Australia and claimed that thought both drought indexes draw consistent conclusion on a general increase in drought frequency over Australia, the increases detected by Soil Moisture Deciles are larger than that detected by Rainfall Deciles. More than that, they argued that the Soil Moisture Deciles is more relevant to resource management and evapotranspiration is more important in determining the severity of droughts in a warming world (Mpelasoka et al., 2008). Therefore, it sounds reasonable to adopt a relative comprehensive drought index to project drought events under future climate scenarios (Asadi Zarch et al., 2015) so that results from researches with various drought indexes could be compared and improve the reliability in adaption to potential drought events.

1.1.3 Water scarcity in Australia

Shortage in rainfall and the uneven distribution between water resource and population makes water scarcity be a serious problem to agricultural production in Australia (Mpelasoka et al., 2007). For instance, Murray-Darling Basin which is the center both to major urban area and agricultural production receives around 6% of total rainfall run off in Australia (Chartres and Williams, 2006; Ejaz Qureshi et al., 2013). On the contrary, the tropical north which is characterized with low population densities has relative abundance of available water (Ejaz Qureshi et al., 2013). What's more, under the ongoing climate change, rainfall has showed declined trend (CSIRO, 2008) and most GCMs' projections support a continuing decrease in annual rainfall but increase in evapotranspiration in Australia (Chiew et al., 2009). Thus, the rain-fed agricultural production system which consumes around 70% of total water consumption may be challenged by more serious water stress in future (Adamson et al., 2009; Pigram, 2007; Wittwer and Griffith, 2011). For instance, Ejaz Qureshi et al. (2013) reported that compared with the expected rice production in Murray-Darling Basin, it was reduced by 70%, 20% and 10% in dry, medium and wet climate scenarios. In this circumstance, it is important to project the potential influence of climate change on water scarcity and offer feasible measures to offset the detriment.

1.2 Scientific problems and objectives

Around 80% of Australia continent is characterized with arid or semi-arid climate where annual rainfall

is less than 600mm, which makes Australia very vulnerable to climate change. Nowadays, there is a possibility in increasing trend in water scarcity and extreme events like drought under the changing climate (CSIRO and BOM, 2015). Thus, drought policy and water management might need to be adjusted accordingly (Kirono and Kent, 2011).

Evapotranspiration (ET) is a key parameter in drought assessment, hydrological cycle, and water management. As reported, the increasing evapotranspiration, which is mainly caused by global warming will worsen the dry conditions in arid regions (Goyal, 2004; Tabari et al., 2011). Given the ongoing climate change, it is necessary to figure out how evapotranspiration has changed in the past, its current behavior and what is going to happen in the future climate scenarios (Kirono et al., 2009). Thorough understanding on evapotranspiration is a prerequisite to project drought and water resource management under future climate scenarios.

In this context, this project aims at offering a comprehensive analysis on climate change impacts on evapotranspiration, drought and water availability in Australia from the recent past to the future (2100), thus reveal the temporal evolution of evapotranspiration, drought, and runoff. This project is going to offer answers to the following questions:

- (1) Are the simplified empirical ETp models reliable in estimating ETp rates, detecting its temporal trends and analyzing its interannual oscillation?
- (2) What is the influence of different ETp models on drought and runoff projection and their response to future climate change?
- (3) How do factors like GCMs, RCPs, and ETp models contribute to the uncertainty in their projection?

The specific goals of this research are to:

- (1) Reveal the factors driving the temporal evolution of evapotranspiration, drought, and runoff regimes;
- (2) Quantify the evapotranspiration, drought, and runoff regimes under future climate scenarios with chosen evapotranspiration models, drought indexes, and hydrological model driven by multi-model ensemble method.

1.3 Significance and outline of this thesis

Evapotranspiration, drought, and runoff are three inter-connected parameters, which are all deeply influenced by climate change. Meanwhile, they can directly or indirectly exert influence on agricultural

production and human society especially to a water-limited country like Australia. Therefore, with climate change going on, a thorough understanding on their temporal evolution in the past and projecting their potential change under future climate scenarios are prerequisites to investigate the response of water availability in the future. This PhD project which combines the concern of “Living in a changing climate” and concern of “water availability” driven by the state-of-the-art multi-model ensemble method will provide such insight. Results of this project are helpful to foresee potential water-stress in eastern Australia thus formulating reasonable adaptation measures to make sure the sustainable development both in water resource and agricultural production under a changing climate.

The thesis is structured as the following. First, a general introduction (Chapter 1) followed by literature review (Chapter 2) was given to clarify the study background and its significance. Then the four mainstay chapters aim to answer the subsequent questions: The performance of empirical ET_p models across different climatic zones (Chapter 3); The response of ET_p to climate change and the uncertainty in ET_p projection (Chapter 4); The response of drought to climate change and the uncertainty in its projection based on multiple ET_p models and ensemble GCMs (Chapter 5); The response of runoff to climate change and the influence of different ET_p inputs on runoff projection (Chapter 6); Chapter 7 summarized the general conclusions, limitations, and future research directions. Figure 1-2 showed the flow chart of the thesis.

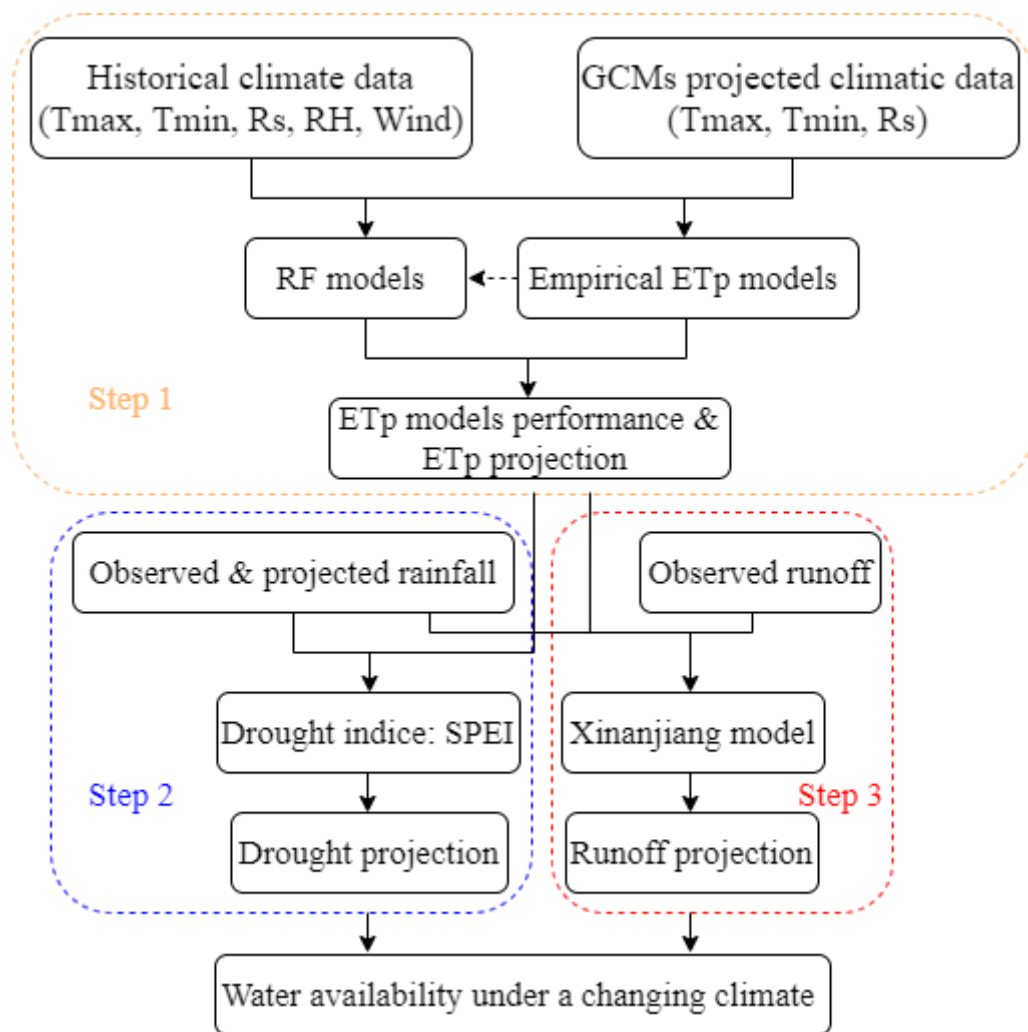


Figure 1-2. Flow chart of this project

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Chapter 2. Literature review

2.1 Climate change

Global climate change has been demonstrated in many aspects including risen temperature, changing precipitation patterns, more extreme climate events, warming ocean, shrinking ice sheets and so on (IPCC, 2014). In specific, temperature has increased by 0.85°C while precipitation increased in tropical areas and decrease in the rest of the world (IPCC, 2014; Wasko et al., 2021). Globally, Kharin et al. (2013) claimed that per degree increase in global mean temperature is likely to induce in 1.5%-2.5% increase in global mean precipitation. In addition, both changes in temperature and precipitation are generally results of extreme temperature events or extreme precipitation events. For instance, Westra et al. (2013) reported that the median intensity of annual maximum daily precipitation would increase by 5.9%-7.7% per K degree increase in mean temperature. Herold et al. (2018) projected that some regions in Australia would experience an increase up to 3.5°C in maximum day time temperatures and all capital cities in Australia are likely to witness a triple increases of heatwave days per year by the far future (2060-2079).

Global climate models (GCMs), which was firstly proposed by Phillips (1956) and regional climate models (RCMs) have been widely used in climate change study and projection (Chen et al., 2012; Ekström et al., 2007; Frei et al., 2006). Given the raw spatial resolution of data extracted from GCMs, both dynamical and statistical downscaling method are used to bridge the gap (Hay and Clark, 2003; Wilby et al., 2000). Both the downscaling process and structure of GCMs will produce uncertainty. In other words, uncertainty is an inevitable problem in climate change projection. The main sources of uncertainty include the following aspects. Firstly, the definition of the greenhouse gas emissions scenarios which is used to drive the GCMs might vary (Wilby and Harris, 2006). Secondly, the GCMs that are developed with different model structures may produce various climate projections even under the same emission scenario (Taylor et al., 2012). Thirdly, the downscale methods used to downscale climatic data from GCMs to finer temporal and spatial scales to force the evapotranspiration models is another source of uncertainty (Maraun et al., 2010; Wilby et al., 2000). Lastly, the diverse evapotranspiration models are also an importance source of uncertainty in drought and runoff projection (Thompson et al., 2013; Wang et al., 2015). The research of uncertainty related to hydrological projection, climatic factors projection (such as rainfall), and extreme climate events projection like drought have been globally reported (Brunner et al., 2021; Kauffeldt et al., 2016). For instance, Arnell (2011) analyzed the uncertainty in projecting runoff response to climate change in UK catchments with the

use of data from 21 GCMs driving a hydrological model. He claimed that the change of runoff ranged from -40% to +20% with an increase of 2°C in mean temperature, showing great uncertainty. Similarly, Barria et al. (2015) projected that runoff in southwestern Australian would experience a reduction ranging from 10% to 80% as a combined result of 0% - 40% reduction in precipitation and 0.5°C – 3°C increase in temperature. They claimed that the range of uncertainty in runoff projection was even larger than earlier studies (Barria et al., 2015). However, these studies mostly focused on analyzing the widespread range of the projected items but were weak in analyzing the contribution of different sources to the uncertainty.

2.1.1 Extreme climate events under a warming climate

One of the main results caused by climate change is the increases in the occurrence and even the concurrent of extreme climate events, such as drought, heatwaves, cold waves, frost, and flood (Hao et al., 2013; Hao et al., 2018). These extreme climate events can have severe influence on agricultural production, water and food security, economic, and many other aspects of human-being life and ecosystem. Take the study of Chen et al. (2020) as an explanation, they projected the extreme climate events in the Yangtze River Basin, China with the use of 12 extreme climate indices and analyzed their effect on maize and rice. Results from their study showed that maize yield in this region was likely to decrease by 5.36% under RCP4.5 and 6.04 under RCP8.5. The corresponding reduction in rice yield was 2.55% and 2.48%. At global scale, Hao et al. (2018) reported that western US, northern South America, western Europe, Africa, western Asia, southeastern Asia, southern India, northeastern China and eastern Australia are likely to experience significant increase in the severity of dry and hot extremes. Herold et al. (2018) demonstrated that drought and the number of days above 30°C is expected to increase across the major wheat-belt in Australia. Meanwhile, the increases are mainly expected in spring when wheat is most vulnerable to heat stress. All these studies highlighted the inevitable increases of extreme climate events and the necessity of carrying out research about them to mitigate the potential dire effects.

Drought is a natural hazard influenced by rainfall and air temperature. The occurrence of drought can have great negative influence on many aspects of human-being life (Hao and Singh, 2015; van Kempen et al., 2021). In the future, drought risk and severity may increase due to the warming climate (Cook et al., 2014). As Cook et al. (2020) reported in their latest research that regions including western North America, Central America, Europe and the Mediterranean, the Amazon, Southern Africa, China, Southeast Asia, and Australia are going to experience strong drying. Meanwhile, the extreme drought events could increase by

200-300% in some regions. With more regions exposing to drought, the aridity areas are also going to shift. In summary, there are two dominant viewpoints in aridity shift. One is the phenomenon of ‘rich-get-richer’, that is, humid regions will be more humid while arid regions will dry out further with global warming (Chen et al., 2017; Chou et al., 2009; Durack et al., 2012); another one supports that arid regions are becoming slightly more humid while humid zones are most likely to become a little bit drier (Asadi Zarch et al., 2017). In this context, the projection of drought in an arid continent is necessary for offering alarm warning and taking early action to mitigate the potential dire effects.

2.1.2 Climate change in Australia

Australia is the second most arid continent on earth and the variety of its climates makes it more vulnerable to climate change. Climate in Australia has been warming and the warming trend will continue in the 21st century. Accompanying with increasing of greenhouse gases emission, average near-surface air temperature in Australia has witnessed a 0.9°C increase since 1910 (CSIRO and BOM, 2015). Meanwhile, extreme weather events happened more frequently. Particularly, extreme heat events obviously outnumbered extreme cool events. Since 1950, heatwaves happening in Australia were accompanied with the characteristic of longer duration, higher frequency and stronger intensity. Change of rainfall in Australia showed spatial and seasonal variation. In general, the tropical north of Australia has experienced increase in rainfall whereas it decreased in the south of Australia since 1950 (Dey et al., 2019). Correspondingly, changes in streamflow also showed similar spatial variation, that is, south of Australia experienced decrease in streamflow while increasing trends were found in north of Australia (Zhang et al., 2016b). Seasonal changes in precipitation presented as decreasing in autumn and winter rainfall while increasing in spring and summer rainfall. It is projected that future climate in Australia will continue to experience increasing temperature with more extremely hot days but fewer extremely cool days (Alexander and Arblaster, 2017); increasing extreme rainfall across most of Australia but southern continental Australia may see decline of winter and spring precipitation (CSIRO and BOM, 2015).

2.2 Evapotranspiration

Evapotranspiration is the sum of evaporation, which is a process that liquid water is lost from soil surface to water vapor in the air and transpiration which describes vaporization of water from vegetation (Allen et al., 1998; Kool et al., 2014). The energy driven evapotranspiration, to a large degree, comes from solar radiation, then secondly comes from air temperature (Jensen and Allen, 2015). In addition to the driving

energy, the gradient of water vapor pressure between the surface of evapotranspiration and the ambient environment offers force to remove the water vapor from the evapotranspiration surface. Meanwhile, wind helps to blow the humid air away and bring drier air, otherwise the evapotranspiration will slow down when the surrounding air becomes more and more humid. In summary it is solar radiation, relative humidity, air temperature and wind speed that affect the process of evapotranspiration from the perspective of meteorology (Eslamian et al., 2011; Zhang et al., 2016a). Apart from meteorological factors, evapotranspiration is also influenced by water availability in the soil, crop characteristics, environment and management practice (Cammalleri et al., 2010; Rana and Katerji, 2000).

As we mentioned above, evapotranspiration is not only influenced by meteorological factors but also crop characteristics, environment, and management. Thus, scientists defined reference evapotranspiration (ET_0), potential evapotranspiration (ET_p), and actual evapotranspiration (ET_a) to describe evapotranspiration under different conditions from the perspective of parameters included. The detail definitions on ET_0 , ET_p , and ET_a are in the following paragraph:

The ET_0 is only meteorological parameters-related, representing the atmospheric power of evaporation. It is defined as evapotranspiration rate from a reference vegetation surface which is covered with an actively growing grass shading the ground totally, with the uniform height of 0.12m, a fixed surface resistance of 70 $s\ m^{-1}$ and an albedo of 0.23 under no water limited condition (Allen et al., 1998). Potential evapotranspiration is the maximum evapotranspiration rate from crop which grows in a large field under ideal environmental and management conditions, bearing zero water stress under a given climate (Li et al., 2016). Actual evapotranspiration is the evapotranspiration rate from crop in reality condition where water scarcity, water logging or unideal might happen thus reducing the evapotranspiration rate (Cammalleri et al., 2010; Farg et al., 2012).

The relationship of ET_0 , ET_p and ET_a can be described via the following equations:

$$ET_p = K_c \times ET_0 \quad (2-1)$$

$$ET_a = K_s \times ET_p = K_s \times K_c \times ET_0 \quad (2-2)$$

where K_c and K_s are crop coefficient and the adjust coefficient standing for the stress from water and environment.

Evapotranspiration is one of the most basic and important components to hydrological, meteorological, agricultural, and ecological communities (Gharbia et al., 2018; Jensen and Allen, 2015). In summary, the importance of evapotranspiration mainly displays in the following aspects: (1) it is an important joint of water

cycle and energy balance. In specific, evapotranspiration accounts for around 67% of precipitation and evapotranspiration is also the media through which radiation onto the earth's surface returns back to the atmosphere as latent and sensible heat (Fisher et al., 2017; Oki and Kanae, 2006); (2) evapotranspiration is an important parameter in hydrological, environmental, and agricultural models; For instance, irrigation water requirement is the difference between effective precipitation and crop water requirement which equals to crop evapotranspiration in value. In hydrological field, evapotranspiration is involved in most hydrological models like SWAT model.

The methods used in measuring evapotranspiration are mainly based on the theory of energy balance, as shown in equation (2-3), and water balance, as shown in equation (2-4) and (2-5) at field or regional scale, or mass transfer method (Jensen and Allen, 2015). Though measurement is the most direct and accurate method in quantifying evapotranspiration, there are obvious disadvantages for this method. Generally speaking, measuring evapotranspiration requires specific devices including lysimeters, tanks, eddy covariance flux tower, or evaporation pan. Normally, these equipments are expensive to installation, labor and time-consuming in management and maintenance, and needs well-trained professional personnel to cope with. Thus, measuring evapotranspiration directly is mainly employed by research purpose (Allen et al., 1998).

Energy balance equation:

$$R_n - G - \lambda ET - H = 0 \quad (2-3)$$

where R_n ($\text{MJ m}^{-2} \text{ day}^{-1}$) represents net radiation; H ($\text{MJ m}^{-2} \text{ day}^{-1}$) represents the sensible heat; G ($\text{MJ m}^{-2} \text{ day}^{-1}$) represents the soil heat flux; λ ($\text{MJ m}^{-2} \text{ day}^{-1}$) represents the latent heat flux, via which express the evapotranspiration rate. λ is the latent heat of vaporization, equaling to 2.45 MJ kg^{-1} at 20°C .

Water balance equations at field scale (2-4) and regional scale (2-5):

$$ET = I + P - RO - DP + CR + \Delta SF + \Delta SW \quad (2-4)$$

$$ET = P - RO \quad (2-5)$$

where I (mm) is irrigation water, P (mm) is precipitation, RO is surface runoff (mm), DP is deep percolation (mm), CR (mm) is capillary rise, ΔSF (mm) is the horizontal surface flow, ΔSW (mm) is the change in soil content.

2.2.1 Models used in estimating evapotranspiration

Given the difficulty in measuring evapotranspiration directly, many models have been developed since

1950s to estimate it with meteorological data (Allen et al., 1998). In literature, around 50 different methods have been reported in estimating evapotranspiration (Lu et al., 2005). In general, these models could be classified into two types – fully physical based model and empirical/semi-empirical model. In specific, empirical model are classified into temperature-based model (Hargreaves and Allen, 2003), radiation-based model (Priestley and Taylor, 1972), mass transfer-based model (Mahringer, 1970) according to the climatic factors incorporated in the model. Among all methods, Penman (Penman, 1948) and Penman-Monteith FAO56 (PM) model are fully physiological based and takes all the related meteorological factors into consideration. The advantage of these two models are that they are able to offer reasonable accuracy result against measured ET independent on climate conditions, thus they can be used to any climate circumstance without calibration (Li et al., 2016). However, meteorological factors required by them may not always be available especially in developing countries (Tabari et al., 2013) and in future climate scenarios (Wang et al., 2015).

As to the empirical or semi-empirical models, they are normally developed based on specific climate conditions, thus they are normally suited to certain climates and should be tested or recalibrated when used under a different climate (Donohue et al., 2010). As a matter of fact, cross comparison of models has been carried out in various regions including European (Alexandris et al., 2008; Bormann, 2010), South America (de la Casa and Ovando, 2016), Iran (Tabari, 2009; Tabari et al., 2013; Valipour et al., 2017), China (Li et al., 2016; Li et al., 2015; Peng et al., 2017), American (Douglas et al., 2009; Lu et al., 2005), Canada (Aladenola and Madramootoo, 2013; Sentelhas et al., 2010). Remarkable difference of model performance exists in these studies. For instance, Valipour et al. (2017) assessed the performance of 15 ET models against PM across various climates in Iran. They found that model Abtew (Ab) has a better performance than other ET modes in semiarid climate; While, Hargreaves performs best in very humid regions and the Mediterranean. Still in different climates of Iran, Tabari (2010) investigated the performance of four ET models (Turc, Makkink, PT and Hargreaves) which are all included in research of Valipour et al. (2017). But he claimed that Hargreaves model outperforms other models under semi-arid and warm humid climate. Thus, it is still a necessary to do location-specific research to choose a best performed simplified ET model at a certain region.

2.2.2 Response of evapotranspiration to climate change

Both positive and negative trends have been noticed in evapotranspiration due to climate change (Dinpashoh et al., 2011; Gao et al., 2017b). The unexpected decreasing evapotranspiration with increasing

temperature has been famous known as “evaporation paradox” (Brutsaert and Parlange, 1998; Roderick and Farquhar, 2002). Air temperature is not the only one factors influencing evapotranspiration, thus the positive effect caused by increasing temperature could be masked by the negative influence of other climatic factors. For instance, Donohue et al. (2010) demonstrated that the contribution of temperature, wind speed, solar radiation and vapor pressure to evapotranspiration change magnitude were 1.5 mm year⁻¹, -1.3 mm year⁻¹, -0.6 mm year⁻¹, and -0.4 mm year⁻¹, respectively. Obviously, the reduced rates caused by wind speed, solar radiation and vapor pressure pronounced more than air temperature did, resulting in a general downward trend in evapotranspiration. In summary, the possible reasons caused decrease in evapotranspiration include (1) the shrunk difference range of diurnal temperature (Roderick and Farquhar, 2002); (2) the global dimming due to increase in aerosol and cloudiness (Fan et al., 2016; Huo et al., 2013; Roderick and Farquhar, 2002); (3) decrease in wind speed which is known global surface stilling (Fan et al., 2016; McVicar et al., 2012).

In terms of sensitivity of evapotranspiration to climatic drivers – air temperature, humidity, solar radiation and wind speed, it could be different depending on the climate conditions, evapotranspiration models adopted and climatic inputs (Bormann, 2010; DeJonge et al., 2015; Irmak et al., 2006). For instance, Xing et al. (2014) suggested that solar radiation followed by air humidity and wind speed was the dominant factor exerting effects on evapotranspiration in the Haihe River Basin, China. However, Eslamian et al. (2011) declaimed that temperature and relative humidity are the foremost factors influencing evapotranspiration in arid and semiarid regions in Iran. Meanwhile, the contribution of climatic factors to evapotranspiration may shift under a changing climate (Eslamian et al., 2011). Thus, it is vital to do updated analysis on this topic.

In Australia, scientists did not draw consistent conclusion in the temporal evolution of evapotranspiration (Jovanovic et al., 2008; Kirono and Kent, 2011; Roderick and Farquhar, 2004). Moreover, most studies on evapotranspiration focused on time before or around 2005 (Guo et al., 2017). But since then, climate change has been still going on, thus a research on longer time period may offer scientists updated insight on evapotranspiration response to climate change.

2.2.3 Projection of evapotranspiration under future climate scenarios

Projection evapotranspiration under future climate scenarios is necessary to assess the possible influence of climate change having on water resource, agricultural production and hydrological regime (Wang et al., 2015). The most commonly used method in evaluation of climate change effects on evapotranspiration is based upon evapotranspiration models driven with climatic data derived from global climate models (GCMs)

which are forced with different CO₂ emissions scenarios (Kirono et al., 2009; Thompson et al., 2013). This method has been adopted in the assessment of climate change influence on evapotranspiration that vary in scale from major river basins (Thompson et al., 2014; Wang et al., 2015; Xing et al., 2014) to medium sized catchment (Bae et al., 2011), the national (Kirono and Kent, 2011), and global scales (Arnell and Gosling, 2013; Gosling and Arnell, 2011).

The main uncertainties associated with project the future evapotranspiration comes from the following aspects. Firstly, the definition of the greenhouse gas emissions scenarios which is used to drive the GCMs might vary. Secondly, the GCMs that are developed with different model structures may produce various climate projections even under the same emission scenario (Taylor et al., 2012). Thirdly, the downscale methods used to downscale climatic data from GCMs to finer temporal and spatial scales to force the evapotranspiration models is another source of uncertainty. Lastly, the diverse evapotranspiration models are also an importance source of uncertainty (Wang et al., 2015). The uncertainty caused by the evapotranspiration models comes from both the model structure and the input data. For instance, Wang et al. (2015) demonstrated that the increase magnitude in evapotranspiration varied among three PM, Hargreaves model and direct downscaled ET from GCMs (up to 70 mm year⁻¹) since 2070s in Hanjiang River Basin, though the increase trend was captured by three different methods. As Thompson et al. (2014) and Kingston et al. (2009) reported that the uncertainty caused by different evapotranspiration models is equal or, in some circumstance, greater than that caused by the difference of GCMs in climate change signals.

In Australia, Morton equations are adopted to simulate evapotranspiration under future climate scenarios with multi GCMs (CSIRO and BOM, 2015). However, given the possible uncertainty caused by different evapotranspiration models, further studies on different evapotranspiration models driven by data from GCMs are a necessary. In addition, Randall (2007) said that compared with wind speed, humidity and solar radiation, temperature from GCMs are more reliable. Thus, it is worthy to adopt more evapotranspiration models including those temperature-based ones to project evapotranspiration under future climate scenarios.

2.3 Drought and its response to climate change

2.3.1 Drought and aridity

Drought and aridity are two important conceptions in describing the climatic character of a certain area. Despite that they are two different concepts, there is ambiguity in the use of drought and aridity (Asadi Zarch, 2015). Thus, it is important to firstly distinguish them from each other. Drought is a natural and recurring

climate event, which can occur to any climatic regimes (Cook et al., 2020; Cook et al., 2014). In conception, drought describes the prolonged period (from months to years) of water deficit mainly caused by rainfall deficient (Wilhite, 2000). In other words, drought is a temporary hazard resulted by below-normal precipitation over a certain period (Dai, 2011). Duration, frequency, and severity are three features to describe drought. In general, drought is classified into the following types (Mishra and Singh, 2010): meteorological drought – a climate event characterized by below-normal precipitation over a region for a period of time from months to years; hydrological drought – describing the phenomenon that water resource stored in lakes, reservoirs or aquifers is below long-term average level; agricultural drought – meaning a period of time that soil moisture fails in meeting the demand of crop evapotranspiration.

In contrast, aridity is a permanent climatic character for arid areas. It describes the climate condition that is caused by a constant scarcity in precipitation. Aridity can generally lead to low soil moisture and low carrying capacity of ecosystems (Asadi Zarch, 2015). Based on aridity index (the ratio of precipitation and potential evapotranspiration), climate can generally be classified into hyper-arid, arid, semi-arid, sub-humid, and humid (UNESCO, 1979). Compared with that in humid or sub-humid areas, hyper-arid, arid, and semi-arid areas have higher chance to expose to more drought events due to the scarcity in rainfall (Sun et al., 2006).

2.3.2 Drought and aridity indices

Drought and aridity indices can be developed with similar parameters, such as precipitation and air temperature. The commonly used drought indices ranging from index which only take precipitation into consideration, such as Rainfall Deciles (Gibbs Maher, 1967) and Standardized Precipitation Index (Hayes et al., 1999) to index which combines precipitation, evapotranspiration, temperature and other atmospheric drivers like Palmer Drought Severity Index (Dai et al., 2004). Similarly, there are also various aridity indices. The commonly used aridity indexes include Budyko's aridity index (Budyko, 1974; Oguntunde et al., 2006), Aridity Intensity Index (Costa and Soares, 2009), De Martonne aridity index (Martonne, 1926; Zhang et al., 2009), Thornthwaite aridity index (Huo et al., 2013; Thornthwaite, 1948), Pinna combinative index (Baltas, 2007; Croitoru et al., 2013), UNESCO aridity index (Feng et al., 2016; Tabari and Aghajanloo, 2013; UNESCO, 1979). These indices are widely used in monitoring, quantifying, and projecting drought and aridity shift under a warming climate (Ahmed et al., 2019; Allan, 2014; Chen et al., 2017). For instance, Huang et al. (2016) projected that dryland would increase by 23% under RCP8.5 and 11% under RCP4.5

based on UNESCO aridity index. This project focused on the projection of drought's change in an arid continent. Therefore, the following paragraph only paid attention to the review the use of drought indices.

Every drought index has its strength and weakness (Dai, 2011; Keyantash and Dracup, 2002). For instance, the Rainfall Deciles has been widely used in Australia. This index is able to provide a statistical measure of rainfall but it does not consider the influence of evapotranspiration on drought (Dai, 2011). Under a warming climate, evapotranspiration may have more weights on drought occurrence. Thus, drought index like Rainfall Deciles may lead to misunderstand in this case. By contrast, Palmer Drought Severity Index (PDSI) is probably one of the most frequently used drought index which was developed based on a 2-layer bucket-type water balance model (Mishra and Singh, 2010; Zargar et al., 2011). It involves both precipitation, temperature, and soil moisture to assess drought and has been used in analyzing the extent, severity and spatiotemporal trend of drought and drought forecasting (Özger et al., 2009) as well as aridity change (Burke et al., 2006; Dai et al., 2004) at global scale. However, it is reported that PDSI is not sensitive enough to the variation of ETp due to the standardization procedure of soil water budget anomalies (Cook et al., 2014). Standardized precipitation evapotranspiration index (SPEI) was put forward by Vicente-Serrano et al. (2010) based on the monthly difference between precipitation and evapotranspiration. After its proposition, SPEI has been widely used to detect and explore the influence of climate change on drought events (Gao et al., 2017a). Compared with SPI (which only considers precipitation) and PDSI (which is complex in calculation), SPEI combined the simplicity of SPI in calculation with the sensitivity of PDSI to temperature fluctuations (Potop et al., 2012).

2.3.3 Impacts of climate change on drought

With climate change going on, drought frequency, intensity, and area affected are likely to increase due to higher temperature and changes in precipitation (Burke and Brown, 2008; Sheffield and Wood, 2008; Sheffield et al., 2012; Wanders and Wada, 2015). However, the magnitude and spatial patterns of drought change are influenced by various factors including the drought indices adopted (Vicente-Serrano et al., 2015), the driving precipitation data (Trenberth et al., 2013), the methods adopted to estimate evapotranspiration and the climate data used to drive evapotranspiration models (Sheffield et al., 2012), and the study area. In an arid region of Pakistan, Ahmed et al. (2019) reported that area affected by lower severity drought with higher return periods would increase in the future periods but the occurrence of severe drought would decrease. Across Australia, Kirono et al. (2011) projected that a general increase in both area affected by

drought and drought's frequency. At global scale, Lu et al. (2019) analyzed the temporospatial change of drought under RCP2.6, RCP4.5, and RCP8.5 with SPEI-PM. They found that increasing trend of drought was found in Africa, North America, South America, and Oceania independence of climate scenarios. Thus, it is necessary to do location-specific projection of drought change to help drought monitoring and forecasting for local farmers and policy makers.

As drought indices which both include precipitation and evapotranspiration are more widely used in assessing the response of drought to climate change. The sensitivity of drought indices to precipitation and evapotranspiration needs to be figured out (Vicente-Serrano et al., 2015), especially the results may vary with different evapotranspiration models used as evapotranspiration estimated by different models may exert influence on drought projection (Donohue et al., 2010). For instance, Chen and Sun (2015) assessed changes of drought in China from 1961 to 2012 based on standardized precipitation evapotranspiration index (SPEI) with Penman-Monteith (PM) model and Thornthwaite (Th) model. They found that SPEI-PM outperforms SPEI-Th in drought monitoring. However, literature which both consider climate change and the difference of ETp models on drought projection is still rare.

2.4 Runoff and its response to climate change

2.4.1 Runoff in hydrological cycle and its simulation

Runoff accompanied with precipitation and evapotranspiration consists of the most important party of hydrological cycle (Allan et al., 2020). How much runoff yielded by precipitation events has large influence on the regional water availability and water resource management. For instance, floods can be intrigued by larger runoff without proper drainage waterways and larger reservoir spillways (Xu, 1999); on the contrary, less runoff may result in hydrological drought and may need higher water supply storage (Xu, 1999). Runoff is influenced by various parameters in hydrological process, such as precipitation (intensity, frequency, and duration), soil moisture, and evapotranspiration (Wasko and Nathan, 2019; Wasko et al., 2019). As reported by Wasko and Nathan (2019), the occurrence of streamflow peaks (flood) are largely related to rainfall peak and the antecedent soil moisture. In another study of Wasko et al. (2021), they found that runoff trends across Australia is closely aligned with rainfall trends with the influence of soil moisture coming in the second place. Based on a global study, Woldemeskel and Sharma (2016) concluded that any flood-projection under a warming climate should take antecedent soil moisture conditions and rainfall into consideration because they are two key factors influencing runoff and extreme flood. Even though the consideration of antecedent soil

moisture has drawn researcher's attention and made the runoff simulation more reliable, the consideration of different evapotranspiration models on runoff projection is still weak. Given that runoff represents the balance between precipitation and evapotranspiration for a certain region from the long run and evapotranspiration projected by different models may vary a lot, it is necessary to investigate the influence of different evapotranspiration projection on runoff simulation under a changing climate (Bae et al., 2011; Oudin et al., 2005).

Hydrological models are indispensable tools for hydrological process simulation (Devia et al., 2015). They have been widely used in forecasting and monitoring flood, water resource management, and projecting the impacts of climate change or land use on runoff (Horton et al., 2021; Sood and Smakhtin, 2015; Zhang et al., 2007). At global scale, Zhang et al. (2016c) evaluated the performance of two lumped conceptual daily rainfall-runoff models including GR4J and simplified version of HYDROLOG in simulating streamflow against a global hydrological model H08, a land surface model (CABLE), and observed streamflow from 644 unregulated catchments. They found that all these models can simulate the seasonal and interannual variability of runoff and the rainfall-runoff models outperformed CABLE and H08 in simulating monthly and annual runoff values. Meanwhile, they claimed that the biases in simulated runoff generally showed a complementary opposite relationship with biases in evapotranspiration. van Kempen et al. (2021) investigated the influence of hydrological model's structure on simulation of extreme runoff events across global catchment with the method of modular modelling framework (FUSE). They found that hydrological model's structure has more influence on the low flow simulation and varied across different climate zones. Similarly, based on their study of runoff simulation at 780 catchments across Australia with three lumped conceptual hydrological models including GR4J, SIMHYD, and Xinanjing, Chiew et al. (2018) claimed that it was more difficult to predict low flow characteristics but the simulation of high flow characteristics were desirable. In Australia, Zhang et al. (2020) adopted SWAT model to simulate the influence of land use change on runoff and found that the influence of land use change on runoff was the most notable at annual scale and urbanization would increase surface runoff but decrease lateral runoff and groundwater. In summary, many aspects about runoff simulation have been investigated in the existing literatures. However, the influence of different evapotranspiration inputs estimated by various evapotranspiration models under future climate scenarios is still rare.

2.4.2 Impacts of climate change on runoff

Hydrological cycle is expected to intensify under a warming climate (Dakhlaoui et al., 2019). However, projection of runoff or extreme streamflow is a very challenging task because many basins and catchments did not have the historical observed runoff and the projected rainfall by GCMs which greatly influences runoff projection is generally accompanied with large uncertainty (Arnell, 2011; Wambura et al., 2015). At global scale, it is reported that runoff is likely to increase in high latitudes, east Africa, and south and east Asia, whereas decrease in other parts of the globe (Arnell, 2003). In specific, Arnell and Gosling (2013) reported that over 47% of the land surface would likely to experience significantly increases in runoff, whereas over 36% was likely to decrease and there was no significant change for the other 17%. In other words, though there is no uniform spatial pattern in response of hydrological regimes to climate change, more of the world is likely to witness an increase in water scarcity (Gosling and Arnell, 2016).

There is no exception in terms of climate change effects on Australia streamflow (CSIRO and BOM, 2015). For instance, it is reported that the median streamflow in Murray-Darling Basin is likely to decrease 9% to 13% under a warming climate (CSIRO, 2008). Similarly, Adamson et al. (2009) also reported decline in the inflow of Murray-Darling Basin as climate change would likely to result in more drought in this region. Across Australia, Wasko et al. (2021) reported that rainfall in Northern parts of Australia have increased from 1960 to 2017. The increase in rainfall also resulted in the increase in soil moisture, evapotranspiration, and runoff over there. However, rainfall in southwest and southeast coast of Australia decreased in the same time period and resulted in the decreases in soil moisture, evapotranspiration, and runoff. The decline in streamflow may intrigue more drought to happen and exacerbate the water stress in Australia. As to reasons for decrease in runoff, it is mainly caused by the change in precipitation, and the change in evapotranspiration may offset the magnitudes of change in runoff (Charles et al., 2020; Yan et al., 2020).

2.5 Reference

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Chapter 3. Performance of potential evapotranspiration models across different climatic zones in New South Wales, Australia

This chapter is based on the following manuscript (in submit):

Lijie Shi, Bin Wang, De Li Liu, Puyu Feng, James Cleverly, Linchao Li, and Qiang Yu. "Performance of potential evapotranspiration models across different climatic stations in New South Wales, Australia.

Abstract: Estimating potential evapotranspiration (ETp) rates, detecting its temporal trends and analysing its interannual oscillation are critical for long-term assessment of water availability and regional drought. The Penman model is physically-based, with robust capacity to characterize ETp in the above-mentioned aspects. However, its application might be limited due to the lack of a complete set of climatic data. Therefore, we aimed to evaluate the comprehensive performance of 12 simplified models in characterizing ETp against Penman at different climate zones across southeastern Australia. We used Taylor skill score (S), normalized root mean square error (nRMSE), and relative mean bias error (rMBE) to estimate models' capability in estimating ETp rates against Penman. Then, we adopted Mann-Kendall test and continuous wavelet transform (CWT) to test temporal trends and periodicity of ETp estimated by all models. Results indicated that radiation-based models including JH, Ab, Tu, Mak and temperature-based model HS were able to estimate both daily and seasonal ETp reasonably. Meanwhile, their ability in capturing change direction, change rates, and periodical oscillation of ETp was also comparable with Penman model. Thus, this study recommended to use these models to estimate ETp when the use of Penman model was limited. The comprehensive investigation on models' performance will shed light on models' selection in estimation of aridity and hydrological cycle.

Keywords: Potential evapotranspiration; Penman; model evaluation; temporal trends; periodicity

3.1 Introduction

Evapotranspiration (ET) is a nexus to water, energy, and nutrients cycles in ecosystems (Jung et al., 2010; Peng et al., 2018), and a key parameter for most widely used drought indices (e.g. SPEI and PDSI) (Beguería et al., 2014; Jian et al., 2019) and hydrological models. Thus, accurate estimation of ET rates and capturing its temporal change are critical for quantifying water availability (Peng et al., 2018), drought assessment (Dai, 2012; Roderick et al., 2015), and answering how climate change is influencing hydrological cycle. Reference evapotranspiration (ET₀) and potential evapotranspiration (ETp) are two of the most important conceptions

via which ET can be estimated (Peng et al., 2017; Xu et al., 2014). Conceptually, ET_p is the maximum possible evaporation rate occurring from a well-watered surface that is completely covered by actively growing vegetation (Donohue et al., 2010; Kumar et al., 1987). As the proxy of atmospheric evaporative demand, ET_p is only influenced by climatic factors and widely used to define aridity (Donohue et al., 2007; Thornthwaite, 1948). Compared with ET_p, ET₀ specifically defines the evaporative surface as an irrigated hypothetical reference crop with height of 0.12m, surface resistance equaling to 70 s m⁻¹, and albedo being as 0.23 (Katerji and Rana, 2011). In irrigation districts, ET₀ accompanied with crop coefficients is widely used to calculate the crop water requirement, based on which the quantity of irrigation can be estimated (the difference between crop water requirement and effective precipitation). In fact, ET_p instead of actual ET is generally the one that is widely used in hydrological models (Oudin et al., 2005) and aridity indices (Scheff and Frierson, 2015; Sheffield et al., 2012) whereas ET₀ is widely used in irrigation, agriculture, agronomy, and ecology (McMahon et al., 2013; Xiang et al., 2020). Despite ambiguity in the use of these two concepts in existing literatures, this study focused on investigating the ET_p models' performance across different climate zones considering their widely use in hydrology and climatology.

Due to the difficulty in measuring evapotranspiration directly, various models have been developed to estimate ET_p (Lu et al., 2005). Most of them represented a simplification of the complex evapotranspiration process and were developed based on statistical functions between meteorological parameters and ET_p (Abteu and Melesse, 2012; Landeras et al., 2008). In general, these models could be classified into four categories based on the input requirements, that is, temperature-based models (Hargreaves et al., 1985), radiation-based models (Priestley and Taylor, 1972), mass transfer-based models (Mahringer, 1970), and combination models (Penman, 1948). Among them, Penman potential evaporation model (Donohue et al., 2010; Penman, 1948) is one of the combination models, which requires four key climatic factors of ET_p as inputs (air temperature, solar radiation, relative humidity, and wind speed) (Milly and Dunne, 2016). Its accuracy and superiority in estimating ET_p (Almorox et al., 2015; Penman, 1948) have been demonstrated across a broad range of climatic conditions. At crop field scale, Li et al. (2016) evaluated the performance of Penman and the other five ET_p models against the eddy covariance measured crop actual evapotranspiration in arid regions of northwestern China. They found that Penman model and Shuttleworth model (which is a modified version of Penman model) outperformed other models in the estimation of daily crop actual evapotranspiration in arid regions. Across four different climate zones including the mountain plateau zone, temperature monsoon zone, temperate continental zone, and subtropical monsoon zone, Yang et al. (2021)

assessed the performance of 18 ETp models against pan-measured evaporation from 1991 to 2000. They concluded that Penman model achieved the highest R^2 against pan-measured evaporation and was the best model for ETp estimates regardless of the climatic zones. In other words, Penman model is considered as the most reasonable approximation to the complex nonlinear process of ETp (Milly and Dunne, 2016).

