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The definitive publisher version is available online at [10.1016/j.powtec.2022.117538](https://doi.org/10.1016/j.powtec.2022.117538)

Experimental Analysis of Water and Slurry flows in Gravity-driven Helical Mineral Separators

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1 **Abstract**

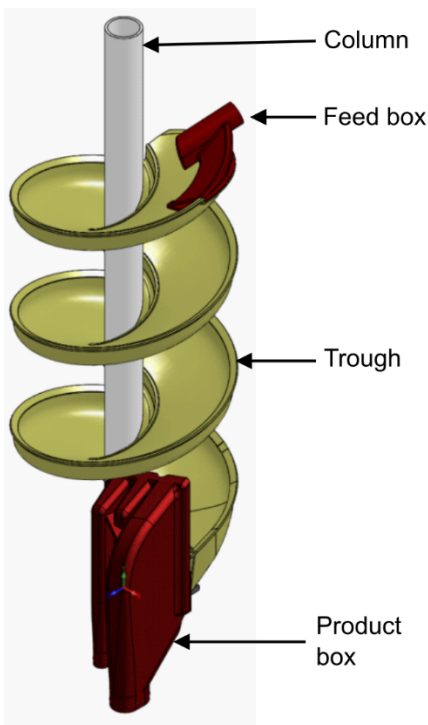
2 This paper aims to provide essential information of the water and slurry flow behaviour in a popular
3 full-scale mineral separation spiral. Besides critical measurements of the free surfaces, the wall
4 roughness and wall contact angle, novel measurements and assessment of the commonly
5 encountered 'bubble line' are provided herein. The free surface shapes of three flows: water-only,
6 chromite slurry and magnetite slurry are compared for the first time, which highlights operational
7 spiral phenomena. The research provides insight into the mechanics behind the 'wetting-in'
8 process by showing that this process affects the wall contact angle more than the surface
9 roughness. The most representative roughness height of the spiral trough was found to be 138.4
10 μm and the wall contact angle of the spiral surface was 88.14°, measured in the water phase. The
11 experiments showed that the free surface shape and the position and width of the bubble line in a
12 water-only flow reached a steady state after 1.25 spiral turns. The results and findings are
13 applicable to spirals of other makes and models and can validate future spiral fluid flow
14 simulations.

15 **Keywords**

16 **Spiral separator, Roughness, Contact angle, Free surface, Bubble line**

17 **1 Introduction**

18 A gravity-driven helical mineral separator, commonly referred to as a 'spiral', separates a slurry,
19 being a mixture of water and suspended mineral particles, into streams of different particle
20 densities. A spiral is a key piece of equipment in transforming ore bodies into valuable
21 commodities, due to its low cost and simple operating principles. A spiral consists of four main
22 components: the central column, the helical surface known as the 'trough', the feed box and the
23 product box, as shown in Figure 1. A slurry is fed into the feed box which directs it onto the trough.
24 The slurry then flows down the trough where gravitational forces and the interaction of the slurry
25 with the trough causes a separation of the slurry by particle density and size. The different streams
26 are collected at the bottom of the spiral by the product box via different offtakes.



27

28 **Figure 1: CS1 mineral separation spiral components**

29

30 An understanding of the flow in spirals has been pursued for decades. Operational observations of
31 the flow in spirals and measurements of their mineral separation efficiency [1-3] formed the basis
32 of understanding the flow behaviour of spirals. These were followed by analytical approximations of
33 the fluid behaviour in spirals [4-6]. These approximations were subsequently improved upon by
34 increasingly complex fluid flow simulations [7-15] to enhance the understanding of the working

35 principals of spiral separators. Due to the complex, and not completely understood [3], fluid
36 behaviour in mineral separation spirals, Computational Fluid Dynamics (CFD) simulations have
37 proved to be a critical tool for many research teams to advance the understanding of the governing
38 principles at work in mineral separation spirals [7-19].

39

40 Practical CFD flow simulation requires approximation models to capture various flow effects, e.g.,
41 lift, drag and turbulence. Due to the large number of available mathematical models to approximate
42 each of these effects, it is critical to validate the complete numerical model to confirm the
43 appropriate selection and interaction of models. Such validation has been applied to fluid flow
44 simulations of mineral separators by various research teams [7-19] through the comparison of the
45 simulation outcomes with experimental data. Due to the industrial nature of a spiral, detailed
46 experimental data available for validation have been scarce and some researchers have used
47 scale models that approximate real spirals to validate their simulation models [13, 17, 18].

48 However, most research teams [7-12, 14-16, 19] validate full-scale spiral flow simulations via
49 experimental data obtained by Holtham and Holland-Batt [4, 20-24] using a single spiral model, the
50 Mineral Technologies' LD9. This spiral model was superseded in the early '90s [22], roughly 30
51 years ago. Thus, recent advances in spiral separation performance, and the possible flow
52 alterations that underpin this, need to be re-examined. Ideally then, further improvement in the
53 understanding of flow behaviour in full-scale spirals through CFD simulation should be based on
54 experimental measurements on current spiral models. This paper aims to provide such data for the
55 widespread CS1 model spiral, which is used around the world to assist in chrome beneficiation
56 [25].

57

58 Given the complex separation processes at play in a mineral separation spiral, and the vast
59 number of different mathematical models available in numerical simulations, it is advisable to firstly
60 perform a CFD analysis for the simplest flow scenario, a water-only flow, to ensure that the fluid
61 flow dynamics are fully understood and that the modelling choices are validated by experimental
62 measurements. Such a validated water-flow simulation can then be used as the basis for the more
63 complex CFD simulation where particles are introduced into the domain. The additional modelling

64 choice accompanying the introduction of particles can subsequently be validated using
65 experimental measurements of a slurry flow in a mineral separation spiral. This two-step approach
66 has been pursued by other research teams, where a water-only flow was firstly analysed [10-12,
67 26] followed by a slurry flow analysis [7-9] to achieve a complete, validated CFD model that can be
68 applied to any mineral separation spiral. To support this methodology, experimental data for both a
69 water-only flow as well as two slurry flows through a modern separation spiral will be provided in
70 this research article.

71

72 Particle separation arises from the interaction of the slurry with the spiral trough wall, through a
73 radial, secondary flow in addition to a primary flow down the spiral [4, 20, 27, 28]. The difference in
74 friction forces between the unhindered air-fluid interface and the hindered fluid-wall interface
75 causes a secondary flow to arise [27]. Given the importance of this slurry-wall interaction on the
76 separation behaviour, such interaction is an inevitable property of any CFD analysis.

77

78 Holland-Batt [4] performed an analytical assessment of the flow behaviour and found that for
79 typical speeds in spirals the flow could not be described as laminar or smooth turbulent. Instead, it
80 was found that the Manning or rough turbulent equation best described the flow behaviour in
81 spirals. Under these conditions, wall roughness influences the flow greatly and is thus an essential
82 input for any CFD simulation, even if this means accepting the default roughness values supplied
83 by the CFD software's manufacturer, especially when modelling a water-only flow. This paper aims
84 to measure the wall properties of a mineral separation spiral and to the best of the authors'
85 knowledge, no such wall roughness data have been published to date.

86

87 A further aspect of the wall-fluid interaction, and a fluid simulation input that must be defined, is the
88 wall-fluid-air contact angle, henceforth referred to as the 'wall contact angle'. This parameter,
89 important in various fields of research [29], describes the interaction of water with a surface. A
90 large wall contact angle defines a hydrophobic wall surface and causes a deposited water droplet
91 to form a bead. A low wall contact angle defines a hydrophilic surface and causes a deposited
92 water droplet to spread out and wet the surface to a greater extent. Holtham [24] showed the

93 importance of this wall contact angle in water-only flows by collecting experimental measurements
94 before and after the application of hydrophilic paint to the trough, since such paint changes the wall
95 contact angle. Before application of the paint, a water-only flow would only partially wet the trough
96 near the outer diameter, whereas after painting the inner regions of the trough were also wetted.
97 The artificially altered wall contact angle acting on the thin water region pulled the start of the water
98 free surface inwards, resulting in a complete wetting of the trough. This makes clear that to
99 accurately validate the simplest flow in a spiral, a water-only flow, knowledge of a realistic wall
100 contact angle is an essential variable in a CFD simulation. Therefore, this variable must either be
101 purposefully defined by a user or naively left as the software's default value. However, although a
102 simulation needs this variable to be input, systematic guidance on defining such wall contact angle
103 of an unmodified spiral surface does not appear to have been published.