Despite the sound performance of Penman model, its application may be limited due to the intensive requirement of inputs (Fisher et al., 2011; Moges et al., 2003). Thus, simplified ETp models have been used as alternatives in this context. Contrary to the sound performance of Penman model across various climatic conditions, the performance of simplified ETp models is mostly location-dependent (Kirono et al., 2009; Xu and Singh, 2001). Therefore, assessments of their accuracy when they were applied outside of the conditions where they were originally developed is necessary (Almorox et al., 2015; Tabari, 2009). Given the sound performance of Penman model, it has been applied as a benchmark to evaluate the performance of simplified ETp models. The intercomparison of models' performance has been widely reported in many regions of the world. Xu and Singh (2002) compared the performance of Hargreaves, Blaney-Criddle, Makkink, Priestley-Taylor, and Rohwer with Penman-Monteith as the benchmark in Switzerland. They found that these models could produce reasonable estimation of ETp with the original constant involved in each model. Lu et al. (2005) assessed the performance of ETp models including Thornthwaite, Hamon, Hargreaves-Samani, Turc, Makkin, and Priestley-Taylor against the actual evapotranspiration, which was calculated according to water balance equation across 36 watersheds in the southeastern United States. They found that ETp calculated by these six models were highly correlated even though ETp values from different models were significantly different from each other. Based on the comparison with actual evapotranspiration, they recommended Priestley-Taylor, Turc, and Hamon models to be used in that region. Azhar and Perera (2011) compared performance of ten reference evapotranspiration models ranging from temperature-based models to data-extensive Penman-Monteith model at three sites in southeastern Australia against evapotranspiration measured from standard-grass weighting lysimeters. They reported that combination methods generally produced the most accurate evapotranspiration estimates. At global scale, Almorox et al. (2015) assessed the performance of 11 temperature-based models for estimating reference or potential evapotranspiration across various climatic conditions with Penman-Monteith as the benchmark. They concluded that the Hargreaves-Samani model produced the most accurate global average performance independence of the climate conditions.

Evapotranspiration under a changing climate is experiencing either increasing (Douville et al., 2013;

Pascolini-Campbell et al., 2021; Tabari et al., 2011) or decreasing (Irmak et al., 2012; Roderick and Farquhar, 2005) temporal trends due to the change of climatic factors such as net radiation, air temperature, vapour pressure, or wind speed (Guo et al., 2017; Tabari and Hosseinzadeh Talaei, 2014). In this context, not only can if ETp models yield reasonable ETp estimates need to be answered but also the ability of ETp models in capturing the long-term dynamics of ETp need to be figured out (Donohue et al., 2010). For instance, Zheng et al. (2017) firstly assessed the performance of fourteen ETp models in yielding reasonable ETp estimates against eddy covariance actual evapotranspiration across different climate zones in China, then assessed the ability of three well performed ETp models in capturing the long-term dynamics of ETp. They found that though Penman, Priestly-Taylor, and Linacre were all able to yield reasonable ETp estimates across all eight stations, only Penman model was capable of representing the annual and seasonal dynamics of ETp both in water-limited and in energy-limited conditions. Similarly, Donohue et al. (2010) assessed the ability of Penman, Priestley-Taylor, Morton point, Morton areal, and Thornthwaite models in capturing the long-term dynamics of atmospheric evaporative demand based on the complimentary relationship between ETp and actual evapotranspiration (represented by precipitation) in water-limited conditions. They concluded that Penman model yielded the most reliable estimates of ETp dynamics.

Besides the long-term dynamics, climatic anomalies often occurred periodically (da Silveira and Pezzi, 2014; Li et al., 2019). For example, Li et al. (2019) investigated the spatiotemporal evolution of extreme temperature events of 552 sites in China over the historical (1961-2000) and future (2001-2100) time stages. They found that six extreme temperature indices (ETIs) showed a 3-10-year period in the historical period and a 2-4-year period in the future period in addition to the increasing/decreasing trends showed by different ETIs. Given the strong influence of climatic factors on ETp, it is reasonable to conjecture that the interannual oscillation of ETp might also show periodically (Liang et al., 2010; Wang et al., 2017). However, few studies have investigated the periodicity of ETp (Liang et al., 2010). Especially, the intercomparison of ability of different ETp models on detecting periodicity of ETp has rarely reported.

In summary, evapotranspiration rates, temporal trends, and interannual oscillation are all important characteristics of ETp (Liang et al., 2010). Comprehensive investigation on models' performance in these perspectives will fill the existing research gap and shed light on models' selection in estimation of aridity and hydrological cycle. Thus, we aimed to evaluate the ability of 12 ETp models in the above-mentioned perspectives against the Penman model across different climate zones in New South Wales (NSW), Australia based on historical climatic data from 1970 to 2014.

3.2 Study area and climate datasets

Locating in southeastern Australia (Figure 3-1), New South Wales (NSW) accounts for 10.4% of the Australian land area ($8.1 \times 10^5 \text{ km}^2$) and is the most populous state in Australia. Meanwhile, it is one of the most important agricultural production states in Australia. For instance, wheat harvested in NSW accounts for 27% of the gross production in Australia. Geographically, NSW is divided into four distinct geographical sections by natural features: the east coast, the mountains (the Great Dividing Range), the central plains, and the western plains. These diverse geographical features create a varied climate across NSW. In general, western NSW is mainly dominant by arid and semi-arid climates, receiving rainfall less than 200 mm year^{-1} in its far northwest area whereas eastern NSW is dominant by humid subtropical or oceanic climate with rainfall may be larger than $1500 \text{ mm year}^{-1}$. Based on the widely used aridity index (rainfall/ETp) (Asadi Zarch et al., 2015; Roderick et al., 2015; UNESCO, 1979), this study divided NSW into arid, semi-arid, sub-humid, and humid zones to investigate the performance of ETp models across different climates, as shown in Figure 3-1. The arid and semi-arid zones account for around two-third of NSW and are sparsely populated. Most land in arid zone is fertile, dry and desert. Grazing native vegetation is the main type of land cover while land in semi-arid zone is mainly used for grassland and dryland agriculture. Most of the NSW wheat belt locates in the sub-humid zone. In addition to wheat, canola and other crops are also cultivated in the sub-humid zone. It is the agricultural powerhouse of NSW because of its rich, fertile soil and adequate water supply. The humid zone is the most populous area in NSW and big cities such as Sydney and Newcastle are located in this region. Land use in this this zone is a mixture of nature conservation, production native forests, and grazing land. The total 2120 stations were also divided into four different climate zones based on their averaged aridity indexes in the research period from 1970 to 2014. In specific, there were 201, 980, 536, and 403 stations in the arid, semi-arid, sub-humid, and humid zone, respectively. The ranges of long-term mean annual minimum and maximum temperatures, solar radiation, relative humidity, rainfall, and potential evapotranspiration for each climate zone were shown in Table 3-1.

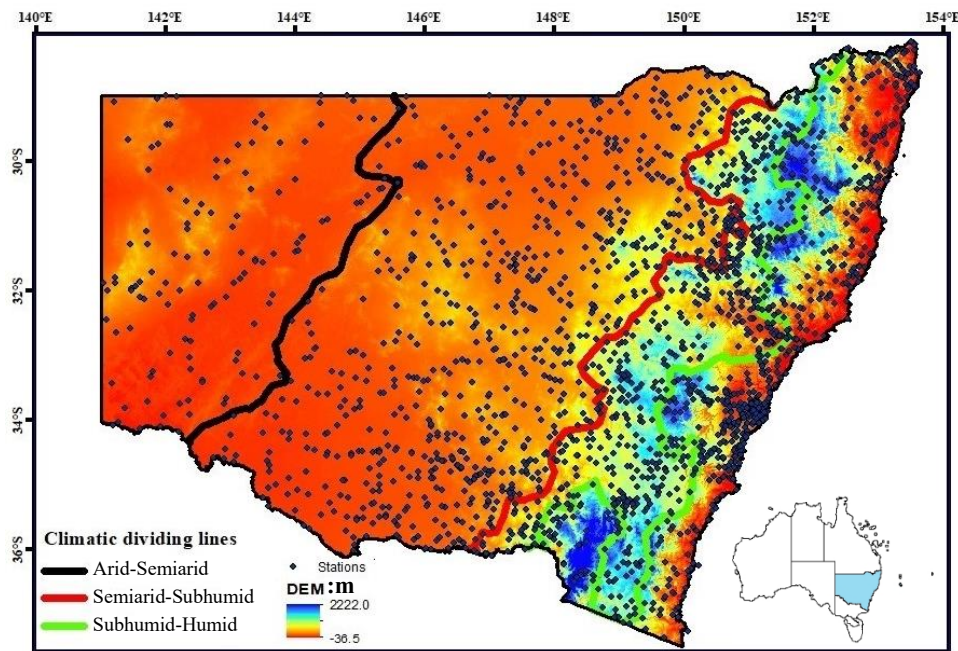


Figure 3-1 The distribution of 2120 stations and the division of climate zones in NSW based on the aridity index (rainfall/potential evapotranspiration).

Table 3-1. The mean minimum (Tmin) and maximum (Tmax) air temperature, solar radiation (Rs), relative humidity (RH), rainfall (P), potential evapotranspiration (ETp), and aridity index (AI) in the study period from 1970 to 2014.

Subzones	AI	Tmin (°C)	Tmax (°C)	Rs (MJ m ⁻² day ⁻¹)	RH (%)	Rainfall (mm)	ETp (mm)	Numbers of stations
Arid	(0.03, 0.20]	9.9,	23.7,	18.0,	47.0,	206,	1625,	201
		14.8	28.3	20.8	64.5	390	2078	
Semi-arid	(0.20, 0.50]	3.7,	16.5,	16.0,	54.6,	334,	1217,	980
		13.7	28.0	19.9	73.7	818	1939	
Sub-humid	(0.50, 0.75]	3.5,	15.7,	15.8,	66.5,	607,	1147,	536
		14.3	26.3	19.0	77.1	1150	1685	
humid	> 0.75	0.4,	9.2,	15.7,	67.2,	862,	993,	403
		16.2	26.0	18.2	80.0	2319	1576	

Note: AI = rainfall/potential evapotranspiration (Asadi Zarch et al., 2015)

Historical climate data including maximum temperature (Tmax), minimum temperature (Tmin),

maximum relative humidity (RHmax), minimum relative humidity (RHmin), rainfall (P), and solar radiation (Rs) for 2120 stations across NSW were obtained from the Scientific Information for Land Owners (SILO) patched point dataset (<https://www.longpaddock.qld.gov.au/silo/datadrill/index.php>). The patched data were generated based on available ground-based observational data with spatial interpolation method at a spatial resolution of 0.05° grid (Jeffrey et al., 2001). Thin plate smoothing spline method was used to construct the missing daily climate variables while ordinary kriging method was used to construct missing daily rainfall. More details about this dataset could be referred to Jeffrey et al. (2001). After its publication, the dataset has been widely used in drought assessment, crop yield simulation, and other climate-related research in Australia (Ahooghalandari et al., 2016; Howden et al., 2014; Karine et al., 2013).

The measured wind speed data for most stations was not available. In this case, this study adopted the recommended 2 m s⁻¹ by FAO56 as the surrogate wind speed (Allen et al., 1998; Tomas-Burguera et al., 2017). The recommended 2m s⁻¹ has been widely used in areas where observed wind speed is not available and is reported that wind speed has relatively small influence on ETp estimates except for arid and windy regions (Popova et al., 2006; Sentelhas et al., 2010). The reasonability of adopting the 2 m s⁻¹ instead of observed wind speed was also tested in this study based on eight stations which were Tibooburra and Wilcannia from arid zone; Cobar and Gunnedah from semi-arid zone; Murrurundi and Paterson from sub-humid zone; and Sydney and Coffs Harbour from humid zone. For these stations, the measured wind speed was obtained from the Bureau of Meteorology (<http://www.bom.gov.au/>). Figure 3-2 showed the scatter plot between ETp estimated with observed wind speed and ETp estimated with the recommended 2 m s⁻¹ by models used in this study which were based on wind speed. It suggested the R² ranged from 0.69 to 0.97, implying the reasonability of use of recommended wind speed.

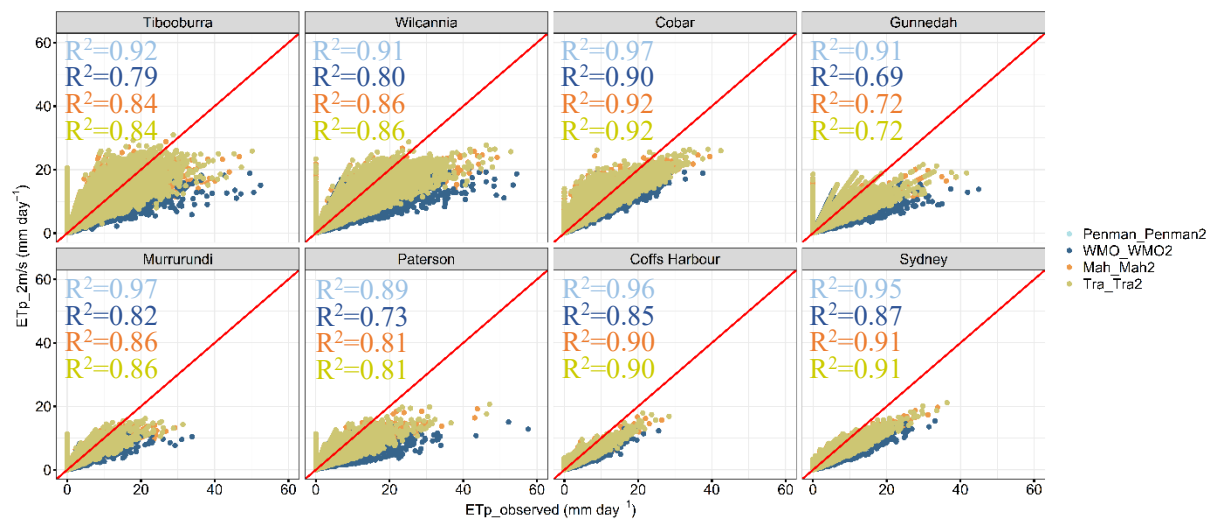


Figure 3-2 Scatter plot with daily ETp from 1970 to 2014 at eight stations belonging to arid (Tibooburra & Wilcannia), semi-arid (Cobar & Gunnedah), sub-humid (Murrurundi & Paterson), and humid (Coffs Harbour & Sydney) zones. ETp_observed (mm day^{-1}) represents daily ETp estimated with Penman, WMO, Mahringer (Mah), and Trabert (Tra) based on observed wind speed whereas ETp_2m/s (mm day^{-1}) represents daily ETp estimated with the corresponding models (Penman2, WMO2, Mah2, and Tra2) based on the recommended wind speed, 2 m s^{-1} . The red line is the 1:1 line.

3.3 Estimation of potential evapotranspiration

3.3.1 Penman model

Penman model, combining radiative component with aerodynamic transfer, was developed to calculate evaporation from an open water surface. In regions where measured evapotranspiration was not available, Penman model was widely used as a benchmark to evaluate the performance of other simplified ETp models (Donohue et al., 2010; Milly and Dunne, 2016). Similar to Penman model, Penman-Monteith model (Penman-FAO56) was another widely used benchmark (Landeras et al., 2008; Shiri et al., 2013). However, this variation of Penman model was designed for the estimation of reference evapotranspiration (ET₀). Despite the commonly interchangeable use of the two conceptions (ETp and ET₀) (McMahon et al., 2016; McMahon et al., 2013), this study adopted Penman model as the benchmark because models assessed in this study was for ETp estimate. Meanwhile, this study analyzed the correlation between ETp-Penman and ET₀-FAO56 across different climate zones with annual evapotranspiration. The R² between them were close to 1, showing strong correlation, as shown in Figure 3-3.

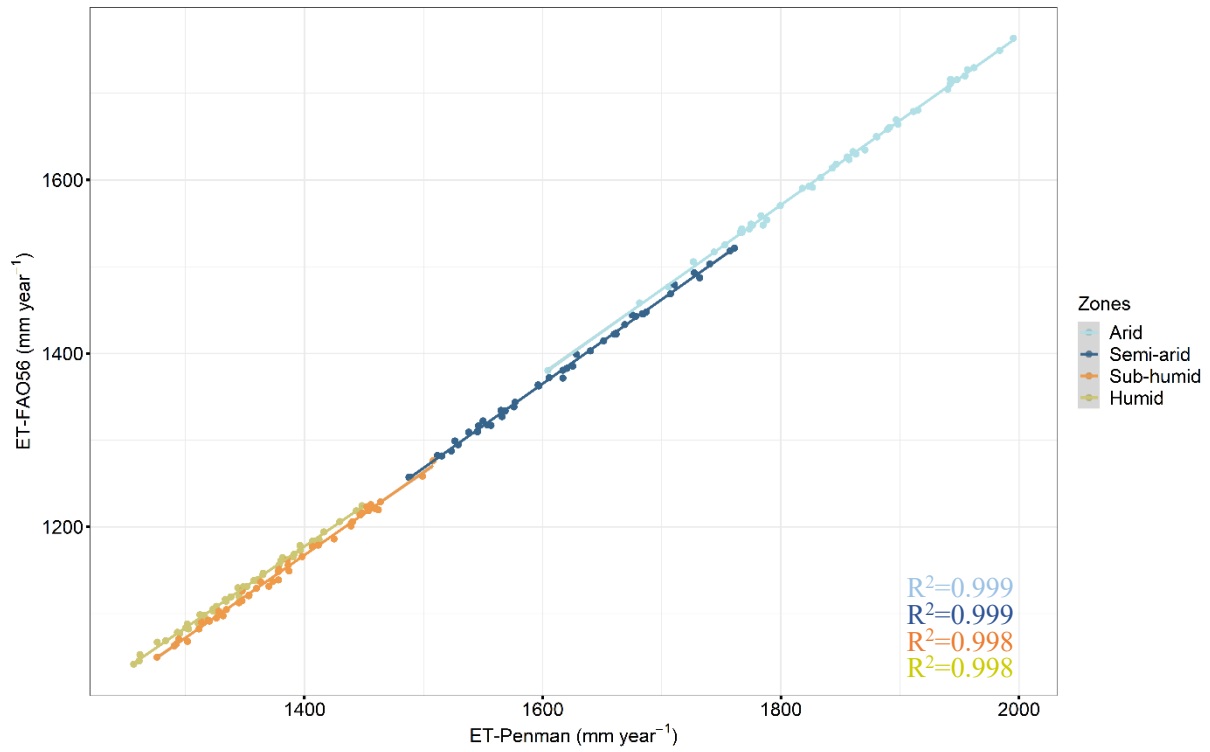


Figure 3-3 Scatter plot between annual ET_p estimated by Penman model (ET-Penman, mm year⁻¹) and ET₀ estimate by Penman-FAO56 (ET-FAO56, mm year⁻¹) at four climate zones from 1970 to 2014.

The mathematical expression of Penman model is shown in equation (3-1):

$$ET_{Penman} = ET_{pR} + ET_{pA} = \frac{0.408\Delta}{\Delta + \gamma} (R_n - G) + \frac{\gamma}{\Delta + \gamma} \frac{6.43(1 + 0.536u_2)(e_s - e_a)}{\lambda} \quad (3-1)$$

where ET_{Penman} (mm day⁻¹) is ET_p from open water; ET_{pR} (mm day⁻¹) is the radiative component and E_{pA} (mm day⁻¹) is the aerodynamic component. R_n (MJ m⁻² day⁻¹) is net radiation, which is the algebraic sum of the net short and long wave radiation. R_n could be calculated based on the process of Allen et al. (1998); G (MJ m⁻² d⁻¹) is soil heat flux density, zero for a day or longer periods (Allen et al., 1998; Irmak et al., 2012); T (°C) is mean daily air temperature at 2 m height; u_2 (m s⁻¹) is wind speed at 2 m height. The recommended 2 m s⁻¹ was used in this study; e_s (kPa) is saturation vapour pressure; e_a (kPa) is actual vapour pressure; $(e_s - e_a)$ (kPa) is saturation vapour pressure deficit; Δ (kPa °C⁻¹) is the slope of the vapour pressure curve; γ (kPa °C⁻¹) is psychrometric constant; λ is the latent heat of vaporization of water, 2.45 MJ kg⁻¹ for temperature around 20°C. The important intermediate parameters used in Penman model can be calculated according to the following equations (Allen et al., 1998):

$$\Delta = \frac{4098 \times \left[0.6108 \exp\left(\frac{17.27T}{T + 237.3}\right) \right]}{(T + 237.3)^2} \quad (3-2)$$

$$R_n = R_{ns} - R_{nl} \quad (3-3)$$

where R_{ns} ($\text{MJ m}^{-2} \text{ day}^{-1}$) is the shortwave radiation, as shown in equation (3-4); R_{nl} ($\text{MJ m}^{-2} \text{ day}^{-1}$) is the longwave radiation, as shown in equation (3-5),

$$R_{ns} = (1 - \alpha)R_s \quad (3-4)$$

where α is albedo, which is influenced by the surface characteristics and the angle or slope of the ground surface. For a green vegetation surface, α varies from 0.20 to 0.25. In this study, $\alpha = 0.23$, as recommended by Allen et al. (1998) for a hypothetical green surface. R_s ($\text{MJ m}^{-2} \text{ day}^{-1}$) is the solar radiation.

$$R_{nl} = 4.903 \times 10^{-9} \times \left(\frac{(T_{\max} + 273.06)^4 + (T_{\min} + 273.06)^4}{2} \right) \times (0.34 - 0.14\sqrt{e_a}) \times \left(1.35 \times \frac{R_s}{R_{so}} - 0.35 \right) \quad (3-5)$$

where T_{\min} ($^{\circ}\text{C}$) and T_{\max} ($^{\circ}\text{C}$) are the minimum and maximum temperature, respectively; R_{so} ($\text{MJ m}^{-2} \text{ day}^{-1}$) is the clear-sky radiation, estimated by extraterrestrial radiation (R_a).

3.3.2 Temperature-based ETp models

Generally, temperature-based models rely on the reliable assumption that temperature is an indicator of the evaporative power of the atmosphere (McKenney and Rosenberg, 1993). Good performance of temperature-based models has been reported in literature. For instance, Tabari (2009) claimed that Hargreaves (HS) was able to estimate ETp accurately in various climates except humid climate. Meanwhile, obvious underestimation of ETp by HS under dry and windy regions was also common (Hargreaves and Allen, 2003). Therefore, we also investigated the performance of temperature-based models including Hargreaves (HS) (Droogers and Allen, 2002), Schendel (Sc) (Djaman et al., 2015; Schendel, 1967), and Ivanov (Iv) (Valipour et al., 2017) in this study. The mathematical equations of these models were shown as following.

Temperatures and extraterrestrial radiation (R_a , $\text{MJ m}^{-2} \text{ day}^{-1}$) were the parameters for HS model:

$$ET_p = 0.0023 \times 0.408 R_a (T_{\max} - T_{\min})^{0.5} (T + 17.8) \quad (3-6)$$

Model Sc was based on temperature and relative humidity (RH, %):

$$ET_p = 16 \frac{T}{RH} \quad (3-7)$$

Similar to Sc, model IV was also based on temperature and relative humidity:

$$ET_p = 0.00006(25 + T)^2 (100 - RH) \quad (3-8)$$

3.3.3 Radiation-based ET_p models

Radiation-based models adopt solar radiation accompanied with air temperature to estimate ET_p based on energy balance (Muniandy et al., 2016; Xu and Singh, 2000). The commonly used radiation-based models including Jensen-Haise (JH) (Jensen and Haise, 1963), Priestley-Taylor (PT) (Priestley and Taylor, 1972), Makkink (Mak1) (Makkink, 1957), modified Makkink (Mak), Abtew (Ab) (Abtew, 1996), and Turc (Tu) were adopted in this study. Among them, PT, Mak1 and Mak are simplifications of Penman model. PT was originally developed to calculate ET_p from a saturated land surface or an open water surface under conditions of minimal advection (Priestley and Taylor, 1972). Mak1 model was developed under temperate humid conditions. The difference between Mak1 and PT is that Mak1 requires the incoming solar radiation whereas PT require net radiation as input. Jensen-Haise (JH) model was developed based on numerous evapotranspiration observations by soil sampling (Jensen and Haise, 1963). Turc (Tu) was developed under general climatic conditions of western Europe (Xu and Singh, 2000). Equations for JH, PT, Mak, Mak1, Ab, and Tu were shown from (3-9) to (3-14),

$$ET_p = 0.0102(T + 3)R_s \quad (3-9)$$

where R_s is observed solar radiation ($MJ m^{-2} day^{-1}$).

$$ET_p = 1.26 \left[\frac{\Delta}{\Delta + \gamma} \frac{R_n}{\lambda} - \frac{G}{\lambda} \right] \quad (3-10)$$

$$ET_p = 0.7 \frac{\Delta}{\Delta + \gamma} \frac{R_s}{\lambda} \quad (3-11)$$

$$ET_p = 0.61 \frac{\Delta}{\Delta + \gamma} \frac{R_s}{\lambda} - 0.12 \quad (3-12)$$

$$ET_p = 0.01786 \frac{R_s T_{max}}{\lambda} \quad (3-13)$$

Parameters in model PT, Mak, Mak1, and Ab have the same meaning with that in Penman model.

$$ET_p = (0.3107R_s + 0.65) \frac{Ta_t}{T + 15} \quad a_t = \begin{cases} 1 & RH \geq 50\% \\ 1 + \frac{50 - RH}{70} & RH < 50\% \end{cases} \quad (3-14)$$

In Tu, a_t is a parameter depended on RH. Other parameters have the same meaning with that in Penman

model.

3.3.4 Mass transfer-based ET_p models

The mass transfer-based models are generally developed based on Dalton's gas Law to estimate evaporation from free water surface. They adopt the aerodynamic concept of water vapour movement from the evaporating surface to the air to estimate ET_p (Muniandy et al., 2016). Three commonly used mass transfer-based models, WMO (Valipour et al., 2017), Mahringer (Mah) (Mahringer, 1970), and Trabert (Tra) (Valipour et al., 2017) were studied in this research. The following equations showed their mathematical expressions:

$$ET_p = (1.298 + 0.934u_2)(e_s - e_a) \quad (3-15)$$

$$ET_p = 2.86u_2^{0.5}(e_s - e_a) \quad (3-16)$$

$$ET_p = 3.075u_2^{0.5}(e_s - e_a) \quad (3-17)$$

Parameters in these equations have the same meaning with that in Penman model.

ET_p for 2120 stations was firstly calculated with each model. The ET_p for each climate zone was the average of those stations locating in the zone.

3.4 Models' performance in estimating ET_p rates

This study adopted Taylor diagram, Taylor skill score (S), normalized root mean square error (nRMSE), and relative mean bias error (rMBE) to assess the performance of 12 alternative ET_p models against Penman model. The S combines correlation coefficient (R) and standard deviation (σ) into one index to comprehensively evaluate model performance (Taylor, 2001; Wang et al., 2015). The nRMSE is a powerful index to measure the relative difference of ET_p calculated by alternative models versus Penman-calculated ET_p. Performance of models is considered excellent if nRMSE is lower than 10.00%; good when it is higher than 10.00% but lower than 20.00%; fair with nRMSE between 20.00% and 30.00%; poor with nRMSE higher than 30.00% (Dettori et al., 2011; Nouri and Homae, 2018). The rMBE is a useful index to evaluate model's bias and systematic error (Nouri and Homae, 2018). The positive (negative) values of rMBE represent the model's tendency to overestimate (underestimate) ET_p relative to Penman model. A high-performing model will have high values of S with values of rMBE and nRMBE close to 0%.

The mathematical equations of these statistical indexes are as following:

$$S = \frac{4(1+R)^2}{\left(\frac{\sigma_M}{\sigma_{Penman}} + \frac{\sigma_{Penman}}{\sigma_M}\right)^2 (1+R_0)^2} \quad (3-18)$$

where S is the Taylor skill score; R is the correlation coefficient between an alternative model and Penman model; R₀ is the maximum correlation coefficient attainable (0.999 is used in this study). σ_M and σ_{Penman} are the standard deviations of ET_p for an alternative model and Penamn model, respectively;

$$nRMSE = \frac{100}{\overline{ET_{Penman}}} \sqrt{\frac{1}{n} \sum_{i=1}^n (ET_{M,i} - ET_{Penman,i})^2} \quad (3-19)$$

$$rMBE = \left(\frac{100}{\overline{ET_{Penman}}}\right) \frac{1}{n} \sum_{i=1}^n (ET_{M,i} - ET_{Penman,i}) \quad (3-20)$$

where $ET_{M,i}$ and $ET_{Penman,i}$ are ET_p calculated with an alternative model and Penman model, respectively.

$\overline{ET_{Penman}}$ is the average Penman-calculated ET_p and n is the number of the sample.

3.5 Models' ability in capturing ET_p dynamics and periodic oscillations

The relationship between ET_p and actual evapotranspiration is complementary under water-limited condition and proportional under energy-limited condition (Yang et al., 2006). In specific, actual evapotranspiration will increase when precipitation increases under water-limited condition whereas ET_p will decrease as a result of the decreases in solar radiation and air temperature, and increases in air humidity (Zheng et al., 2017). Referred to Donohue et al. (2010), they compared the trends of ET_p estimated by five different models against the trends in precipitation to assess ET_p model's ability in representing the long-term dynamics of evaporative demand. In other words, models which show inverse trends against precipitation are reliable in capturing the dynamics of evaporative demand under water-limited conditions. This study followed the method and compared the trends of ET_p and precipitation tested by Mann-Kendall to assess models' ability in capturing the dynamics of evaporative demand.

The Mann-Kendall (M-K) test is highly recommended by the World Meteorological Organization to identify trends in hydro-meteorological time series (Han et al., 2018). Under a changing climate, this method has also been widely used to determine temporal trends in climatic variables and ET_p series (Lin et al., 2018; Lv et al., 2016). The standardized test statistic, Z, is provided in M-K test to indicate if the temporal trend of a variable is significant. At the 95% confidence level, temporal trends are significant when $|Z| > 1.96$; time series trends are significant at 99% confidence level when $|Z| > 2.58$. A positive Z-value shows an

increasing trend, while a negative Z-value indicates a decreasing trend. The statistical value, S_v , and the standardized test statistic, Z , are defined by the following equations (Han et al., 2018):

$$S_v = \sum_{k=1}^{n-1} \sum_{j=k+1}^n \text{sgn}(x_j - x_k) \quad (3-21)$$

with

$$\text{sgn}(x) = \begin{cases} 1 & \text{if } x > 0 \\ 0 & \text{if } x = 0 \\ -1 & \text{if } x < 0 \end{cases} \quad (3-22)$$

with the variance of S_v

$$\sigma^2 = \left\{ n(n-1)(2n+5) - \sum_{j=1}^p t_j(t_j-1)(2t_j+5) \right\} / 18 \quad (3-23)$$

$$Z = \begin{cases} \frac{S_v - 1}{\sigma} & \text{if } S_v > 0 \\ 0 & \text{if } S_v = 0 \\ \frac{S_v + 1}{\sigma} & \text{if } S_v < 0 \end{cases} \quad (3-24)$$

where x_j and x_k are two sequential values of the variable, n is the length of the data sequence, p is the number of tied groups, t_j is the number of data values in the j th group. In addition to the M-K test, Sen's slope estimator test was applied to calculate the magnitude of the ETp trend. The slope β (Gao et al., 2017) is calculated as:

$$\beta = \text{Median} \left(\frac{x_j - x_k}{j - k} \right), \quad 1 < k < j \quad (3-25)$$

Continuous wavelet transform (CWT) is a powerful tool for analysing the periodic oscillations of climate anomalies (e.g. temperature) (da Silveira and Pezzi, 2014; Torrence and Compo, 1998) and natural hazards (e.g. droughts) (Özger et al., 2009; Wang et al., 2017). In this method, signals were decomposed into wavelet coefficients, which localised in both time and frequency due to dilation and translation of a mother wavelet. We used the Morlet wavelet as the mother wavelet in this study. The Morlet wavelet is a plane wave modified by a Gaussian, having a zero mean and providing a balance between time and frequency localizations (Zhang et al., 2007). It is defined as:

$$\psi_0(t) = \pi^{-1/4} e^{i\omega_0 t} e^{-t^2/2} \quad (3-26)$$

where ω_0 , the dimensionless angular frequency, was set to 6 to render the Morlet wavelet analytical (Farge, 1992).

3.6 Results

3.6.1 Performance of models in estimating ETp rates

Generally, models with higher S were also marked with lower nRMSE and lower absolute rMBE independent of time scale (daily or seasonal). However, significant differences were found in S, nRMSE, and rMBE among models both at daily and seasonal scales. Figure 3-4 showed that models generally achieved S larger than 0.60 at daily scale. The difference of S among models was largest in arid and humid zones than that in semi-arid and sub-humid zones. In addition, compared with radiation-based models, temperature-based and mass transfer-based models except HS generally showed weaker correlation with Penman model. Take humid zone as an example, the correlation coefficients of temperature-based and mass transfer-based models were around 0.80 whereas the coefficients for radiation-based models were ranging from 0.97 to 0.99.

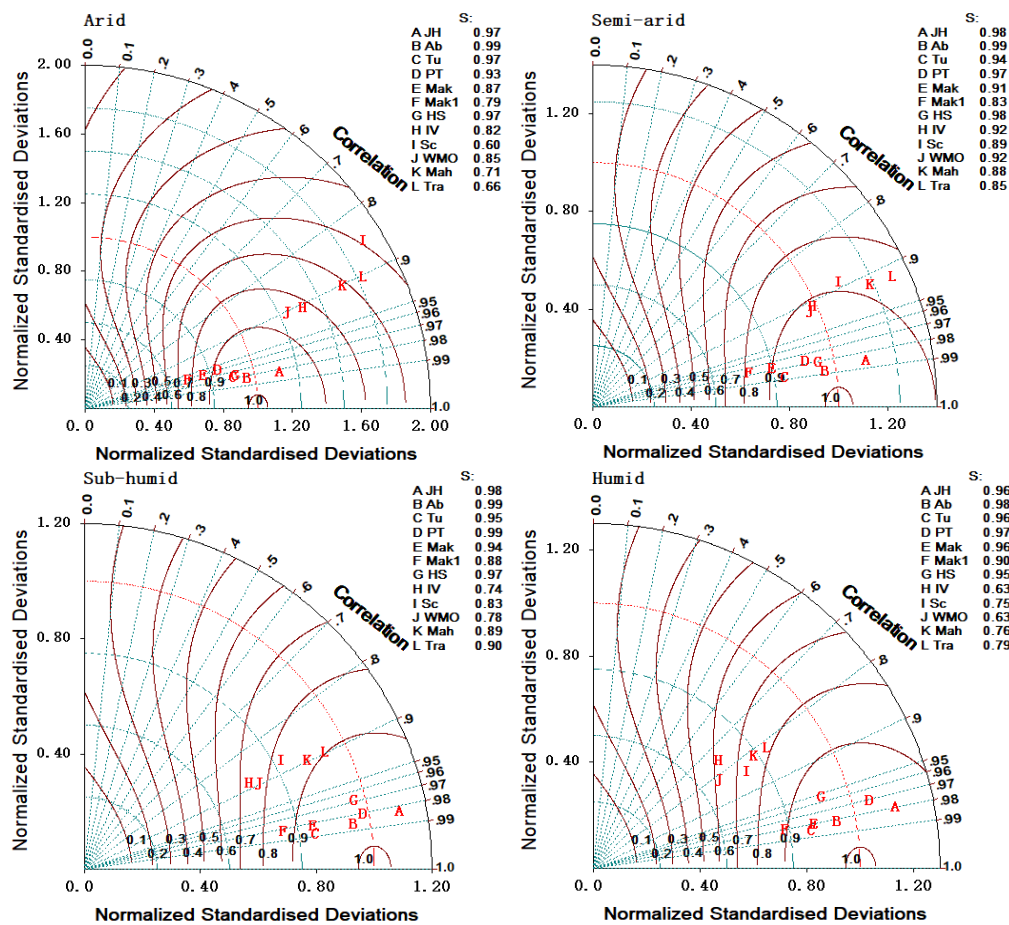


Figure 3-4 Models' ability in estimating daily ET_p, shown by Taylor diagram. Taylor diagram displayed the performance of 12 ET_p models in terms of amplitude of their variations (the radial distance from the origin the points was proportional to the pattern standard deviations) and their correlation coefficients (given by the azimuthal position of the test field) against Penman-calculated ET_p. The dark red lines represented the skill scores. The data used to plot the Taylor diagrams was the average daily ET_p for each climate zone from 1970 to 2014. The X-axis and Y-axis both represented standard deviations (SDs) of ET_p. The column of S in this figure was daily Taylor skill score for each model.

Models including JH, HS, Tu, Ab, Mak, and PT generally had mean nRMSE lower than 30% for four climate zones (Figure 3-5) whereas mean nRMSE for the rest models ranged from 31% to 71%. Meanwhile, the distances between upper and lower box boundaries for radiation-based models and the temperature-based model HS were generally smaller than that of mass transfer-based models. This indicated that these models showed not only reasonable but also stable performance among different stations for a certain climate zone. On the contrary, performance of mass transfer-based models and temperature-based model Sc showed larger difference among stations though the difference was narrowed in sub-humid and humid zones.

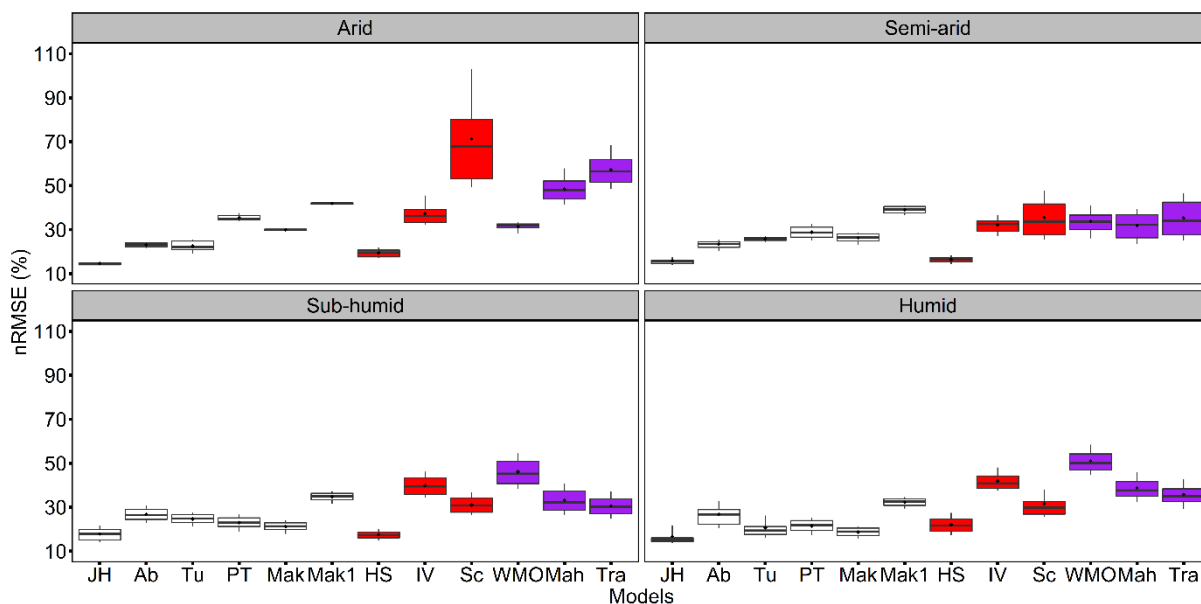


Figure 3-5 The distribution of nRMSE (%) between daily ET_p estimated by simplified ET_p models and ET_p estimated by Penman model from 1970 to 2014. Data used for each climate zone is the daily nRMSE of stations locating in this zone, that is, 201 stations for arid zone, 980 stations for semi-arid zone, 536 stations for sub-humid zone, and 403 stations for humid zone. The upper and lower box boundaries indicate the 75th and 25th percentiles; the black line and the black dot within the box represents the median and mean value, respectively; the upper and lower whiskers are the 10th and 90th percentiles. The hollow boxes represented for the radiation-based models. The red boxes were for temperature-based models and the purple boxes represented for the mass transfer-based models.

From the perspective of rMBE, all models except IV, Sc, Tra, and Mah in arid/semi-arid zone showed a tendency to underestimate ET_p (Figure 3-6). Radiation-based model JH followed by temperature-based model HS generally had the smallest underestimation for all climate zones. The mean underestimation of JH at four climate zones were 7% (arid), 9% (semi-arid), 12% (sub-humid), and 6% (humid). The corresponding mean underestimation yielded by HS were 15%, 11%, 10%, and 14% respectively. Among radiation-based models, Mak1 followed by PT was the model with largest underestimation of ET_p. Similar to the boxes of nRMSE, boxes of rMBE produced with the temperature-based models IV and Sc, and mass transfer-based models had larger distance between the upper and lower boundaries, which confirmed the difference of their performance among stations. Thus, though they might have a lower mean rMBE (such as Sc and Mah in semi-arid zone), they were not recommendable in daily ET_p estimations.

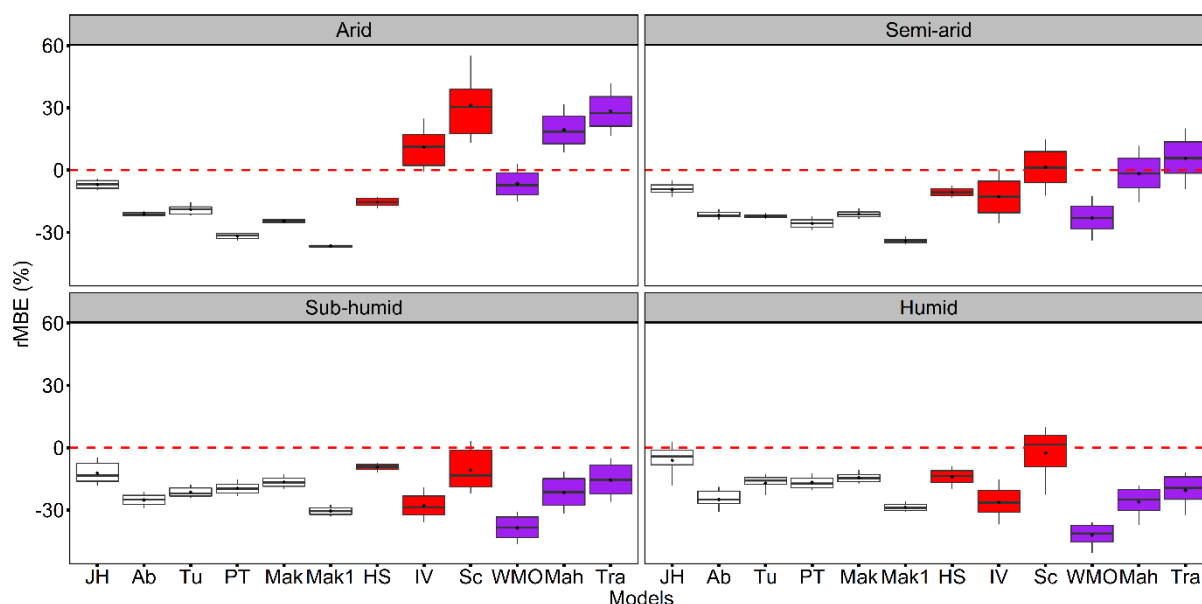


Figure 3-6 Distribution of rMBE (%) between daily ET_p estimated by simplified ET_p models and ET_p estimated by Penman model from 1970 to 2014. Data used for each climate zone is the daily rMBE (%) of stations locating in this zone, that is, 201 stations for arid zone, 980 stations for semi-arid zone, 536 stations for sub-humid zone, and 403 stations for humid zone. The upper and lower box boundaries indicate the 75th and 25th percentiles; the black line and the black dot within the box represents the median and mean value, respectively; the upper and lower whiskers are the 10th and 90th percentiles. The hollow boxes represented for the radiation-based models. The red boxes were for temperature-based models and the purple boxes represented for the mass transfer-based models.

The seasonal S showed similar patterns with daily S among models (Figure 3-7). In other words, the difference of S among models was larger in arid zone but was narrowed with climate becoming wetter mainly because the performance of the mass transfer-based models and temperature-based models Sc and IV was improved in wetter climate. In specific, S of radiation-based models except PT in arid and semi-arid zones were larger than 0.60 independence of seasons. Though the seasonal difference of S for radiation-based models was small, the S for spring and summer were generally larger than that in autumn and winter. Similarly, the temperature-based model HS also had larger S in spring and summer. By contrast, S of mass transfer-based models were generally larger in spring and winter than their summer and autumn values.

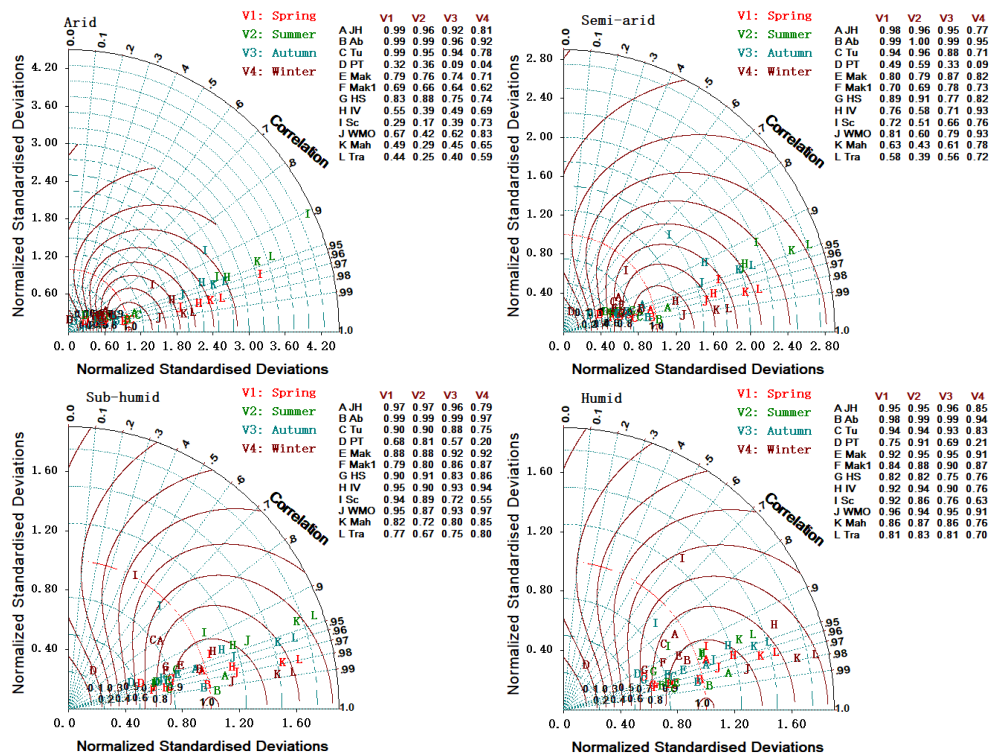


Figure 3-7 Models' ability in estimating seasonal ETp, shown by Taylor diagram. The data used to plot the Taylor diagrams was the averaged seasonal ETp for each climate zone from 1970 to 2014. The column of S in this figure was seasonal Taylor skill scores for each model. Other explanations of Taylor diagram were the same with Figure 3-4.

Both nRMSE and rMBE of models showed obvious seasonal difference (Figure 3-8 & Figure 3-9). In general, radiation-based models yielded the largest nRMSE in winter followed by spring. The seasonal variation of nRMSE for mass transfer-based models in arid and semi-arid climates was not unified. In wetter climates, they produced smaller nRMSE in autumn and winter. Temperature-based model HS produced mean nRMSE barely larger than 20%, implying its good performance in seasonal ETp estimates. In addition to HS, radiation-based models including Tu and Mak were also reliable in estimating seasonal ETp with mean nRMSE ranging from 11% to 26%. Performance of model JH was good (nRMSE < 20%) in all seasons but winter. Similarly, Ab showed fair (20% < nRMSE < 30) performance for all seasons but winter. Mak1 followed by PT were the two models generally performed poorly (nRMSE > 30%). Despite the possible low mean nRMSE showed by mass transfer-based models and the other two temperature-based models IV and Sc, they were not recommendable due to their unstable performance among stations.

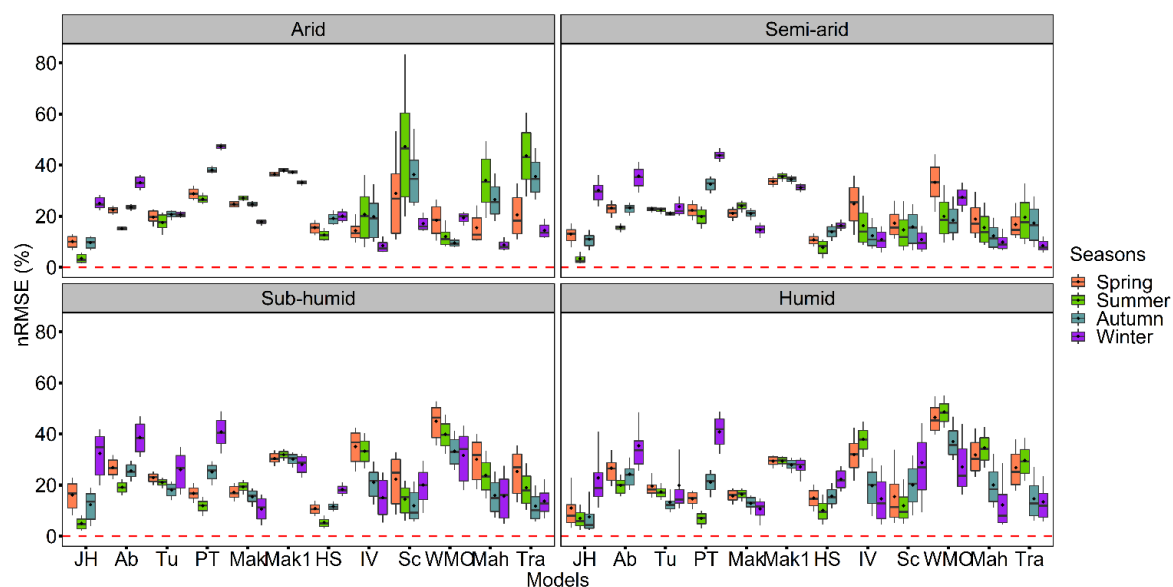


Figure 3-8 The distribution of nRMSE (%) between seasonal ET_p estimated by simplified ET_p models and ET_p estimated by Penman model from 1970 to 2014. Data used for each climate zone is the seasonal nRMSE of stations locating in this zone, that is, 201 stations for arid zone, 980 stations for semi-arid zone, 536 stations for sub-humid zone, and 403 stations for humid zone. The explanation of boxes was the same with that in Figure 3-5.

The seasonal variation of rMBE for models was similar to that showed by models' nRMSE (Figure 3-9). For instance, the absolute mean rMBE of JH in summer and autumn was rarely larger than 10% whereas its maximum mean underestimation of ET_p produced by JH in spring and winter could be as large as 16% and 32%, respectively. Similar seasonal variation pattern could also be found in the other radiation-based model Ab. Overall, temperature-based models HS and radiation-based models including Tu and Mak had relatively smaller underestimation of ET_p and the seasonal variation of their rMBE was also less significant. Though the other two radiation-based models PT and Mak1 performed better than the mass transfer-based models and the other two temperature-based models IV and Sc, they were not recommendable either due to the large seasonal variation of its performance (PT) or due to the general large underestimation (Mak1).

In summary, radiation-based models except Mak1 and PT and temperature-based model HS were able to estimate both daily and seasonal ET_p reasonably independence of climate zones. Mass transfer-based models and the other two temperature-based models IV and Sc were capable of producing reasonable ET_p estimates in humid stations. However, their performance was not stable across different stations even for the same climate condition. Meanwhile, their performance also showed relatively large seasonal variation. Thus,

this study did not recommend these models in ETp estimation in NSW.

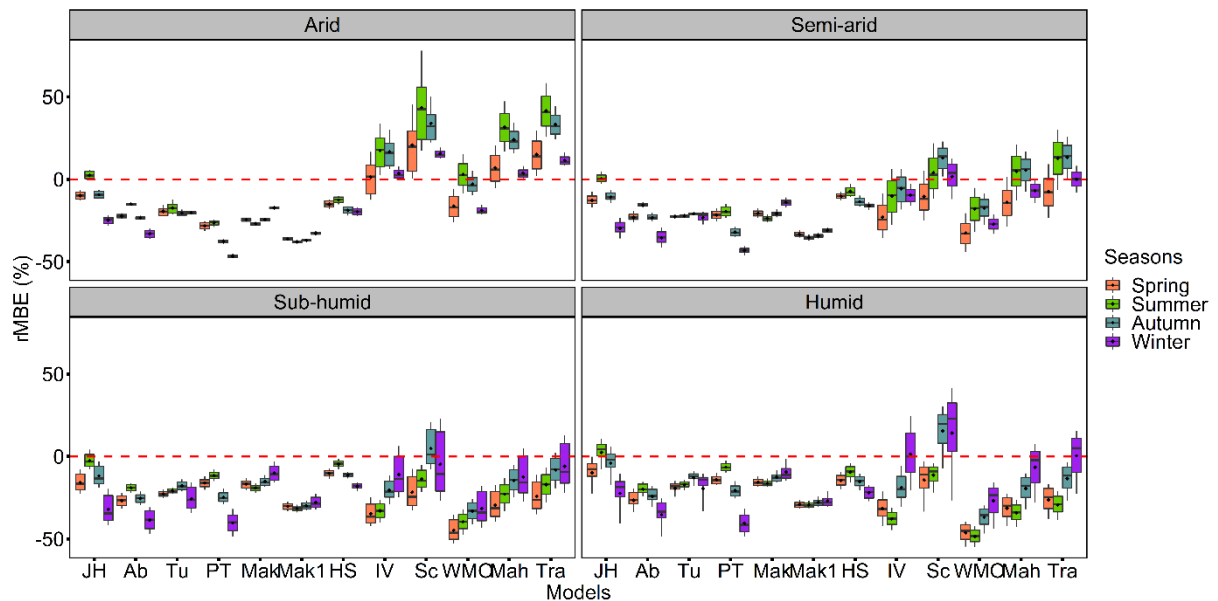


Figure 3-9 Distribution of rMBE (%) between seasonal ETp estimated by simplified ETp models and ETp estimated by Penman model from 1970 to 2014. Data used for each climate zone is the seasonal rMBE (%) of stations locating in this zone, that is, 201 stations for arid zone, 980 stations for semi-arid zone, 536 stations for sub-humid zone, and 403 stations for humid zone. The explanation of boxes was the same with that in Figure 3-5.

3.6.2 Ability of alternative models in capturing the dynamics of ETp

Figure 3-10 displayed that Penman-calculated ETp showed great inter-annual variation regardless of the climate condition. The other 12 ETp models seemed to be capable to detect the inter-annual variation. Figure 3-11 showed that precipitation generally showed decrease trend except for winter precipitation at sub-humid and humid zones, but the temporal dynamics for precipitation was not significant. According to the complementary relationship between precipitation and ETp under water-limited condition, ETp was expected to increase while precipitation decreases, as shown in Figure 3-12 and Figure 3-13. The inverse relationship between ETp and precipitation demonstrated that these models were generally able to capture the direction of ETp dynamics.

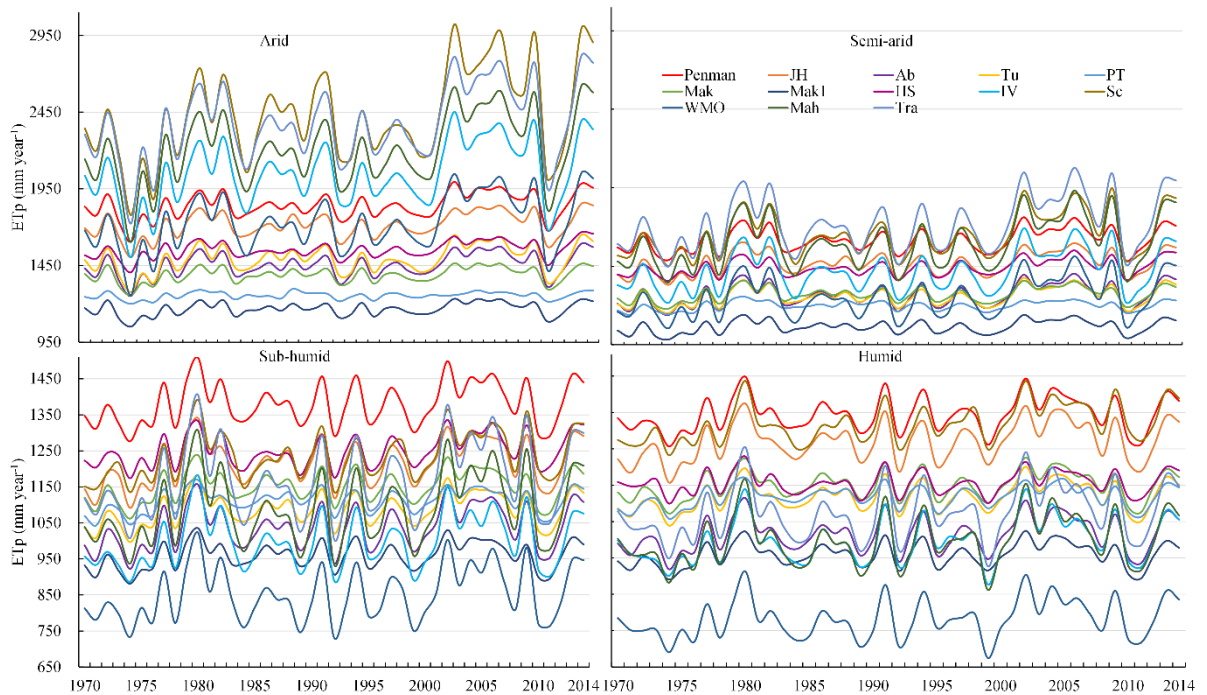


Figure 3-10 Temporal evolution of ETp estimated by 13 models from 1970 to 2014 for each climate zone.

However, the magnitudes of ETp dynamics significantly varied among models. In general, mass transfer-based models and temperature-based models except HS generally exaggerated the magnitude of the variation. On the contrary, the inter-annual variation showed by radiation-based models especially for PT, Mak, and Mak1 was smaller than that detected by Penman. For instance, mass transfer-based models agreed with Penman model that the increase of ETp was only significant for arid and semi-arid climate zones, but the increased rates captured by mass transfer-based models were two to three times of that tested by Penman model. As a comparison, the increase rates detected by PT, Mak, and Mak1 at arid zone were 0.5 mm year^{-1} , 1.4 mm year^{-1} , and 1.3 mm year^{-1} , which was much smaller than Penman model (2.8 mm year^{-1}) detected at the same zone. The other radiation-based models including JH, Ab, and Tu and temperature-based model HS were able to capture comparable increase rates with Penman model. Another common pattern detected by all models was that arid and semi-arid zones experienced more increases in ETp than the humid climate zones did.

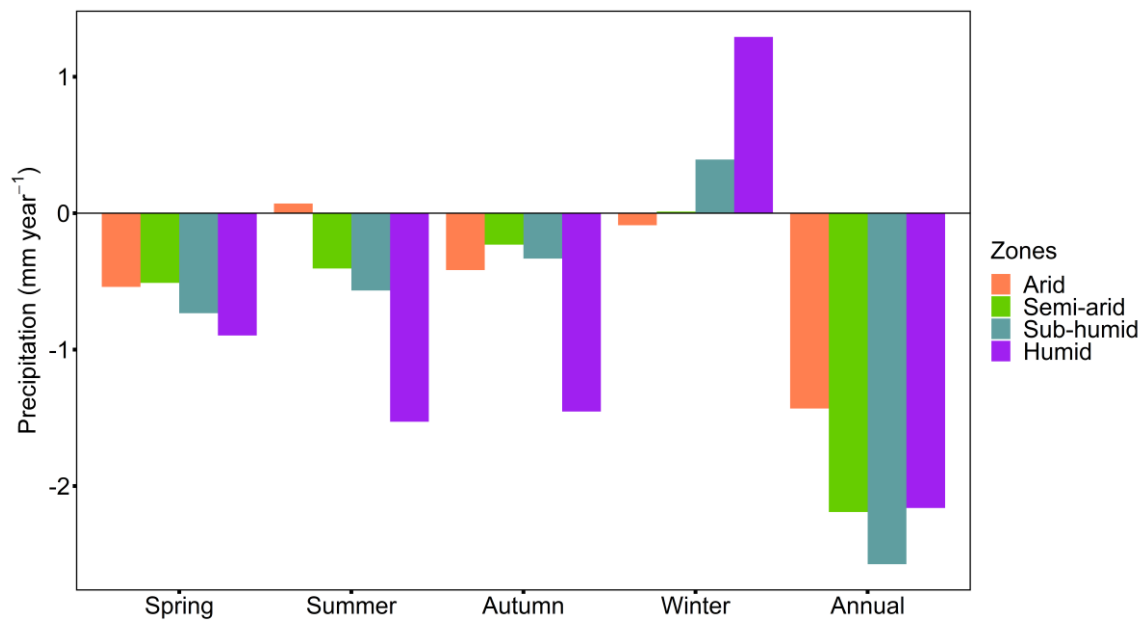


Figure 3-11 The temporal trends of precipitation both for seasonal and annual scales at four climate zones in the research period from 1970 to 2014.

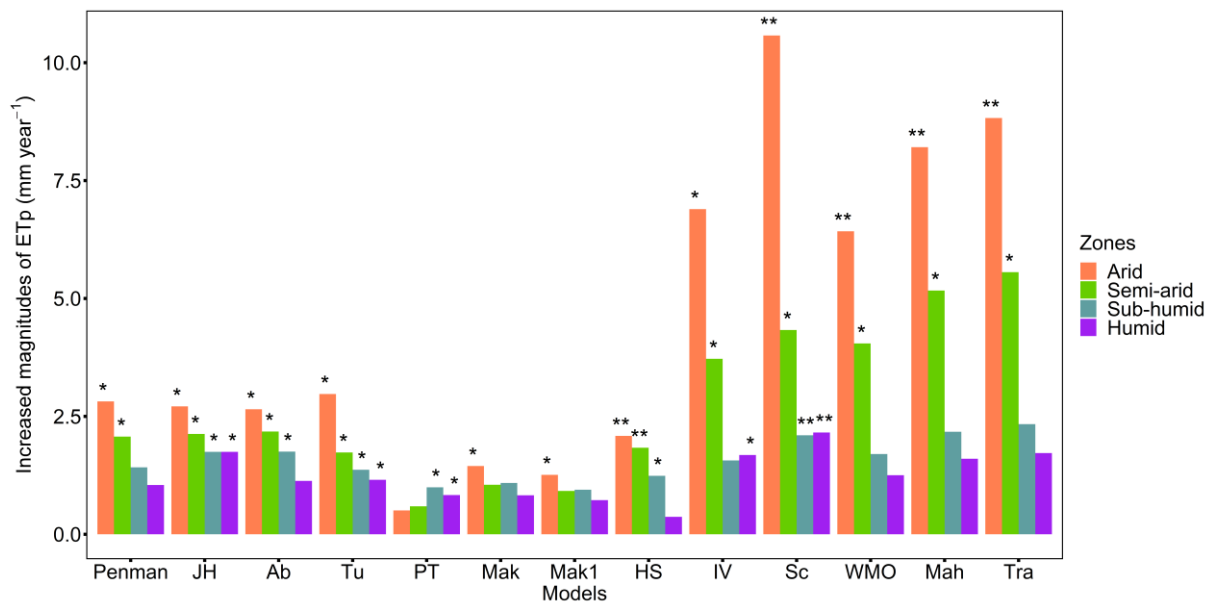


Figure 3-12 The temporal trends of annual ETp (mm year⁻¹) estimated by 13 models at four climate zones in the research period from 1970 to 2014. The asterisk symbol (*) showed the significant level. *: significant at 95% confidence level; **: significant at 99% confidence level.

The change of seasonal ETp also showed complementary relationship with change in seasonal precipitation (Figure 3-10 & Figure 3-12). In terms of the magnitudes of ETp increase, Penman detected that the spring increase rates of ETp were 1.4 mm year⁻¹ at arid climate, 1.1 mm year⁻¹ at semi-arid climate, 0.8

mm year⁻¹ at sub-humid climate, and 0.7 mm year⁻¹ at humid climate. The increase patterns of spring ETp detected by the simplified models were similar to the annual patterns, that is, mass transfer-based models and temperature-based models except HS exaggerated the increase rates whereas radiation-based models including PT, Mak, and Mak1 captured smaller increase magnitudes. The increasing rates detected by models including JH, Ab, Tu, and HS were comparable to that detected by Penman model.

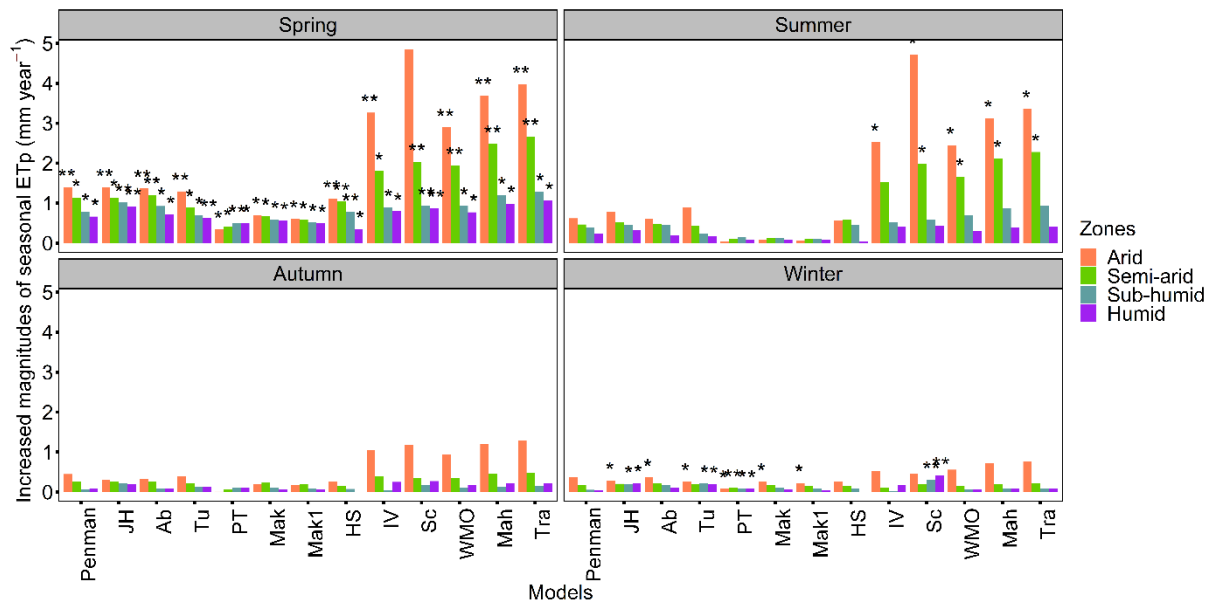


Figure 3-13 The temporal trends of seasonal ETp (mm year⁻¹) estimated by 13 models at four climate zones in the research period from 1970 to 2014. The asterisk symbol (*) had the same meaning with that in Figure 3-12.

3.6.3 Ability of alternative models to analyze the periodicity in ETp

The results of wavelet analysis showed that all models were capable to detect the rough periods of ETp (Figure 3-14) and periods detected by different models were similar. ETp in humid climates showed more obvious and constant periodicity than that in arid climates. In specific, ETp estimated by all models showed a significant 3-4-year oscillation in the period from 1990 to 2000 in sub-humid and humid zones. The 3-4-year short period in arid zone was less significant than that in humid zones. In addition to the short period, a 8-10-year period was also observed in the research period from 1970 to 2014.

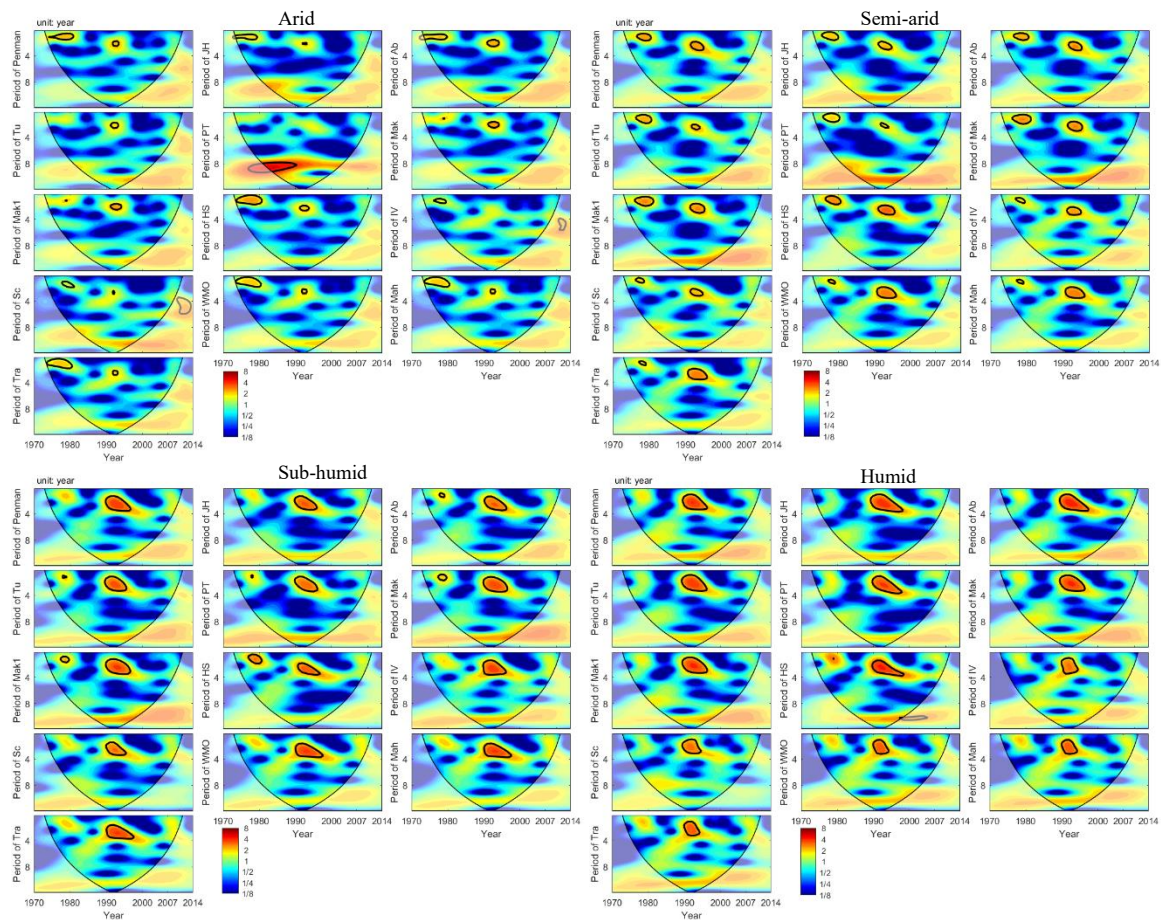


Figure 3-14 The wavelet-spectra and variances of annual ETp estimated by 13 models at four climate zones. The thin solid lines denote the cones of influence, and the thick solid lines show the 95% confidence levels. The colour bar means the vibration intensity of the periods at different timescales.

3.7 Discussion

Our results showed that radiation-based models were generally able to estimate daily and seasonal ETp rates but JH, Tu, Ab, and Mak showed more stable performance than PT and Mak1 did. Meanwhile, compared with PT and Mak1, the other four radiation-based models performed better in capturing the temporal evolution of ETp. Compared with that in arid and semi-arid climates, performance of PT and Mak1 was improved in sub-humid and humid climates (Trajkovic and Kolakovic, 2009). The failure of PT and Mak1 models was mainly attributed to the original coefficients embedded in the models. PT model was developed for saturated land and open water surfaced where advection effects were negligible (Priestley and Taylor, 1972). However, studies have demonstrated that wind speed may be the dominant factor influencing evapotranspiration in arid environments (Shan et al., 2015). Thus, the original commonly used coefficient of

1.26 in PT would lead to large underestimation of ET_p (Li et al., 2017; Tongwane et al., 2017).

The temperature-based model HS was able to produce good or fair estimates across all four climate zones at both daily and seasonal scales, whereas performance of IV and Sc showed great variation among climate zones or seasons. HS has been recommended by Allen et al. (1998) as a substitution when Penman could not be used due to lack of measured parameters. Almorox et al. (2015) also claimed that HS, among 11 temperature-based models, generally performed the best across different climates in global scale. Similarly, Tabari (2009) reported that HS was the most precise model among Mak, Tu, PT, and HS under warm humid and semi-arid climates. The poor performance of Sc and IV at arid zone might mainly due to the models' structure. High temperature and low relative humidity were common at arid climates, thus leading to very high values of ET_p calculated by Sc.

Mass transfer-based models were not recommendable to use in NSW due to their unstable performance among stations even under a certain climate zone. This poor performance of mass transfer-based models, especially in arid and semi-arid climates might be partially explained by the 2 m s⁻¹ wind speed used in these models. As shown in Figure 3-2, the R² between ET_{p_2m/s} and ET_{p_observed} were low at arid and semi-arid stations. The results highlighted that attention should be paid in the use of mass transfer-based models in arid or semi-arid climates, especially when observed wind speed was not available (Popova et al., 2006; Sentelhas et al., 2010).

Though trends of ET_p estimated by different models generally showed complementary relationship with the trend of precipitation (Figure 3-11, Figure 3-12, & Figure 3-13), the magnitudes of ET_p increases might be exaggerated or much smaller compared with that detected by Penman model. As Bormann (2010) concluded that different ET_p models showed obviously different sensitivities to observed change of climatic factors, resulting in that simplified ET_p models only agreed with Penman model on the change of ET_p at stations which exhibited strong climate trends (e.g. significant temperature increase). Donohue et al. (2010) evaluated the ability of five models (Penman, PT, Morton point, Morton areal and Thornthwaite) in capturing the dynamics of ET_p in Australia. They found that the Penman is the model that most faithfully reproduced the temporal change of ET_p. Their study highlighted the necessity of including all climatic drivers of ET_p to detect its temporal trends and capture the change rates. Based on these results, it might be reasonable to infer that both the required climatic inputs and models' structure play important roles in their ability to project temporal trends of ET_p under a changing climate (Bormann, 2010; Guo et al., 2017; McCuen, 1974; Valipour et al., 2017).

The comparison of models' ability in detecting periodicity of ETp was rare in literature. According to our study, we found that the studied models showed roughly equal ability in detecting the periodicity of ETp. 3-4-year and 8-10-year periodical oscillation of ETp have also been observed in this study, which was also supported by other researchers. For instance, Wang et al. (2017) claimed that the periods of 2.4, 3.4, and 9.6 years of ETp existed in China from 1961 to 2013. They claimed that El Niño/Southern Oscillation (ENSO) might be the climatic force of the oscillations of ETp (Wang et al., 2017). Similarly, we found that the low peaks of ETp were corresponding to the classic La Niña years while the high peaks of ETp were corresponding to the classic El Niño events occurred in Australia (BOM, 2012). When El Niño occurs it generally results in less rainfall, higher temperature and reduced cloudiness, thus increasing ETp and actual ET if water is available. At Taoer River basin of Northeast China, Liang et al. (2010) reported a 2-8 year periods of ETp from 1961 to 2005. They argued that the periodicity of maximum temperature, mean air temperature, relative humidity and solar radiation were main climate variables leading to the periodical oscillation in evapotranspiration.

Models evaluated in this study were temperature-based, radiation-based, or mass transfer-based. Among them, the use of some mass transfer-based models has been abandoned due to the great deviations in ETp estimated by these models (Bormann, 2010; Xiang et al., 2020). Especially, temperature-based and radiation-based models may be more feasible in ETp projection under future climate scenarios given the fact that the projection of temperature and radiation is more reliable than that of wind speed and humidity (Guo et al., 2017). Thus, based on findings in this study, radiation-based models including JH, Mak, and Ab, and temperature-based models HS were recommended to project future ETp.

It is likely that a location-specific calibration might improve model performance (Cristea et al., 2013; Shiri, 2017; Sumner and Jacobs, 2005; Xu and Singh, 2002). However, the readjustment of models' coefficients could be site-specific (Ravazzani et al., 2012) and greatly depend on the study period (Raziei and Pereira, 2013; Tabari and Talaei, 2011). In other words, the possibility of misleading to decision-makers companies with the readjustment of original coefficients embedded in empirical modes (Nouri and Homaei, 2018). Thus, we only evaluated models' performance based on the original coefficients.

3.8 Conclusions

The performance of 12 models in estimating ETp rates and capturing its temporal trends and interannual oscillation were evaluated against Penman model at four different climate zones in NSW from 1970 to 2014.

This study showed that radiation-based models and temperature-based model HS exhibited acceptable and stable performance in estimating both daily and seasonal ETp rates across all stations. Meanwhile, they showed comparable ability against Penman model in detecting the periodical oscillation of ETp in the research period. However, radiation-based models PT and Mak1 generally underestimated the increase rates of ETp. Thus, this study recommended the use of JH, Tu, Ab, Mak, and HS to estimate ETp in NSW when the whole set of climatic data was not available to use Penman model.

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Chapter 4. Projecting potential evapotranspiration change and quantifying its uncertainty under future climate scenarios: A case study in southeastern Australia

This chapter is based on the following publication:

Lijie Shi, Puyu Feng, Bin Wang, De Li Liu, James Cleverly, Quangxiao Fang, and Qiang Yu. "Projecting potential evapotranspiration change and quantifying its uncertainty under future climate scenarios: A case study in southeastern Australia" *Journal of Hydrology*, 584 (2020), DOI: <https://doi.org/10.1016/j.jhydrol.2020.124756>

Abstract: Projecting the likely change of potential evapotranspiration (ETp) under future climate scenarios is crucial for quantifying the impacts of climate change on the hydrologic cycle and aridity conditions. However, there are different sources of uncertainty in projecting future ETp that may arise from global climate models (GCMs), emission scenarios, and multiple ETp models used. In this study, we developed three random forest-based (RF-based) ETp models with solar radiation and air temperature at eight climatic stations in southeastern Australia. With Penman model as the benchmark, their performance was firstly compared with four empirical models (Jensen-Haise, Makkink, Abtew, and Hargreaves), which requires the same meteorological inputs. In general, the RF-based ETp models showed better performance in ETp estimates across all stations, with coefficients of determination (R^2) ranging from 0.68 to 0.92, root mean square errors (RMSE) ranging from 0.58 mm day⁻¹ to 1.46 mm day⁻¹, and relative mean bias errors (rMBE) ranging from -16.10% to 9.73%. The RF-based and empirical models were then used to project future ETp for the eight stations based on statistically downscaled daily climatic data from 34 GCMs under two different representative concentration pathways (RCP4.5 and RCP8.5). All models indicated that ETp was likely to increase at the eight stations. The ensemble increases of mean ETp across eight stations ranged from 33 mm year⁻¹ (2.1%, 2040s) to 129 mm year⁻¹ (9.2%, 2090s) and from 43 mm year⁻¹ (2.8%, 2040s) to 248 mm year⁻¹ (17.6%, 2090s) under RCP4.5 and under RCP8.5, respectively. In addition, we also quantified uncertainties in ETp projections originating from ETp models, GCMs, RCPs, and their combined effects using the analysis of variance (ANOVA) method. Results showed that RCP-related uncertainty contributed the most to projected ETp uncertainty (around 40% for most stations) while GCM-related and ETp model-related uncertainties accounted for roughly equal amounts of projected ETp uncertainty (10%-30%). This study demonstrated the better performance of RF-based ETp models. It is advisable to use multiple ETp models

driven by various GCMs under different RCPs to produce reliable projections of future ETp.

Keywords: potential evapotranspiration; empirical ETp models; random forest; uncertainty; climate change; southeastern Australia

4.1 Introduction

The hydrological cycle has intensified in the last century and the rate of intensification for the coming century is accelerating due to climate change (Durack et al., 2012; Pan et al., 2015). This may lead to a global shift in aridity or make dry regions become drier while wet regions become wetter (Chen et al., 2017). Thus, it is important to investigate the influence of climate change on the water cycle. As one of the most important components of hydrological and climatological processes, evapotranspiration (ET) accounts for around 70% of precipitation falling on land and consumes more than 50% of the solar energy absorbed by the earth (Guo et al., 2017; Pan et al., 2015; Vicente-Serrano et al., 2014). Thus, ET is a very useful indicator to analyse the changing behaviour of the hydrologic regime (Wang et al., 2017b).

However, ET is not easy to measure. For instance, although lysimeters are frequently used to directly measure ET, they are sparsely distributed around the world because they are expensive and laborious to manage (Azhar and Perera, 2011). Therefore, ET is generally estimated by various empirical models that estimate either potential evapotranspiration (ETp) or reference evapotranspiration (ET₀) (Almorox et al., 2015). ETp represents the maximum possible evapotranspiration rate from a well-watered, vegetative surface (Donohue et al., 2010; McMahon et al., 2016), and is regarded as the optimum measurement of evaporative demand from actual land surfaces under specified metrological conditions (Zheng et al., 2017). In fact, ETp (rather than actual ET) has been widely used as an important input to various hydrological models (Thompson et al., 2013) and aridity indexes (Sheffield et al., 2012). In general, ET models can be classified into four categories according to their input requirements, i.e. temperature-based models (Hargreaves et al., 1985), radiation-based models (Jensen and Haise, 1963; Makkink, 1957), mass transfer-based models (Mahringer, 1970), and combination models (Penman, 1948). Among them, the Penman model and the FAO56 Penman-Monteith (PM-FAO56) model are two variants of the Penman-Monteith-type models. They are both physically-based models (Milly and Dunne, 2016; Yang et al., 2019) that can accurately estimate ET across various climate conditions (Donohue et al., 2010; Milly and Dunne, 2016). Therefore, they are widely used as benchmarks to assess the performance of other ETp/ET₀ models. In contrast to the Penman model, PM-FAO56 considers the surface conductance of a reference crop, and provides estimates of ET₀ while the

Penman model provides estimates of ET_p. Both of these models require the complete set of climatic data, which may limit their use in some regions. In the particular case of future ET projection, downscaled climatic data, such as wind speed and relative humidity, may not be reliable (Randall et al., 2007), thus limiting the use of Penman-Monteith-type models.

Compared with the Penman model, simplified empirical ET_p models require fewer climate inputs to offer acceptable estimates (Almorox et al., 2015). These empirical ET_p models (e.g., temperature-based models) may be preferable for future ET_p projection because GCM-simulated temperature is considered to have higher confidence than other climatic variables (CSIRO and BOM, 2015; Randall et al., 2007). For instance, Kay and Davies (2008) used both the Penman-Monteith model and a temperature-based model to estimate ET_p of Britain with climate data from five GCMs and eight regional climate models. They demonstrated that ET_p estimated by the temperature-based model with temperature from a climate model matched MORECS ET_p (a gridded dataset of estimated ET_p based on observed climatic data with the Penman-Monteith model) better than ET_p estimated by the Penman-Monteith model with climate model data. Similarly, Ravazzani et al. (2014) adopted a temperature-based model and an energy balance-based ET_p model which requires a complete set of climate data to quantify the influence of climate change on water resources in Northern Italy. They found that a simple temperature-based ET_p model is sufficiently accurate for analysing the climate change effects on hydrological regimes.

In addition to empirical ET_p models, newly emerging machine learning techniques have recently been used to estimate ET_p (Feng et al., 2018b; Kisi, 2015; Kişi, 2013; Kisi and Alizamir, 2018; Mehdizadeh, 2018; Tabari et al., 2012; Wang et al., 2017a). The major advantage of machine learning techniques is that they are capable of tackling non-linear relationships between the dependent and independent variables without requiring knowledge of the internal variables (Fan et al., 2018; Mehdizadeh, 2018). Performance comparisons between machine learning techniques and conventional empirical models for estimating ET have been widely reported. For instance, Tabari et al. (2012) evaluated the performance of support vector machines (SVM), adaptive neuro-fuzzy inference systems (ANFIS), multiple linear regression, multiple non-linear regression, four temperature-based ET₀ models, and eight radiation-based ET₀ models for estimating ET₀ compared with the PM-FAO56 model in a semi-arid highland environment in Iran. They found that SVM and ANFIS performed better than the regression-based models and the corresponding conventional ET₀ models (i.e., models requiring the same climatic inputs). In the Poyang Lake Watershed, Lu et al. (2018) adopted three tree-based machine learning methods including M5Tree, random forest (RF), and gradient

boosting decision tree (GBDT) and four empirical models to estimate pan evaporation from 2001 to 2015. They found machine learning models, especially GBDT and RF, showed great potential for estimating daily pan evaporation regardless of the input combination. In Spain, Shiri et al. (2012) assessed the performance of Gene Expression Programming (GEP), ANFIS, Hargreaves, and Priestley-Taylor for calculating daily ET₀ compared with the PM-FAO56 model and found that both GEP and ANFIS performed better than the two conventional models. In summary, machine learning models generally outperformed conventional empirical models (i.e., for models requiring the same climatic inputs) in accurately estimating ET. However, their use in projecting future ET_p is still rare.