104

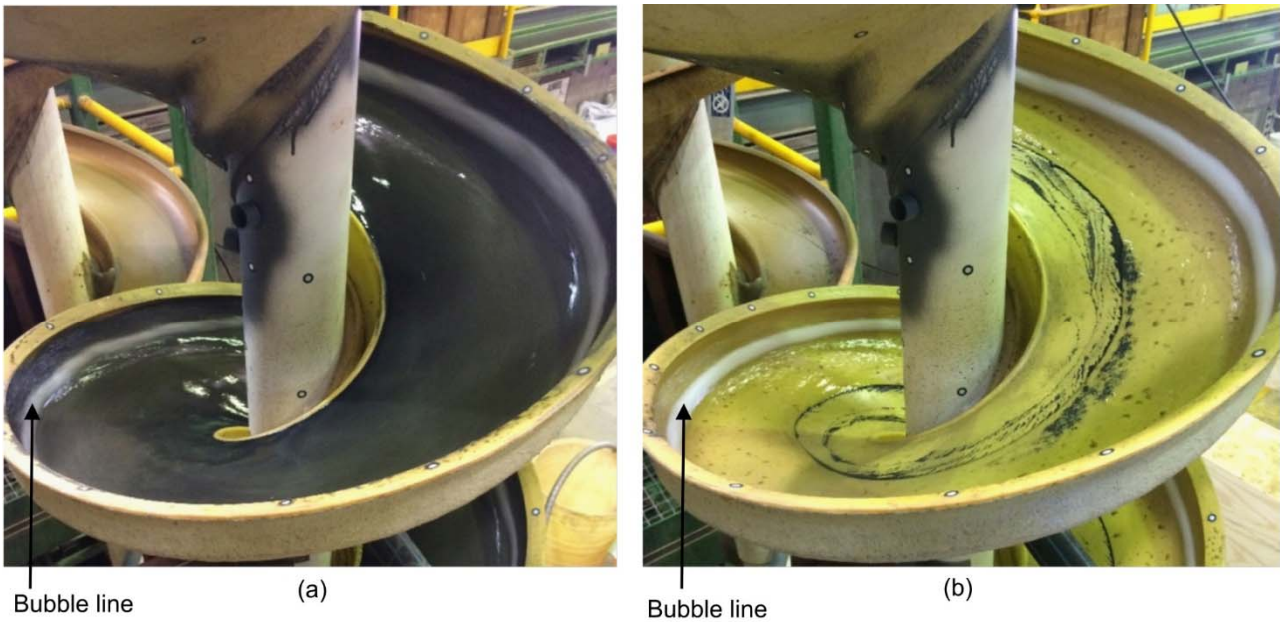
105 A final aspect of the important wall-fluid interaction is to accurately reflect the shape of the trough
106 in the fluid flow simulation. The helical base shape of a spiral can be distorted by the influence of
107 manufacturing processes and gravitational forces. To this end, the exact shape of the trough is
108 measured at six locations along the length of an upright, production-ready spiral.

109

110 Mineral separation spirals have been developed for well over 100 years [1]. It is not surprising that
111 different spiral manufacturers have progressed their spiral design along similar lines. The fact that
112 various spiral manufacturers have adopted polyurethane as their spirals' wear layer [30-32] is
113 testament to this design process as well as to the excellent wear properties of this material. This
114 general application of a polyurethane wear layer in spiral separators makes the presented
115 measurements applicable to a wide variety of spiral makes and models.

116

117 A clearly-defined line of entrained air bubbles, henceforth referred to as the 'bubble line', is often
118 encountered in industrial applications of mineral separation spirals, as shown in Figure 2.



119
120 **Figure 2: Bubble line in a mineral separation spiral with a chromite dominated slurry (a) and water-only flow (b)**

121 The bubble line has not been the subject of significant research efforts. Palmer et al. [2] theorised
122 that the bubble line could be the result of various interacting flows [2]. Jain & Rayasam [6]
123 suggested that the bubble line is indicative of high turbulence where 'water at the periphery
124 reaches escape point and spins back on the trough due to its curved profile. The splashing back of
125 water is subdued because of the continuous flow of water and is observed as a continuous line of
126 fine bubbles running down along the periphery of spiral trough'. Given the common occurrence of
127 the bubble line, general observations thereof can be used qualitatively in other spiral makes and
128 models.

129 **2 Materials and Methods**

130 This section describes the measurement of the wall roughness, the wall contact angle, the trough
131 surface, the free surface, and the bubble line size and position of a full-scale operational CS1-type
132 spiral running a water-only flow and two slurry flows.

133
134 All measurements were conducted on a so-called 'wetted-in' spiral. During the manufacturing of
135 the trough, a release agent is applied to the mould to aid in the demoulding process. This release
136 agent is hydrophobic, adheres to the demoulded trough and has the potential to affect the location
137 and shape of the water free surface [24], the wall roughness and wall contact angle. When water or
138 a slurry has worn the release agent away, the spiral is said to be 'wetted-in'. Prior to the

139 experimental measurements described in this research paper, the spiral was run continuously for 7
 140 days with an abrasive iron ore slurry to ensure any release agent residue has been worn away.
 141 The particle size distributions and particle density distributions of both slurries were measured
 142 through Heavy Liquid Separation (HLS) and are given in Table 1 and Table 2.

143

Chromite slurry		Magnetite slurry	
Size (μm)	Percentage (%) by weight	Size (μm)	Percentage (%) by weight
+850	1.5		
-850+500	5.1	+500	0.5
-500+250	24.8	-500+250	14.9
-250+150	28.6	-250+150	46.2
-150+106	13.1	-150+75	35.5
-106+75	9.5		
-75+38	10.7	-75+38	2.1
-38+20	2.9	-38+20	0.2
-20	3.7	-20	0.6
Total	100.0	Total	100.0
<i>D50 (μm):</i>	185	<i>D50 (μm):</i>	175

144

145 **Table 1: The particle size distribution of the chromite and magnetite slurries**

Chromite slurry			Magnetite slurry		
Size Fraction	Specific Gravity (SG) of the fraction	Percentage (%) by weight	Size Fraction	Specific Gravity (SG) of the fraction	Percentage (%) by weight
+20 μm	-2.85	9.2	+20 μm	-2.85	3.7
	+2.85 -3.6	38.6		+2.85 -3.6	22.8
	+3.6 -4.05	6.5		+3.6 -4.05	1.3
	+4.05	41.9		+4.05	71.6
	<i>sub -total</i>	96.3		<i>sub -total</i>	99.4
-20 μm	-	3.7	-20 μm	-	0.6
Total	-	100.0	Total	-	100.0