Another widely discussed problem in the estimation of future ET_p is related to the uncertainty generated by various ET_p models, GCMs, and emission scenarios (Bae et al., 2011; Wilby and Harris, 2006; Xu et al., 2014). For instance, Wang et al. (2015) found that the directly downscaled ET_p values from HadCM3 and ET_p estimated by PM-FAO56 and Hargreaves models would all increase under future climate scenarios in the Hanjiang River Basin. However, the magnitudes of the ET_p increases varied greatly among these ET_p models, up to 70 mm year⁻¹. Other researchers (Arnell and Gosling, 2013; Kay and Davies, 2008) also reported that the projected ET_p under future climate scenarios could be significantly different due to the differences in GCMs and ET_p models, indicating the large uncertainty in future ET_p projections. Thus, it is necessary to quantify the uncertainty originating from various sources in order to evaluate the reliability of ET_p projections. Thompson et al. (2014) concluded that GCM-related uncertainty was about 3.5 times larger than ET_p model-related uncertainty for the projection of river flow in the Mekong River Basin. For the projection of future global ET_p with various ET_p models and GCMs, Kingston et al. (2009) claimed that ET_p model-related uncertainty was equal to or, in some circumstance, greater than GCM-related uncertainty. However, to our knowledge, few studies have systematically quantified the uncertainties originating from conventional ET_p models as well as machine learning-based models, GCMs, emission scenarios, and their combined effects.

Australia is a water-scarce and drought-vulnerable country (Howden et al., 2014; Verdon-Kidd and Kiem, 2009). The warming climate may exacerbate the water-scarce situation in this region. Therefore, studying the likely change of ET_p in Australia is necessary for the development of proposals and policies for adapting water management to climate change. In this study, we first proposed a machine learning method to estimate ET_p in southeastern Australia and used multiple ET_p models driven by statistically downscaled climate data from a large number of GCMs to quantify the impacts of climate change on ET_p. The objectives of this study

were to 1) assess the performance of machine learning-based ETp models for estimating daily ETp; 2) explore the likely change of future ETp in the study area based on various ETp models; and 3) quantify the contributions of different sources of uncertainty, including GCMs, ETp models, emission scenarios, and their combined effects, to the uncertainty in future ETp projections. This research will provide a good reference for researchers to better understand the performance of machine learning-based ETp models in projecting future ETp. Additionally, knowledge of the uncertainty in future ETp projections would also help researchers to understand the potential bias in projecting the hydrological cycle and water availability under future climate scenarios.

4.2 Study area

New South Wales (NSW) is located in southeast Australia (Figure 4-1). It accounts for 10.4% of the Australian land area ($8.1 \times 10^5 \text{ km}^2$) and has a population of more than eight million, making NSW the most populous state in Australia. The production of agricultural crops in NSW is important to the agricultural industry in Australia. For instance, wheat grown in NSW accounts for 28% of the total wheat-planted area in Australia (Feng et al., 2019). However, topography and climatic characteristics in NSW vary greatly from east to west, making it vulnerable to climate change. In general, NSW can be divided into four distinct geographical sections based on their natural features, namely the east coast, the mountains, the central plains, and the western plains. Climatically, the east coast and the mountains are characterized by humid or sub-humid climates while the central and western plains experience semi-arid or arid climates. Average annual rainfall gradually increases from 50 mm year^{-1} in the westernmost region to $1500 \text{ mm year}^{-1}$ on the east coast. Similarly, average annual temperature gradually increases from around $10 \text{ }^\circ\text{C}$ in the southeast to greater than $20 \text{ }^\circ\text{C}$ in the northwest.

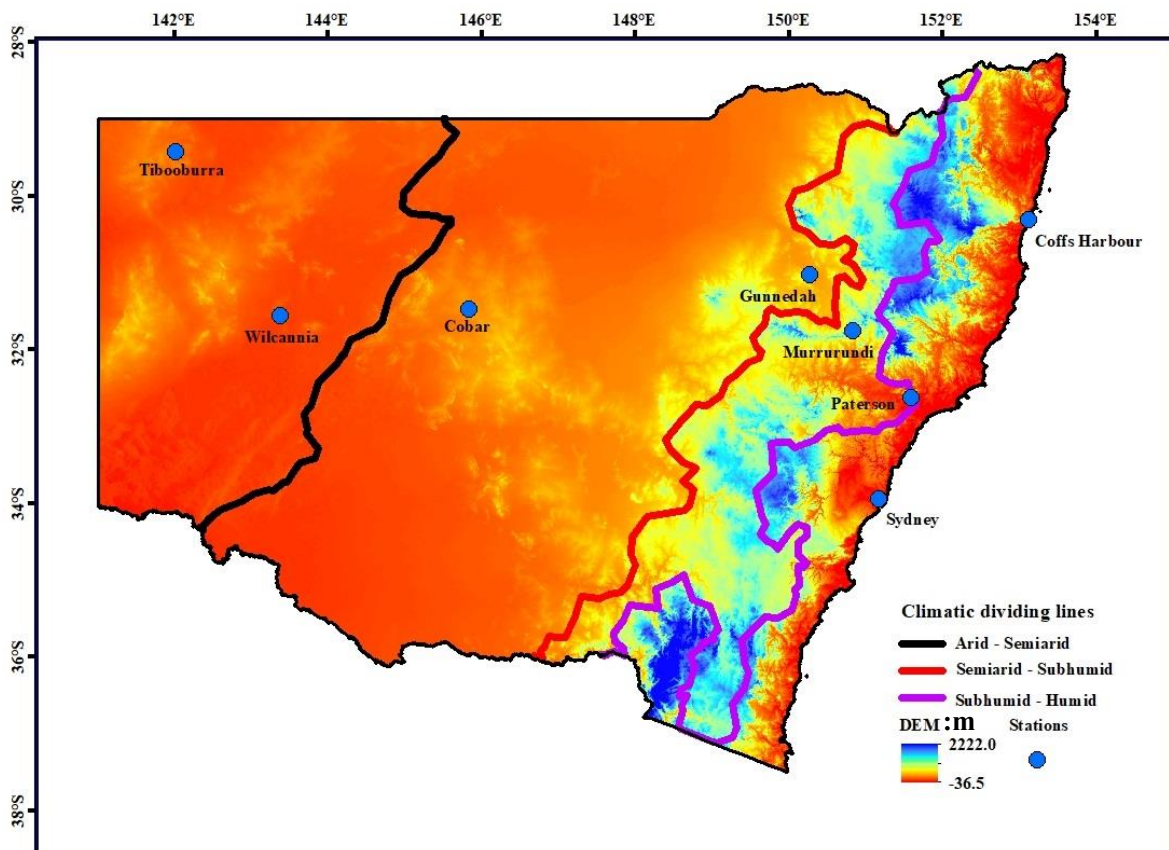


Figure 4-1 The location of eight stations in four different climate zones across New South Wales, Australia, and their elevations (m) determined by digital elevation model (DEM). The climate dividing lines is developed based on the widely used aridity index (rainfall/ETp) (UNESCO, 1979)

Climate in NSW is expected to change under the influence of future global warming. For instance, temperature in NSW is projected to rise by 2.1 °C by 2070 while annual rainfall is likely to decrease (CSIRO and BOM, 2015; Vaze et al., 2008). Furthermore, extreme weather events such as heatwaves and droughts may occur more frequently (Feng et al., 2018a), which might exacerbate water scarcity in NSW and result in new water management challenges. Thus, it is necessary to project ETp changes under future climate scenarios to predict the effects of climate change on water resource management and drought prediction.

Eight stations locating in four different climate zones across NSW (Figure 4-1) were selected for examination in this study because they have complete sets of climate data that are required for the Penman model to estimate daily ETp. Geographic information, ETp-related climate variables, annual rainfall, and aridity index of these stations are shown in Table 4-1.

Table 4-1 Geographical and long-term average meteorological information for eight stations locating in for different climate zones across New South Wales, Australia. The values in parentheses are the standard deviations for each variable

	Lon	Lat	DEM	T ^a	Rs ^b	RH ^c	Wind ^d	Rainfall	ETp	AI ^e	Period
	(°E)	(°S)	(m)	(°C)	(MJ m ⁻² d ⁻¹)	(%)	(m/s)	(mm)	(mm)		
Tibooburra	142	-29.4	183	20.8 (0.7)	20.8 (0.7)	48.1 (4.4)	2.4 (1.0)	248 (143)	2133 (267)	0.12 (0.08)	1953-2014
Wilcannia	143.4	-31.6	75	19.5 (0.5)	19.7 (0.6)	55.3 (3.7)	2.7 (0.6)	272 (126)	2072 (173)	0.14 (0.07)	1957-2014
Cobar	145.8	-31.5	260	19.0 (0.7)	19.4 (0.7)	54.4 (4.6)	2.1 (0.5)	397 (156)	1865 (171)	0.22 (0.10)	1963-2014
Gunnedah	150.3	-31	307	18.3 (0.6)	18.6 (0.7)	63.3 (3.3)	1.8 (0.3)	632 (161)	1639 (102)	0.39 (0.11)	1951-2014
Murrurundi	150.8	-31.8	466	15.5 (0.5)	17.5 (0.7)	71.2 (2.7)	1.6 (0.4)	857 (197)	1429 (122)	0.61 (0.17)	1965-2014
Paterson	151.6	-32.6	30	18.0 (0.5)	16.9 (0.5)	71.5 (1.9)	2.3 (0.5)	930 (196)	1533 (107)	0.61 (0.15)	1968-2014
Sydney	151.2	-34	6	17.9 (0.7)	16.4 (0.5)	68.6 (3.0)	3.1 (0.8)	1123 (309)	1551 (154)	0.74 (0.25)	1950-2014
Coffs Harbour	153.1	-30.3	5	18.7 (0.5)	17.4 (0.6)	72.6 (1.6)	2.7 (0.4)	1720 (467)	1539 (85)	1.13 (0.34)	1952-2014

^aair temperature, ^bsolar radiation, ^crelative humidity, ^dwind speed, ^earidity index calculated as rainfall/ETp.

4.3 Climate data and downscaling method applied

Historical daily climate data during the research period, including maximum temperature (T_{\max}), minimum temperature (T_{\min}), maximum and minimum relative humidity (RH_{\max} and RH_{\min} , respectively), rainfall, and solar radiation (R_s), were obtained from the Scientific Information for Land Owners (SILO) patched point dataset (<https://www.longpaddock.qld.gov.au/silo/datadrill/index.php>). In addition, wind speed

data were obtained from the Bureau of Meteorology (BOM, <http://www.bom.gov.au/>). The percentage of missing daily wind speed data was less than 5% for each station. To estimate the missing wind speed values, we first used years with consecutive daily wind speed to calculate the long-term average wind speed for each day of the year. Then we used the average wind speed for the i -th (i ranges from 1 to 365) day of the year as the proxy wind speed for that day of the year with a missing value. To project ET_p under future climate scenarios, we downscaled 34 GCMs (Table 4-2) from the Coupled Model Intercomparison Project Phase 5 (CMIP5) dataset to extract daily T_{\max} , T_{\min} , rainfall, and R_s from 1900-2100 based on the statistical downscaling method developed by Liu and Zuo (2012).

Statistical downscaling is an effective method to downscale the raw monthly climatic data from GCMs at coarse spatial resolutions to a finer spatial and temporal scale. Firstly, the monthly climatic data from GCMs were downscaled to specific sites using the inverse distance weighted interpolation method. Then bias correction was applied to the monthly values of climatic factors for each site. Thirdly, we used a stochastic weather generator to produce daily climatic factors for each site. The detailed information about this method has been described by Liu and Zuo (2012). This study used the downscaled data to project future ET_p with the chosen empirical and machine learning-based ET_p models under RCP4.5 and RCP8.5 climate scenarios.

For data downscaled from 34 GCMs, we defined the period from 1990 to 2014 as the baseline period. The near future projected period was defined as 2026 to 2050 (2040s); the medium projected period was from 2051 to 2075 (2065s); and the far future period was 2076-2100 (2090s).

Table 4-2 Identifying information for 34 global climate models (GCMs). GCMs were used for statistically downscaling outputs for eight stations across New South Wales, Australia, under the RCP4.5 and RCP8.5 scenarios.

Model ID	Name of GCM	Abbr. of GCM	Institute ID	Country
1	ACCESS1-0	AC1	CSIRO and BoM	Australia
2	ACCESS1-3	AC2	CSIRO and BoM	Australia
3	BCC-CSM1-1	BC1	BCC	China
4	BCC-CSM1-1-m	BC2	BCC	China
5	BNU-ESM	BNU	GCESS	China
6	CanESM2	CaE	CCCMA	Canada
7	CCSM4	CCS	NCAR	USA
8	CESM1-BGC	CE1	NSF-DOE-NCAR	USA
9	CESM1-CAM5	CE2	NSF-DOE-NCAR	USA
10	CESM1-WACCM	CE5	NSF-DOE-NCAR	USA
11	CMCC-CM	CM2	CMCC	Europe
12	CMCC-CMS	CM3	CMCC	Europe
13	CNRM-CM5	CN1	CNRM-GAME	France
14	CSIRO-Mk3-6-0	CSI	CSIRO-QCCCE	Australia
15	EC-EARTH	ECE	EC-EARTH	Europe
16	FIO-ESM	FIO	FIO	China
17	GISS-E2-H	GE1	NASA GISS	USA
18	GISS-E2-H-CC	GE2	NASA GISS	USA
19	GISS-E2-R	GE3	NASA GISS	USA
20	GFDL-CM3	GF2	NOAA GFDL	USA
21	GFDL-ESM2G	GF3	NOAA GFDL	USA
22	GFDL-ESM2M	GF4	NOAA GFDL	USA
23	HadGEM2-AO	Ha5	NIMR/KMA	Korea
24	INM-CM4	INC	INM	Russia
25	IPSL-CM5A-LR	IP1	IPSL	France

26	IPSL-CM5A-MR	IP2	IPSL	France
27	IPSL-CM5B-LR	IP3	IPSL	France
28	MIROC5	MI2	MIROC	Japan
29	MIROC-ESM	MI3	MIROC	Japan
30	MIROC-ESM-CHEM	MI4	MIROC	Japan
31	MPI-ESM-LR	MP1	MPI-M	Germany
32	MRI-CGCM3	MR3	MRI	Japan
33	NorESM1-M	NE1	NCC	Norway
34	NorESM1-ME	NE2	NCC	Norway

4.4 Empirical ET_p models and random forest-based ET_p models

In this study, the widely used Penman model was still used as the benchmark to evaluate the performance of other models. Among key climatic factors driving evapotranspiration, Priestley and Taylor (1972) and Samani (2000) reported that air temperature and solar radiation could explain at least 80% of variations in ET_p (Almorox et al., 2015). Meanwhile, most GCMs have reliable prediction of air temperature. Thus, this study also adopted commonly used temperature-based and radiation-based models to compare their performance with random forest-based (RF-based) ET_p models, and to project future ET_p. Based on the performance assessment carried out in Chapter 3, the temperature-based model Hargreaves (HS), and the three radiation-based models including Jensen-Haise (JH), Makkink (Mak), and Abtew (Ab) were used in this study as a corresponding comparison with RF-based models. Their mathematical expressions were as follows:

$$ET_{p, Penman} = \frac{0.408\Delta}{\Delta + \gamma} (R_n - G) + \frac{\gamma}{\Delta + \gamma} \frac{6.43(1 + 0.536u_2)(e_s - e_a)}{\lambda} \quad (4-1)$$

$$ET_{p, HS} = 0.0023 \times 0.408 R_a (T_{\max} - T_{\min})^{0.5} (T + 17.8) \quad (4-2)$$

$$ET_{p, JH} = 0.0102(T + 3) R_s \quad (4-3)$$

$$ET_{p, Mak} = 0.7 \frac{\Delta}{\Delta + \gamma} \frac{R_s}{\lambda} \quad (4-4)$$

$$ET_{p, Ab} = 0.01786 \frac{R_s T_{\max}}{\lambda} \quad (4-5)$$

where Δ (kPa °C⁻¹) is the slope of the saturation vapor pressure curve, determined by air temperature (T); γ (kPa °C⁻¹) is the psychrometric constant; R_n (MJ m⁻² day⁻¹) is net radiation determined according to Allen et al. (1998); G (MJ m⁻² day⁻¹) is soil heat flux density, assumed to equal zero for periods of a day or longer; u_2 (m s⁻¹) is wind speed at 2 m height; e_s (kPa) is saturation vapor pressure, determined by T; e_a (kPa) is actual vapor pressure, determined by T and relative humidity (RH); $(e_s - e_a)$ (kPa) is saturation vapor pressure deficit; and λ is the latent heat of vaporization of water, which is calculated as a function of T, value of 2.45 MJ kg⁻¹ for T around 20°C; T_{max} (°C) and T_{min} (°C) are maximum temperature and minimum temperature, respectively.

Random forest (RF) is one of the tree-based machine learning methods developed by Breiman (2001). Compared with most well-established machine learning methods (e.g., artificial neural networks and SVM), RF only needs two parameters: the number of decision trees (n_{tree}) and the number of variables (m_{try}). Moreover, RF has a strong predictive power to deal with non-linear and hierarchical relationships between the predictors and the response. In fact, RF has been widely used for classification and regression tasks (Fan et al., 2018; Heung et al., 2014; Wang et al., 2018b). Thus, we adopted RF as a representative machine learning technique to estimate ETp in this study. Briefly, around 2/3 of the original data were randomly chosen as the “bootstrapped” dataset to generate numerous decision trees (n_{tree}) with a random subset of the total variables (m_{try}) each step. Thus, a variety of decision trees were generated that formed the “Forest”. The remaining original data (around 1/3), which were not chosen to build the “bootstrapped” dataset (known as the “Out-of-Bag Dataset”) were used for validation. Based on the “Forest”, the projector used predicted data and ran those data through all of the decision trees. The final prediction was the average of the results of all trees. More information about RF can be found in Breiman (2001), and a schematic diagram of RF is shown in Figure 4-2.

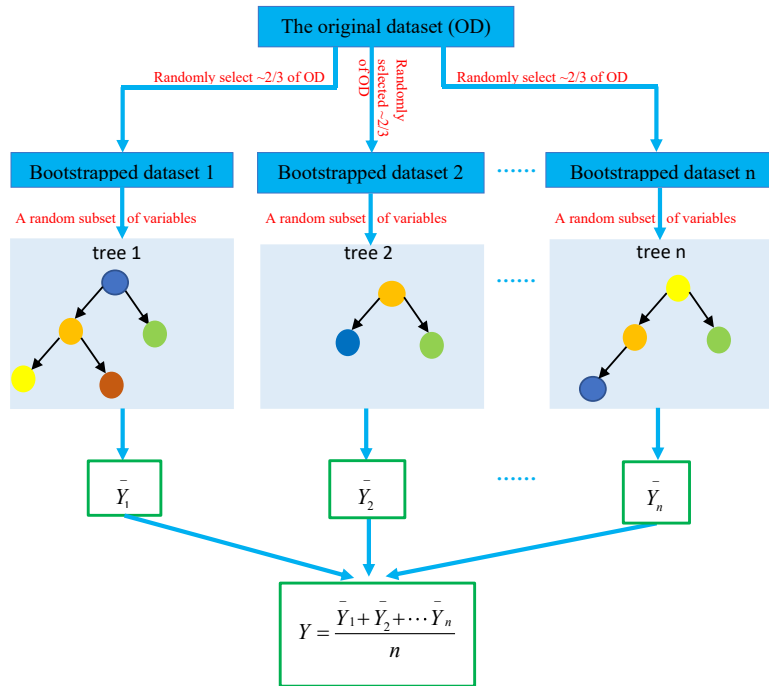


Figure 4-2 Flow diagram of the random forest model.

This study adopted the “randomForest” package in R (Liaw and Wiener, 2002) (<https://cran.r-project.org/web/packages/randomForest/index.html>) to develop RF-based ETP models with observed historical climatic data. The daily climatic data from 1950 (or the starting year of the station shown in Table 4-1) to 2000 were used to train RF-based ETP models while the data from 2001 to 2014 were used to test these RF-based ETP models. Three RF-based ETP models (Table 4-3) were developed, namely RF1 based on T_{\max} , T_{\min} , and R_s to compare with JH and Mak; RF2 based on T_{\max} , T_{\min} , and extra-terrestrial solar radiation (R_a) to compare with HS; and RF3 based on T_{\max} and R_s to compare with Ab. We set n_{tree} as 500 to ensure that every input row would be predicted a few times. The default value of m_{try} is generally around 1/3 of the number of input variables (p) (Guio Blanco et al., 2018). Because of the small number of input variables in the current study, we used m_{try} values which were somewhat larger than $0.33p$. The number of predictors in our study was 3 for RF1 and RF2, and 2 for RF3. Thus, we set m_{try} as 2 for RF1 and RF2, and 1 for RF3.

Table 4-3. The input requirements of seven ETp models used in this study.

Models	Inputs
RF1	$T_{\max}^a, T_{\min}^b, R_s^c$
Jensen-Haise (JH)	T_{\max}, T_{\min}, R_s
Makkink (Mak)	T_{\max}, T_{\min}, R_s
RF2	$T_{\max}, T_{\min}, R_a^c$
Hargreaves (HS)	T_{\max}, T_{\min}, R_a
RF3	T_{\max}, R_s
Abtew (Ab)	T_{\max}, R_s

^amaximum air temperature, ^bminimum air temperature, ^csolar radiation, ^dextraterrestrial solar radiation

4.5 Model evaluation

Performance (with regards to estimates of ETp rates) of RF-based (RF1, RF2, and RF3) and empirical (JH, Mak, HS, and Ab) ETp models was evaluated against the Penman model with the commonly used statistical parameters: coefficient of determination (R^2), root mean square error (RMSE, mm day⁻¹), and relative mean bias error (rMBE, %). These parameters were calculated via the following equations:

$$R^2 = \left(\frac{\sum_{i=1}^n (ET_{p, Penman, i} - \overline{ET_{p, Penman}}) (ET_{p, others, i} - \overline{ET_{p, others}})}{\sqrt{\sum_{i=1}^n (ET_{p, Penman, i} - \overline{ET_{p, Penman}})^2} \sqrt{\sum_{i=1}^n (ET_{p, others, i} - \overline{ET_{p, others}})^2}} \right)^2 \quad (4-6)$$

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^n (ET_{p, Penman, i} - ET_{p, others, i})^2} \quad (4-7)$$

$$rMBE = \left(\frac{1}{\overline{ET_{p, Penman}}} \right) \times \frac{1}{n} \sum_{i=1}^n (ET_{p, Penman, i} - ET_{p, others, i}) \times 100 \quad (4-8)$$

where $ET_{p, Penman, i}$ and $ET_{p, others, i}$ are the i -th day ETp calculated by Penman model and other ETp models aforementioned, respectively. These statistical indexes have been widely used in model's performance assessment (Almorox et al., 2015; Arellano and Irmak, 2016). R^2 measured how much the variability in the Penman-estimated ETp can be explained by ETp estimated by other ETp models. A good performed ETp model is expected to have R^2 close to 1 (Bai and Liu, 2018). RMSE measured the difference

between the Penman-estimated ET_p and ET_p estimated by other models. The smaller RMSE is, the better the model performed (Shiri et al., 2012). The relative underestimation or overestimation of ET_p by other models can be told from rMEB. Good performed model is expected to have rMBE close to 0% (Nouri and Homae, 2018).

4.6 Future ET_p projection

Both the validated RF-based (RF1, RF2, and RF3) and the four empirical (JH, Mak, HS, and Ab) ET_p models were used to project future ET_p with downscaled daily climatic data from 34 GCMs under RCP4.5 and RCP8.5 climate scenarios. Daily ET_p values were then summed to obtain annual ET_p for each GCM at the eight stations. The ET_p change for a certain future period was the difference between the mean annual ET_p for that period and the mean annual ET_p for the baseline period.

4.7 Contribution analysis of uncertainty in future ET_p projections

The analysis of variance (ANOVA) technique has been widely used to quantify the contribution of different sources in uncertainty analysis (Aryal et al., 2019; Su et al., 2017; Tao et al., 2018; Wang et al., 2018a). This technique is able to partition the total observed variances into different sources, thus identifying the contribution of different sources to the total variance. Compared with other commonly used methods (e.g., recursive models, parameter identification, and Bayesian approaches) in uncertainty analysis (Ashraf Vaghefi et al., 2019; Freni et al., 2009), the ANOVA method requires fewer assumptions and considers the interactive contributions of different sources of the uncertainty to the total variance (Ashraf Vaghefi et al., 2019; Yip et al., 2011). Thus, we used a three-way (three factors) ANOVA to quantify the relative contribution of GCMs, RCPs, and ET_p models to the uncertainty in ET_p projections. A three-way ANOVA can be split into seven fractions that include the three main effects and the four interaction effects. The total sum of squares (SST) was calculated as:

$$SST = \underbrace{SS_{GCMs} + SS_{RCPs} + SS_{ET_p, models}}_{\text{main effects}} + \underbrace{SS_{GCMs:RCPs} + SS_{GCMs:ET_p, models} + SS_{RCPs:ET_p, models} + SS_{GCMs:RCPs:ET_p, models}}_{\text{interaction effects}} \quad (4-9)$$

4.8 Results

4.8.1 Performance of ET_p models during the historical period

Historical ET_p estimation (2001-2014, Figure 4-3 & Figure 4-4) indicated that RF-based ET_p models generally outperformed the corresponding empirical ET_p models (i.e., empirical ET_p models which required

the same inputs). Specifically, RF-based ETp models generally produced greater R^2 , smaller RMSE, and smaller absolute rMBE than the corresponding empirical ETp models did at nearly all eight stations. For example, consider the results for the RF1, JH, and Mak models. Their R^2 values all ranged from 0.80 to 0.90. However, the RMSE of RF1 ranged from 0.58 mm day⁻¹ to 1.31 mm day⁻¹, generally lower than that of JH (from 0.76 mm day⁻¹ to 1.42 mm day⁻¹) and Mak (from 0.99 mm day⁻¹ to 2.28 mm day⁻¹). Moreover, ETp values calculated by RF-based models generally followed the Penman model, while other empirical models (e.g., MaK and HS) tended to underestimate ETp (compare blue regression lines with red 1:1 lines in Figure 4-4). Even at stations where nearly all RF-based and empirical models underestimated ETp, such as at Cobar and Sydney, RF-based models still performed better, showing better consistency with the Penman model. The better performance of RF-based models may be explained by their ability to deal with non-linear processes between response variable and predictors. In addition, RF1 and RF3 showed similar performance at the eight stations, indicating that T_{min} might not be a key factor influencing the accuracy of RF-based ETp models. Again, these two models performed better than RF2 which might denote that R_s instead of R_a was a more important factor for estimating ETp with RF-based ETp models.

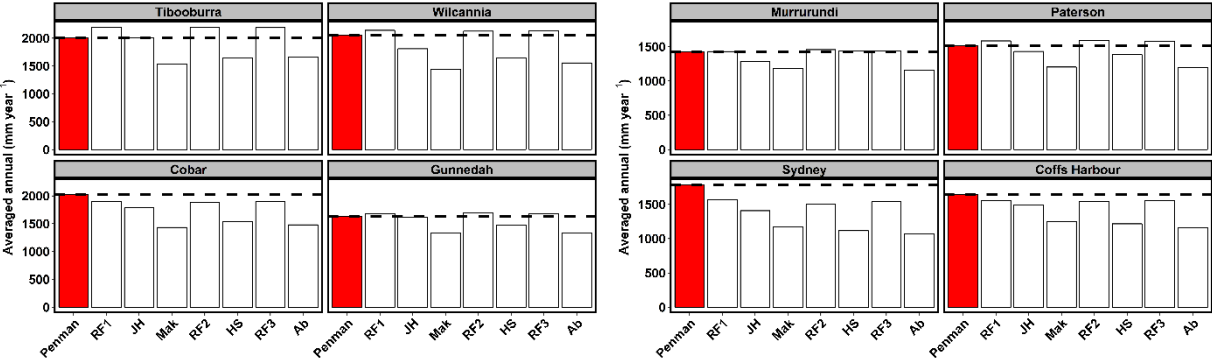


Figure 4-3 The average annual ETp (mm year⁻¹) calculated by eight ETp models for each station during the model testing period (2001 - 2014). The dashed lines and red bars indicate the average annual ETp calculated by the Penman-Monteith model.

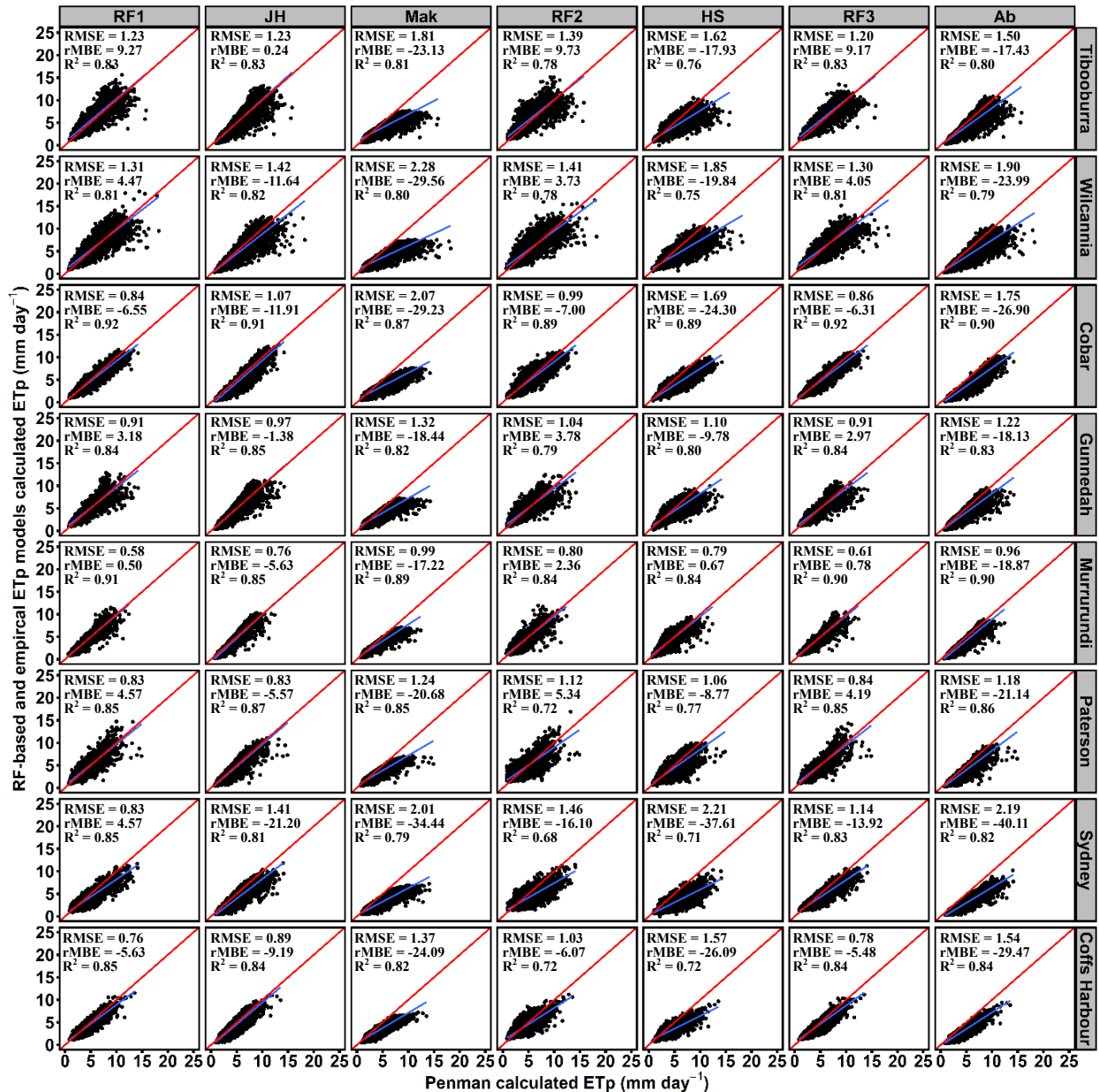


Figure 4-4. Scatter plots of the Penman-calculated daily ETp (mm day⁻¹) vs ETp calculated by RF-based and empirical ETp models during the model testing stage (2001 - 2014) for each of eight stations in New South Wales, Australia. The units for RMSE and rMBE are mm day⁻¹ and %, respectively. Blue lines are linear regression lines and red lines are 1:1 lines.

4.8.2 The change of climatic factors under future climate scenarios

Consistent increases were observed in T_{\max} (Figure 4-5a) and T_{\min} (Figure 4-5b) irrespective of RCP scenarios and stations. Specifically, the increases of mean T_{\max} ranged from 0.61 °C by the 2040s to 2.33 °C by the 2090s under RCP4.5 while the range for mean T_{\min} was 0.88 °C (2040s) to 2.02 °C (2090s). Under

RCP8.5, larger increases were found in both T_{\max} and T_{\min} than under RCP4.5 for a certain future period. For instance, the range of increases of mean T_{\max} and mean T_{\min} under RCP8.5 were 0.79 °C (2040s) to 4.58 °C (2090s) and 1.10 °C (2040s) to 4.39 °C (2090s), respectively. Moreover, as time increased into the future period, the increase in T_{\max} and T_{\min} became larger. Similar increasing trends were also found in R_s , independent of stations. Mean R_s (Figure 4-6a) was projected to increase by 0.08-0.32 MJ m⁻² day⁻¹ under RCP4.5 and 0.01-0.29 MJ m⁻² day⁻¹ under RCP8.5.

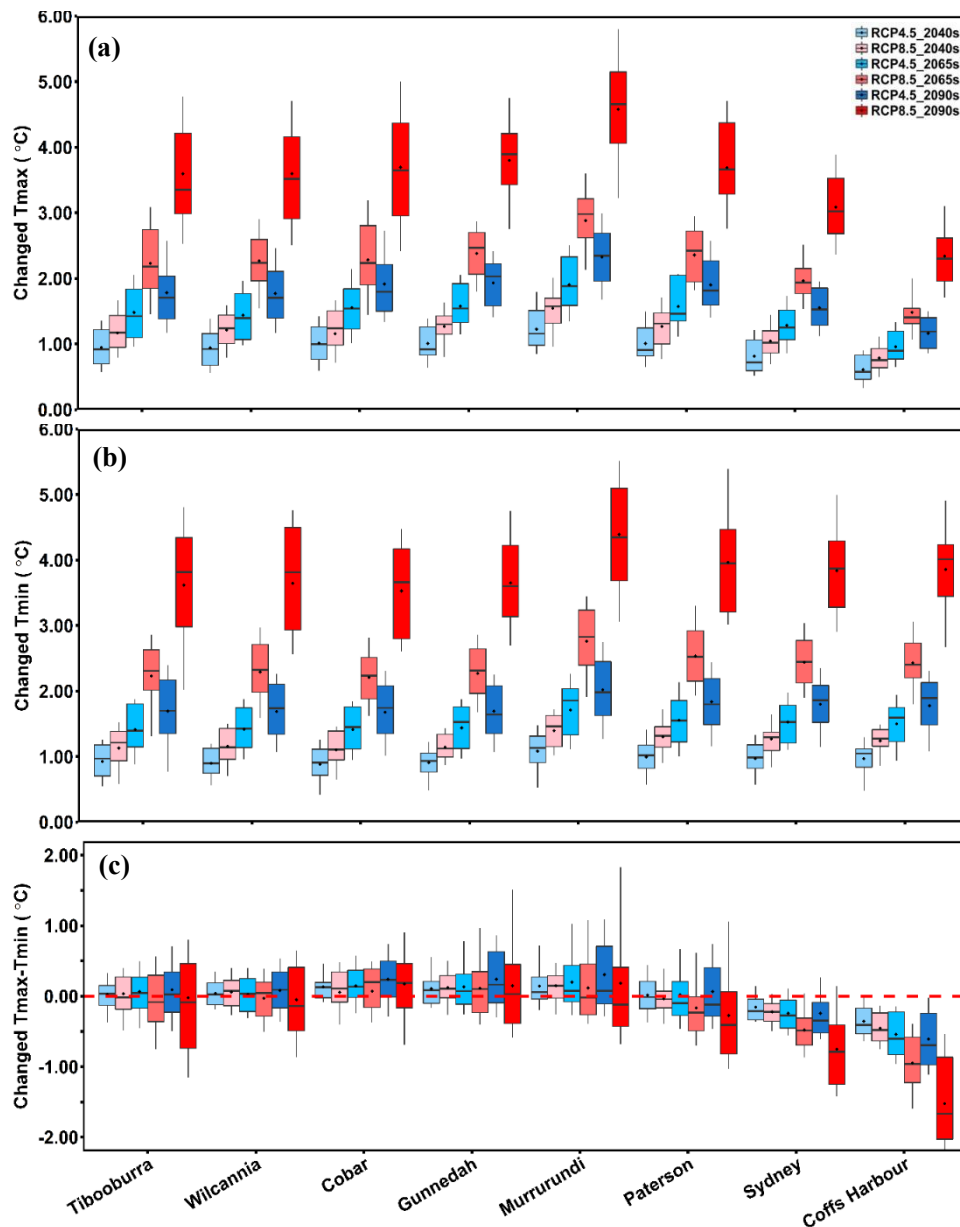


Figure 4-5. Projected changes in T_{max} ($^{\circ}C$), T_{min} ($^{\circ}C$), and $T_{max}-T_{min}$ ($^{\circ}C$) in the near future (2026 – 2050, 2040s), the medium future (2051 – 2075, 2065s), and the far future (2076 – 2100, 2090s) at eight stations in New South Wales, Australia, under RCP4.5 and RCP8.5 scenarios based on 34 GCMs compared with baseline values (1990 - 2014). Lower and upper box boundaries indicate the 25th and 75th percentiles, respectively. The black lines and dots inside the box mark the median and mean, respectively. The lower and upper whiskers indicate the 10th and 90th percentiles, respectively.

In contrast to the uniform increase in T_{max} and T_{min} was the obvious difference found among stations in the direction and magnitude of change of ΔT over time (Figure 4-5c). For instance, mean ΔT at Murrurundi increased by 0.14-0.31 $^{\circ}C$ under RCP4.5 and by 0.12-0.18 $^{\circ}C$ under RCP8.5 whereas it decreased by 0.36-

0.61 °C under RCP4.5 and by 0.45-1.52 °C under RCP8.5 at Coffs Harbour. ΔT is related to the degree of cloud cover (Allen et al., 1998) and is a good indicator of solar radiation and relative humidity (Allen et al., 1998; Kingston et al., 2009). In particular, ΔT is an important input for the HS model. The variance change of ΔT may influence the change of ET_p estimated by the HS model. There was no uniform direction in the change of rainfall over time (Figure 4-6b). The ranges of mean rainfall change were -34 mm year⁻¹ to 9 mm year⁻¹ under RCP4.5 and from -14 mm year⁻¹ to 26 mm year⁻¹ under RCP8.5.

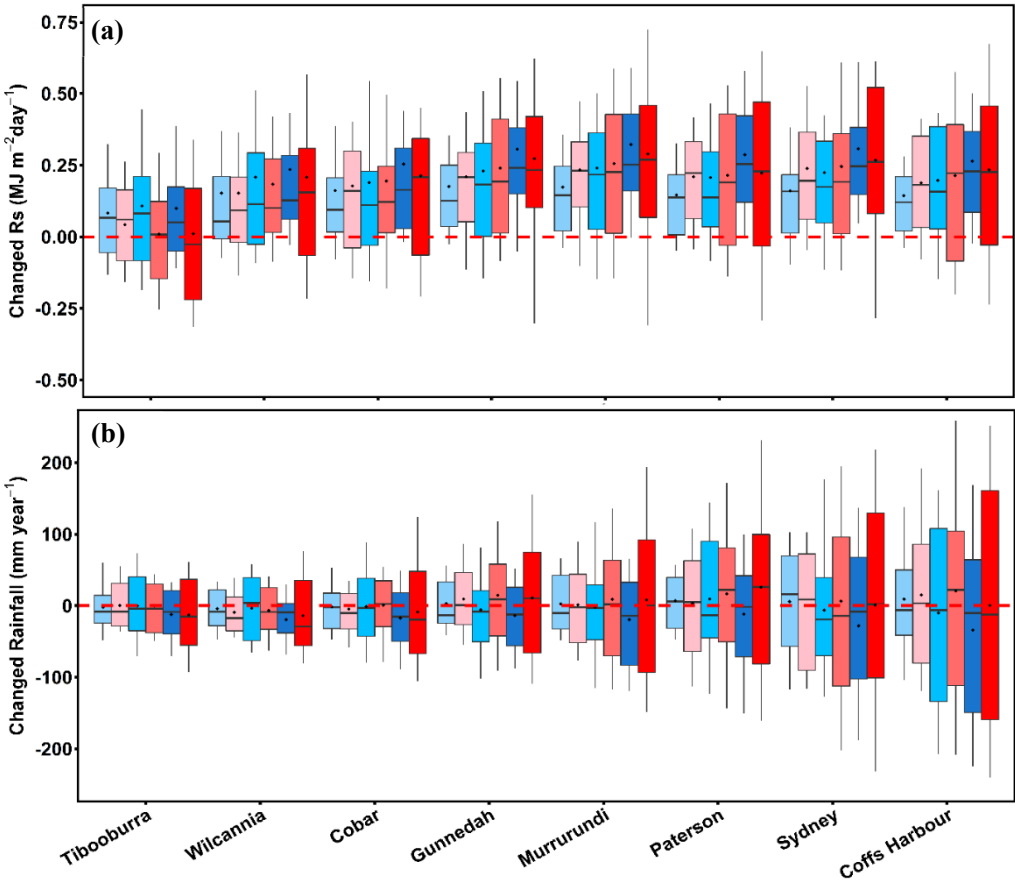


Figure 4-6. Projected changes in R_s ($\text{MJ m}^{-2} \text{ day}^{-1}$), and rainfall (mm year^{-1}) in the near future (2026 – 2050, 2040s), the medium future (2051 – 2075, 2065s), and the far future (2076 – 2100, 2090s) at eight stations in New South Wales, Australia, under RCP4.5 and RCP8.5 scenarios based on 34 GCMs compared with baseline values (1990 - 2014). Lower and upper box boundaries indicate the 25th and 75th percentiles, respectively. The black lines and dots inside the box mark the median and mean, respectively. The lower and upper whiskers indicate the 10th and 90th percentiles, respectively

4.8.3 ETp and its change under future climate scenarios

As expected, ETp estimated by all models showed obvious increases under RCP4.5 and RCP8.5 scenarios at all stations except Coffs Harbour where the HS-calculated ETp showed a slight change (Figure 4-7). However, both the future ETp (Figure 4-8) and the increasing magnitude showed large differences among ETp models for each station regardless of RCP scenarios. In general, RF-based models projected higher future ETp and larger increases than empirical ETp models did for all stations. For instance, RF1 generally projected the largest increase of mean ETp among models for a given future period, ranging from 49 mm year⁻¹ (3.2%, 2040s) to 164 mm year⁻¹ (11.7%, 2090s) under the RCP4.5 scenario, and from 64 mm year⁻¹ (4.1%, 2040s) to 346 mm year⁻¹ (24.1%, 2090s) under the RCP8.5 scenario. In contrast, mean ETp projected by Mak generally showed the smallest increase, ranging from 27 mm year⁻¹ (1.3%, 2040s) to 69 mm year⁻¹ (4.9%, 2090s) under RCP4.5, and from 28 mm year⁻¹ (1.4%, 2040s) to 113 mm year⁻¹ (8.0%, 2090s) under RCP8.5. Influenced by the change differences of T_{max} , T_{min} , and R_s (Figure 4-5a, 4-5b, and 4-6a, respectively), ETp projected by any given model also showed larger increases under the RCP8.5 scenario than under the RCP4.5 scenario for any given future period. Again, ETp increases became larger as time into the future period increased. The ensemble increases of mean ETp across eight stations ranged from 33 mm year⁻¹ (2.1%, 2040s) to 129 mm year⁻¹ (9.2%, 2090s) under RCP4.5, and from 43 mm year⁻¹ (2.8%, 2040s) to 248 mm year⁻¹ (17.6%, 2090s) under RCP8.5.