146

147

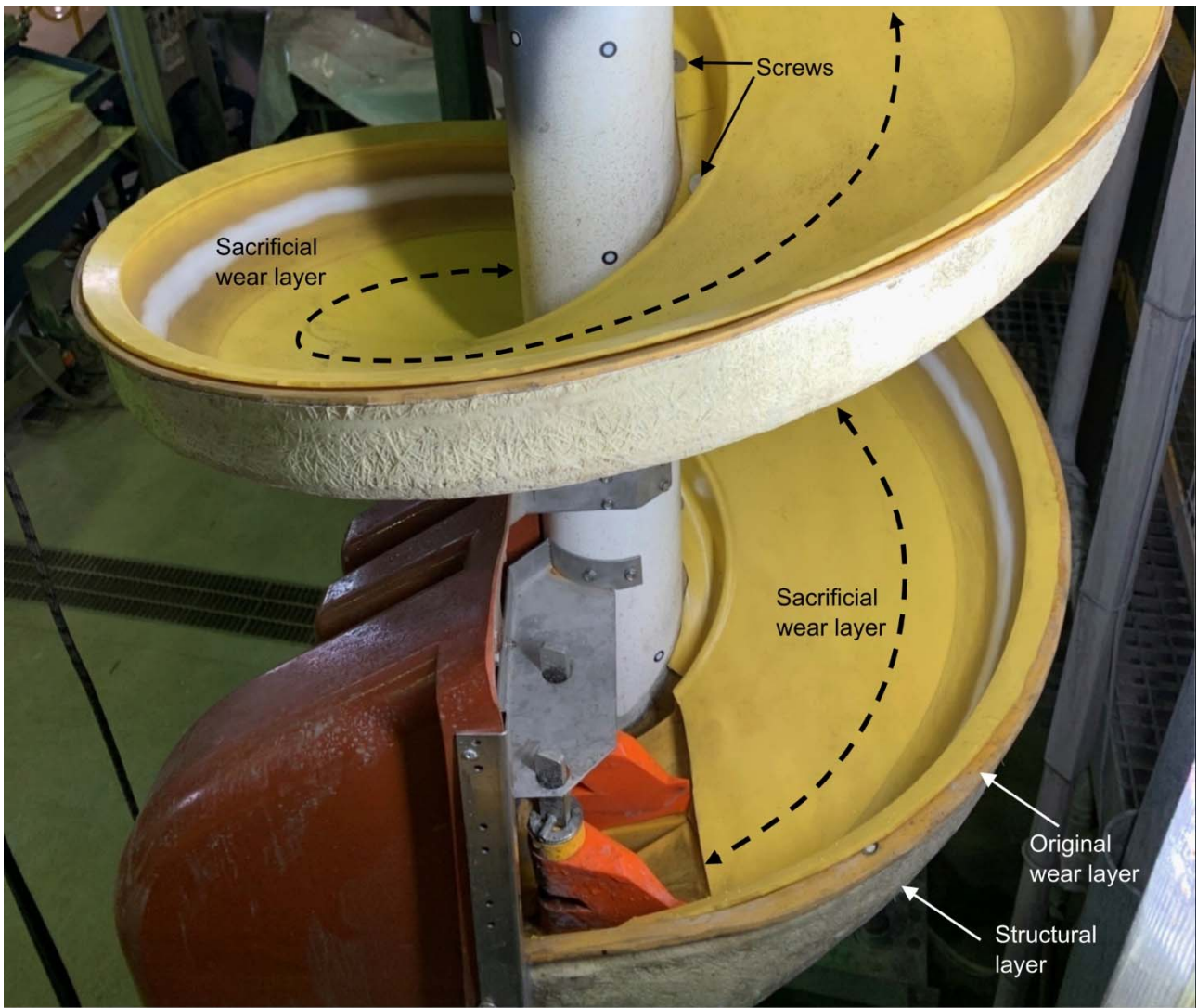
148 **Table 2: The density profile of the chromite and magnetite slurries**

149 2.1 Specimen preparation

150 Normally a spiral trough consists of a polyurethane wear layer which, due to its flexible nature,
 151 needs to be supported by a structural layer to withstand the forces of gravity and the moving slurry.
 152 Due to the curvature of the spiral in two directions, one being the downwards helix, and the other
 153 being the curved cross-sectional shape, specimens extracted from any location on a spiral would
 154 not be flat and could not be flattened due to the inseparable rigid structural layer. This poses a
 155 problem in wall roughness and contact angle testing as a flat or slightly uneven specimen is
 156 preferred to prevent distortion of the measurements. This issue was circumvented by introducing a
 157 sacrificial wear layer.

158

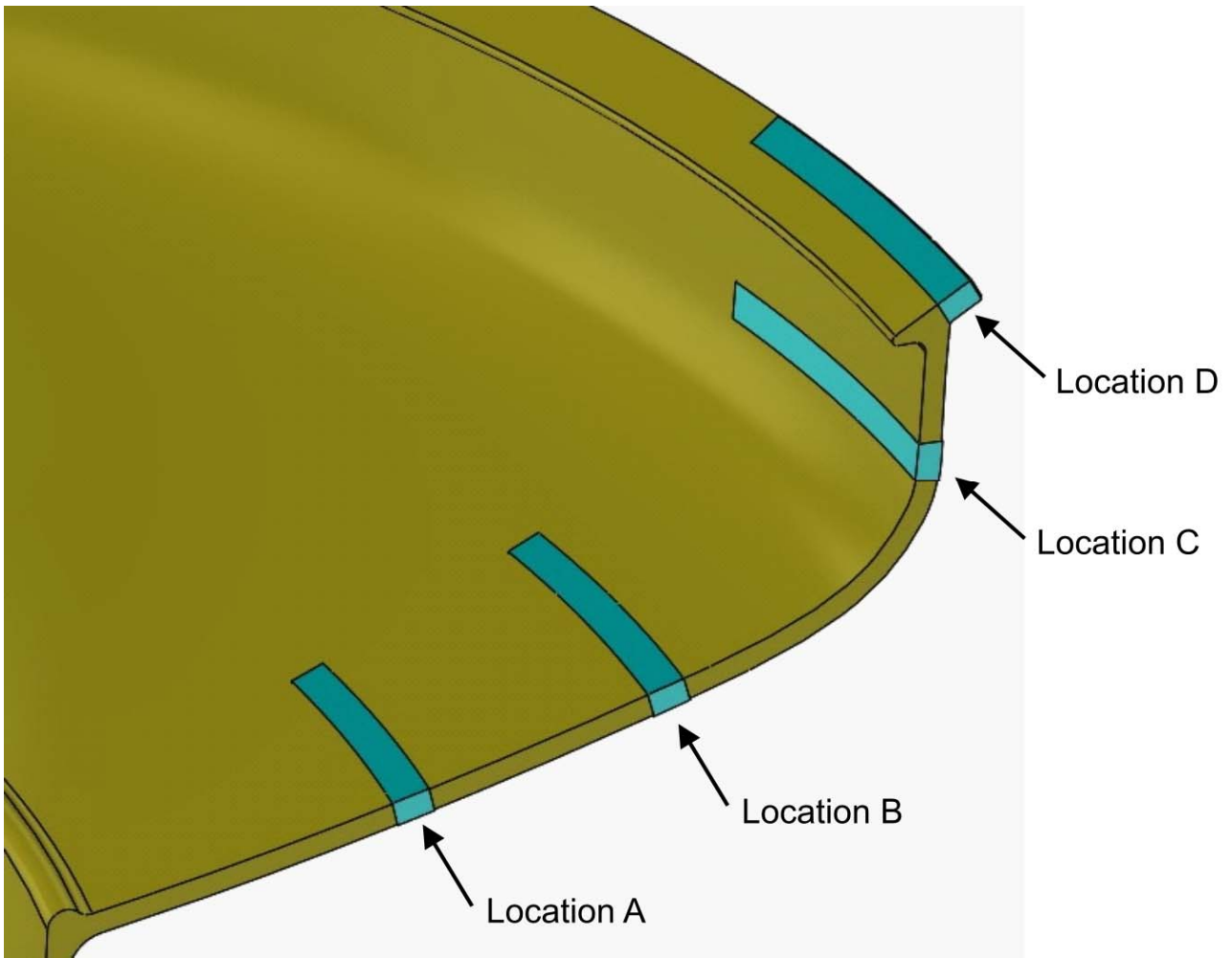
159 A sacrificial wear layer, without the rigid support layer, was produced using the same mould for a
160 normal dual-layered spiral. This sacrificial wear layer is made from the same polyurethane as the
161 original wear layer. Figure 3 shows how this layer was cut to size and overlaid onto the CS1 spiral,
162 then attached to the spiral using screws in unobtrusive locations so they did not interact with the
163 fluid flow. The centripetal force of the moving water and slurries ensured that the outer diameter of
164 the sacrificial wear layer was forced into the shape of the existing wear layer. The feed box was
165 attached on top of the sacrificial wear layer to ensure that the transition from the feed box onto the
166 spiral trough was not altered. The sacrificial wear layer stopped before the product box and thus
167 introduced a disturbance to the flow at this location, possibly altering the mineral separation
168 performance. However, since the spiral's separation performance is not a subject of investigation
169 in this research paper, and this disturbance is not located in the vicinity of the six free surface
170 measurement locations, this transition does not affect any measurements or conclusions. After
171 running the spirals for the prescribed time, the flexible sacrificial wear layer was removed from the
172 spiral and specimens were then extracted from it. This approach thus resulted in specimens of the
173 wear layer of a mineral separation spiral that were worn under realistic flow conditions and were
174 able to be flattened for the roughness and wall contact angle measurements.