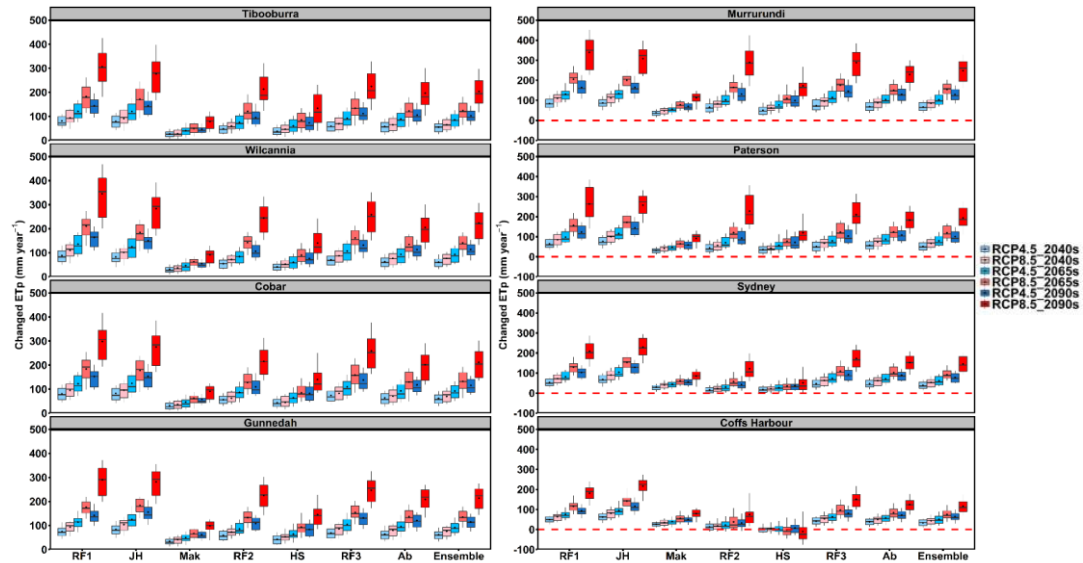


Figure 4-7. Projected ETp changes for eight stations in New South Wales, Australia in the near future (2026 - 2050, 2040s), the medium future (2051 - 2075, 2065s), and the far future (2076 - 2100, 2090s) under RCP4.5 and RCP8.5 scenarios based on 34 GCMs compared with baseline ETp (1990 - 2014). Lower and upper box boundaries indicate the 25th and 75th percentiles, respectively. The black lines and dots inside the box mark the median and mean, respectively. The lower and upper whiskers indicate the 10th and 90th percentiles, respectively.

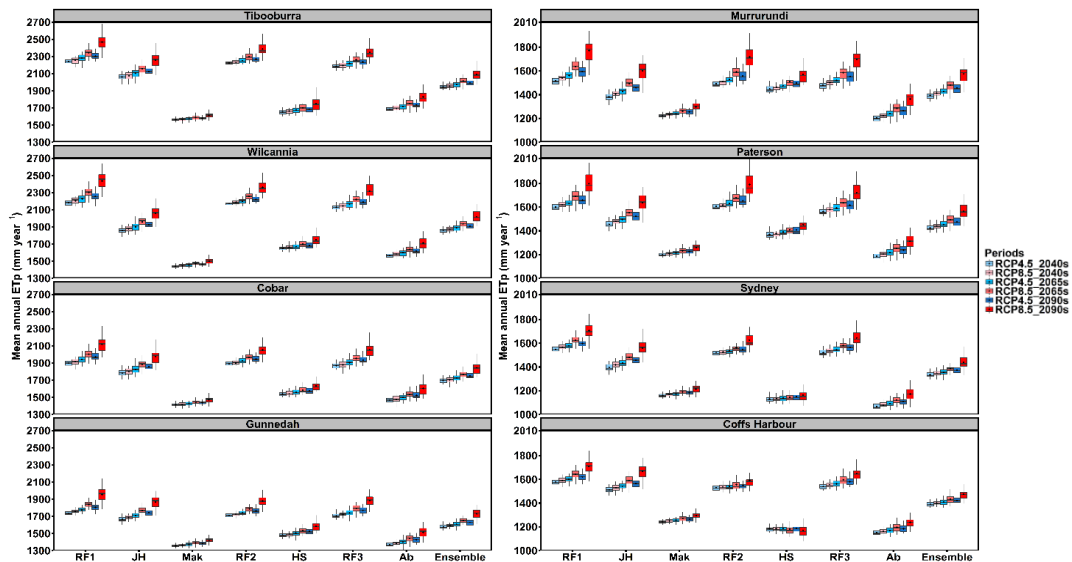


Figure 4-8 25-year mean annual ETp (mm year^{-1}) at eight stations for the near future (2026 – 2050, 2040s), the medium future (2051 – 2075, 2065s), and the far future (2076 – 2100, 2090s) under RCP4.5 and RCP8.5. Box boundaries indicate the 25th and 75th percentiles; the black lines and dots inside the box mark the median and mean, respectively; the lower and upper whiskers indicate the 10th and 90th percentiles, respectively.

4.8.4 Contribution of climatic factors to ETp change

The influence of a certain climatic factor on ETp change projection may be varied among ETp models. Guo et al. (2017) analyzed the sensitivity Penman-Monteith and Priestley-Taylor to different climatic factors with the use of global sensitivity analysis across different climatic zones in Australia. They found that temperature is the most important factor resulting in the changes of ETp in Australia. Models used in this thesis to project ETp under future climate scenarios are either temperature-based or radiation-based. Meanwhile, downscaled climatic data used in this study to project future ETp only included maximum and minimum temperatures, solar radiation. Thus, we only focused on the contribution of temperature and radiation, which can be more reliably projected by GCMs to changes of ETp under future climate scenarios.

In order to determine the relationships between the change of ETp and changes of meteorological factors, multiple linear regression was performed for each station using changes of T_{\max} , T_{\min} , R_s , and rainfall as independent variables and changes of ETp as the dependent variable. Our analysis showed that changes in T_{\max} , T_{\min} , R_s , and rainfall generally accounted for more than 92.0% of the ETp change, and the change of rainfall had only a slight influence in ETp for most stations (Figure 4-9). We also found that relationships between the change of T_{\max} , T_{\min} , and R_s and the change of ETp could be grouped based on the input requirements of ETp models. In general, compared with T_{\max} and T_{\min} , a unit increase of R_s led to a larger increase of ETp projected by RF1, JH, and Mak. In contrast, the largest ETp increases (ranging from 64.0 mm year⁻¹ to 116.7 mm year⁻¹) projected by RF2 and HS were caused by a unit increase of T_{\max} , while changes in T_{\min} and R_s were negatively related to ETp changes. Lastly, for RF3 and Ab, one unit increase in R_s and T_{\max} could contribute roughly equally to the change in ETp.

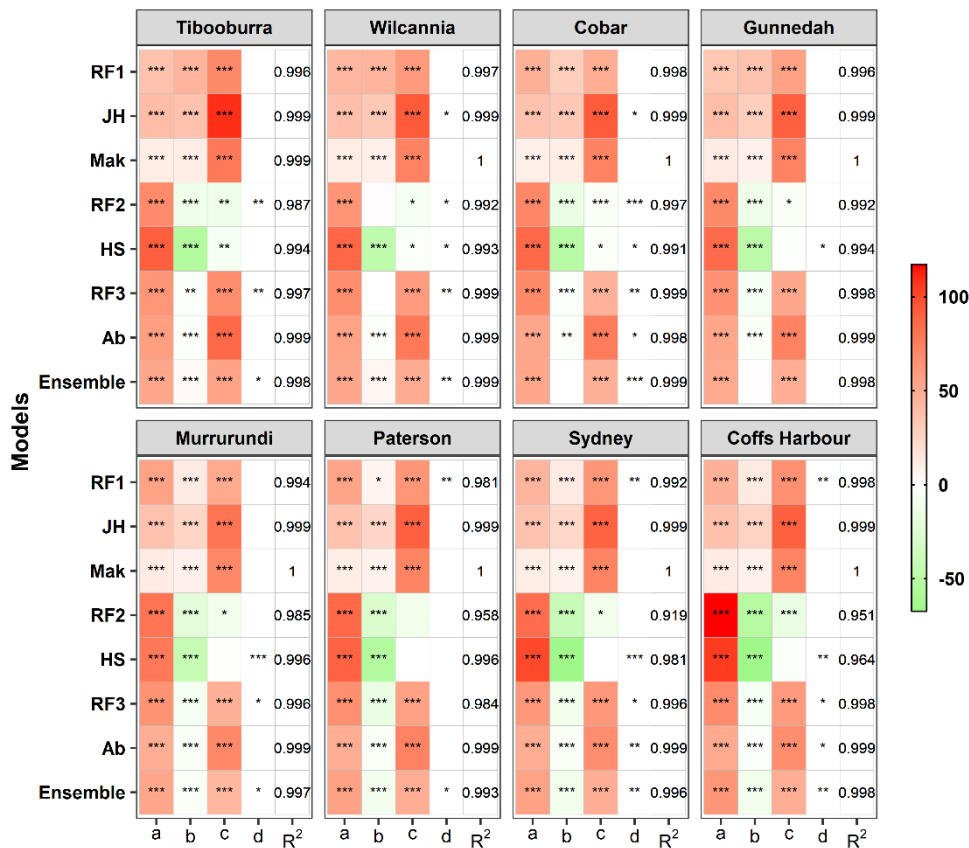


Figure 4-9 Regression coefficients for changes in ETp (ΔET_p , mm year⁻¹) with changes in maximum temperature (ΔT_{max} , °C), minimum temperature (ΔT_{min} , °C), solar radiation (ΔR_s , MJ m⁻² day⁻¹), and rainfall (ΔP , mm year⁻¹) in a multiple linear regression model ($\Delta ET_p = a \Delta T_{max} + b \Delta T_{min} + c \Delta R_s + d \Delta P$); units for a and b are mm year⁻¹ °C⁻¹; unit for c is mm year⁻¹ (MJ m⁻² d⁻¹)⁻¹; unit for d is mm year⁻¹ mm⁻¹. ***:p < 0.001, **:p < 0.01; *:p < 0.05

4.8.5 Contribution of different sources to the uncertainty of ETp projections

Both ranges of future ETp and ETp differences among models and RCP scenarios indicated the existing uncertainty in future ETp projections. Thus, we used ANOVA to quantify the relative contributions of GCMs, ETp models, and RCP scenarios to the uncertainty of ETp projections (Figure 4-10). The RCPs accounted for around 40.0% of the uncertainty of ETp projections at all stations except the humid stations (Sydney, Coffs Harbour), indicating the dominant role of RCPs in the uncertainty of ETp projections. Following RCPs, the contribution of GCMs to uncertainty ranged from 16.7% to 28.8% among the eight stations. The ETp models contributed less than 16.0% to uncertainty at most stations. However, at Sydney and Coffs Harbour, the contribution of ETp models to uncertainty was roughly equal to or even higher than that observed for RCPs.

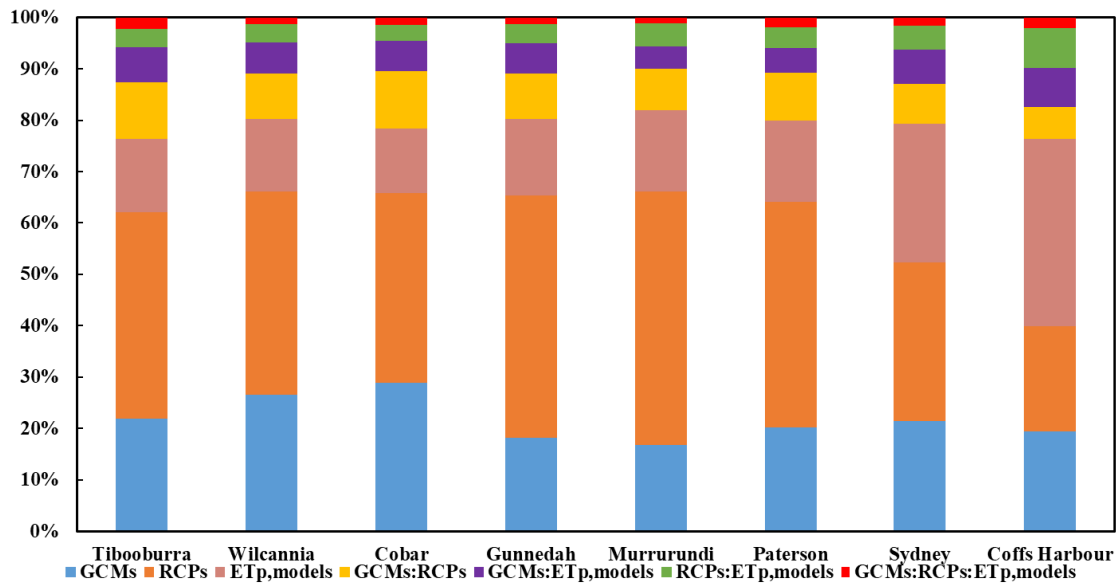


Figure 4-10. The contribution of uncertainty sources to the change of ETp.

4.9 Discussion

Our study found that RF-based models produced ETp values that were much closer to Penman-calculated ETp during the historical period, indicating that RF-based ETp models generally outperformed empirical ETp models (Figure 4-3 & Figure 4-4). For the empirical ETp models, JH-calculated ETp was close to RF-calculated ETp during both the historical and future periods, whereas the rest of the empirical ETp models produced relatively lower ETp (Figure 4-3, Figure 4-8). Though the use of RF-based models for projecting future ETp is rare, their good performance in estimating historical evapotranspiration has been reported by other researchers (Fan et al., 2018; Feng et al., 2017). For instance, Feng et al. (2017) compared the performance of RF-based and generalized regression neural networks (GRNN)-based models in estimating daily ET0 against the PM-FAO56 model based on two different input combinations. They found that the RF-based models (with R^2 ranging from 0.89 to 0.98) generally outperformed the GRNN-based models. Although there is no strong evidence to guarantee which model is more reliable for predicting future ETp (Kay and Davies, 2008), the use of RF-based ETp models is still advisable due to the following reasons. Firstly, these models have more flexibility for adding climatic inputs to improve their accuracy (Fan et al., 2018). Thus, when reliable climatic parameters are available, it is more feasible and efficient to train RF-based models than to calibrate empirical ETp models. Secondly, the testing and training of RF-based ETp models are more easily accomplished and it is possible to efficiently do cross-station validation. In contrast, one of the most commonly used methods to improve performance of simplified empirical models is to re-

calibrate the empirical coefficients based on a linear relationship against observed ET or Penman-Monteith-type models (Droogers and Allen, 2002; Tabari and Talaei, 2011). However, these coefficients are generally location-specific and may result in less accurate performance in another region. Even if empirical coefficients are calibrated for a certain station, the updated coefficients may vary with time due to climatic changes and variations (Nouri and Homaei, 2018).

ET_p projected by all models showed an overall increase under future climate scenarios and the increase was the largest at the end of the 21st century under the RCP8.5 scenario (Figure 4-7). The increases in T_{max} , T_{min} , and R_s all contributed to the upward trend of ET_p (Pan et al., 2015; Scheff and Frierson, 2014), as shown in Figure 4-9. Although ET_p increases under future climate scenarios have been widely reported (Dong et al., 2019; Gharbia et al., 2018; Pan et al., 2015; Scheff and Frierson, 2014; Tao et al., 2015; Wang et al., 2017b; Wang et al., 2015), large variances and uncertainties were observed in the magnitudes of the increases. At the global scale, Scheff and Frierson (2014) adopted the PM-FAO56 model with climatic data from 13 GCMs to project the future ET_p. They found ET_p generally increased 10.0% to 45.0% by the end of the 21st century. Also at the global scale, Pan et al. (2015) adopted the Dynamic Land Ecosystem Model to project future global terrestrial evapotranspiration under the A2 and B1 emission scenarios. They found that compared with the 2000s, terrestrial evapotranspiration by the 2090s would increase 14.0% under the A2 scenario and 4.5% under the B1 scenario. In the Shannon River catchment, Ireland, Gharbia et al. (2018) adopted the Hamon model with climatic data from multi-GCMs to project future ET_p and found that ET_p could increase up to 13.5% by the 2080s compared with ET_p in 1961-2014. In Australia, Johnson and Sharma (2010) used outputs from five GCMs to drive the PenPan model and projected open body water evaporation in the future. They claimed that the average increase in open body water evaporation in 2070 would be approximately 7% under the A2 scenario and 5% under the B1 scenario. In our study, the RF-based ET_p models generally produced a roughly comparable increase in ET_p to that of the above-mentioned studies, ranging from 2.1% to 11.7% under RCP4.5 and from 4.8% to 24.1% under RCP8.5 by the end of 21st century. As CSIRO and BOM (2015) indicated, there was high confidence in the increase of ET_p during this time period, but only medium confidence was found for the magnitude of the increase.

The large uncertainty in future ET_p projections may be due to differences in GCMs (Teng et al., 2012), ET_p models (Kingston et al., 2009), and RCPs (Wilby and Harris, 2006). Our study found that the dominant reason leading to uncertainty in ET_p projection was attributable to the differences in the RCP scenarios, accounting for around 40% of the uncertainty (Figure 4-10). This result is likely due to the fact that predicted

changes of the major inputs (e.g., T_{\max} , T_{\min} , and R_s) for ETp models were clearly different under the different RCPs (Figure 4-5 & Figure 4-6). It is well known that the GCMs we used in this study project raw monthly climatic data such as air temperature and solar radiation that include uncertainties and biases that are attributable to differences between GCMs and climate variables. However, we applied an improved statistical downscaling method (Liu and Zuo, 2012) that effectively corrected biases in the GCM-projected climate variables and matched observed climate while preserving the inter-annual and intra-seasonal variabilities of GCM projections (Liu et al., 2017). This approach effectively minimized the additional uncertainty from the downscaling method while the projected climate change signals were maintained for our analysis of GCM uncertainties. In addition, we also found that the predictions of both climatic factors (Figure 4-5 & Figure 4-6) and ETp (Figure 4-7 & Figure 4-8) showed wider ranges under RCP8.5 than under RCP4.5, especially for the 2090s. This might indicate that GCMs behaved more differently from each other under RCP8.5 in the future (Shen et al., 2018), which might also contribute to the dominant role of RCPs in uncertainty of ETp projection. Following RCPs, GCM-related and ETp model-related uncertainty contributed roughly equally to ETp uncertainty, ranging from 10% to 30% (Figure 4-10). Similar to our results, Kingston et al. (2009) projected global ETp with six alternative ETp models driven by data from five GCMs. They found that ETp model-related uncertainty was of a similar magnitude or, in some cases, greater than GCM-related uncertainty. Since ETp is an important input to hydrological models, the uncertainty in ETp projection may also influence hydrological projections (Thompson et al., 2014), thus reducing the confidence in predictions of water availability in the future. To deal with the uncertainty in future ETp projections, we recommend using multiple GCMs to drive various ETp models under different RCP scenarios, so that a relatively reliable projection is produced.

Quantifying the future increase in ETp can provide insights into future water availability and agricultural production in NSW. For instance, increased ETp indicates that atmospheric evaporative demand will be higher under future climate scenarios. However, both our study (Figure 3e) and other studies (Chiew et al., 2009; Vaze and Teng, 2011) suggested that annual rainfall in NSW will not show significant increases in the future. With the combined influence of increasing ETp and normal or even decreased rainfall, there is a high possibility that runoff in NSW would decrease and this region would be drier (Teng et al., 2012). As Nicholls (2004) put it, rising temperatures and increasing ETp, even without decreasing rainfall, would increase the severity of droughts in Australia. Similarly, Feng et al. (2018a) projected changes of drought across the wheat belt of NSW with climatic data from 28 GCMs under RCP8.5. They found that decreasing rainfall combined

with increasing temperature may lead to an expansion (from west to east) of the winter-spring drought-prone areas. Furthermore, we found that the increase in ET_p at the traditionally arid stations (e.g. Tibooburra and Wilcannia, Figure 4-7) was larger than at the humid stations (e.g., Sydney & Coffs Harbour, Figure 4-7), which might indicate that the traditionally dry areas might become drier at a faster rate than the humid areas.

One limitation of this study is that we did not consider the influence of increasing atmospheric CO₂ on stomatal conductance. A higher CO₂ concentration will result in greater surface resistance (r_s). This may offset the magnitude of the ET_p increases caused by the warming climate. In a recent study, Yang et al. (2019) developed an equation to describe the relationship between r_s and atmospheric CO₂ concentration. Based on the equation, they revised the PM-FAO56 model to consider the influence of increasing atmospheric CO₂. Their research offered a new perspective to assess the comprehensive impact of climate change on ET_p and should be considered in future studies.

4.10 Conclusions

This study developed RF-based ET_p models and assessed their performance against four empirical ET_p models (JH, Mak, HS, and Ab), with the Penman-calculated ET_p as a benchmark. The random forest-based models and the four empirical ET_p models were used to project ET_p at eight stations across NSW using climatic data from 34 GCMs under the RCP4.5 and RCP8.5 scenarios. Study results indicated that random forest-based models generally outperformed the empirical ET_p models in estimating historical daily Penman ET_p. Contrary to empirical ET_p models, which was generally developed for a certain climate, random forest models is easy to be trained at any kind of climate. Thus, the use of random forest method in ET_p or drought projection is promising not only in arid regions like Australia but also any other regions in the world. All of these models projected that ET_p would increase over time. However, the increased ET_p estimates produced by the random forest-based models better matched results obtained in other studies. The ensemble increases of mean ET_p across eight stations ranged from 33 mm year⁻¹ (2.1%, 2040s) to 129 mm year⁻¹ (9.2%, 2090s) under RCP4.5, and from 43 mm year⁻¹ (2.8%, 2040s) to 248 mm year⁻¹ (17.6%, 2090s) under RCP8.5. Furthermore, differences in RCPs accounted for around 40% of the uncertainty in future ET_p projections due to the great disparity in the expected temperature increases among the different emission scenarios. The large uncertainty in the projected increases of ET_p highlights the necessity of adopting multiple model ensemble to project future ET_p under different RCPs so that more reliable projections can be produced.

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Chapter 5. Quantifying future drought change and associated uncertainty in southeastern Australia with multiple potential evapotranspiration models

This chapter is based on the following publication:

Lijie Shi, Puyu Feng, Bin Wang, De Li Liu, and Qiang Yu. "Quantifying future drought change and associated uncertainty in southeastern Australia with multiple potential evapotranspiration models." *Journal of Hydrology*, 590 (2020), DOI: <https://doi.org/10.1016/j.jhydrol.2020.125394>

Abstract: Projection of drought under a changing climate is important for drought risk assessment. Changes in precipitation (P) and potential evapotranspiration (ET_p) are expected to influence future drought occurrence. Thus, it is important to include both factors to accurately quantify change in drought frequency under future climate scenarios. Standardized precipitation evapotranspiration index (SPEI) is a widely used index in drought assessment because it considers the influence of both P and ET_p on drought. Thus, in this study we used SPEI to quantify change in drought frequency under two different emission scenarios (RCP4.5 and RCP8.5) in the wheat belt of southeastern Australia with climatic data downscaled from 34 global climate models (GCMs). We also investigated whether differences in ET_p models would make a difference on drought projection. Therefore, we employed five different traditional ET_p models (Penman, Jensen-Haise, Makkink, Abtew, Hargreaves) and three random forest (RF)-based models to calculate SPEI in this study. Results showed that drought, especially moderate and severe drought, would occur more frequently under future climate scenarios and the increased frequency was generally greater in spring and winter than in summer and autumn. Severe drought occurring in spring would increase by 3.1% – 21.7% under RCP4.5 and 5.2% – 41.0% under RCP8.5. In autumn, the likely mean increase of severe drought frequency was 0.7% – 13.0% under RCP4.5 and 2.7% – 27.9% under RCP8.5. Differences in the projected increase of drought frequency were found among the different ET_p models. In general, RF-based ET_p models, which projected larger increases in ET_p, generally also projected larger increases in drought occurrence. A multilinear regression relationship was built between changes in drought frequency and changes in ET_p and P. The regression showed that the increased drought frequency was a combined result of the increasing ET_p and decreasing P, and that the increasing ET_p might be the more dominant factor. The contribution of GCMs, RCPs, different ET_p models, and their interaction to the uncertainty in drought projection was quantified with the use of analysis of variance. Results showed that GCMs and their interaction with RCPs were the

dominant factors influencing uncertainty in drought projection.

Keywords: Standardized precipitation evapotranspiration index; drought projection; climate change; potential evapotranspiration model; uncertainty

5.1 Introduction

Drought is a recurring and insidious extreme climate event, which is primarily induced by a prolonged period of deficiency in precipitation (Asadi Zarch et al., 2015). In general, drought can be classified as meteorological (prolonged period of shortage in precipitation), agricultural (insufficient soil moisture to meet crop growth), hydrological (shortage of ground and surface water), or socioeconomic drought (failure of water resource systems to meet demands of people and their activities) (Ayantobo et al., 2017). These droughts can occur in almost all climatic regimes and cause various kinds of damage to human society, such as reduced water supply and crop failure (Asadi Zarch et al., 2015; Mishra and Singh, 2010). For example, the 2006 drought in Australia reduced winter cereal crop production by 36% and resulted in economic loss of AUD\$3.5 billion (Wong et al., 2009). Given that increases in air temperature and changes in patterns of precipitation can influence the occurrence of drought events (Mishra and Singh, 2010; Svoboda et al., 2012), it is necessary to project the likely change in drought occurrence due to climate change so that agricultural producers and policy makers can take actions to mitigate its dire impacts.

The most common method to study drought change is adopting appropriate drought indices. In general, a drought index is a prime variable derived from one or multiple meteorological or hydrological factors, such as precipitation (P), temperature (T), and potential evapotranspiration (ET_p) (Asadi Zarch et al., 2015). It is estimated that more than 160 drought indices have been developed to detect, monitor, and characterize different types of drought (Niemeyer, 2008). Among them, the widely used drought indices include the Rainfall Anomaly Index (RAI), the Standardized Precipitation Index (SPI), the Reclamation Drought Index (RDI), and the Palmer Drought Severity Index (PDSI). Each of these indices has its strengths and weaknesses. For instance, SPI can monitor drought at various timescales, ranging from one month to 72 months (McKee et al., 1993). However, SPI is based on precipitation alone and fails to consider other variables such as temperature that may also trigger drought events (Svoboda et al., 2012). Thus, SPI may not be suitable for identifying possible changes in drought occurrence and severity under a changing climate, as increasing temperature can have significant effects on drought severity (Vicente-Serrano et al., 2010). In contrast, PDSI is generally cited as a physical index based on soil moisture balance. However, PDSI shows low sensitivity

to the variation of ETp because of the standardization procedure of soil water budget anomalies (Cook et al., 2014; Vicente-Serrano et al., 2015), which may make PDSI less suitable under the scenario where ETp changes are considered.

In the last decade, the standardized precipitation evapotranspiration index (SPEI), based on the balance between P and ETp (Vicente-Serrano et al., 2010), has been widely used in drought assessment (Potop et al., 2012; Stagge et al., 2015; Vicente-Serrano et al., 2010). The inputs of SPEI are similar to the dryness index (DI), which is also known as aridity index (AI) (Creed and Spargo, 2012; Feng et al., 2016). However, DI is calculated as the ratio of precipitation and ETp, and is generally used to describe the climate of a certain region as dry or wet (Roderick et al., 2015; Sahin, 2012). Thus, this study did not include the discuss of DI. Compared with PDSI, SPEI shows equal sensitivity to precipitation and ETp (Vicente-Serrano et al., 2015). Therefore, it might be a better choice for investigating the influence of different ETp models on drought projection. In addition, the multi-scalar characteristics of SPEI enable it to identify different drought types and effects under a changing climate (Vicente-Serrano et al., 2010). Relatively short-term precipitation anomalies generally influence soil moisture conditions, while longer-term precipitation anomalies influence streamflow (Svoboda et al., 2012). Thus, 1- or 2-month SPEI is generally used to assess meteorological drought; anywhere from 1-month to 6-month SPEI is used for agricultural drought (Labudová et al., 2017; Parsons et al., 2019); and any other longer-term SPEI is able to assess hydrological drought (Beguería et al., 2014; Svoboda et al., 2012). The use of 3-month SPEI in seasonal agricultural drought assessment is common in literature (Feng et al., 2018a; Feng et al., 2019; Gao et al., 2017). Feng et al. (2019) combined remotely-sensed factors with 3-month SPEI and found that wheat yields showed high correlation with the 3-month SPEI-assessed drought conditions in southeastern Australia. Based on both 3-month and 12-month SPEI, Yu et al. (2014) assessed changes of drought characteristics from 1951 to 2010 in China and concluded that severe and extreme drought areas have increased by ~3.72% per decade since the 1990s.

Despite the extensive usage of SPEI, there is still controversy regarding which equation should be used to estimate ETp (Beguería et al., 2014; Sheffield et al., 2012; Stagge et al., 2014). Originally, Vicente-Serrano et al. (2010) suggested the use of the Thornthwaite (Th) equation, which only requires monthly mean temperature (Thornthwaite, 1948). However, recent studies have indicated that the Th equation underestimates ETp in arid and semiarid regions and overestimates ETp in humid equatorial and tropical regions (Kumar et al., 1987; Valipour, 2015). Moreover, this equation leads to an overestimation of ETp with increasing air temperature and might not be suitable for climate change studies (Sheffield et al., 2012). Yao

et al. (2019) compared the effects of different ETp models on drought assessment based on SPEI in China. They found that the differences of ETp models had greater effects on drought assessment in arid regions than in humid regions. Similarly, Beguería et al. (2014) analyzed the sensitivity of SPEI to three different ETp models and also found that drought assessment was more affected by ETp model choice in arid areas. Thus, selecting an appropriate model to estimate ETp is of great importance for obtaining reliable drought assessment. The physically-based Penman model can normally estimate ETp with high accuracy, but it requires multiple climatic factors as inputs that are sometimes not available. Other empirical models require less input information but are inevitably limited in accuracy. Recently, machine learning methods have gained attention and have shown good performance in ETp estimation (Fan et al., 2018; Shi et al., 2020). For instance, Tabari et al. (2012) developed multiple machine learning methods including support vector machines (SVM), adaptive neuro-fuzzy inference system (ANFIS), multiple linear regression (MLR), and multiple non-linear regression (MNLR) to estimate reference evapotranspiration in Iran. They found that SVM and ANFIS showed better performance than empirical evapotranspiration models when provided with the same input information. However, to the best of our knowledge, there is no study that has been conducted to investigate the influence of ETp estimated by machine learning-based methods on drought assessment with SPEI.

Another problem related to future drought projections is uncertainty (Touma et al., 2015). Climate projections, emission scenarios, and drought indices can all result in uncertainties in drought projections. Quantifying the sources of uncertainty throughout the entire process is crucial for reliable climate change impact assessment (Burke and Brown, 2008; Lu et al., 2019; Taylor et al., 2012). Burke and Brown (2008) projected global changes in drought based on four indices under two different CO₂ scenarios. They found that the increase of areas affected by drought varied from 5% to 45% among different indices, which indicated that there are large uncertainties in future drought projections from drought indices. Similarly, Touma et al. (2015) adopted SPI, the Standardized Runoff Index (SRI), SPEI, and the Supply-Demand Drought Index (SDDI) with data from 15 GCMs to project change in drought under RCP8.5 at global scale. In their study, drought changes projected by SPEI and SDDI were stronger than changes projected by SPI and SRI, demonstrating index-related uncertainty in drought projection. In addition to drought indices, the differences in climate projections, emission scenarios, and ETp models may also result in uncertainty in drought assessment (Aryal et al., 2019; Shi et al., 2020). Lu et al. (2019) projected changes of drought based on soil moisture anomalies using climate data from 17 global climate models (GCMs) and found that the GCMs contributed more than 80% to the uncertainty in the process. However, the contribution of different ETp

models to uncertainty in drought projections has rarely been investigated.

The wheat belt in New South Wales (NSW) in southeastern Australia is vulnerable to drought. Under a warming climate, drought is likely to occur more frequently in the future (Feng et al., 2018a; Feng et al., 2019; Kirono et al., 2011; Kirono and Kent, 2011). For instance, based on the 3-month SPEI, Feng et al. (2018a) projected that more frequent and more severe winter-spring droughts were likely to occur in this region, and that these droughts will affect more areas. Similarly, Kirono et al. (2011) adopted RDI with climatic data from 14 GCMs to project drought in Australia and found that more occurrences of drought were likely to happen across NSW in the future. However, these studies generally focused on the projection of future drought without quantifying the uncertainty in their projections. Therefore, not only was our study designed to better understand future changes in drought under different future climate scenarios, but it was also designed to assess the associated uncertainties of future drought projections. An additional objective of our study was to use SPEI driven by different ETp models with climatic data downscaled from multiple GCMs under different emission scenarios (RCPs) to investigate the influence of ETp models on drought projection. Our objective was to answer three questions:

- (1) How do different ETp models influence SPEI at different locations in southeastern Australia?
- (2) How will drought be changing in the future under different scenarios?
- (3) What is the dominant factor determining the uncertainty of future drought projections?

5.2 Study sites

The study was designed to assess the effects of climate change on drought in the New South Wales (NSW) wheat belt, in southeastern Australia. Winter wheat (*Triticum aestivum* L.) grown in this region accounts for 28% of the total wheat-planted area in Australia (Feng et al., 2019). However, this region is vulnerable to climate change due to its diverse climate conditions (Wang et al., 2018). In the past decades, wheat yield showed high variation, ranging from 0.62 t ha⁻¹ to 2.75 t ha⁻¹, mainly as a result of precipitation variability and drought occurrence (Wang et al., 2015). Therefore, accurate drought projections for this region will be important for predicting both the economy and food supply of NSW.

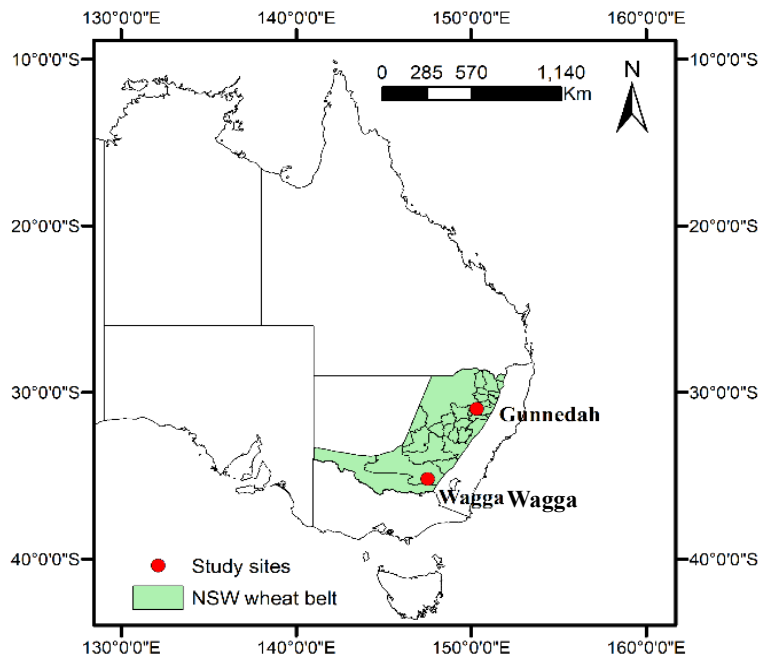


Figure 5-1 Location of the two study sites in the wheat belt of New South Wales (NSW), Australia.

Temperature in the NSW wheat belt generally increases from the southeast to the northwest while precipitation gradually increases from the southwest to the southeast (Feng et al., 2018a). Gunnedah (31.0°S, 150.3°E) and Wagga Wagga (35.2°S, 147.5°E) are two representative sites in the NSW wheat belt (Figure 5-1) that are located in the northeast and southeast, respectively. More importantly, these two sites have long-time series of observed climatic data, including air temperature, solar radiation, relative humidity, precipitation, and wind speed. Both sites experience hot summers and cold winters, but differ in air temperature and annual precipitation. Gunnedah is warmer than Wagga Wagga, with temperature ranging from 12.2 °C to 24.6 °C compared with temperature at Wagga Wagga ranging from 8.9 °C to 22.2 °C. Average annual precipitation values at Gunnedah and Wagga Wagga are 640 mm and 583 mm, respectively. Detailed information for these two sites is shown in Table 5-1.

Table 5-1 Geographical and long-term averaged meteorological information for Gunnedah and Wagga Wagga, Australia. The geographical information includes longitude (Lon), latitude (Lat), and elevation (DEM). The meteorological information includes air temperature (T), solar radiation (Rs), relative humidity (RH), wind speed (Wind), precipitation (P), and potential evapotranspiration (ETp).

Sites	Lon (degrees)	Lat (degrees)	DEM (m)	T (°C)	Rs (MJ m ⁻² d ⁻¹)	RH (%)	Wind (m/s)	P (mm)	ETp (mm)	Period
Gunnedah	150.3	-31.0	307	18.5	18.6	63.2	1.8	640	1650	1951-2014
Wagga Wagga	147.5	-35.2	212	15.5	17.5	67.2	2.0	583	1522	1950-2014

5.3 Climatic data

Historical climatic data and future climate scenarios were used to drive ETp models and then for subsequent calculation of the SPEI. For the historical period, observed daily precipitation (P, mm), maximum and minimum air temperature (T_{\max} and T_{\min} , °C), maximum and minimum relative humidity (%), and solar radiation (R_s , MJ m⁻² day⁻¹) at the two sites were obtained from the Scientific Information for Land Owners (SILO) patched point dataset (<https://www.longpaddock.qld.gov.au/silo/datadrill/index.php>) (Jeffrey et al., 2001). Historical observed daily wind speed (m s⁻¹) at these sites was obtained from the Bureau of Meteorology (BOM, <http://www.bom.gov.au/>). Climatic data for future climate scenarios was obtained using a statistical downscaling method developed by Liu and Zuo (2012) to extract daily T_{\max} , T_{\min} , P, and R_s in the period of 1900 to 2100 from 34 GCMs under the RCP4.5 and RCP8.5 scenarios. A bias correction was conducted to ensure that downscaled GCM climatic data matched well with the historical climatic data (Liu and Zuo, 2012). In this study, we compared the SPEI driven by downscaled GCM data with SPEI driven by observed climate data in the historical period (1971-2010), using a qq-plot technique. Results showed that the simulations with downscaled GCM data matched well with the observations, as shown in Figure 5-2. The downscaled data were divided into three periods, namely the baseline period from 1971 to 2010, the near future period from 2021 to 2060 (2040s), and the further future period from 2061 to 2100 (2080s).



Figure 5-2 The qq-plots between simulated SPEI driven by downscaled climatic data from 34 GCMs and observed SPEI driven by observed climatic data from SILO at Gunnedah (the upper panels, a) and Wagga Wagga (the bottom panels, b) under RCP4.5 (left panels) and RCP8.5 (right panels) scenarios. RF1, RF2, and RF3 (random forest models 1, 2, and 3, respectively); JH (Jensen-Haise); Mak (Makkink); HS (Hargreaves); Ab (Abteu). Abbreviations above the individual panels refer to specific GCMs.

5.4 Calculation of potential evapotranspiration

When air temperature, relative humidity, solar radiation, and wind speed are all available, the Penman model is able to accurately estimate ETp (Milly and Dunne, 2016), and has been widely used as a benchmark to estimate performance of other simplified ETp models (Donohue et al., 2010). However, future projections of climatic data downscaled from GCMs, such as wind speed and relative humidity, may not be available or may have low reliability, thereby limiting the use of the Penman model (Guo et al., 2017). In contrast, simplified ETp models such as temperature-based and radiation-based models may have more advantages for future ETp projection because of greater confidence associated with downscaled air temperature than for other climatic data (Randall et al., 2007). In this study, the physically-based Penman model (Penman, 1948), the radiation-based Jensen-Haise (JH), Makkink (Mak), and Abtew (Ab) models, and the temperature-based Hargreaves (HS) model were used to estimate daily ETp. Their mathematical equations are shown in Table 5-2.

Table 5-2 Potential evapotranspiration (ETp) models used in this study. The Penman model was used as the benchmark to develop and train the RF-based models and to assess the performance of the RF-based and the empirical ETp models. ETp estimated by the four empirical ETp models was compared with ETp estimated by the RF-based models which required the same inputs. Specifically, JH and Mak were compared with RF1; HS was compared with RF2; and Ab was compared with RF3.

Model	Reference	Formula
Penman	Donohue et al. (2010)	$ET_p = \frac{0.408\Delta}{\Delta + \gamma} (R_n - G) + \frac{\gamma}{\Delta + \gamma} \frac{6.43(1 + 0.536u_2)(e_s - e_a)}{\lambda}$
Abtew	Abtew (1996)	$ET_p = 0.01786 \frac{R_s T_{\max}}{\lambda}$
Hargreaves	Hargreaves et al. (1985)	$ET_p = 0.0023 \times 0.408 R_a (T_{\max} - T_{\min})^{0.5} (T + 17.8)$
Jensen-Haise	Jensen and Haise (1963)	$ET_p = 0.0102 (T + 3) R_s$

$$ETp = 0.7 \frac{\Delta}{\Delta + \gamma} \frac{R_s}{\lambda}$$

Note: Δ (kPa °C⁻¹): the slope of the saturation vapor pressure curve; γ (kPa °C⁻¹): the psychrometric constant; R_n (MJ m⁻² day⁻¹): net radiation; G (MJ m⁻² day⁻¹): soil heat flux density, assumed to equal to zero for periods of a day or longer (Allen et al., 1998); u_2 (m s⁻¹): wind speed at 2 m height; e_s (kpa): saturation vapor pressure; e_a (kpa): actual vapor pressure; λ (MJ kg⁻¹): the latent heat of vaporization of water, equal to 2.45 MJ kg⁻¹ at 20 °C; T_{max} (°C): maximum air temperature; T_{min} (°C): minimum air temperature; T (°C): air temperature; R_s (MJ m⁻² day⁻¹): solar radiation; R_a (MJ m⁻² day⁻¹): extra-terrestrial radiation.

In addition to these traditional ETp models, we also developed machine learning-based ETp models with the use of the random forest (RF) method. RF has been widely used in evapotranspiration estimation (Fan et al., 2018; Feng et al., 2017). One of the advantages of the RF method is that it only requires two parameters to train the model: the number of decision trees (n_{tree}) and the number of variables (m_{try}) (Breiman, 2001). Three RF-based (RF1, RF2, and RF3) ETp models were developed based on different input combinations to compare with the traditional ETp models. RF1 required the same input as JH and Mak (T_{max} , T_{min} , and R_s); RF2 required the same input as HS (T_{max} , T_{min} , and R_a [extra-terrestrial radiation]); and RF3 required the same input as Ab (T_{max} and R_s). The historical climate data (1950/1951-2014) were separated into a set to train the RF models (1950/1951 to 2000) and a set to test the RF models (2001 to 2014). In the training process, n_{tree} was set as 500 to guarantee that every input row would be predicted a few times. The value of m_{try} was set as 2 for RF1 and RF2, and 1 for RF3 based on the rule that m_{try} is generally around 1/3 of the number of input variables (Guio Blanco et al., 2018). More information on the development of RF models can be found in Breiman (2001). The “randomForest” package in R (Liaw and Wiener, 2002) (<https://cran.r-project.org/web/packages/randomForest/index.html>) was used to develop RF-based ETp models in this study.

5.5 Calculation of standardized precipitation evapotranspiration index

The SPEI was developed by Vicente-Serrano et al. (2010) based on a monthly climatic water balance, (i.e., $P - ETp$), and therefore SPEI accounts for the influence of water demand on drought. In this study, five traditional (Penman, JH, Mak, HS, and Ab) and three machine learning-based (RF1, RF2, and RF3) models were used to estimate daily ETp. The monthly ETp was the accumulation of daily ETp. ETp values estimated from these models were used to calculate SPEI in order to investigate the influence of different ETp models on drought assessment with SPEI. Similar to SPI, SPEI can also be used to assess drought at different time

scales (Potop et al., 2012). Three months with P-ET_p significantly lower than the normal level will generally result in a decrease in soil moisture, thus leading to crop failure and the occurrence of agricultural drought (Vicente-Serrano et al., 2011). Therefore, a 3-month SPEI can describe soil water conditions during crop growing seasons. In this study, a 3-month time period was used to calculate seasonal SPEI based on the accumulated monthly water balance. For instance, spring SPEI was based on the accumulated water balance from September to November while summer SPEI was based on the accumulated water balance from December to February.

In specific, the calculation of SPEI is described as following:

(1) Calculation of monthly water balance:

$$D_j = P_j - ETp_j \quad (5-1)$$

where, P_j (mm) and ETp_j (mm) are the total precipitation and ETp of the j -th month, respectively.

(2) Calculation of the 3-month accumulated water balance for seasonal SPEI calculation

$$\begin{cases} X_{i,j}^3 = \sum_{l=10+j}^{12} D_{i-1,l} + \sum_{l=1}^j D_{i,l} & \text{if } j < 3 \\ X_{i,j}^3 = \sum_{l=j-2}^j D_{i,l} & \text{if } j \geq 3 \end{cases} \quad (5-2)$$

where $X_{i,j}^3$ is the 3-month accumulated water balance in the j -th month of the i -th year; in this study, j is in 11 (November for spring), 2 (February for summer), 5 (May for autumn), and 8 (August for winter). $D_{i,l}$ is the monthly water balance in the l -th month of i -th year.

(3) Normalize the $X_{i,j}^3$ data sequence with the three-parameter log-logistic probability distribution recommended by Vicente-Serrano et al. (2010). The accumulative function of the log-logistic probability distribution $F(X)$ is expressed as:

$$F(X) = \left[1 + \left(\frac{\alpha}{X - \gamma} \right)^\beta \right]^{-1} \quad (5-3)$$

where α , β , and γ are scale, shape, and position parameters, respectively. They could be calculated with equations suggested by Vicente-Serrano et al. (2010).

p is the probability of a definite $X_{i,j}^3$ value:

$$p = 1 - F(X) \quad (5-4),$$

$$\text{if } p \leq 0.5, \quad w = \sqrt{-2 \ln p}, \quad SPEI = w - \frac{C_0 + C_1 w + C_2 w^2}{1 + d_1 w + d_2 w^2 + d_3 w^3},$$

$$\text{if } p > 0.5, \quad w = \sqrt{-2 \ln(1-p)}, \quad \text{SPEI} = \frac{C_0 + C_1 w + C_2 w^2}{1 + d_1 w + d_2 w^2 + d_3 w^3} - w$$

where $C_0 = 2.515517$, $C_1 = 0.802853$, $C_2 = 0.010328$, $d_1 = 1.432788$, $d_2 = 0.189269$, and $d_3 = 0.001308$.

Based on the SPEI values, drought was classified as one of three different levels: mild drought ($-1 < \text{SPEI} \leq -0.5$), moderate drought ($-1.5 < \text{SPEI} \leq -1$), and severe drought ($\text{SPEI} \leq -1.5$).

5.6 Contribution analysis of uncertainty in future drought projection

Differences in GCMs, RCPs, and ETp models can lead to uncertainties in future drought projections. The analysis of variance (ANOVA) technique is capable of partitioning the total observed variances into different sources, thereby identifying the contributions of different sources to the total variance (Aryal et al., 2019). The ANOVA method not only quantifies the relative contributions of different sources to the total variance, but also considers the interactive contributions of different sources of the uncertainty to the total variance (Yip et al., 2011). Therefore, we used a three-way (three factors) ANOVA to quantify the relative and interactive contributions of GCMs, RCPs, and ETp models to the uncertainties in drought projections under future climate scenarios (Morim et al., 2019). A three-way ANOVA can be split into seven fractions that include the three main effects and the four interaction effects. The total sum of squares (SST) was calculated as equation (5-5):

$$SST = \underbrace{SS_{GCMs} + SS_{RCPs} + SS_{ETp,models}}_{\text{main effects}} + \underbrace{SS_{GCMs:RCPs} + SS_{GCMs:ETp,models} + SS_{RCPs:ETp,models} + SS_{GCMs:RCPs:ETp,models}}_{\text{interaction effects}} \quad (5-5)$$

5.7 Results

5.7.1 Droughts occurring in the historical period

Figure 5-3 shows the frequency of seasonal drought occurring in the period of 1971 to 2010 at Gunnedah and Wagga Wagga. Differences in the frequency of mild, moderate, and severe droughts were observed among ETp models. The frequency of mild drought in spring (left columns of upper two panels of Figure 5-3) estimated by the Penman model was about 20% at both sites while the other ETp models produced lower frequencies at Gunnedah and higher frequencies at Wagga Wagga. However, the differences in total drought frequency among ETp models were not great (lower two panels of Figure 5-3). For instance, the frequency of seasonal drought estimated by the Penman model was generally equal to that estimated by other ETp models at Gunnedah. In addition, mild ($-1 < \text{SPEI} \leq -0.5$) and moderate ($-1.5 < \text{SPEI} \leq -1$) droughts happened more frequently than severe droughts ($\text{SPEI} \leq -1.5$) during the historical period. The average

frequency of mild drought at Gunnedah ranged from 9% (in winter) to 20% (in spring) while the corresponding values for severe drought ranged from 2% (in summer) to 6% (in spring).

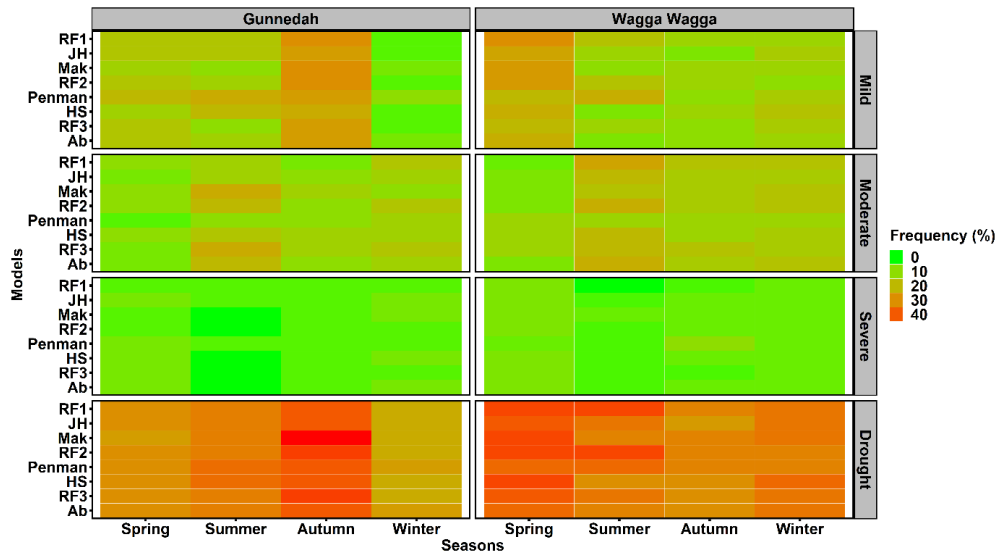


Figure 5-3 Frequency of seasonal droughts occurring in the period from 1971 to 2010 at Gunnedah and Wagga Wagga, Australia, using eight potential evapotranspiration models. RF1, RF2, and RF3 (random forest models 1, 2, and 3, respectively); JH (Jensen-Haise); Mak (Makkink); HS (Hargreaves); Ab (Abtew). Mild, moderate, and severe drought classifications are based on Standardized Precipitation Evapotranspiration Index values as described in section 5.5. Drought refers to the total of all drought classifications.

Differences in ETp estimated by different models are shown in Figure5-4. The RF-based ETp models generally produced similar values as the Penman model. In contrast, the other ETp models generally produced smaller ETp values. However, the underestimated seasonal ETp did not always produce less drought occurrence. This may indicate that drought assessment was mainly dominated by precipitation while ETp played only a minor role in the historical period.

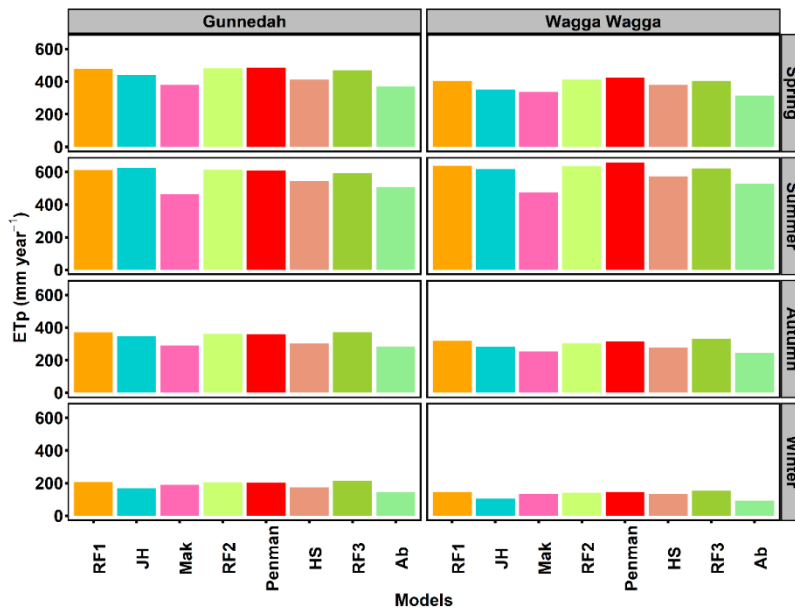


Figure 5-4 Mean seasonal potential evapotranspiration (ETp, mm year⁻¹) from 1971 to 2010 at Gunnedah and Wagga Wagga, Australia calculated by eight ETp models. RF1, RF2, and RF3 (random forest models 1, 2, and 3, respectively); JH (Jensen-Haise); Mak (Makkink); HS (Hargreaves); Ab (Abteu).

5.7.2 Projected changes of climatic factors under future scenarios

Minimum (T_{\min}) and maximum (T_{\max}) air temperatures were all expected to increase under future climate scenarios (Figure 5-5, upper panels, a1, a2 and b1, b2). The magnitudes of temperature increases were different in different seasons. Larger mean increases of both T_{\min} and T_{\max} were generally found in spring and winter. Moreover, the increases in temperature were larger in the 2080s than in the 2040s. By the 2080s (2061 - 2100), T_{\max} was likely to increase by 1.72 °C to 2.33 °C under RCP4.5 and by 3.22 °C to 4.08 °C under RCP8.5. The corresponding increases of T_{\min} ranged from 1.73 °C to 2.48 °C under RCP4.5 and from 3.26 °C to 4.64 °C under RCP8.5. Similar to the temperature increases, solar radiation (R_s) was also projected to increase (Figure 5-5, lower left panels, c1 and c2) and the R_s increases in the further future period were larger. Regarding seasonal variation, R_s in winter showed the largest mean increases followed by the increases in spring and autumn R_s , which were generally close. The increases in R_s during winter by the 2080s were 0.36 MJ m⁻² day⁻¹ at Gunnedah and 0.44 MJ m⁻² day⁻¹ at Wagga Wagga under RCP4.5, and 0.52 MJ m⁻² day⁻¹ at Gunnedah and 0.82 MJ m⁻² day⁻¹ at Wagga Wagga under RCP8.5.

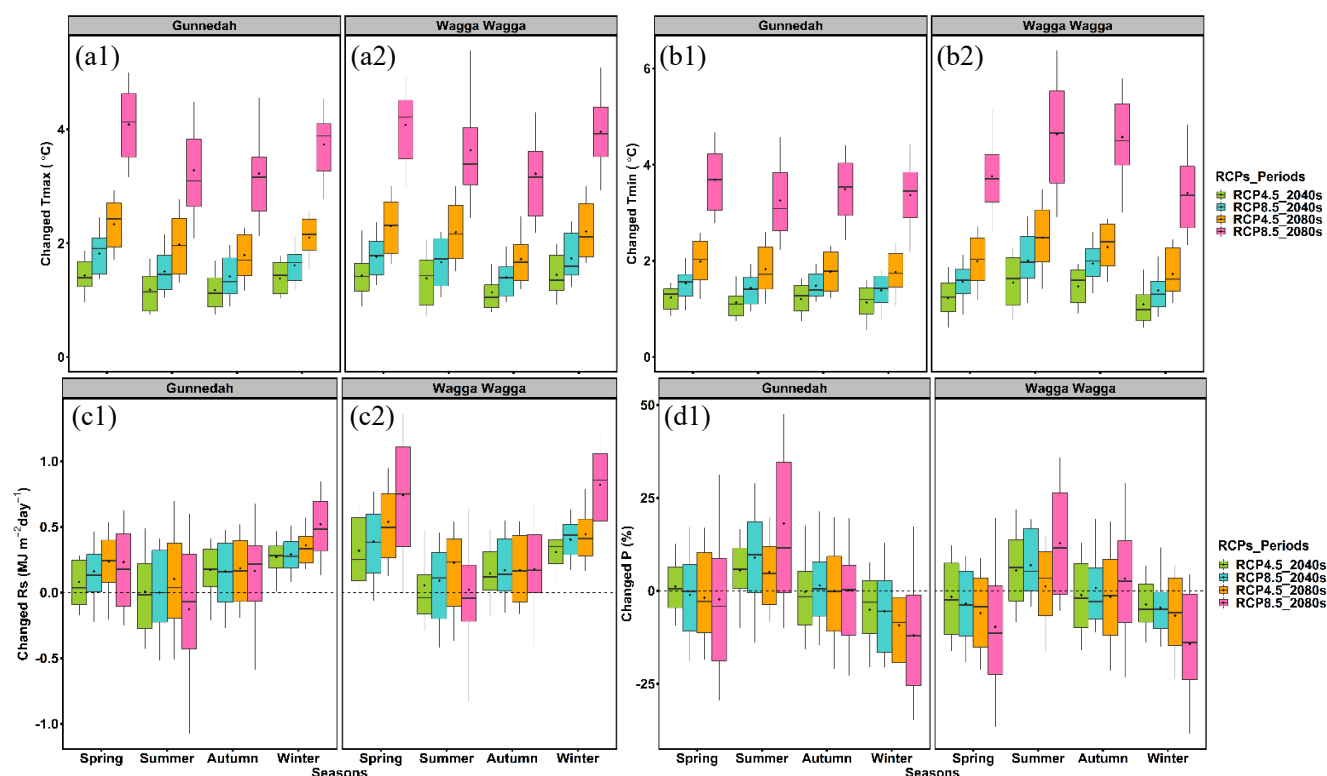


Figure 5-5 Projected changes in maximum (T_{max} , °C, a1, a2) and minimum (T_{min} , °C, b1, b2) air temperature, solar radiation (R_s , $\text{MJ m}^{-2} \text{day}^{-1}$, c1, c2), and precipitation (P , %, d1, d2) in the 2040s and 2080s at Gunnedah (a1, b1, c1, d1) and Wagga Wagga (a2, b2, c2, d2), Australia, under RCP4.5 and RCP8.5 scenarios. Lower and upper box boundaries indicate the 25th and 75th percentiles, respectively. The black line and dot inside each box indicate the median and mean, respectively. The lower and upper whiskers indicate the 10th and 90th percentiles, respectively.

The projected changes in P showed seasonal variation under future climate scenarios (Figure 5-5, lower right panels, d1 and d2). Specifically, summer P was projected to increase at both sites. The mean increases of summer P ranged from 1.14% to 5.49% under RCP4.5 and ranged from 6.93% to 18.10% under RCP8.5. In contrast, spring and winter P was likely to decrease. The maximum mean decreases of spring and winter P were 9.72% and 14.34%, respectively. Even though the predicted autumn P in the future was observed to be similarly variable as predicted for other seasons, the mean values of autumn P under future scenarios were close to those in the baseline period.

5.7.3 Projected changes of potential evapotranspiration under future climate scenarios

ETp projected by all models was likely to increase under future climate scenarios, although the magnitudes of increase varied among models (Figure 5-6). In general, RF-based models (followed by JH and Ab) produced larger ETp increases, whereas Mak and HS yielded smaller increases. Moreover, the ETp increases showed similar seasonal variation with that of temperatures, i.e., larger increases were generally observed in spring and winter, whereas smaller increases were observed in summer and autumn. By the 2080s (2061 - 2100), the mean increases in spring ETp ranged from 4.6% to 15.6% under RCP4.5 and from 7.7% to 26.9% under RCP8.5; the mean summer ETp values were likely to increase by 2.9% to 10.1% under RCP4.5 and by 3.5% to 16.1% under RCP8.5; in autumn, the projected increase of mean ETp ranged from 2.9% to 11.2% under RCP4.5 and from 3.6% to 22.7% under RCP8.5; and the likely increases in mean winter ETp ranged from 7.5% to 23.3% and 13.1% to 44.0% under RCP4.5 and RCP8.5, respectively. Results of the multiple linear regression (Figure 5-7, $\Delta ETp (\%) = a_0 \cdot \Delta T_{max} (^\circ C) + b_0 \cdot \Delta T_{min} (^\circ C) + c_0 \cdot \Delta R_s (MJ\ m^{-2}\ day^{-1})$) showed that changes in ETp could be almost entirely explained by changes in Tmax, Tmin, and Rs. However, the sensitivity of ETp models to these climatic factors varied. In general, models requiring the same inputs showed similar sensitivity to the same climatic factors. For instance, ETp estimated by RF1, JH, and Mak was more sensitive to changes in Rs than to changes in Tmax or Tmin. In contrast, a unit increase

in Tmax led to a larger increase in ETp estimated by HS and RF2 than Rs did.

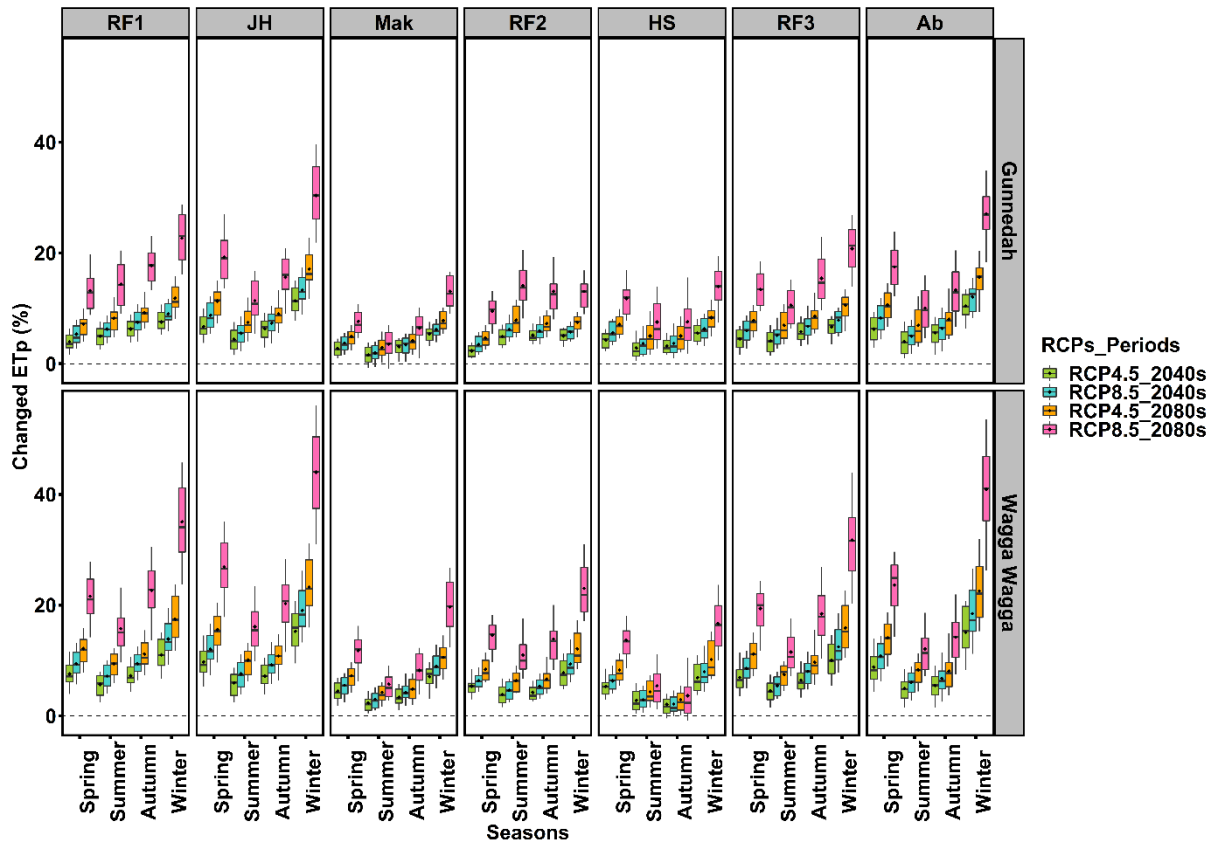


Figure 5-6 Projected changes in potential evapotranspiration (ETp, %) in the near future (2021-2060, 2040s) and further future (2061-2100, 2080s) at Gunnedah and Wagga Wagga, Australia, under RCP4.5 and RCP8.5 scenarios based on 34 GCMs compared with baseline values (1971-2010). Lower and upper box boundaries indicate the 25th and 75th percentiles, respectively. The black line and dot inside each box mark the median and mean, respectively. The lower and upper whiskers indicate the 10th and 90th percentiles, respectively.

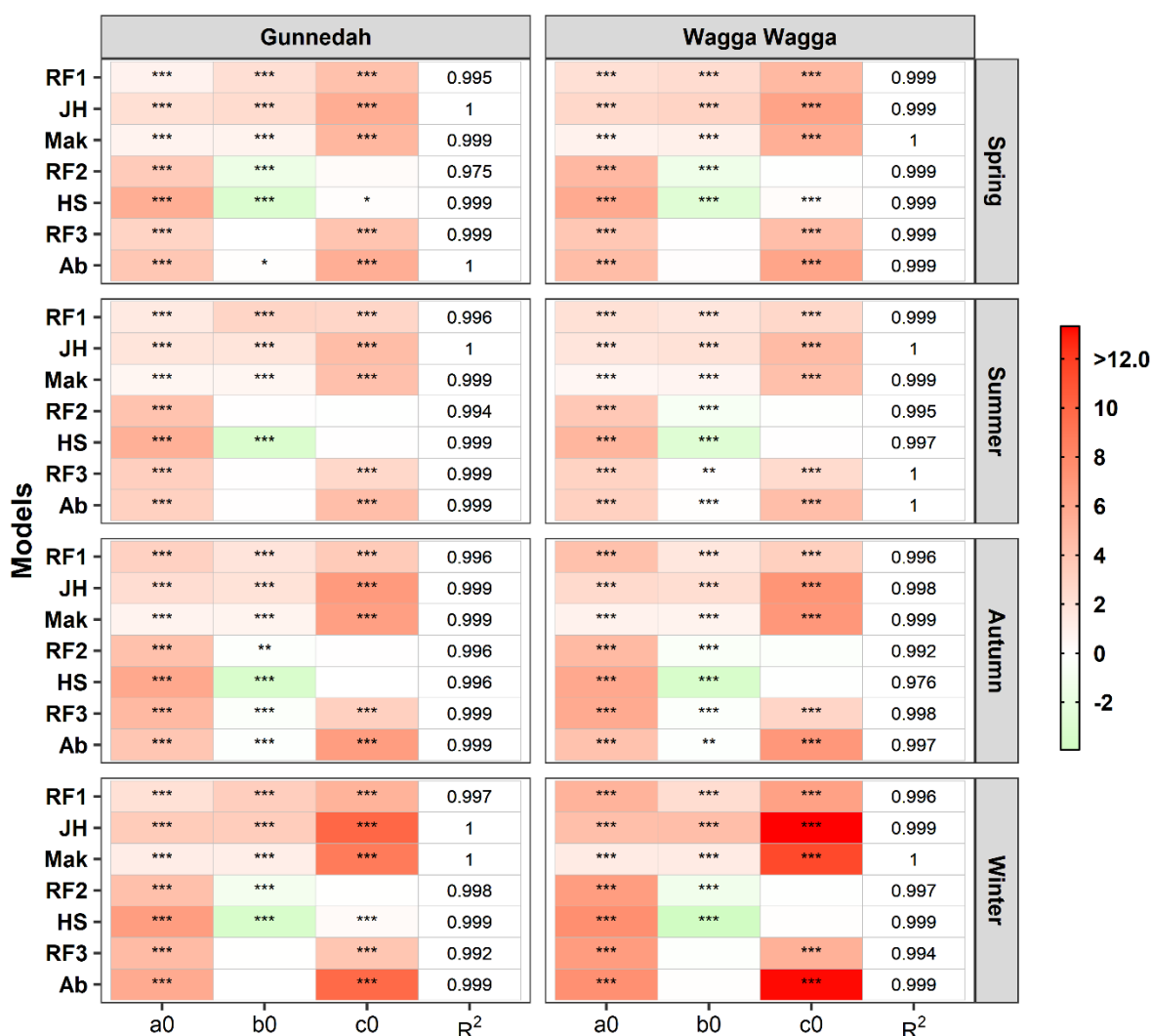


Figure 5-7 Regression coefficients for changes in ETp (ΔET_p , %) at Gunnedah and Wagga Wagga, southeast Australia, with changes in Tmax (ΔT_{max} , °C), Tmin (ΔT_{min} , °C), and Rs (ΔR_s , MJ m⁻² day⁻¹) in a multiple linear regression model (ΔET_p (%) = $a_0 \cdot \Delta T_{max}$ (°C) + $b_0 \cdot \Delta T_{min}$ (°C) + $c_0 \cdot \Delta R_s$ (MJ m⁻² day⁻¹)) for seven ETp models; ***:p < 0.001, **:p < 0.01; *:p < 0.05. RF1, RF2, and RF3 (random forest models 1, 2, and 3, respectively); JH (Jensen-Haise); Mak (Makkink); HS (Hargreaves); Ab (Abtew). Units for a0 and b0 are % °C⁻¹; units for c0 are % (MJ m⁻² day⁻¹)⁻¹. The color legend represents the values of a0, b0, and c0.

5.7.4 Projected changes in drought frequency and their relationship with climatic factors

Compared with the baseline period (1971 - 2010), droughts, especially moderate (Figure 5-8, upper right panels) and severe (Figure 5-8, lower left panels) droughts, were projected to occur more frequently in the future (Figure 5-8 & Figure 5-9). The amount of increase projected by different ETp models was different.

Compared with traditional ETp models, RF-based models generally produced larger increases than traditional ETp models, except for JH which projected similar or even larger increases. For example, RF1 projected that summer severe drought would increase by 28.4% on average by the 2080s under RCP8.5 at Wagga Wagga while the corresponding increase projected by Mak was 5.7%. In addition, the increase of drought frequency under RCP8.5 was larger than that observed under RCP4.5. Severe drought occurring in spring would increase by 3.1% to 21.7% under RCP4.5 and by 5.2% to 41.0% under RCP8.5. Frequency of winter severe drought was likely to increase by 4.5% to 20.9% under RCP4.5 and by 7.9% to 37.4% under RCP8.5. The increased frequency of summer and autumn droughts was smaller than the increased frequency of spring and winter droughts. By the 2080s, the maximum mean increase of summer severe drought would be 18.3% under RCP4.5 and 28.4% under RCP8.5. The corresponding increases for autumn severe drought would be 13.0% under RCP4.5 and 27.9% under RCP8.5.

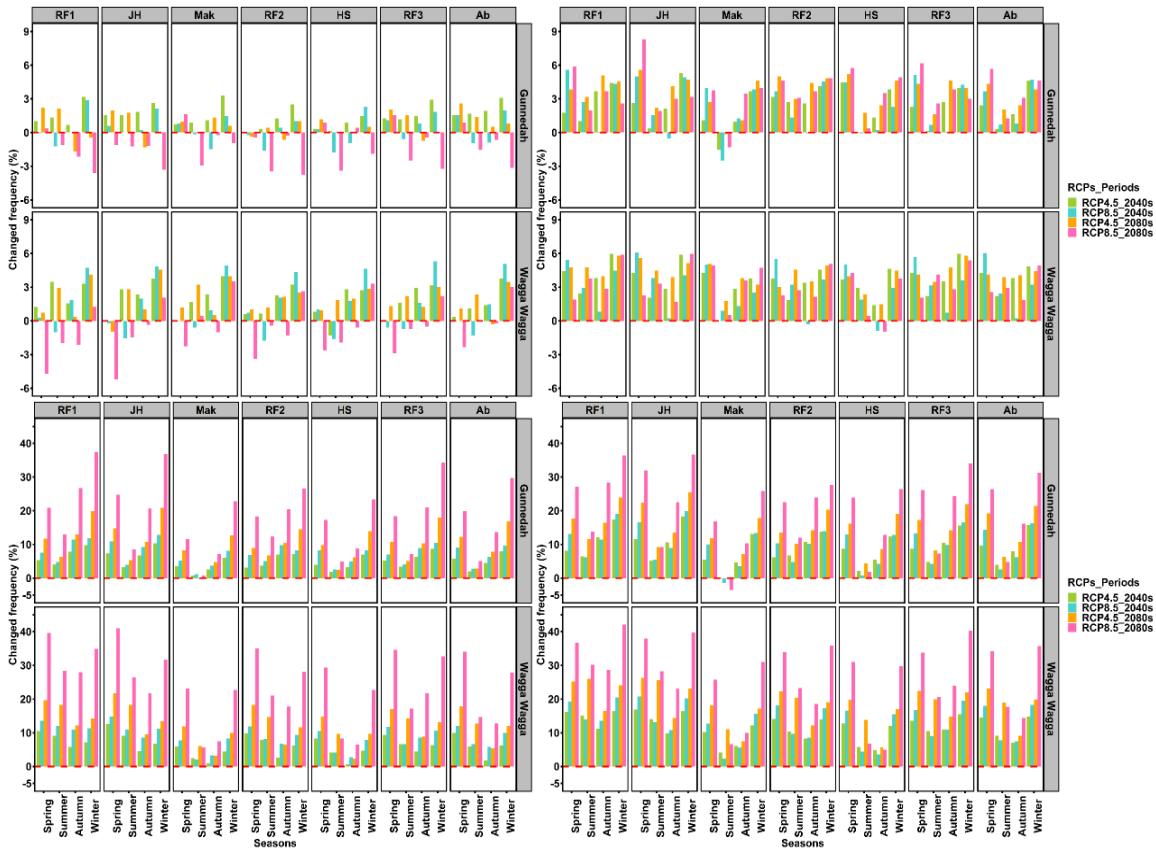


Figure 5-8 Changes in the frequency of seasonal mild drought (upper left panels, $-1 < \text{SPEI} \leq -0.5$), moderate drought (upper right panels, $-1.5 < \text{SPEI} \leq -1$), severe drought (lower left panels, $\text{SPEI} \leq -1.5$), and the total drought ($\text{SPEI} \leq -0.5$) in the near (2021 – 2060, 2040s) and further (2061 – 2100, 2080s) future periods compared with the baseline period (1971 - 2010) at Gunnedah and Wagga Wagga, Australia. The calculation of SPEI was based on seven ETp models driven by downscaled climatic data from 34 GCMs under RCP4.5 and RCP8.5 scenarios. Data presented are changed mean frequency in the 40-year values for the 34 GCMs compared with that of the baseline period. RF1, RF2, and RF3 (random forest models 1, 2, and 3, respectively); JH (Jensen-Haise); Mak (Makkink); HS (Hargreaves); Ab (Abtew).

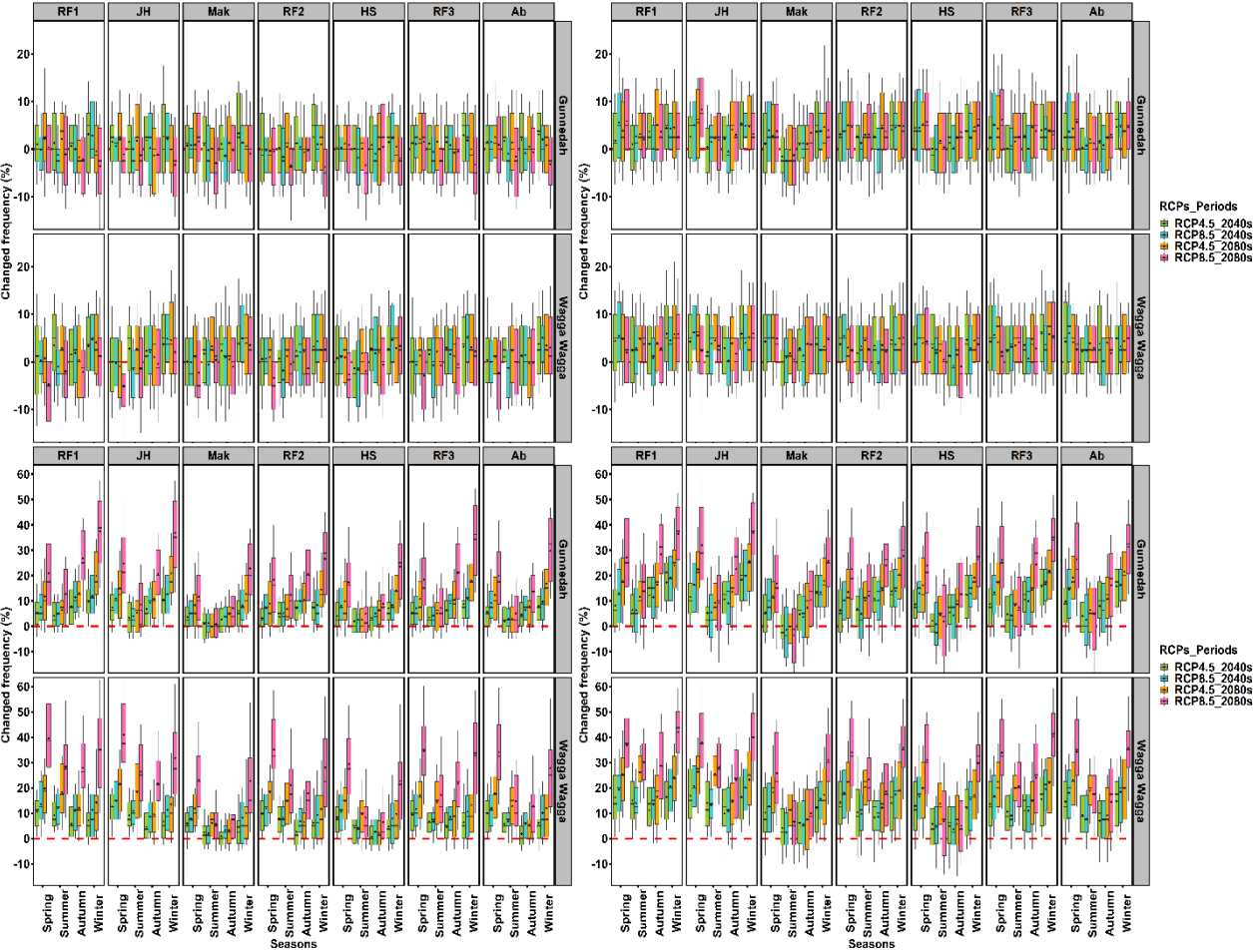


Figure 5-9 Changes in the frequency of seasonal mild drought (upper left panels, $-1 < \text{SPEI} \leq -0.5$), moderate drought (upper right panels, $-1.5 < \text{SPEI} \leq -1$), severe drought (lower left panels, $\text{SPEI} \leq -1.5$), and the total drought (lower right panels, $\text{SPEI} \leq -0.5$) in the near (2021-2060, 2040s) and further (2061 – 2100, 2080s) future periods compared with the baseline period (1971 - 2100) at Gunnedah and Wagga, Australia. The calculation of SPEI was based on seven ET_p models driven by downscaled climatic data from 34 GCMs under RCP4.5 and RCP8.5 scenarios. Data presented are changed frequency in the 40-year values for each of the 34 GCMs compared with that of the baseline period. Lower and upper box boundaries indicate the 25th and 75th percentiles, respectively. The black line and dot inside each box mark the median and mean, respectively. The lower and upper whiskers indicate the 10th and 90th percentiles, respectively. RF1, RF2, and RF3 (random forest models 1, 2, and 3, respectively); JH (Jensen-Haise); Mak (Makkink); HS (Hargreaves); Ab (Abtew). RF1, RF2, and RF3 (random forest models 1, 2, and 3, respectively); JH (Jensen-Haise); Mak (Makkink); HS (Hargreaves); Ab (Abtew).

Changing P pattern and increasing ET_p were expected to exert their influence on frequency of drought occurrences under future climate scenarios. To investigate the contribution of changes in climatic factors to drought frequency, multiple linear regression was performed after checking for multicollinearity among independent factors based on the variance inflation factor (VIF). In this study, independent factors with VIF values greater than 10 (Table 5-3) were discarded to minimize the influence of multicollinearity (Feng et al., 2018b). Thus, only ET_p and P were retained while T_{min}, T_{max}, and R_s were discarded to build the regression relationship ($\Delta F (\%) = a \cdot \Delta P (\%) + b \cdot \Delta ET_p (\%)$) between changes in drought frequency and changes in climatic factors. Figure 5-10 shows that changes in P and ET_p mainly (generally greater than 80% contribution) explained the change in the frequency of severe drought at both locations. In addition, a unit increase in ET_p generally caused a larger increase in drought frequency than caused by a unit decrease in P. For example, the ET_p regression coefficient (b) ranged from 1.09 to 1.84 among ET_p models for severe drought in spring at Gunnedah (Figure 5-10), while the absolute value of the P coefficient (a) ranged from 0.36 to 0.46. The larger absolute values of regression coefficients for ET_p compared with P indicated that changes in ET_p were the major factor resulting in greater frequency of drought.

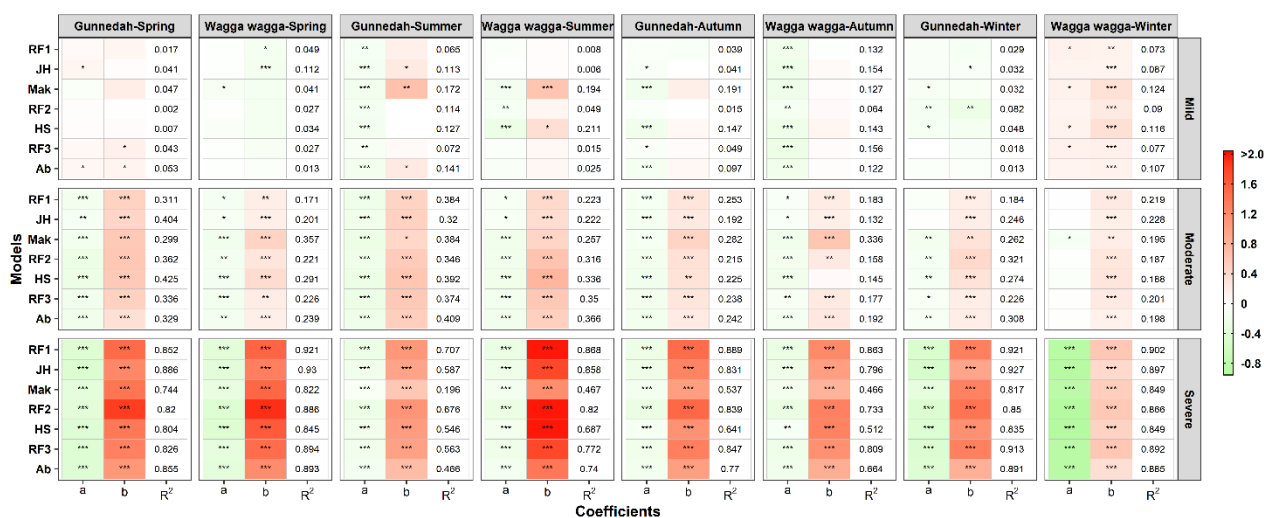


Figure 5-10 Regression coefficients for changes in frequency of seasonal droughts (ΔF , %) at Gunnedah and Wagga Wagga, Australia with changes in precipitation (ΔP , %) and potential evapotranspiration (ΔET_p , %) in a multiple linear regression model (ΔF (%) = $a \cdot \Delta P$ (%) + $b \cdot \Delta ET_p$ (%)) for seven ET_p models; ***: $p < 0.001$, **: $p < 0.01$; *: $p < 0.05$. RF1, RF2, and RF3 (random forest models 1, 2, and 3, respectively); JH (Jensen-Haise); Mak (Makkink); HS (Hargreaves); Ab (Abtew). Coefficients a and b are dimensionless. The color legend represents the values of a and b.

Table 5-3 Variance inflation factors (VIF) to choose independent factors for multiple linear regression.