175

176 **Figure 3: Sacrificial wear layer installed on the CS1 spiral.**

177 To derive a representative average roughness of the trough surface, specimens are needed from
178 multiple locations. Three locations were selected where the iron ore slurry contacted the trough
179 during the wetting-in process, Location A, B and C in Figure 4. A further location, where the slurry
180 flow never touched the trough, Location D in Figure 4, was selected as a control. Specimens
181 measuring 10 mm × 50 mm were cut using scissors where the long dimension of the specimen
182 was cut to follow the curvature of the spiral. The extracted specimens were used in subsequent
183 experiments to measure the wall roughness and wall contact angle.

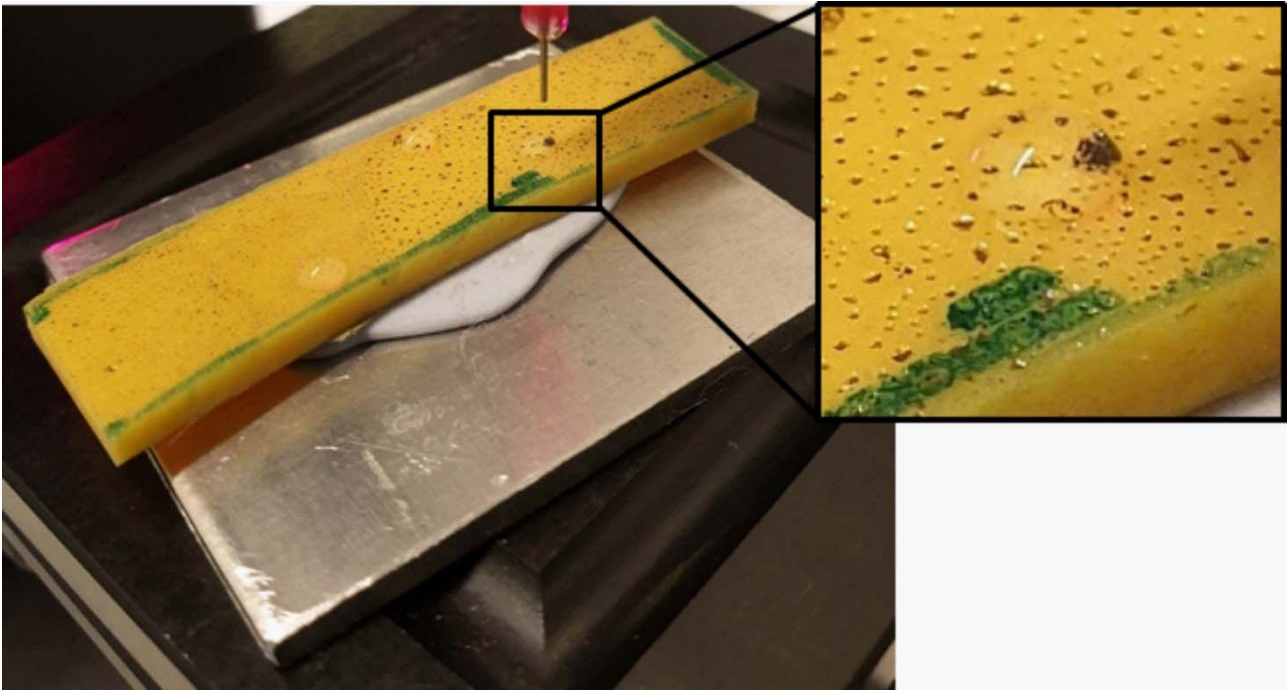


184

185 **Figure 4: Location on the spiral trough of the extracted specimens**

186 **2.2 Surface roughness measurements**

187 For the roughness measurements, the specimens described in section 2.1 were affixed to a flat
188 aluminium backing plate using 'Blu-Tack', a putty-like adhesive. This allowed the top surface to be
189 positioned parallel to the horizontal plane to the best of the operator's ability, as shown in Figure 5.



190

191 **Figure 5: A trough specimen affixed to a flat aluminium backing plate using 'Blu-Tack' adhesive, and a zoomed**
192 **in view of the specimen's surface porosity**

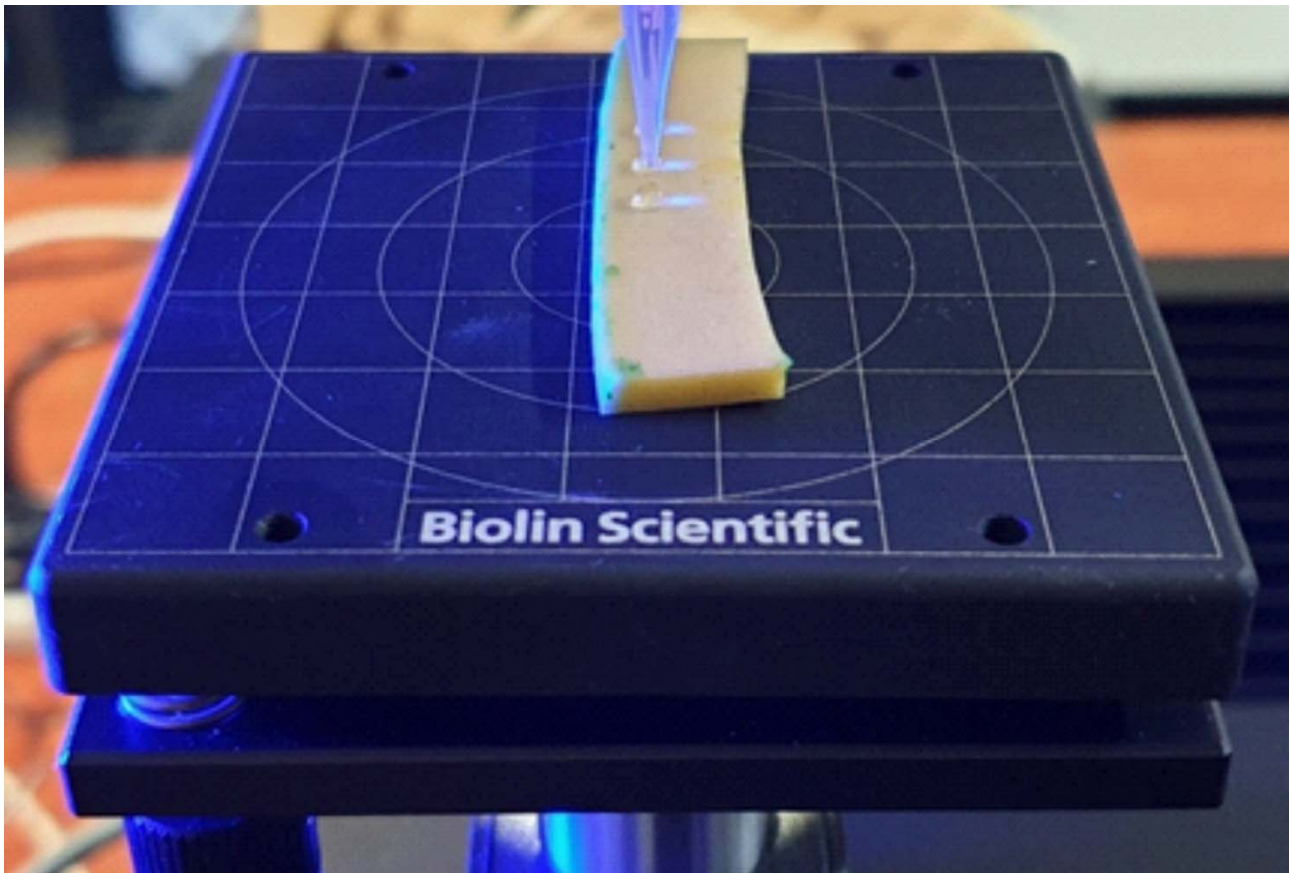
193 The surface was scanned with an Olympus OLS5000 3D measuring laser microscope using a 10×
194 zoom level on a 10 × 10 mm portion of each specimen. To correct any remaining curvature a
195 digital second-order polynomial curvature correction was utilised. Tilt correction was applied to
196 digitally level the specimens. Digital noise correction was utilised during the scan. Roughness
197 values were determined by digitally assessing, and averaging, the topology height along a
198 minimum of 6 equally spaced, parallel lines across the 10 x 10 mm scan area. Two roughness
199 values were reported: the commonly used Arithmetic Mean Deviation (Ra), and the Maximum
200 Height (Rz).

201

202 Due to the porosity of the specimen, the potential exists that iron ore particles imbed or become
203 lodged in cavities along the trough top surface. Care was thus taken to not clean the specimens
204 before testing in order to capture, as realistically as possible, the surface roughness of the trough
205 as experienced by a moving slurry and water flow. The surface porosity of the specimen is
206 highlighted by the iron ore residue forming black dots that can be observed in the inset zoomed-in
207 view of Figure 5.

208 **2.3 Wall contact angle measurements**

209 The same specimens used in the roughness measurements were placed in the Biolin Scientific
210 Attension Theta Flex Optical Tensiometer to perform wall contact angle measurements. Specimen
211 levelling was achieved via the manually operated tilt frame so that the surface was flat from the
212 tensiometer camera's viewpoint, as shown in Figure 6.



213

214 **Figure 6: The specimen levelled using the tilt mechanism on the tensiometer, the syringe has just deposited the**
215 **third sessile drop**

216 For each specimen, the height of the specimen tilt frame was entered in the tensiometer software,
217 as was the specimen thickness. This allowed the software to set an appropriate starting position of
218 the syringe tip. Default software settings were used, including positioning the camera to minus 2° to
219 allow the capture of the droplet's reflection on the specimen. With these settings, the tensiometer
220 was set to run a sessile drop experiment, where firstly an automatically dispensed droplet made
221 from 5 microliters of distilled water was suspended at the syringe tip. The syringe, and thus the
222 suspended droplet, were then automatically lowered, based on the specimen thickness and tilt
223 frame settings, so that the droplet contacts the specimen surface, wetting it partially. The syringe
224 was subsequently raised, which forced the droplet to detach from the syringe tip and completely

225 wet the surface. Once the syringe started its ascent, 10 s of video was recorded at 33 frames per
226 second. For each specimen (Location A, B, C and D) a minimum of 3 sessile drop experiments
227 were performed via this procedure.

228

229 The wall contact angle is calculated through post-processing of the recorded video using the
230 tensiometer data analysis software. Default Young-Laplace curve fitting is used to automatically
231 approximate the curvature of the droplet mathematically. This curvature is intersected by a
232 horizontal line determined by the specimen surface, the so-called 'baseline'. For each individual
233 sessile drop test, the baseline was set to where the bubble curvature meets its reflection, as
234 captured by the camera. At the two intersection points of the baseline with the droplet curvature, on
235 both sides of the droplet, the software calculates the wall contact angle, measured inside the water
236 phase. As the bubble needs to settle after the removal of the syringe tip, the wall contact angle was
237 calculated for every frame once the change in angle is less than 0.15%. At each frame, the
238 resulting wall contact angles were exported from the tensiometer software and averaged over both
239 time and the readings from the two sides of the droplet.

240 **2.4 Free surface and bubble line measurements**

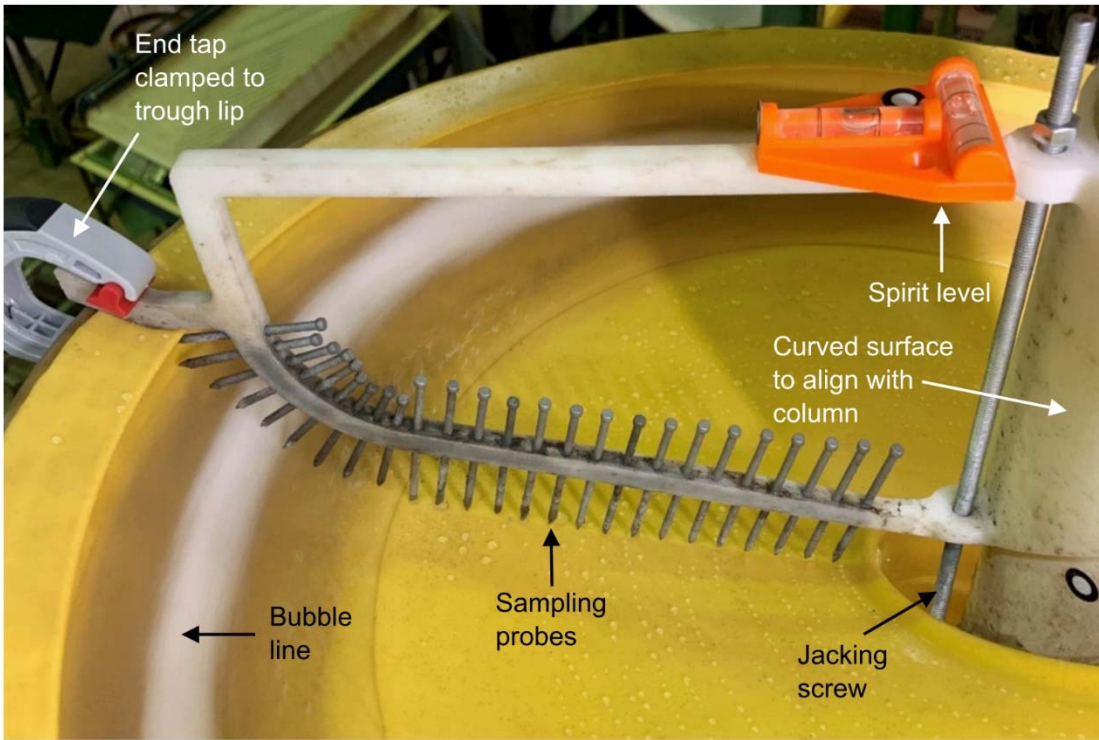
241 Measurements on the flow behaviour of a CS1 mineral separation spiral were conducted for a
242 water-only flow at a flow rate of 6.3 m³/hr, a Chromite slurry at a flow rate of 7.9 m³/hr with a 46.2%
243 solids content, and a Magnetite slurry at a flow rate of 7.9 m³/hr with a 45.7% solids content.