Models	Factors	VIF (Gunnedah)				VIF (Wagga Wagga)			
		Spring	Summer	Autumn	Winter	Spring	Summer	Autumn	Winter
RF1	T	67.3	39.9	59.8	91.5	215.2	278.5	41.7	37.9
	Rs	12.3	3.9	7.1	7.1	39.6	28.7	3.9	6.7
	P	1.7	1.3	1.5	1.7	1.8	1.3	1.8	1.9
	ET	93.1	42.0	67.6	116.0	328.0	310.0	46.4	55.7
JH	T	418.0	637.8	163.1	396.8	253.9	456.0	137.6	326.4
	Rs	80.6	275.5	71.0	51.2	51.7	126.6	24.4	59.1
	P	1.8	1.3	1.5	1.6	1.8	1.3	1.8	2.3
Mak	ET	592.6	904.0	242.0	576.7	399.3	593.0	175.9	573.4
	T	370.3	254.2	161.1	325.2	183.7	178.1	149.3	350.3
	Rs	435.6	855.1	465.0	280.5	239.1	369.3	175.9	524.6
RF2	P	1.8	1.3	1.6	1.7	1.8	1.3	1.8	2.4
	ET	1016.3	1096.3	643.4	883.0	595.4	558.4	368.5	1467.4
	T	5.2	9.2	5.9	5.5	7.6	4.9	6.6	6.3
HS	Rs	2.0	1.3	1.6	2.0	2.3	1.3	2.1	3.5
	P	1.8	1.3	1.5	1.7	1.8	1.4	1.8	1.9
	ET	5.6	9.1	6.2	5.4	8.2	5.0	7.1	7.0
RF3	T	3.2	1.8	1.4	2.5	3.8	1.3	1.1	2.6
	Rs	2.0	1.4	1.7	2.1	2.3	1.3	2.1	3.4

	P	1.8	1.3	1.5	1.7	1.8	1.4	1.8	1.9
	ET	3.5	1.8	1.7	2.4	4.3	1.2	1.3	2.4
	T	22.3	9.4	7.2	12.0	22.1	10.4	7.7	9.8
RF3	Rs	7.9	3.6	2.9	2.6	8.5	3.4	2.7	4.5
	P	1.8	1.3	1.5	1.7	1.8	1.4	1.8	1.9
	ET	33.2	11.6	8.8	15.1	37.5	12.6	9.2	14.6
	T	25.4	9.4	7.0	12.3	23.3	10.8	7.0	12.0
Ab	Rs	10.2	7.1	6.7	4.1	11.0	7.3	5.6	7.6
	P	1.8	1.3	1.5	1.7	1.8	1.4	1.8	2.0
	ET	39.7	15.0	12.6	19.3	43.4	17.0	11.9	25.8

5.7.5 Uncertainty analysis in drought projection

The contributions of different sources of variation and their interactions to the total uncertainty in projecting drought frequency are shown in Figure 5-11. GCMs and their interaction with RCPs (GCMs:RCPs) contributed the most to the total uncertainty independent of drought level, season, and site. The uncertainty contribution of GCMs and GCMs:RCPs ranged from 19.2% to 53.0% and from 17.2% to 44.3%, respectively. The contribution of RCPs to severe drought and the interaction of GCMs, RCPs, and ETp models (GCMs:RCPs:Models) to mild and moderate droughts were also large. In contrast, the contribution of ETp models to the total uncertainty was negligible, generally less than 5.0%. The results of this uncertainty analysis indicated that the projection of drought under future climate was only slightly influenced by the differences in ETp models, but greatly influenced by GCMs and RCPs.

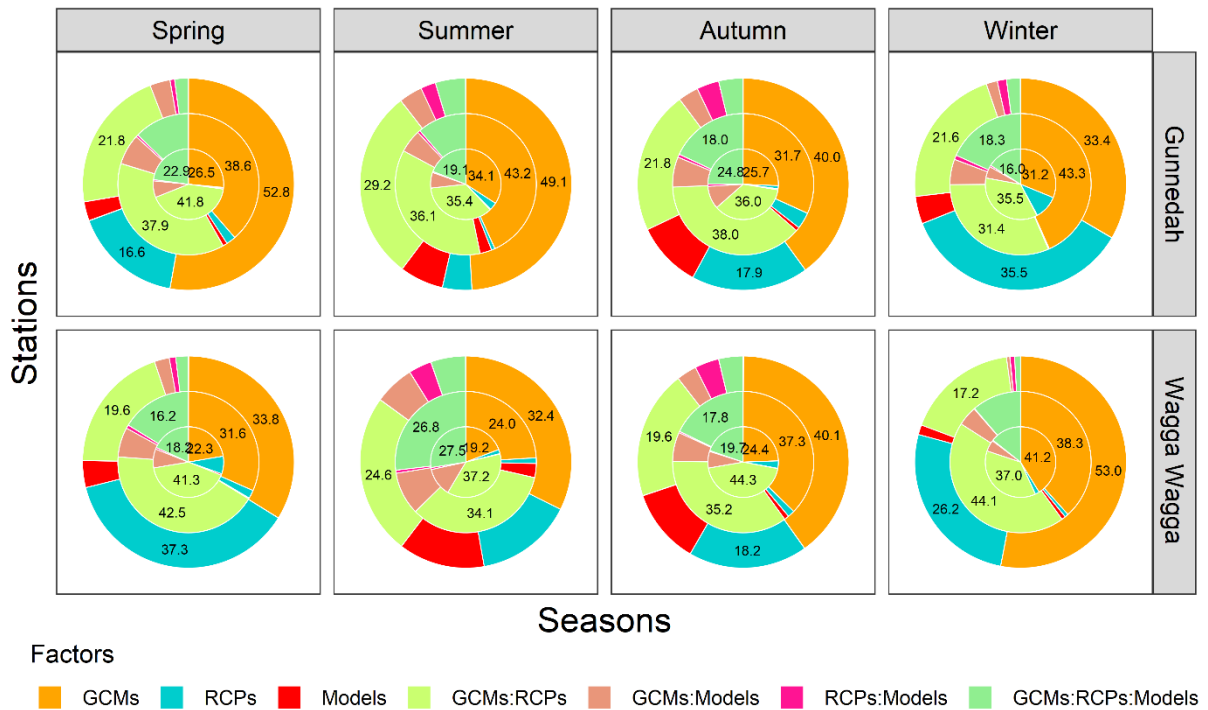


Figure 5-11 Contribution (%) of GCMs, RCPs, and ETp models to the uncertainty in drought frequency projection at Gunnedah and Wagga Wagga, Australia for each season. Results for mild, moderate, and severe drought are shown from inward to outward circles, respectively. Contributions larger than 15% are shown by numbers in the figure.

5.8 Discussion

This study used SPEI computed from P and ETp estimated by different ETp models to project the potential change in drought occurrence under the RCP4.5 and RCP8.5 climate scenarios for two sites in the wheat belt of southeast Australia. In addition, the sensitivity of SPEI to different ETp models and the contribution of different sources to the uncertainty of drought projection were also analyzed. During the historical period, the total occurrence of drought showed little difference among different ETp models (Figure 5-3). However, differences among ETp models could be found in the frequency of mild, moderate, and severe droughts. In contrast, differences in the increase in drought frequency projected by different ETp models was larger during the future period (Figure 5-8 & Figure 5-9). The differences generally indicated that RF-based models projected larger increases in drought frequency (especially for severe drought) than traditional ETp models did. This pattern was also found in the projection of increases in ETp (Figure 5-6), i.e., ETp models which produced larger increases in ETp in the future also projected larger increases in drought frequency in

the future. Yao et al. (2019) assessed the influence of different ETp models on drought monitoring in China with the use of SPEI. They concluded that the accuracy of ETp models played only a minor role in drought assessments at wetter sites where P was greater than 500 mm year⁻¹, while ETp models made a large difference in drought assessment at drier sites. The mean historical annual P at our study sites was slightly greater than 500 mm, but it was projected to decrease (Figure 5-5, d1 and d2) under future climate scenarios. This can explain why the influence of different ETp models on drought projection was greater in the future periods. Additionally, other studies (Asadi Zarch et al., 2017; Asadi Zarch et al., 2015; Cook et al., 2014) have shown that ETp was more important to future drought projection than to historical drought assessment. For instance, Asadi Zarch et al. (2015) used both SPI (based only on P) and RDI (based on ETp and P) to assess changes in global drought. They found that there was a significant agreement in drought assessment between SPI and RDI only in historical periods. However, a significant difference was observed in future drought projection between the two methods, and RDI projected more occurrences of drought in the future than SPI did. They stated that “agreement between SPI and RDI is affected and decreases remarkably over time”. Therefore, it is necessary to include ETp in future drought projection studies and attention should also be given to ETp model use.

Increases in drought frequency at Wagga Wagga were generally larger than those observed at Gunnedah (Figure 5-8). This may be explained by the greater increases in temperature and solar radiation at Wagga Wagga. Additionally, precipitation is likely to be somewhat less at Wagga Wagga than at Gunnedah in the future (Figure 5-5, d1 and d2). During the historical period, Wagga Wagga was also slightly drier than Gunnedah. Thus, the greater increase in drought is likely to present greater challenges to agricultural production at this site. In addition to the increase in future drought projected by offline indices, direct GCM outputs, such as soil moisture and runoff, have also supported the increase in future drought on a large scale (Zhang et al., 2018; Zhao and Dai, 2015; Zhao and Dai, 2017). For instance, Zhao and Dai (2015) used sc_PDSI, soil moisture in the 0-10 cm surface soil layer, and runoff from 14 GCMs to project drought under the RCP4.5 scenario at global scale. They found that all of these measures projected increases in drought over most land areas. Although general increases have been widely reported across the world, the magnitudes of the increases have varied among studies (Dai, 2012; Dai and Zhao, 2017; Milly and Dunne, 2016; Naumann et al., 2018). Based on 12-month SPEI with the Penman-Monteith model, Naumann et al. (2018) projected that drought magnitudes could double for 30% of the global landmass with 1.5 °C warming. Meanwhile, they found that water supply-demand deficit could increase by fivefold for Australia if

contemporary warming rates continue. However, Milly and Dunne (2016) reported that ETp-dependent metrics may overpredict drought increases. Similarly, Yang et al. (2018) found that regardless of the obvious drying atmosphere trend for the 21st century, surface runoff was likely to increase across most of the global land area. In our study, the increases in drought varied greatly depending on seasons, ETp models, and climate scenarios (Figure 5-8). The discrepancies among these studies demonstrate the need for further research studies in drought projection. The discrepancies also indicate that drought projection is partially influenced by drought definition and the indices used. The results of our study provide a substantial contribution to the debate on the effect of different ETp models on drought quantification.

According to our study, more frequent and severe drought under future climate scenarios was generally the result of a combined effect of increasing ETp and decreasing P (Figure 5-10) and the increase of ETp might play a major role in the increase of drought in the future period. Similar to our study, Cook et al. (2014) also found that declines in P would push the climate towards drought while the increased ETp would amplify the precipitation-induced drought. The projected increase in drought occurrence will inevitably lead to decreased crop yields and cause more challenges to cropping systems (Dijk et al., 2013; Lobell et al., 2015). Because spring and winter are key growing seasons for wheat and canola (*Brassica napus* L.) in this region of Australia and because these crops are mainly grown under rainfed conditions, they will be more vulnerable to drought-induced yield losses in the future (Feng et al., 2020; Luo et al., 2005). Thus, measures should be taken to minimize the negative influence of droughts. Breeding new crop varieties that have greater drought tolerance, use of irrigation, and changing planting date are three possible measures that could mitigate drought-induced yield loss (Chenu et al., 2011; Watson et al., 2017).

This study found that differences in GCMs and their interaction with RCPs (GCMs:RCPs) contributed the most to the uncertainty in the process of drought projection (19.2% - 53% and 17.2% - 44.3%, respectively; Figure 5-11). Lu et al. (2019) found that differences in GCMs could account for more than 80% of the uncertainty in drought projection based on soil moisture anomalies. The large contribution of GCMs might be due to the differences in P projected by different GCMs. For instance, Hawkins and Sutton (2011) found that GCMs generally played a dominant role among GCMs, RCPs, and the random, internal variations in climate with regard to the uncertainty of P projection for lead times longer than 30 years. Different RCPs generally resulted in different temperature predictions, which would influence ETp prediction. Shi et al. (2020) found that RCP differences could explain around 40% of the uncertainty in ETp projection. This may explain why the GCMs:RCPs interaction also played a key role in the uncertainty of drought projection in

our study. The dominant contribution of GCMs and GCMs:RCPs to drought assessment highlighted the importance of using a wide range of GCMs and different emission scenarios to avoid the underestimation of the total uncertainty. For policymakers, the less uncertainty that there is in drought projections, the more reliable are the measures that can be recommended. Therefore, the possibility of reducing uncertainty in drought projection should be investigated in the future. The availability of more and more GCMs from CMIP6 might provide the possibility of reducing such uncertainty through the consideration of more environmental factors, the use of more advanced numerical simulation methods, and the generally higher resolution (Eyring et al., 2016).

A few limitations in our study should be acknowledged. In addition to SPEI, there are other drought indices such as RDI (Tsakiris et al., 2007), and their sensitivity to different ETp models was not reported in this study. Therefore, more drought indices should be included in future studies to better understand the comprehensive influence of evapotranspiration on drought. In addition, the influence of enriched CO₂ environment on drought projection is complex (Berdugo et al., 2020; Vicente-Serrano et al., 2019). There were two reasons for why we did not consider CO₂ fertilization in our study. First, we used the open-water Penman model rather than the reference crop Penman-Monteith model to calculate ETp instead of ET₀ or actual evapotranspiration. Second, increasing atmospheric CO₂ concentration is expected to influence plant structure (e.g., leaf size, root length), and function (e.g., stomatal resistance, vegetation evapotranspiration) (Pritchard et al., 1999; Yang et al., 2019). Thus, the effects of enriched CO₂ on drought projection should ideally involve a consideration of other biophysical factors such as plant development and their response to the changing meteorological factors (Sheffield et al., 2012). The biophysical modelling component was not considered in our study. Recently, Yang et al. (2019) modified the Penman-Monteith model by adding a trained relationship between CO₂ and surface resistance to consider the influence of elevated CO₂ on ET₀. They adopted the modified and the original Penman-Monteith model, and direct outputs from 16 GCMs to project global drought under RCP8.5 based on PDSI, and observed that the degree of increase in drought was much smaller with the modified Penman-Monteith model because the elevated CO₂ offset the ET₀ increase caused by increased temperature (Yang et al., 2020). Their study sets an example for future studies to comprehensively assess the influence of climate change on drought with consideration of plant response to elevated CO₂. However, elevated CO₂ will not only lead to partial stomatal closure (reducing evapotranspiration,) but will also lead to larger leaf size (Pritchard et al., 1999) (increasing evapotranspiration). Additionally, as Berdugo et al. (2020) reported in their response to Keenan et al. (2020),

the positive effect of CO₂ fertilization on vegetation growth and evapotranspiration may be dampened or even reversed by the effects of increased soil temperature, continued drying, and extreme climatic events in the future. In this context, there is a need to consider other important factors when exploring the impacts of climate change and CO₂ fertilization on future drought.

5.9 Conclusions

This study used SPEI to project possible changes of drought under two different emission scenarios (RCP4.5 and RCP8.5) for two locations in the wheat belt of southeastern Australia based on climate data downscaled from 34 GCMs. Three newly developed random forest (RF1, RF2, and RF3) models and five traditional potential evapotranspiration (ET_p) models were used to calculate SPEI to investigate the influence of ET_p models on drought assessment. The influence of ET_p models on drought assessment with SPEI was evident for future periods even though little difference was observed among these ET_p models in the historical drought assessment period. Generally, RF-based ET_p models which projected larger increases in ET_p also projected larger increases in drought frequency. This finding emphasized the necessity of using drought indices which include both P and ET_p to predict drought under a changing climate. A greater increase in frequency of moderate and severe droughts was predicted than for mild droughts. The increased occurrence of droughts showed seasonal variations, with larger increases in spring and winter and smaller increases in autumn and winter. For instance, the maximum mean increase of frequency of severe drought in spring was 21.7% under RCP4.5 and 41.0% under RCP8.5 by the 2080s, while the corresponding increase for autumn severe drought was 13.0% under RCP4.5 and 27.9% under RCP8.5. The projection of droughts under future climate scenarios was accompanied by uncertainties. Our study showed that the uncertainty was mainly due to differences in GCMs (19.2% - 53%) followed by the interaction of GCMs with RCPs. Despite the uncertainty, results from our study highlight the necessity of identifying mitigation and adaptation strategies to deal with the potential negative impacts caused by more moderate and severe droughts in the future.

5.10 Reference

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Chapter 6. Subtle difference observed in runoff projection with different potential evapotranspiration inputs based on Xinanjiang model

This chapter is from the manuscript ‘Assessing future runoff changes with different potential evapotranspiration inputs based on multi-model ensemble of CMIP5 projections’ authored by Lijie Shi, Bin Wang, De Li Liu, Hong Zhang, Puyu Feng, Qiang Yu. The manuscript is now under internal review before submitting to Journal for publication

Abstract: Runoff projection under future climate has been widely studied to investigate the impacts of climate change on regional water availability based on different hydrological models. Potential evapotranspiration (ETp) is one of the most important inputs for most hydrological models. However, the influence of different ETp inputs on runoff projection under future climate scenarios has not been fully assessed. To fill this knowledge gap, we adopted ETp estimated by Penman, Abtew, Hargreaves, Jensen-Haise, modified Makkink, and a global evapotranspiration product (PML_V2) to calibrate and validate Xinanjiang (XAJ) model in historical periods. The validated XAJ model was then used to project runoff in North Johnstone catchment, northeast Australia with downscaled climate data from 34 GCMs under RCP4.5 and RCP8.5 scenarios. This study found that XAJ model had a good performance in simulating historical runoff regardless of the difference in ETp inputs. In specific, R^2 between simulated and observed runoff was around 0.89 (calibration period) and 0.82 (validation period) for different ETp inputs; The NSE ranged from 0.83 to 0.87 among different ETp inputs for calibration period and ranged from 0.74 to 0.80 for validation period; The corresponding RMSE ranged from 2.57 mm day⁻¹ to 2.98 mm day⁻¹ and 2.67 mm day⁻¹ to 3.09 mm day⁻¹. The difference in runoff projection with different ETp inputs under future climate scenarios was also subtle. XAJ model with all ETp inputs projected that runoff was likely to decrease in spring and winter whereas there was no significant change for summer and autumn runoff. The maximum mean decreases of spring runoff ranged from 15.4% to 18.2% by 2090s under RCP8.5. For winter runoff the maximum mean decreases were 6.9%-14.8% by 2090s under RCP8.5. The uncertainty in runoff projection was mainly caused by the differences in GCMs and RCPs. This study indicated that the wet tropical North Johnstone catchment was likely to be exposed to decrease in water availability due to climate change in the future.

Keywords: runoff, Xinanjiang model, potential evapotranspiration inputs, climate change, North Johnstone river basin

6.1 Introduction

Runoff is one of the key processes for water transport both for surface water bodies (e.g., rivers, lakes, wetlands, and oceans) and groundwater (Clifton et al., 2018). How much runoff is produced for each precipitation event has direct or indirect influences on water availability in many aspects of human activities such as agricultural and industrial production, and domestic life and ecosystems (Allan et al., 2020). Under a changing climate, runoff is influenced by the changing patterns in precipitation and other internal fluctuations of the climate system. Thus, projecting runoff at future climate scenarios plays a significant role in understanding water resources availability and revealing the impacts of a changing climate on hydrological cycle (Allan et al., 2020; Yan et al., 2020).

Methods such as climate elasticity (Xing et al., 2018; Yang and Yang, 2011), Bayesian approach (Freni et al., 2009), and hydrological model (Chiew et al., 2018; Islam et al., 2014) can all be used in runoff simulation and projection. Compared with other methods, one of the most important advantages of hydrological models is that they are capable to detect the hydroclimate response to changes by offering the most comprehensive and reliable means at a certain catchment (Guo et al., 2017; Li et al., 2020). In literature, hydrological models have been widely used as powerful tools to investigate runoff response to climate change (Fowler et al., 2018; Pechlivanidis et al., 2016; Vaze and Teng, 2011). In specific, historical observed rainfall and runoff sequences are used to calibrate and validate the performance of hydrological models (Fowler et al., 2020). Then, runoff can be projected with the climatic factors derived from global climate models (GCMs) to drive the calibrated hydrological models (Arnell, 2011; Chen and Yu, 2015). For instance, Chen and Yu (2015) assessed the response of flood runoff in southeast Queensland to climate change and land-use change with RORB, a rainfall-runoff model, based on projected rainfall from two GCMs. They found that it is unlikely to increase for future flood magnitudes. Islam et al. (2014) investigated the hydrologic impact of climate change on the Murray-Hotham catchment in Western Australia based on the Land Use Change Incorporated Catchment model (LUCICAT). In their study, climatic data was downscaled from 11 GCMs under A2 and B1 emission scenarios to drive LUCICAT model for the future rainfall-runoff projection. They found that projected decrease in rainfall would result in large decrease in runoff for Western Australia in the mid and late of 21st century.

However, most studies in runoff projection focused on analyzing the trends of runoff under future climate scenarios but were weak in disentangling the relationship between changes in runoff and its driving

factors (Vaze and Teng, 2011; Zheng et al., 2018), or simply attributed the changes in runoff to changes in rainfall and evaporation without the consideration of the effects of changes in soil moisture (Barria et al., 2015; Li et al., 2020; Xing et al., 2018). Runoff is an integration of rainfall, evapotranspiration, and soil moisture (Chiew et al., 1995; Wasko and Nathan, 2019). Historical studies showed that changes in rainfall, changes in evapotranspiration, or changes in soil moisture could all exert their influence on the changes in runoff (Liu et al., 2020). Thus, simply attributing the changes of runoff to rainfall or evapotranspiration may lead to misunderstand (Wasko et al., 2019; Woldemeskel and Sharma, 2016). In other words, changing patterns in rainfall and runoff not always matched very well. As Sharma et al. (2018) antecedent hydrologic conditions may partially explain why the increasing precipitation extremes not always lead to increase in flood. Thus, it is vital to take soil moisture conditions into account in projecting runoff response to climate change (Woldemeskel and Sharma, 2016).

According to closed water balance, runoff for a certain region is the difference between rainfall and actual evapotranspiration (ET_a) in a long-term period (Montaldo and Oren, 2018). Therefore, the estimation of ET_a is expected to influence the simulation of runoff (Riegger and Tourian, 2014). As a proxy of ET_a, potential evapotranspiration (ET_p) is a necessary input for most hydrological models to simulate runoff (Bai et al., 2016; Li and Zhang, 2017). However, ET_p is also generally estimated by models varying from temperature-based to physically-based Penman models, and the estimates may vary among models (Feng et al., 2016; Kumar et al., 1987; Kumar Roy et al., 2020). Thus, which ET_p model could produce better runoff simulation is an important question to answer. In other words, is the difference in ET_p estimates going to result in different runoff simulation? This question might be more urgent to answer in runoff projection under a changing climate because air evaporative demand is a vital factor when it comes to climate change and may lead to uncertainty in runoff projection (Seiller and Anctil, 2016). Oudin et al. (2005) adopted ET_p estimated by 27 ET_p models to drive four rainfall-runoff hydrological models and investigate the influence of different ET_p inputs on runoff simulation over 308 catchments across France, Australia, and the United States. They found that these hydrological models showed low sensitivity to ET_p inputs but temperature-based and radiation-based ET_p model yielded the best runoff simulation. Under future climate scenarios, Seiller and Anctil (2016) assessed the sensitivity of 20 hydrological models in runoff projection to ET_p estimated by 24 different equations. They found that the significantly different ET_p series exerted moderate influence on runoff projection and claimed that it was important to test different ET_p models in runoff projection under a decision-making context. In Korea, Bae et al. (2011) investigated the sensitivity of three hydrological models

to seven ETp methods in runoff projection with downscaled climate data from 13 GCMs. They concluded that the influence of different ETp on runoff projection became larger and brought more uncertainty in runoff projection by 2071-2100. Their study indicated that the influence of different ETp inputs on runoff projection may have more weight over time. Contrary to their results, Dakhlaoui et al. (2020) found that discharge simulated by three hydrological models was not sensitive to the ETp estimates even in the future climate period. Thus, it is still a necessary to investigate the exact influence of different ETp inputs on runoff projection to explain the existing discrepancies.

Runoff projection heavily relies on climatic factors derived from global climate models (GCMs). However, assumptions about the emission scenarios of greenhouse gases (RCPs), atmospheric aerosols, and land-surface properties will have effects on the climate projections by GCMs, thus leading to uncertainty in the projected climate data (Knutti and Sedláček, 2012; Wang et al., 2020). The daily downscaled climate datasets from GCMs are key inputs to most hydrological models, and will pass the uncertainty onto the runoff projection. The uncertainty in rainfall projection from GCMs and its influence on runoff projection have been widely discussed (Potter et al., 2020; Rajulapati et al., 2020; Teng et al., 2015). In Victoria southeastern Australia, Charles et al. (2020) adopted quantile-quantile mapping bias-correction (BC) method to correct raw daily rainfall from Weather Research and Forecasting (WRF) regional climate model and investigated its impact on runoff projection based on GR4J model. They found that the projected runoff showed too large increase when increase was found in WRF-raw rainfall. On the contrary, small decrease in WRF-raw rainfall produced exaggerated small decrease in runoff. In addition to GCMs, another two key sources that may result in uncertainty in runoff projection are RCPs and evapotranspiration estimation in hydrological models (Arnell, 2003). Therefore, this study also aimed to quantify the relative contribution of major sources to the uncertainty in runoff projections.

Australia is one of the arid continents and is very vulnerable to climate change. This study adopted Xinanjiang (XAJ) model driven by ETp inputs estimated by different models with climatic data extracted from 34 GCMs under RCP4.5 and RCP8.5 to: 1) investigate the sensitivity of XAJ model to different ETp inputs in runoff simulation/projection; 2) project the possible change of runoff under different climate scenarios in the tropical North Johnstone river basin, northeastern Australia; and 3) to quantify the uncertainty in runoff projection.

6.2 Materials and methods

6.2.1 Study area

The study area is North Johnstone catchment (Figure 6-1), locating in the Wet Tropics, Queensland. The North Johnstone catchment covers an area of 924km², with elevation ranging from 18 m to 1370 m (Zhang et al., 2020a). One of the reasons why we adopted North Johnstone catchment as our study area is that there is no reservoir in this catchment, which means that the influence of human activities on water resource availability and management is limited in this basin. Therefore, the change of runoff under future climate scenarios can be mainly attributed to climate change. On the other hand, rainfall in this region is the highest in Australia and has a runoff coefficient (the ratio of annual runoff to rainfall) as high as 0.75. Compared with Dry Tropics, this basin receives regular rain throughout the year. However, influenced by the monsoon and tropical lows/depressions, most of its rainfall concentrated in the wet months from December to April. The upper (tablelands or hinterland) area, the middle (the Range or World Heritage), and the lower (coastal or floodplain) area are three distinct areas of this basin.

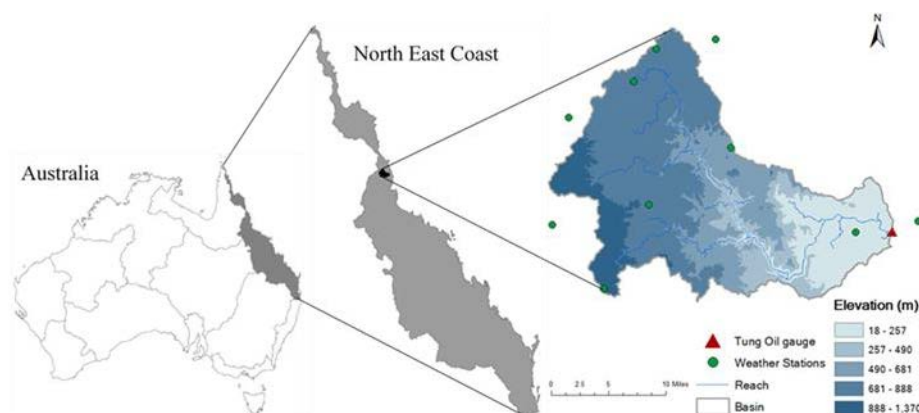


Figure 6-1 Location of the North Johnstone River catchment, Queensland, Australia and the distribution of 10 weather stations and the location of Tung Oil gauge (a hydrologic gauge station).

As shown in Figure 6-1, ten weather sites within or near by the catchment were chosen. The geographical information, the area each site covers, and the multi-year mean climatic factors of these sites were shown in Table 6-1. The Tung Oil gauge received most of the streamflow from the catchment.

Table 6-1 Geographical and the multi-year (2001-2017) mean meteorological information in the research period for ten stations in North Johnstone catchment.

	Lat	Lon	DEM	Area	T	Rs	Rainfall	ETp
	(°S)	(°E)	(m)	(km ²)	(°C)	(MJ M ⁻² day ⁻¹)	(mm)	(mm)
Evelyn State Forest (ESF)	-17.5	145.5	1006	21.5	19.6	18.4	1235	1519
Gadgarra Forest Reserve (GFR)	-17.3	145.7	762	11.2	22.5	18.5	2506	1639
Malanda Post Office (MPO)	-17.4	145.6	762	96.6	20.8	18.4	1845	1566
Millaa Millaa (MM)	-17.5	145.6	830	264.0	20.5	18.4	2233	1548
Pearamon (PRM)	-17.3	145.6	760	38.8	20.3	18.4	1893	1534
Shottery (STR)	-17.6	145.6	914	37.4	19.5	18.4	1640	1505
Topaz Towalla Rd (TTR)	-17.4	145.7	710	181.0	22.0	18.5	3242	1604
Barron Upper 1 (BU)	-17.4	145.5	800	51.6	20.7	18.5	1508	1573
Bottom of Pin Grin Hill (PGH)	-17.5	146.0	40	2.96.0	23.8	18.4	3375	1620
East Palmerston Nerada (EPN)	-17.5	145.9	80	219.0	24.0	18.5	3402	1644

6.2.2 Xinanjiang (XAJ) model

As a lumped conceptual rainfall-runoff hydraulic model, the XAJ model has been widely used to simulate runoff in humid and sub-humid regions (Li et al., 2012; Zhang et al., 2019a). The area-mean daily precipitation and daily potential evapotranspiration are inputs for this model while daily runoff and actual evapotranspiration, and soil moisture are its outputs. XAJ model includes four layers, namely evapotranspiration, runoff production, separation of runoff components, and flow concentration, as shown in Figure 6-2. In specific, the actual evapotranspiration output from XAJ model come from three soil layers, namely the upper soil layer (0 - 20 cm), the lower soil layer (20 – 50 cm), and the deepest soil layer (> 50 cm). The values of tension water capacity corresponding to the three layers are determined by experience (Ren-Jun, 1992). In general, they varied from 5-20 mm for the upper layer, 60-90 mm for the lower layer, and 80-90 mm for the deep layer. The runoff simulated by XAJ model is based on the assumption that runoff is produced after the soil moisture content of the aeration zone has reached field capacity (Ren-Jun, 1992). As we mainly focus on the climate change effect on runoff, the XAJ model this study used did not consider vegetation and its interaction with the atmosphere.

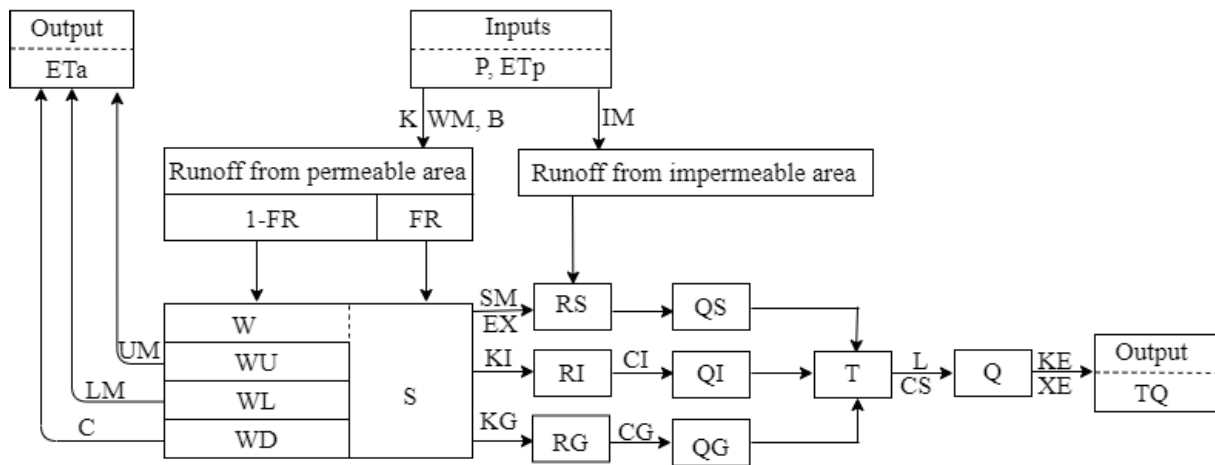


Figure 6-2 The flow chart for the XAJ model.

The actual evapotranspiration (ET_a) yielded by XAJ model is the sum of the evapotranspiration from the upper, the lower, and the deepest soil layers. The meaning of parameters in XAJ model are as follow: W represents for areal mean tension water storage; W_U , W_L , and W_D are three components of W , representing for the upper, the lower, and the deepest tension water storage, respectively. Correspondingly, W_M , W_L , and W_D as shown in Table 6-2 are the parameters for these state variables. FR means the runoff producing area whereas $1-FR$ is area that does not produce runoff. S represents for areal mean free water storage; RS represents for surface runoff; RI represents for interflow runoff; and RG represents for groundwater runoff. Runoff from permeable area has these three components whereas runoff from impermeable area is surface runoff. T represents for the total sub-basin inflow to the channel network and Q is the discharge from a sub-basin. Q_S , Q_I , and Q_G are three components of Q . Lastly, TQ is the total discharge from the whole basin. Table 2 showed the meaning of each parameter and values of these parameters. More detail information on XAJ can be found in Ren-Jun (1992).

Table 6-2 The 16 calibrated parameters and their value that were good for all ETp models to produce the best runoff simulation in the North Johnstone river catchment. The values of parameters were the results of cross-model validation.

Layers	Parameters	Meaning of parameters (units)	Values
Evapotranspiration	UM	Areal mean tension water capacity in the upper layer (mm)	10
	LM	Areal mean tension water capacity in the lower layer (mm)	90
	C	Coefficient of deep evapotranspiration	0.0461
Runoff production	WM	Areal mean tension water capacity (mm)	120
	B	Exponent of the tension water capacity (mm)	0.3500
	IM	Ratio of the impervious to the total area of the basin	0.0384
Separation of runoff components	SM	Areal mean of the free water capacity of the surface soil layer (mm)	10
	EX	Exponent of the free water capacity curve	1.1007
	KG	Outflow coefficient of the free water storage to groundwater	0.3000
	KI	Outflow coefficient of the free water storage to interflow	0.5000
	CI	Recession constant of the interflow storage	0.3618
	CG	Recession constant of groundwater storage	0.9200
	CS	Recession constant of surface water storage	0.1834
Flow concentration	L	Lay time (day)	0
	KE	Parameters of the Muskingum method (h)	24
	XE	Parameters of the Muskingum method	0.2370

6.2.3 Climate data and observed runoff

Historical daily climatic data at 10 chosen climate stations (Figure 6-1) were extracted from the Scientific Information for Land Owners (SILO) patched point dataset (<https://www.longpaddock.qld.gov.au/silo/datadrill/index.php>). The climatic data from SILO is well qualified by Jeffrey et al. (2001) with spatial interpolation method. This climatic data used in this study were maximum temperature (Tmax), minimum temperature (Tmin), maximum relative humidity (RHmax), minimum relative humidity (RHmin), solar radiation (Rs), and rainfall. Meanwhile, this study extracted historical daily observed discharge at the Tung Oil gauge from the Bureau of Meteorology website

(<http://www.bom.gov.au/waterdata/>) to calibrate and validate XAJ model.

In addition to historical climate data, daily climatic data including Tmax, Tmin, Rs, and rainfall under RCP4.5 and RCP8.5 scenarios were downscaled from 34 global climate models (GCMs). The downscale method was developed by Liu and Zuo (2012) and has been widely used in the assessment of climate change effects on drought (Feng et al., 2018a), crop yield (Ruan et al., 2018), rainfall (Feng et al., 2018b), and runoff projection (Zhang et al., 2019a).

6.2.4 The remote sensing-based evapotranspiration product and empirical ETp models

The PML-V1 and PML-V2 are two different versions of Penman-Monteith-Leuning model, which accounts for the physical features of canopy and soil water loss to more accurately estimate surface conductance (Leuning et al., 2008). Compared with PML-V1, which couples Leuning surface conductance model with Penman-Monteith model to estimate transpiration from the plant canopy (Zhang et al., 2016), the PML-V2 model uses a water-carbon coupled canopy conductance model to estimate ET based on remote sensed leaf area index, albedo, and surface emissivity (Gan et al., 2018). Lately, Zhang et al. (2019b) furtherly improved PML-V2 model by incorporating the vapor pressure deficit to constrain canopy conductance and transpiration. Thus, PML-V2 can assess the influence of change in CO₂ concentration on canopy conductance and plant evapotranspiration. The resolution of global PML-V2 is 500 m and 8-day. It is generated by using 500-m Moderate Resolution Imaging Spectroradiometer (MODIS) remote sensing data in the Google Earth Engine. In Zhang et al. (2019b), they compared and validated the 8-day evapotranspiration product with the 8-day evapotranspiration measurements by 95 widely-distributed flux towers from 2002 to 2017. They found that the RMSE and bias between the PML_V2 ET and measured ET was 0.69 mm day⁻¹ and -1.8%. The RMSE and bias during the leave-one-out cross-validation was 0.73 mm day⁻¹ and -3%. They concluded that the PML_V2 products are significantly better than most global evapotranspiration products. Thus, in this study we included evapotranspiration extracted from this product as the benchmark. The global PML-V2 products are freely accessed for global water and carbon studies through the Google Earth Engine and more details about this product can be found in Zhang et al. (2019b). The PML-V2 products have been updated to May 2020 from February 2000. Zhang et al. (2020b) simulated runoff at ungauged regions across Australia with PML_V2 to drive XAJ and SIMHYD models and found that PML_V2 was reliable in simulating monthly runoff and mean annual runoff.

In addition to PML_V2, empirical models including the physically-based Penman model, radiation-based Jensen-Haise (JH), Abtew (Ab), and modified Makkink (Mak), and temperature-based Hargreaves (HS) models were also used to drive XAJ model. ET_p estimated by these models was firstly accumulated into 8-day ET_p, then input the 8-day ET_p into XAJ model to simulate runoff. Thus, to evaluate the difference of XAJ model in simulating runoff with empirical ET_p models and PML_V2.

6.2.5 Calibration and validation of XAJ model

The historical climatic data and observed runoff data from 2000 to 2010 were used to calibrate XAJ model while the data from 2011 to 2017 were used for model's validation. This study used SCE-UA (Shuffled Complex Evolution method developed at the University of Arizona), a global optimization method to optimize XAJ model parameters. As different ET_p models were used to calculate ET_p and drive XAJ model, the parameters calibrated by a certain ET_p model were also used to validate XAJ model for other ET_p models in addition to the one used for calibration. In other words, cross-model validation was carried out among these ET_p models to investigate the sensitivity of XAJ model to different ET_p models. The parameters that produced for the best runoff simulation for all ET_p models were then used in runoff projection with downscaled climatic data under future climate scenarios, as shown in Table 6-2. To project the change of runoff in the future period, we divided the downscaled climatic data into five time periods, namely baseline period from 2001 to 2020; near future period from 2021 to 2040 (2030s); middle future period from 2041 to 2060 (2050s); far future period from 2061 to 2080 (2070s); and further future period from 2081 to 2100 (2090s).

6.2.6 Evaluation of model performance

Nash-Sutcliffe Efficiency (NSE), coefficient of determination (R^2), and root mean square error (RMSE) were used to evaluate the performance of the XAJ model driven by different models-estimated ET_p. The NSE has been widely used in comparing hydrologic model performance (Fang et al., 2020; Li et al., 2009). It ranges from $-\infty$ to 1. The value of 1 represents that the model-simulated runoff perfectly matches with the observed runoff. Therefore, the closer the NSE value is to 1, the better the hydrological model performs. Generally, a hydrological model with NSE and R^2 larger than 0.50 is capable to effectively simulate stream flow for a certain catchment (Zhang et al., 2019a). The NSE, R^2 , and MBE were calculated with the following equations:

$$NSE=1-\frac{\sum_{i=1}^N(\mathcal{Q}_{obs,i}-\mathcal{Q}_{sim,i})^2}{\sum_{i=1}^N(\mathcal{Q}_{obs,i}-\bar{\mathcal{Q}}_{obs})^2} \quad (6-1)$$

$$R^2=\frac{\left[\sum_{i=1}^N(\mathcal{Q}_{obs,i}-\bar{\mathcal{Q}}_{obs})(\mathcal{Q}_{sim,i}-\bar{\mathcal{Q}}_{sim})\right]^2}{\sum_{i=1}^N(\mathcal{Q}_{obs,i}-\bar{\mathcal{Q}}_{obs})^2\sum_{i=1}^N(\mathcal{Q}_{sim,i}-\bar{\mathcal{Q}}_{sim})^2} \quad (6-2)$$

$$RMSE=\sqrt{\frac{1}{n}\sum_{i=1}^n(PML_V2-ET_{p,models})^2} \quad (6-3)$$

6.2.7 Partitioning uncertainty to different sources

As we mentioned in the section of 6.1, GCMs, RCPs, and ETp models are the main sources contributing to the uncertainty for runoff projection in this study. To analyze their relative contribution and associated interactions among them, this study adopted a three-way analysis of variance (ANOVA), which has been widely used in uncertainty assessment (Morim et al., 2019; Wang et al., 2020). The relative contribution and their associated interactions were quantified as the proportion of the partial squares to the total sum of the squares, shown as the following equation:

$$SST = \underbrace{SS_{GCMs} + SS_{RCPs} + SS_{ETp,models}}_{main\ effects} + \underbrace{SS_{GCMs:RCPs} + SS_{GCMs:ETp,models} + SS_{RCPs:ETp,models} + SS_{GCMs:RCPs:ETp,models}}_{interaction\ effects} \quad (6-4)$$

6.3 Results

6.3.1 ETp calculated with empirical models PML_V2

ETp represents the atmospheric evaporation demand while ETa is the actual evapotranspiration. Only when rainfall (soil moisture) is not limited could ETa be as satisfied as ETp. Figure 6-3 indicated that the temperature-based model HS followed by the radiation-based model JH showed higher correlation with PML_V2, with R² ranging from 0.33 (BU) to 0.81 (STR) and from 0.25 (BU) to 0.71 (TTR), respectively. On the contrary, Mak showed the weakest correlation with PML_V2. The R² of Mak ranged from 0.14 (BU) to 0.58 (TTR). In addition, the R² of models showed variation among stations. It generally became smaller in the following order among stations, namely TTR, STR, MM, GFR, ESF, PRM, PGH, MPO, EPN, and BU.

In terms of RMSE, Ab and HS generally produced smaller values than other models. For instance, RMSE produced by HS ranged from 0.70 mm day⁻¹ to 1.42 mm day⁻¹ whereas JH model, despite the high R² produced higher RMSE, ranging from 1.23 mm day⁻¹ to 2.59 mm day⁻¹. In summary, model HS showed both higher R² and lower RMSE, thus was the model that produce the closest ET estimation as PML_V2 did.