244 Measurements of the free surface of the water-only and slurry flows were taken using a bespoke
245 free surface sampling jig. The jig is based on a design proposed by Holland-Batt [4], which was
246 also applied by Loveday [17], but has been improved upon to match the curvature of the CS1 to
247 ensure the most accurate fit and ease of measurements. The 3D printed free surface sampling jig
248 is shown in Figure 7. #

249

250 Once a steady state flow was reached, the jig was positioned above the trough by aligning the
251 curved surface to the outside of the column. The end tap was placed on the trough lip and secured,
252 and adjustment of the jacking screw ensured that the spirit level showed no out-of-plane
253 positioning of the jig. The sampling probes were subsequently lowered to intermittently touch the

254 free surface of the water or slurry. Intermittent contact is important as 'steady contact would tend to
255 underestimate the flow depth' [4]. Once the probes were positioned correctly, the jig was removed
256 while ensuring the probes remained fixed in place. Measurements were then taken from the top of
257 the probe to the bottom of the jig along the axis of each probe. These measurements were
258 recorded and copied to the 3D CAD model of the jig, which, through the known length of each
259 probe, determined the position of each probe tip relative to the jig. To relate the position of the jig
260 to the trough, the probe closest to the column was always brought into contact with the trough
261 surface.



(a)



(b)

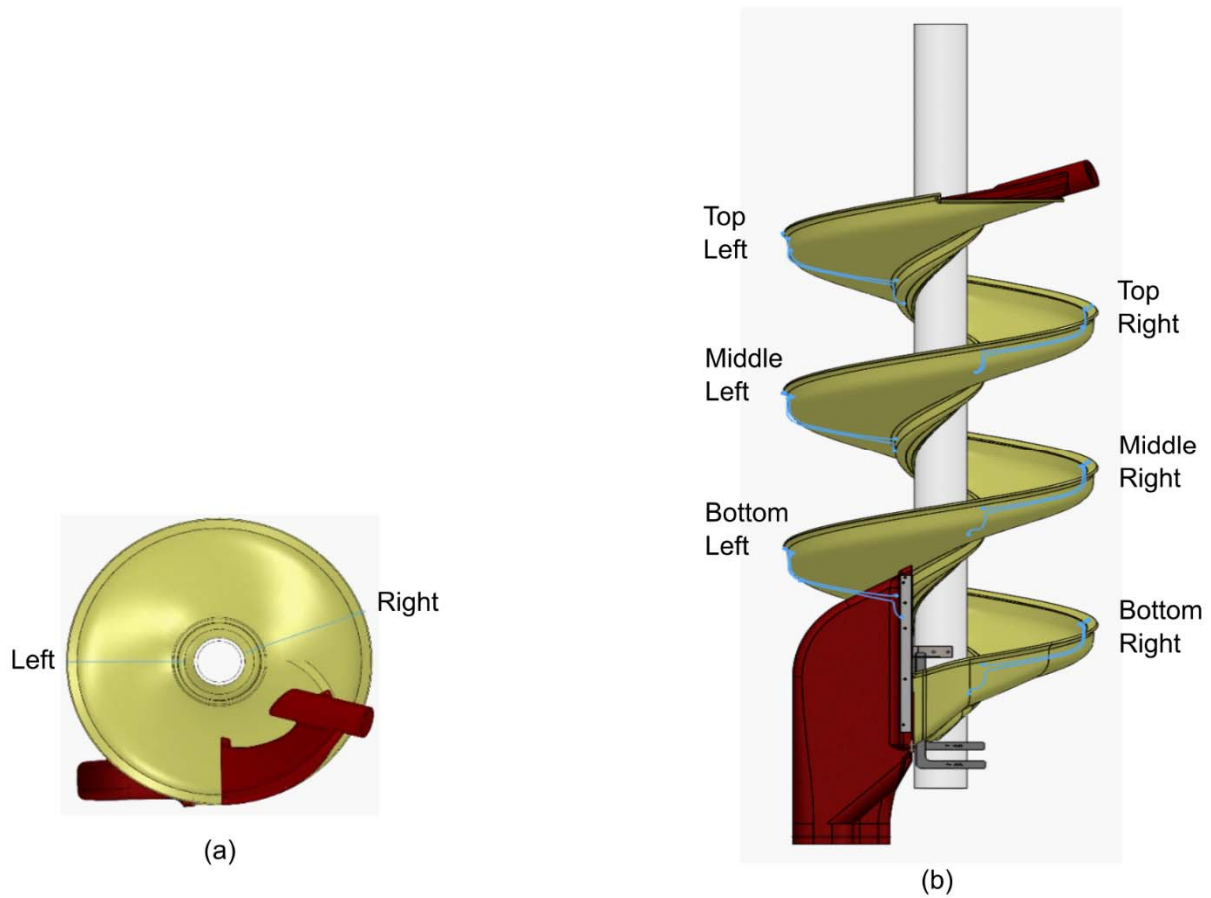
262

263 **Figure 7: 3D printed free surface sampling jig for the CS1 spiral applied to the water (a) and iron ore slurry (b)**
 264 **flows**

265 The bubble line is clearly visible in Figure 7 and the sampling jig was also used to record the
 266 position and width of this bubble line, supported by the assessment of slow-motion video footage of
 267 the experiments.

268

269 Six sampling locations along the spiral trough were selected to measure the free surface and the
270 bubble line position and width, as shown in Figure 8.



271

272 **Figure 8: Top view (a) and front view (b) of the six sampling locations on the CS1 spiral**

273 **2.5 Trough surface profile measurements**

274 Measurements of the shape of the water free surface and location of the bubble line would be
275 meaningless without firstly measuring the trough surface to which these measurements can be
276 related. Although a 3D CAD model of the CS1 spiral exists, this model was only used to produce
277 the mould onto which the spiral was created. Therefore, the existing CAD model does not account
278 for shrinkage that occurs during the trough's curing process. Additionally, when attaching the
279 trough to the column, the trough is stretched to achieve the desired pitch. Furthermore,
280 gravitational forces deform the trough when it is mounted upright. As such, a 3D CAD model
281 cannot be relied upon to represent an assembled, production-ready, upright spiral.

282

283 To capture the accurate shape of the trough, the sampling jigs were used to determine the shape

284 of the empty sacrificial wear layer at the same six sampling locations listed in Figure 8.

285 **2.6 Bubble origin assessment**

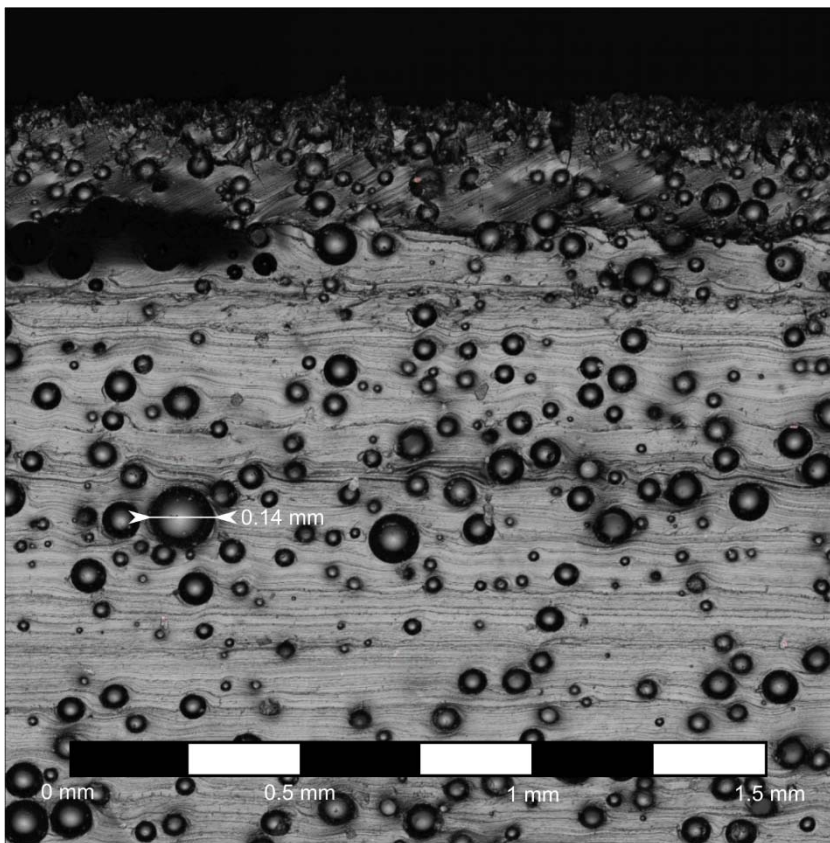
286 To assess the origin of the bubbles in the spiral, a see-through feed box was manufactured and
287 utilised during testing. This allowed the opportunity to gauge whether the bubble line is created by
288 entraining air in the water flow along the trough or if the bubbles are already present at the inlet of
289 the feed box.

290 **3 Experimental Results**

291 **3.1 Surface roughness measurements**

292 The porosity of the specimen's top surface varied greatly along the spiral trough. In fact, the
293 distribution of black dots in Figure 5 make it clear that the porosity is not uniform along individual
294 specimens. To assess the porosity along the specimen thickness, a 1.8×1.8 mm scan of the side
295 of Location D was performed using a $20\times$ zoom. The result of this scan is shown in Figure 9 where
296 the top of the specimen corresponds to the top of the image.

297



298

299 **Figure 9: Microscopic $1.8 \text{ mm} \times 1.8 \text{ mm}$ scan of the side of Location D**

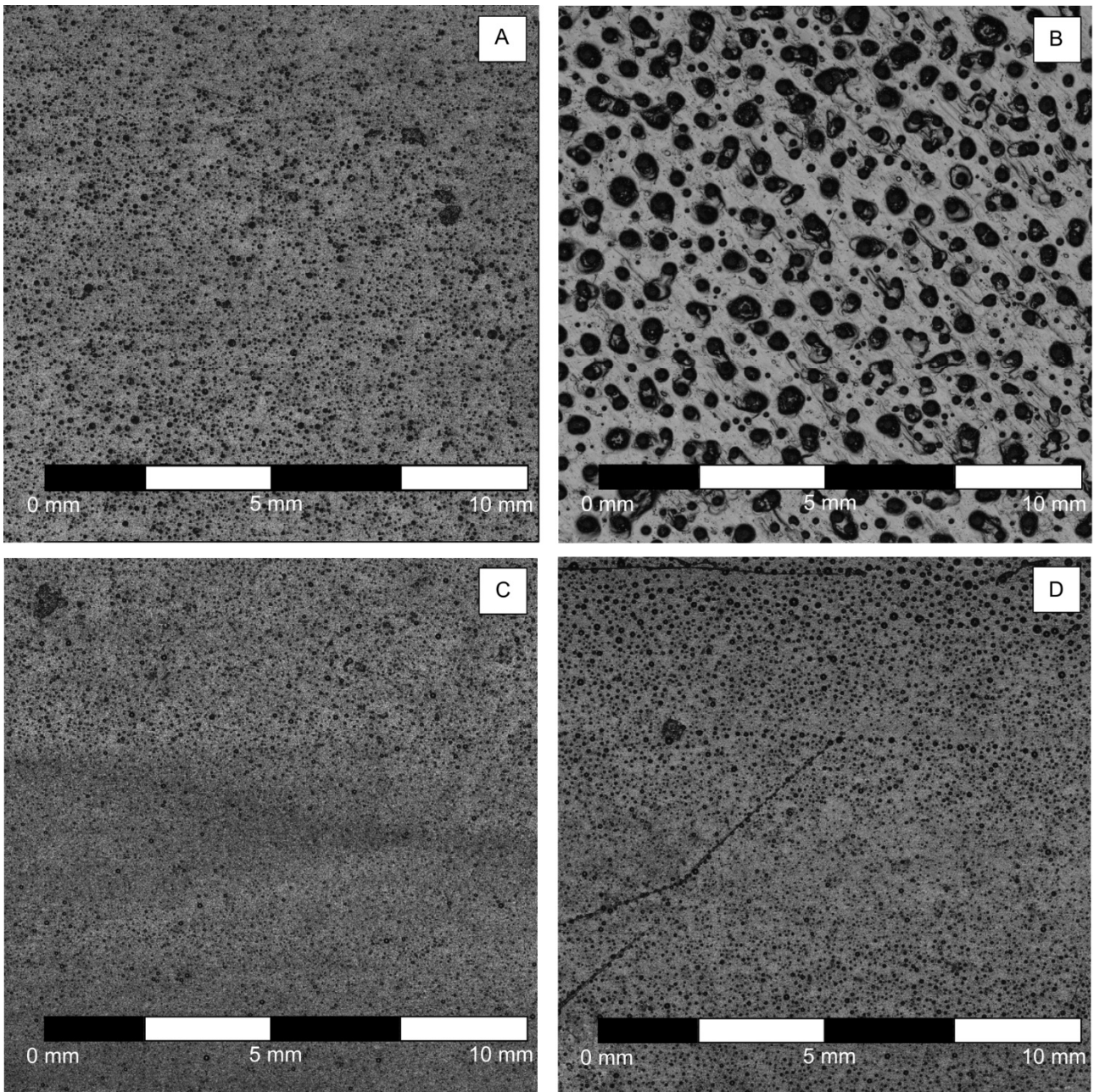
300 This cross-sectional view shows that the porosity varies throughout the specimen thickness and
301 the large variations in surface porosity, shown in Figure 5 are thus unsurprising. It is believed that
302 the porosity results from the manufacturing process of the polyurethane layer or is a consequence
303 of its curing process, or both.

304

305 To account for the large differences in porosity, a scan area measuring 10 mm × 10 mm was
306 selected as being the most representative of each specimen location. Given the 10 mm × 50 mm
307 specimen dimensions, the scan areas captured 20% of each specimen's surface area. The scan
308 areas were thus a large, representative area of each specimen's surface area. Six independent
309 roughness measurements were taken, and averaged, ensuring that each measured roughness
310 value was representative of each location.

311

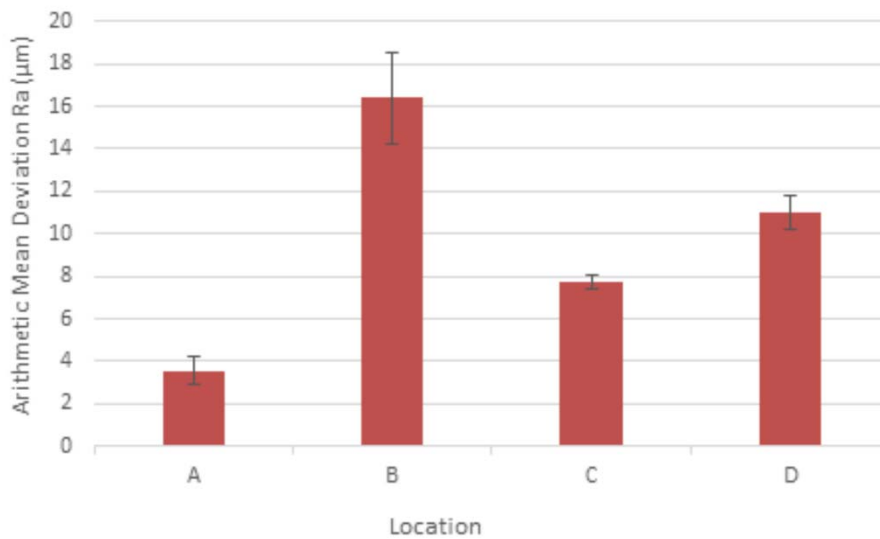
312 The large range of porosity differences is evident in Figure 10 which shows the scan area of all
313 four Locations (A,B,C and D), acquired through the Olympus OLS5000 3D measuring laser
314 microscope, all at a 10× zoom level.