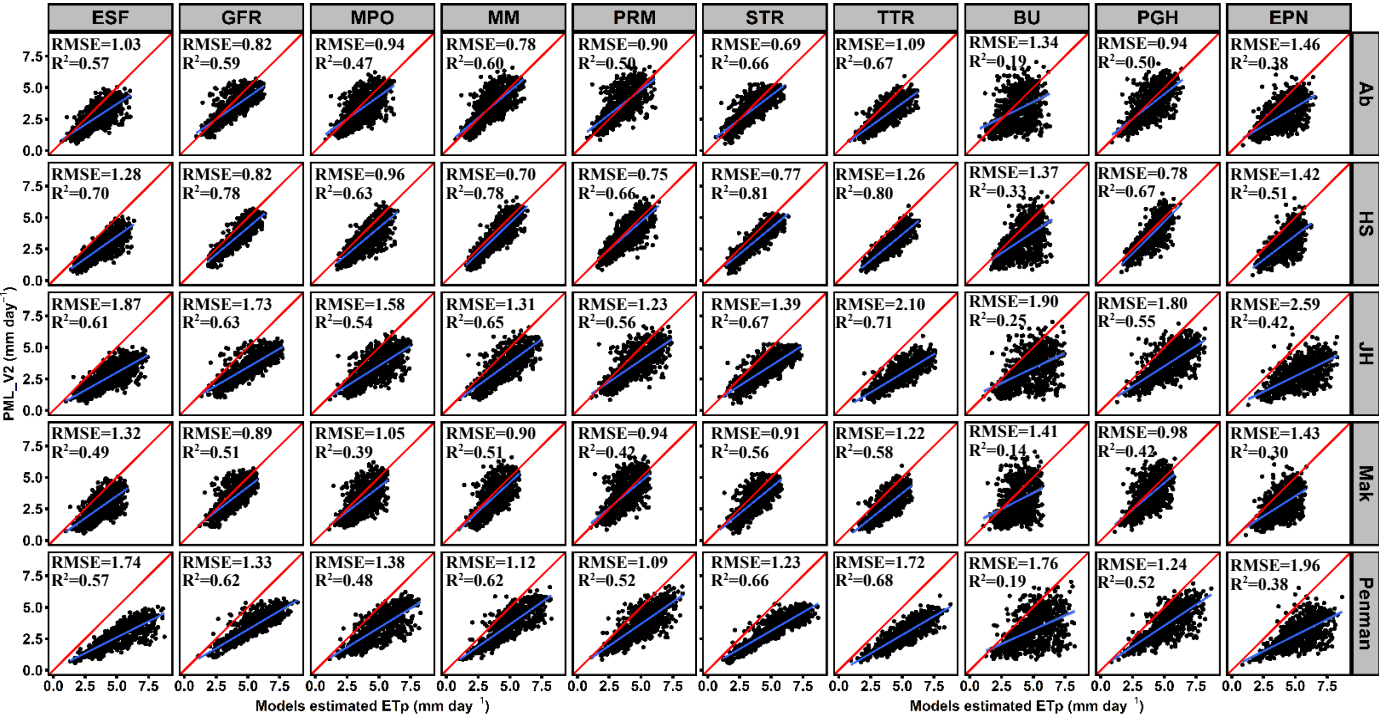


Figure 6-3 Scatter plots of the daily ETa (mm day⁻¹) estimated by PML_V2 vs ETp estimated by empirical ETp models from 2000 to 2017 for each of ten stations in North Johnstone river catchment, Queensland, Australia. The unit for RMSE is mm day⁻¹. The red and the blue lines represent the 1:1 lines and the linear regression lines, respectively.

6.3.2 XAJ model calibration and cross-model validation

Calibrated parameters with the chosen ETp models for XAJ model in the North Johnstone river catchment were shown in Table 6-3. With the six group of parameters, the performance of XAJ model driven by different ETp models were assessed via the statistical indexes (R², NSE, RMSE) between the observed and the simulated runoff, as shown in Table 6-4.

Table 6-3 Group of parameters calibrated with ETp estimated by different models to drive XAJ model.

	Ab	HS	JH	Mak	Penman	PML_V2
WUM	10	10	10	10	10	10
WLM	90	90	90	88	90	86
C	0.0461	0.0996	0.0608	0.0974	0.0431	0.0918
WM	120	120	120	120	120	120
B	0.3500	0.3500	0.3500	0.3500	0.3500	0.3499
IM	0.0384	0.0400	0.0400	0.0400	0.0400	0.0400
SM	10	10	10	10	10	10
EX	1.1007	1.1375	1.4453	1.4659	1.499	1.2355
KG	0.3000	0.3000	0.3000	0.3002	0.3000	0.3000
KI	0.5000	0.4658	0.4998	0.4998	0.4917	0.4972
CI	0.3618	0.2202	0.3506	0.2283	0.2947	0.2905
CG	0.9200	0.9200	0.9200	0.9200	0.9200	0.9200
CS	0.1834	0.2166	0.1949	0.2174	0.2106	0.1792
L	0	0	0	0	0	0
KE	24	24	24	24	24	24
XE	0.2370	0.1898	0.1374	0.0029	0.4835	0.2735

The performance of XAJ model with a certain group of parameters did not show significant difference among ETp models in the simulation of runoff (Table 6-4). The R^2 between the simulated and the observed runoff were generally larger than 0.89 for the calibration period and larger than 0.80 for the validation period no matter which group of parameters in Table 6-3 was used to calibrate XAJ model. Similarly, the NSE for the calibration and the validation periods were larger than 0.83 and 0.74, respectively. Meanwhile, the largest RMSE for the corresponding periods were less than 3.00 mm day⁻¹ for calibration period and 3.10 mm day⁻¹ for the validation period. On the one hand, the high R^2 and NSE indicated that the observed runoff was well simulated by XAJ model. On the other hand, the small difference of the statistical indexes among different ETp models showed that XAJ model was not sensitive to the difference of ETp models.

Table 6-4 The R², NSE, and RMSE between observed runoff and simulated runoff with the six groups of parameters shown in Table 6-3. The ETp model that was used to calibrated XAJ model was marked as red during cross-model validation. The unit for RMSE is mm day⁻¹.

	Calibration			Validation			Calibration			Validation		
	R ²	NSE	RMSE	R ²	NSE	RMSE	R ²	NSE	RMSE	R ²	NSE	RMSE
Ab	0.89	0.87	2.62	0.83	0.80	2.67	0.89	0.87	2.62	0.83	0.80	2.67
HS	0.89	0.85	2.78	0.82	0.79	2.76	0.89	0.85	2.77	0.82	0.79	2.76
JH	0.89	0.83	2.98	0.81	0.76	2.97	0.89	0.83	2.98	0.81	0.76	2.97
Mak	0.89	0.86	2.68	0.83	0.80	2.71	0.89	0.86	2.68	0.83	0.80	2.72
Penman	0.89	0.83	2.97	0.80	0.74	3.09	0.89	0.83	2.96	0.80	0.74	3.09
PML_V2	0.90	0.87	2.57	0.82	0.80	2.67	0.90	0.87	2.57	0.82	0.80	2.67
Ab	0.89	0.87	2.62	0.83	0.80	2.67	0.89	0.87	2.62	0.83	0.80	2.67
HS	0.89	0.85	2.78	0.82	0.79	2.76	0.89	0.85	2.77	0.82	0.79	2.76
JH	0.89	0.83	2.98	0.81	0.76	2.97	0.89	0.83	2.98	0.81	0.76	2.97
Mak	0.89	0.86	2.68	0.83	0.80	2.71	0.89	0.86	2.68	0.83	0.80	2.71
Penman	0.89	0.83	2.96	0.80	0.74	3.09	0.89	0.83	2.96	0.80	0.74	3.09
PML_V2	0.90	0.87	2.57	0.82	0.80	2.67	0.90	0.87	2.57	0.82	0.80	2.67
Ab	0.89	0.87	2.62	0.83	0.80	2.67	0.89	0.87	2.62	0.83	0.80	2.67
HS	0.89	0.85	2.78	0.82	0.79	2.76	0.89	0.85	2.77	0.82	0.79	2.76
JH	0.89	0.83	2.98	0.81	0.76	2.97	0.89	0.83	2.98	0.82	0.76	2.96
Mak	0.89	0.86	2.68	0.83	0.80	2.72	0.89	0.86	2.68	0.83	0.80	2.71
Penman	0.89	0.83	2.96	0.80	0.74	3.09	0.89	0.83	2.96	0.80	0.74	3.08
PML_V2	0.90	0.87	2.57	0.82	0.80	2.67	0.89	0.87	2.57	0.82	0.80	2.67

The temporal variation of runoff at daily and annual scale with the group of parameters calibrated with Ab model were shown in Figure 6-4 and Figure 6-5, respectively. Generally, the temporal trends were well replicated by XAJ model regardless of the difference in ETp inputs. However, the simulated peak runoff was generally smaller than the observed one. As shown in Figure 6-5, the simulated annual runoff generally underestimated observed runoff. The underestimation yielded by PML_V2 was overall smaller than that

produced by other ETp models whereas Penman model generally produced the largest underestimation. Though PML_V2 and Penman are both physically-based models, the remote-sensing based PML_V2 model estimated the actual evapotranspiration while Penman model calculate the ETp. This might explain why XAJ model driven by PML_V2 performed better than that driven by Penman model. In addition, the worse performance of XAJ model driven by Penman model may also indicate that it is not always a necessary to adopt a complex ETp model in runoff projection.

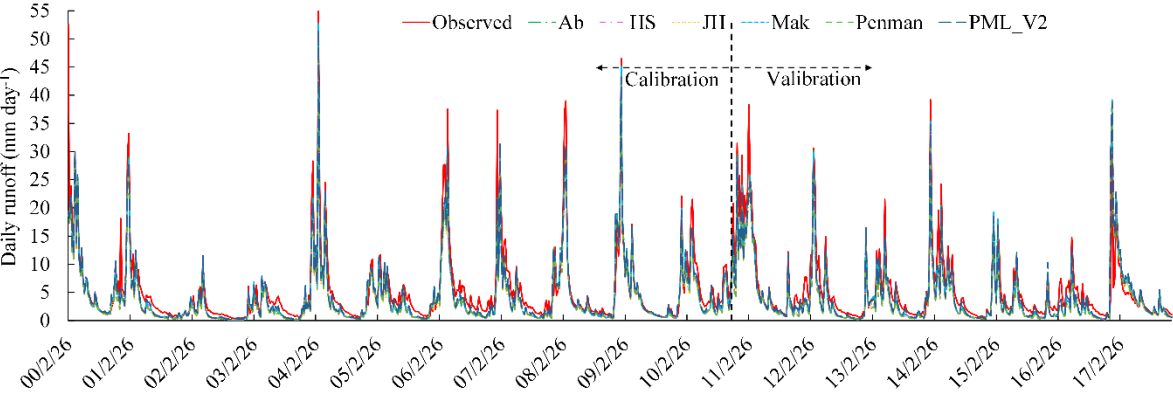


Figure 6-4 The observed daily runoff and the simulated daily runoff by XAJ model with calibrated parameters of Ab model (as in Table 6-1) during calibration (2000-2010) and validation (2011-2017) periods in the North Johnstone catchment.

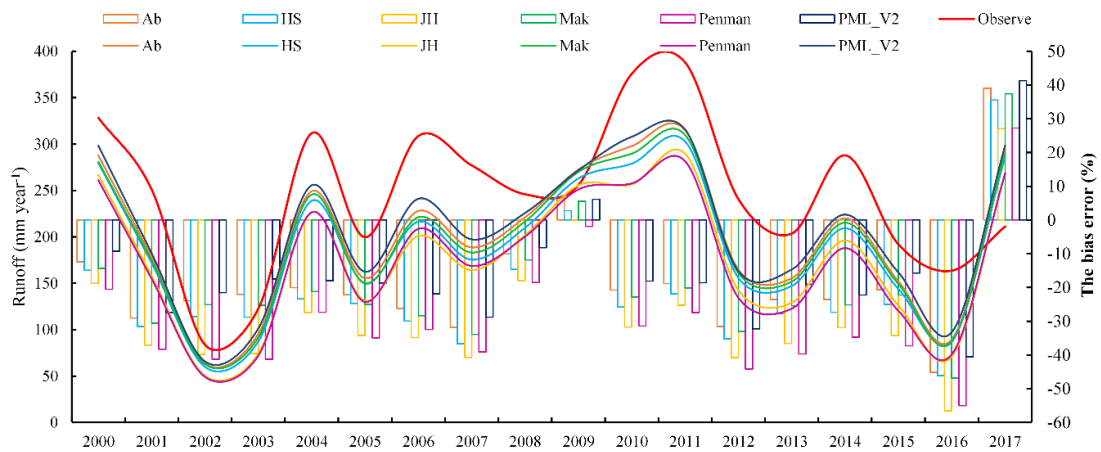


Figure 6-5 The annual historical observed and simulated runoffs with calibrated parameters shown in Table 1 in the North Johnstone river basin. The bar plot (second-y-axis) showed the bias error (simulated runoff-observed runoff)/observed runoff*100) between simulated runoff and observed runoff.

6.3.3 Changes in rainfall and evapotranspiration under future climate scenarios

Compared with the baseline period (2001-2020), the change of rainfall under future climate scenarios showed seasonal difference, as shown in Figure 6-6. Except the small increase under RCP4.5 in 2030s, spring rainfall showed a general decrease. The smallest mean decrease in spring rainfall was 2% under RCP4.5 in 2050s. By 2090s under RCP8.5, the decrease was 12%. Though winter rainfall also decreased in the future, the magnitudes of decrease were smaller than that in spring, ranging from 3% to 8%. The changes of rainfall in summer and autumn did not show a uniform trend and the mean change magnitudes were small.

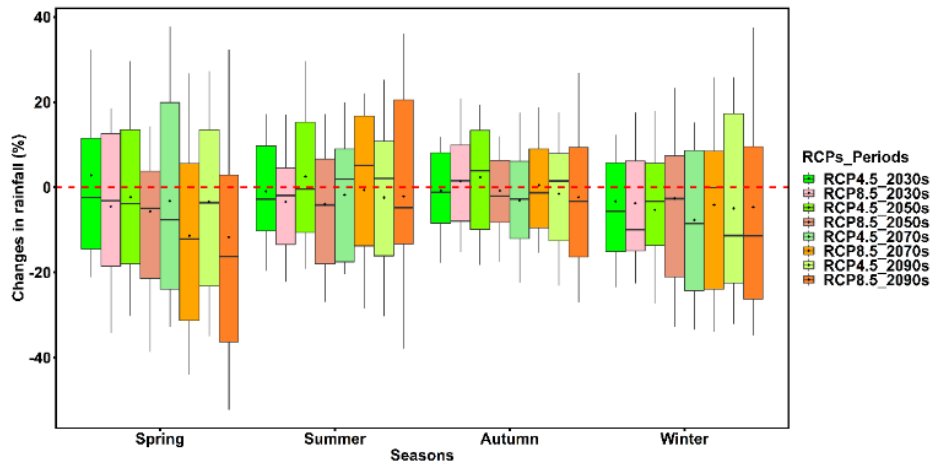


Figure 6-6 Projected seasonal changes in rainfall (%) in the near future (2021-2040, 2030s), middle future (2041-2060, 2050s), far future (2061-2080, 2070s), and further future (2081-2100, 2090s) under RCP4.5 and RCP8.5 scenarios based on 34 GCMs compared with the baseline period (2001-2020). The upper and lower box boundaries indicate the 75th and 25th percentiles; the black line and the black dot within the box represents the median and mean value, respectively; the upper and lower whiskers are the 10th and 90th percentiles.

Figure 6-7 showed that ETp projected by all models showed increases for all seasons and the increasing patterns were similar among seasons. In general, model JH followed by Ab projected larger increases of ETp than Mak and HS did for a certain future period. The mean increases of ETp projected by JH and Ab varied from 1.6% by the 2030s under RCP4.5 to 15.7% by the 2090s under RCP8.5. The corresponding mean increases projected by Mak and HS ranged from 0.2% to 6.9%. Contrary to the uniform increases of ETp for all seasons, the changes of ETa showed seasonal variation. In specific, spring ETa was likely to decrease, especially the decrease became larger with time going into further future period. Other seasons tended to experience increases in ETa. However, the increases of ETa were obviously smaller than that in ETp. For instance, the largest mean increases of ETa in summer, autumn, and winter were 5.6%, 8.9%, and 4.5%, respectively. The unmatched changes of ETp and ETa may indicate that evapotranspiration in North Johnstone catchment may be limited by water supply in the further future period with the decreases in rainfall.

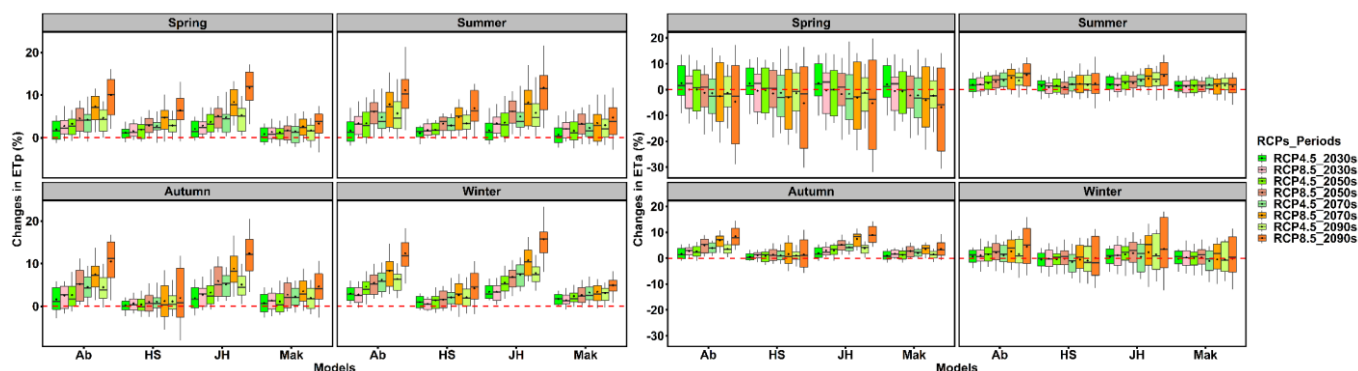


Figure 6-7 Projected seasonal changes in ETp (%) and ETa (%) for different ETp models in the near future (2021-2040, 2030s), middle future (2041-2060, 2050s), far future (2061-2080, 2070s), and further future (2081-2100, 2090s) under RCP4.5 and RCP8.5 scenarios based on 34 GCMs compared with the baseline period (2001-2020). The upper and lower box boundaries indicate the 75th and 25th percentiles; the black line and the black dot within the box represents the median and mean value, respectively; the upper and lower whiskers are the 10th and 90th percentiles.

6.3.4 Changes in soil moisture under future climate scenarios

Contrary to the general increases in evapotranspiration, soil moisture generally showed decreases under future climate scenarios (Figure 6-8). Compared with summer and autumn, spring and winter were likely to experience larger decreases in soil moisture. Meanwhile, the decreases in soil moisture became larger with time going into further future periods. The maximum mean decreases for soil moisture in spring, summer, autumn, and winter were 9.4%, 5.3%, 3.1%, and 6.7% respectively. As to the changes in soil moisture at different layers, variation was observed. Spring soil moisture at upper layer showed general increases with the exception under RCP8.5 by the far and further future periods. The decreases of soil moisture at upper layer in winter were larger than that in summer and autumn. Soil moisture at lower layer tended to decrease for all seasons and the decreases in spring was the largest, ranging from 3.9% to 25.6%. The seasonal variation for changes in deeper soil moisture was significant, that is, significant decreases for spring and summer but no obvious change for autumn and winter.

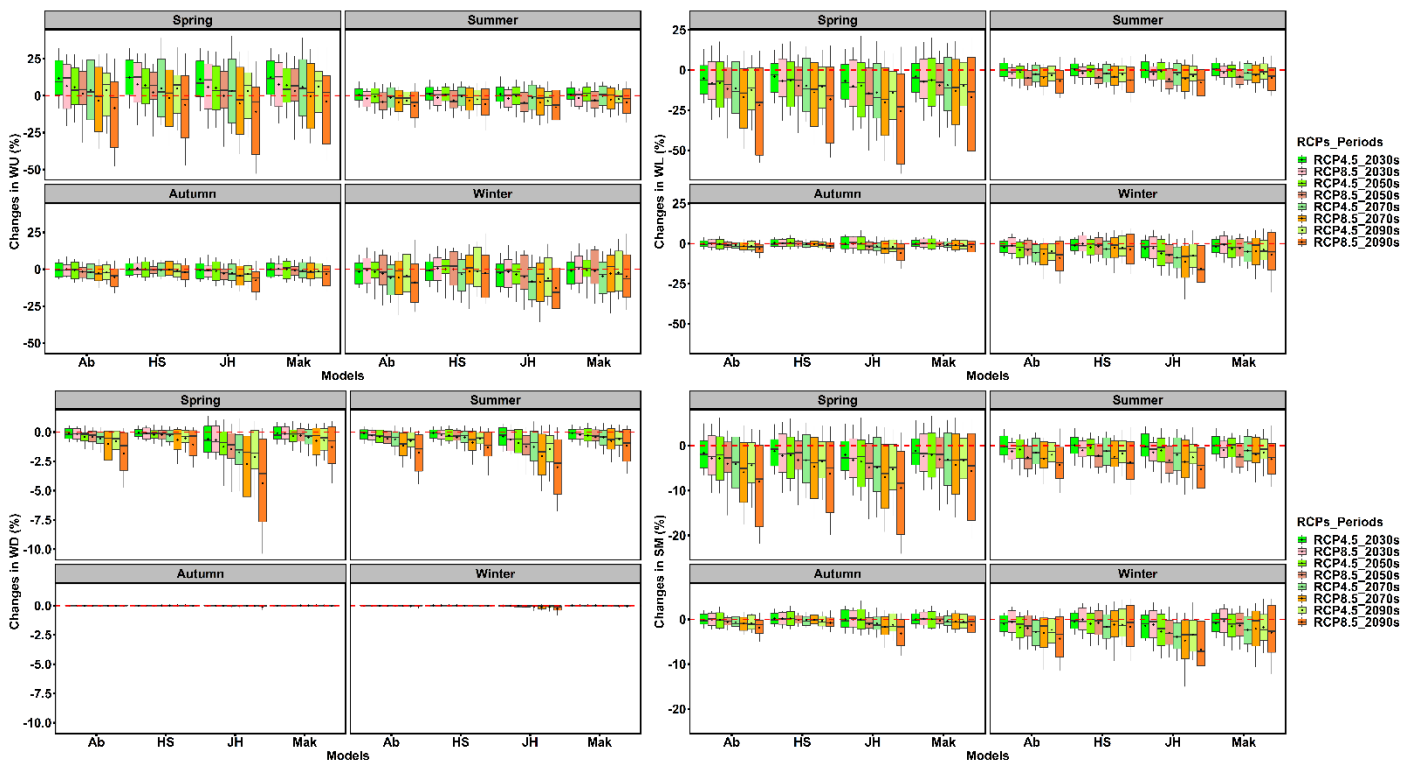


Figure 6-8 Projected seasonal changes in soil moisture for different layers, namely the upper soil layer (0 - 20 cm), the lower soil layer (20 – 50 cm), and the deepest soil layer (> 50 cm) in the near future (2021-2040, 2030s), middle future (2041-2060, 2050s), far future (2061-2080, 2070s), and further future (2081-2100, 2090s) under RCP4.5 and RCP8.5 scenarios based on 34 GCMs compared with the baseline period (2001-2020). The upper and lower box boundaries indicate the 75th and 25th percentiles; the black line and the black dot within the box represents the median and mean value, respectively; the upper and lower whiskers are the 10th and 90th percentiles

6.3.5 Changes in runoff under future climate scenarios at different time scales

Despite the difference of change in ET_p projected by four ET_p models, nuanced difference was observed among ET_p models in terms of the changes in runoff projected by XAJ model driven by different ET_p models (Figure 6-9). Changes of runoff under RCP4.5 and RCP8.5 scenarios showed seasonal difference. Similar to the changes of rainfall, mean runoff showed significant decreases in spring and winter whereas summer and autumn mean runoff barely showed change. In addition, the decreases of runoff under RCP8.5 were larger than that under RCP4.5 for the same future period, and the decreases got larger with time going into further future period. For instance, the spring mean runoff showed subtle increase (around 1.0%) in 2030s under RCP4.5 whereas the same period under RCP8.5 witnessed an 8.0% decrease in runoff, which

was even larger than the decrease (6.7%) in 2090s under RCP4.5. By 2090s under RCP8.5 the decrease for spring runoff was largest with maximum mean decreases ranging from 15.4% to 18.2% by 2090s. The mean decrease of winter runoff was generally smaller than the corresponding periods of that in spring, ranging from 2.9% to 14.8%, with the largest decrease found by 2090s under RCP8.5 ranging from 6.9%-14.8%.

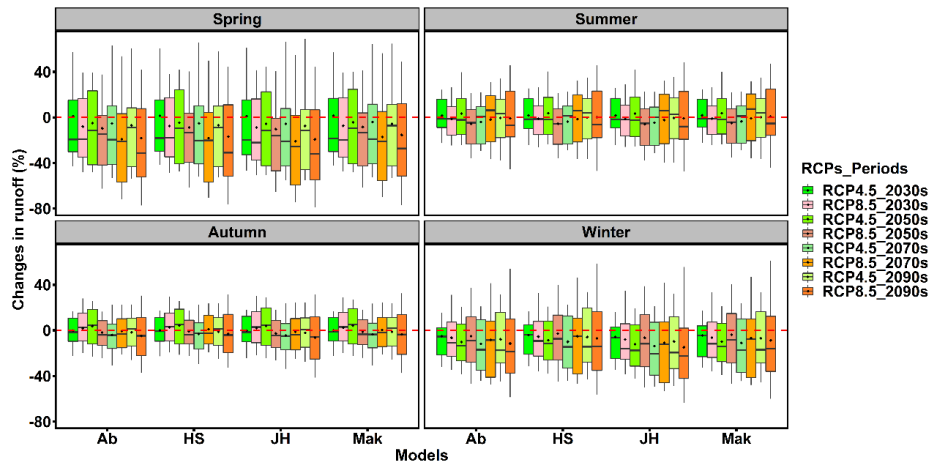


Figure 6-9 Projected seasonal changes in runoff (%) for different ETp models in the near future (2021-2040, 2030s), middle future (2041-2060, 2050s), far future (2061-2080, 2070s), and further future (2081-2100, 2090s) under RCP4.5 and RCP8.5 scenarios based on 34 GCMs compared with the baseline period (2001-2020). The upper and lower box boundaries indicate the 75th and 25th percentiles; the black line and the black dot within the box represents the median and mean value, respectively; the upper and lower whiskers are the 10th and 90th percentiles

To disentangle the relationships among runoff and its driving factors, this study analyzed their correlation based on Pearson correlation coefficients, shown in Figure 6-10. In general, ETp showed negative relationships with all other factors while the other factors are generally positively related. The coefficients between rainfall and runoff were generally larger than 0.95, showing the strongest correlation. Following rainfall, soil moisture at the upper (WU) and lower (WL) layers also showed strong correlation with runoff, coefficients between them ranging from 0.64 to 0.82. On the contrary, the correlation between soil moisture at deep layer (WD) and runoff was weak. The correlation between ETa and runoff showed seasonal variation, that is, they showed stronger relationship in spring and winter than they did in summer and autumn. As to ETp, its relation with runoff showed variation among ETp models, namely ETp projected by HS followed by JH showed the weakest relation with runoff while ETp projected by Ab and Mak showed stronger one.

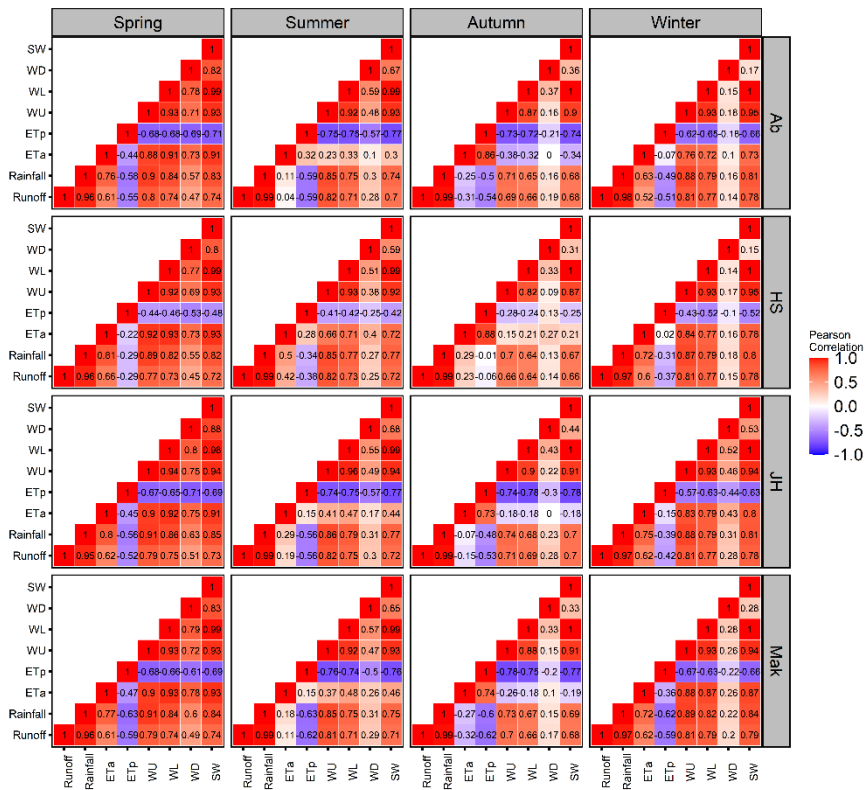


Figure 6-10 Pearson correlation coefficients for the relation between runoff and its related factors. The purple color showed negative correlation while the red color showed the positive correlation.

6.3.6 Uncertainty in runoff projection

Figure 6-11 showed the relative contribution of different sources to the uncertainty caused in runoff projection for each season. In general, GCMs contributed the most to the uncertainty, ranging from 49.3% to 60.9%. The interaction between GCMs and RCPs also played a significant role in the total uncertainty, ranging from 35.8% to 47.9%. In contrast, the uncertainty caused by different ETP models was minor for all seasons, even though it was getting larger in winter than that in spring. The minor role of ETP models may be explained by the fact that runoff projection via XAJ model was rarely influenced by the difference of ETP models, as shown in Figure 6-9.

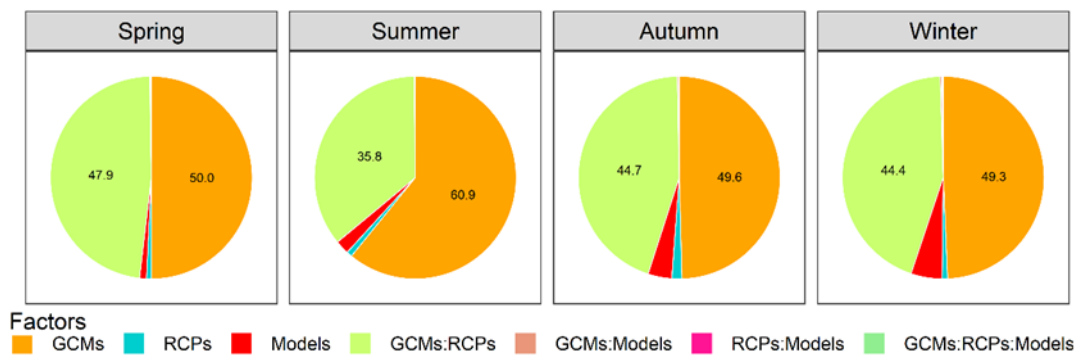


Figure 6-11 The relative contribution of GCMs, RCPs, ETp models and their interactions to the uncertainty caused in runoff projection for each season.

6.4 Discussion

Both R^2 and RMSE between estimated ETp and PML_V2 varied from station to station (Figure 6-3) and the spatial variation among the five empirical models were very similar. Overall, ETp estimated by all models showed the worst correlation with PML_V2 at BU followed by EPN. ETp estimated by empirical models represented the atmospheric evaporative demand. In stations where ETp is larger or equal to rainfall, the actual evaporation is mainly limited by water supply of the evaporative surface and will be smaller than ETp whereas in relative humid station ($ETp < \text{rainfall}$) water supply is not a limiting factor and ETa may approach to ETp. As shown in Table 6-1, rainfall in BU is no larger than its ETp, this may explain why R^2 between ETp and PML_V2 in this station was the smallest for all models.

The modelled ETa showed similar trends with ETp (generally increase, Figure 6-7) but opposite trends with rainfall (decrease in spring and summer, Figure 6-6). This confirmed that despite the decrease in rainfall and runoff in North Johnstone catchment, evapotranspiration in this region is still energy limited instead of water limited under future climate scenarios. However, the magnitudes of increases of ETa did not match with that of ETp (Figure 6-7). This may be explained by the fact that ETa is a function of ETp and soil moisture (Arnell, 2003). When water limited happens in soil moisture, the ETa would also be limited and cannot be as large as ETp. Thus, the general decrease in soil moisture, rainfall, and runoff may still highlight the possibility of water shortage in this region.

Despite the obvious difference in ETp estimation, this study found that runoff simulated with different ETp inputs was similar (Figure 6-4, Figure 6-5, & Figure 6-9), which may indicate that the influence of ETp inputs on runoff simulation/projection by XAJ model is subtle. In specific, PML_V2 produced more accurate simulated runoff than empirical models did but the difference was small. In other words, the improvement in

runoff projection yielded by improvement of estimates in ETp was marginal (Kelleher and Shaw, 2018). This may indicate that as a rainfall-runoff model, XAJ was not sensitive to the biases in ETp inputs. Similar to findings in this study, Oudin et al. (2005) investigated sensitivity of four different rainfall-runoff models to ETp inputs estimated by 27 models. They observed that temperature-based and radiation-based ETp models was likely to provide the best runoff simulation whereas the physically-based Penman model seemed less advantageous. In this study, the difference in changes of runoff among different ETp models under future climate scenarios was also insignificant (Figure 6-9). In this case, it is an encouraging and convenient result from the perspective of choice in ETp models in runoff projection in the future as climate data (e.g. wind speed or relative humidity) from GCMs are not always available or reliable (Oudin et al., 2005; Randall et al., 2007). However, the sensitivity of different hydrological models may be different with XAJ model, or a drier climate may make hydrological models more sensitive to ETp inputs (Gosling and Arnell, 2011; Kingston et al., 2009). Therefore, special attention is still needed to pay to the choice of ETp models to drive hydrological models.

This study projected a general decrease in runoff under future climate scenarios, especially for the spring and winter runoff (Figure 6-9). A drier future is consistent with that reported by other studies (Chiew et al., 2010; Islam et al., 2014). For instance, Chiew et al. (2009) adopted SIMHYD, a conceptual rainfall-runoff model, driven by climate data from 15 GCMs to project runoff across southeast Australia. They claimed that there would be less runoff in southeast Australia under a 0.9 °C increase in surface air temperature. The change patterns in runoff were very similar with that in rainfall (Arnell, 2003). In our study, the Pearson correlation between runoff and rainfall was largest (Figure 6-10). This indicated that rainfall is the main driving factors in the change of runoff. Followed rainfall, changes in soil moisture played a secondary role in the changes of runoff. This finding was also supported by Wasko et al. (2021). The role of evapotranspiration in runoff change is reported as that it would cause an additional reduction in runoff under a warming climate but would not change the relative results (Charles et al., 2020). In southwest Western Australia, Barria et al. (2015) found that runoff by 2050-2080 would decrease by 10%-80% compared to runoff in 1970-2000 and they claimed that the reduction in runoff was mainly due to reduction in precipitation and was strengthened by the increase in temperature. Based on Budyko's curve, Donohue et al. (2011) assessed the sensitivity of runoff to changes in precipitation and potential evapotranspiration. They found that despite the spatial variation of the sensitivity of runoff showed to these two factors, the change of precipitation caused larger change in runoff than the same change of ETp caused. The low sensitivity of runoff to ETp may also

partially explain why runoff projected by hydrological models driven by different ETp models did not show much difference.

GCMs followed by interaction between GCMs and RCPs was the dominant source resulting in uncertainty in runoff projection (Figure 6-11) (Barria et al., 2015). Similar to our study, Her et al. (2019) also reported that the uncertainty caused by GCM projections was dominant in runoff projection. At global scale, Arnell and Gosling (2013) also reported that uncertainty in hydrological projection was mainly dominated by spatial difference of climate change projected by different GCMs. This may be explained by the fact that the projection of runoff is more influenced by the projection of rainfall, which showed great uncertainty among different GCMs (Charles et al., 2020; Rajulapati et al., 2020). The uncertainty in runoff projection proposed challenge for decision makers in taking measures to adapt to the possible water scarcity and stress. The possibilities to narrow uncertainty in future projection has been discussed among researchers (Hawkins and Sutton, 2011). This study adopted the CMIP5 climatic data, with new improved modelling (CMIP6) there is potential to reduce the uncertainty.

6.5 Conclusion

This study aimed to investigate the influence of different ETp inputs into Xinanjiang model on runoff simulation and projection in North Johnstone catchment. In historical period, runoff simulated with empirical ETp models was slightly worse than that simulated with PML_V2 but still showed high correlation with observed runoff. In the future periods, runoff projected with different ETp models showed similar changes, decreasing in spring and winter and no significant change in summer and autumn. The subtle difference among runoff projected with different ETp models indicated that adoption of simple empirical ETp models in runoff projection is feasible and convenient from an operational point of view as climatic data from GCMs are not always available or reliable. The unsensitivity of Xinanjiang model to ETp models was also supported by the relatively small contribution of ETp models to the uncertainty in runoff projection. The runoff decrease was mainly contributed to the decrease in rainfall. Meanwhile, the unmatched magnitudes of increasing showed by ETa and ETp and the decrease of soil moisture indicated that North Johnstone region might shift from energy-limited to water-limited from the perspective of evapotranspiration. Lastly, the decrease of runoff may make the water-rich North Johnstone catchment shift to the edge of decrease in water availability.

6.6 Reference

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Chapter 7. Summary and future research

7.1 Summary

Evapotranspiration is an important nexus both to hydrological cycle and climate system. This study firstly explored the capability of simplified empirical ETp models in estimating ETp rates, detecting its temporal trends, and capturing its periodically oscillation across different climate zones. Based on findings of which, three random forest-based models were developed as a comparison with their corresponding empirical models including radiation-based Jensen-Haise, Abtew, modified Makkink, temperature-based model Hargreaves in ETp estimation and projection. Then, the response of ETp, drought, and runoff to climate change and the uncertainty in their projection under both RCP4.5 and RCP8.5 scenarios were investigated. The main findings and insights displayed by this thesis could be summarized as the following:

- (1) Radiation-based models and the temperature-based model HS generally outperformed the other two temperature-based models and mass transfer-based models. Meanwhile, the performance of random forest-based models outperformed their corresponding empirical models. This finding shed a light on model choice for situations when measured evapotranspiration was not available or when the climatic data was not supportive for the use of physically based Penman model.
- (2) Despite the difference in the magnitudes estimated by different models, ETp under both RCP4.5 and RCP8.5 scenarios were likely to increase mainly due to the increase in temperature and solar radiation. The increases of ETp showed variation among stations, namely the more arid the station was, the larger increase of ETp showed under future climate scenarios. This may imply that the western areas of NSW may become drier at a speed than the eastern part of NSW. More than 2/3 of NSW is characterized with arid or semi-arid climates. The increasing of ETp suggest that the atmospheric evaporative demand in this region is going to be stronger. In this context, some area of NSW may shift from sub-humid or humid climates to arid or semi-arid climates without the increase in rainfall, thus challenging the agricultural production in this region.

Uncertainty in the projection of ETp under future climate scenarios was mainly caused by the difference of RCPs and GCMs while the contribution of ETp models was relatively small except at humid stations. This finding highlights the importance of adopting the ensemble method with multiple GCMs and RCPs to yield reasonable ranges of future projection.

- (3) The occurrence of drought under future climate scenarios was likely to increase, especially for

moderate and severe droughts. Meanwhile, spring and winter would experience more increases in drought occurrence than summer and autumn would do. Drought is one of the most serious natural disasters agricultural production in Australia faces. There is no doubt that more moderate and severe droughts would bring more challenge to agricultural production, or even worse making some areas not suitable for crop production any more without proper measures for the adaptation. Especially, a few key growth periods of winter wheat happen in spring and winter, more drought occurrence in these two seasons may bring serious reduction in crop yield. In order to adapt to the potential negative effects resulting from more drought, new drought-resistant varieties of crop may be a necessary. In addition, development of drought-forecasting system will also help to offer powerful information to guide agricultural production. From the perspective of farmers, they may shift the sowing windows accordingly to adapt to climate change effects.

Compared with historical period, the role of ETp in drought occurrence was going to improve under future climate scenarios. This finding confirmed the suggestion that it is necessary to use drought indexes which not only developed based on rainfall but also include evapotranspiration for drought projection under future climate scenarios.

- (4) The influence of different ETp inputs on runoff simulation and projection by Xinanjiang model was subtle. In other words, improve the complexity of ETp models can only result in marginal improvement for the performance of Xinanjiang model in runoff simulation. Independence of ETp inputs, runoff projected by Xinanjiang model was likely to decrease in spring and winter while the change of summer and autumn runoff did not show uniform pattern. The patterns of runoff changes were similar with the changes in rainfall. The decrease in runoff is possible to yield hydrological drought and have negative effects on the tropical ecosystem. The difference in GCMs and their interaction with RCPs were the two dominant factors leading to uncertainty in runoff projection. The low sensitivity of Xinanjiang model to different ETp inputs is convenient and encouraging for ETp models choice in runoff projection under future climate scenarios given the fact that not all climatic data from GCMs have high reliability to support the use of complex ETp models.

In summary, whether it is from the perspective of agricultural drought occurrence or from the perspective of runoff, eastern Australia is likely to face higher water stress. Agricultural production in eastern Australia is mainly rain-fed.

7.2 Limitations and future research

Though this study offered useful information on performance of widely used empirical, and random forest models in ETp estimates, their influence on drought, and runoff projection. There are a few limitations of this study. First, performance of these ETp models was assessed against the Penman model instead of observed evapotranspiration, which may result in bias. With the improvement in monitoring technologies, long time sequences of observed evapotranspiration data from eddy covariance stations or remote sensing may be available in the future. It is necessary to tap into these state-of-the-art technologies in evapotranspiration research. Second, the key problem in existing ETp models is that existing ETp models ignore the vegetation response to elevated CO₂, leading to a higher hydrological sensitivity to temperature. Thus, the drought projection based on such ETp models may have slightly overestimation and bias (Keenan et al., 2020; Milly and Dunne, 2017). Thus, in future study, it is important to consider the effects of CO₂ fertilization on plant evapotranspiration so that to assess the response of drought and runoff to climate change at a more accurately level (Fowler et al., 2019; Yang et al., 2019; Yang et al., 2020). Lastly, in addition to the difference of GCMs, RCPs, and ETp models, the downscaling method used to downscale the coarse GCMs climatic data from global to regional scale is another key source resulting in uncertainty in future projection (Anandhi et al., 2011; Wilby et al., 2000). This study only adopted data downscaled with a statistical downscaling method. In future study, it is necessary to do investigation on the influence of different downscaling methods.

7.3 Reference

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