315

316 **Figure 10: Microscopic images of a representative 10 mm × 10 mm scan area of Location A, B, C and D**

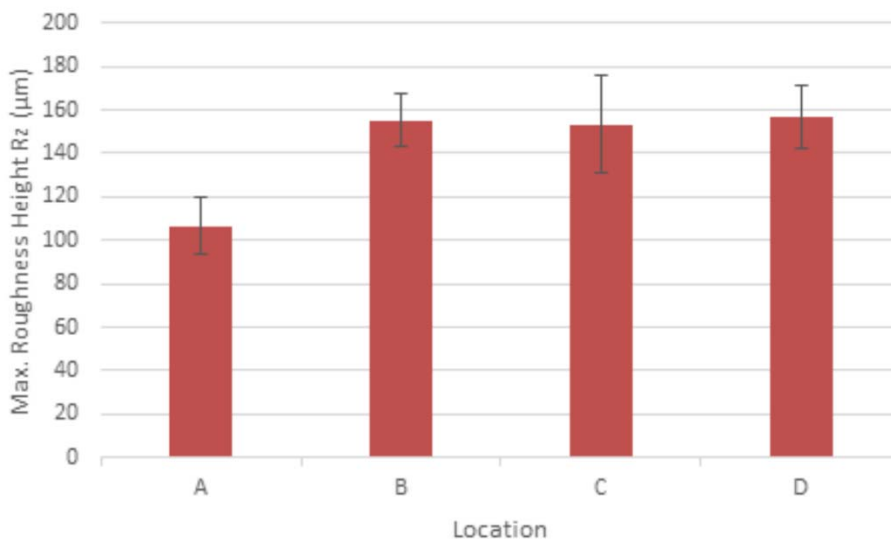
317 Noticeable is the scan area of Location B, where the pores are much larger than those found at the
318 other Locations. These porosity differences are reflected in the Arithmetic Mean Deviation (Ra) per
319 Location, including the standard deviation.



320

321 **Figure 11: Averaged Arithmetic Mean Deviation (Ra), and its deviation, for the scanned areas of Location A, B, C**
 322 **and D**

323 The Maximum Roughness Height (Rz) metric is less sensitive to the porosity as it focusses on the
 324 deepest and highest parts of the scan area. The resulting roughness values of the same scan
 325 areas shown in Figure 10 are given in Figure 12. The results indicate that the Rz values fluctuate
 326 less over the specimens than the Ra roughness metric.



327

328 **Figure 12: Averaged Maximum Roughness Height (Rz), and its standard deviation, for the scanned areas of**
 329 **Location A, B, C and D**

330 The averaged Arithmetic Mean Deviation (Ra), Maximum Roughness Height (Rz), and their
 331 respective standard deviation, averaged over the wetted-in Locations (A, B and C) and the non-

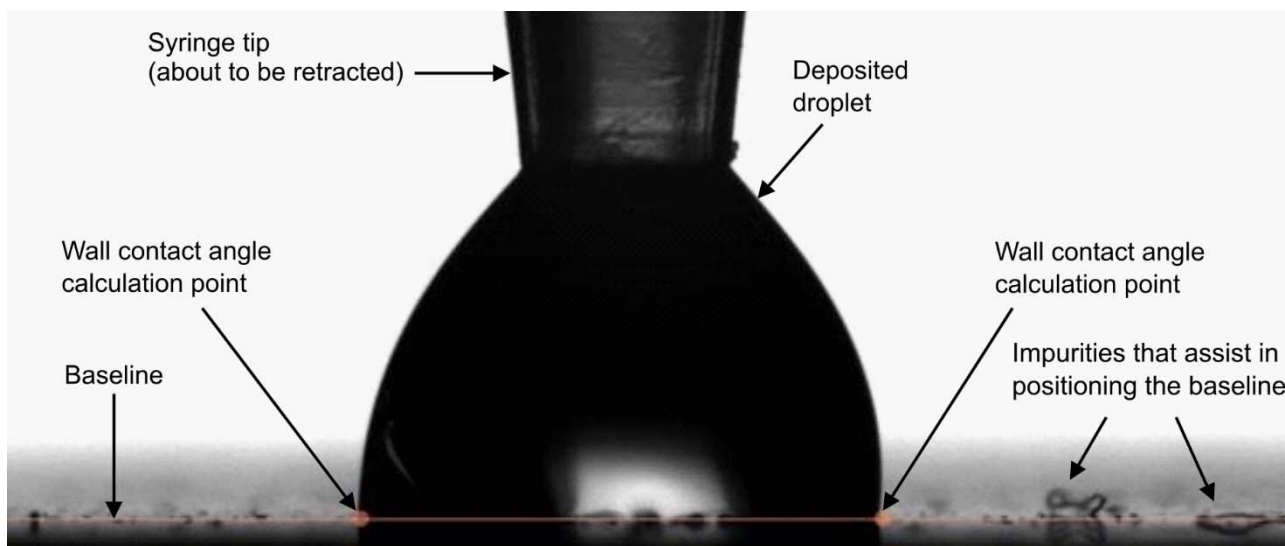
332 wetted-in Location D are given in Table 3.

	Trough surface	
	Wetted-in	Non-wetted-in
Arithmetic Mean Deviation (Ra)	9.2 μm (5.5)	11.0 μm (0.8)
Maximum Roughness Height (Rz)	138.4 μm (27.9)	156.7 μm (14.47)

333
334 **Table 3: The roughness values and wall contact angle of the wetted-in versus the non-wetted-in trough surface**

335 3.2 Wall contact angle measurements

336 For each video recording of a sessile drop test, the baseline was determined in a post-processing
337 step. A correctly set baseline is shown in Figure 13 where, next to the reflection of the droplet itself,
338 the reflection of impurities on the specimen surface were used to position the baseline. At the
339 intersection of the baseline with the curvature of the droplet, the wall contact angle was
340 determined. These wall angle calculation points are highlighted in Figure 13.

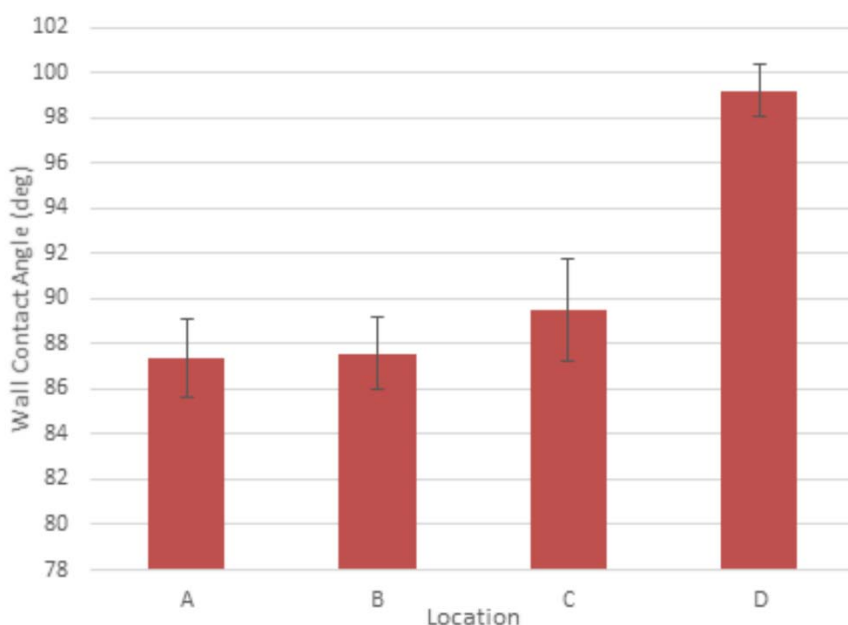


341
342 **Figure 13: An example of a correctly set baseline**

343 In Figure 13, the droplet had been brought into contact with the surface while still connected to the
344 syringe tip, following the sequence described Section 2.3. Subsequently, the syringe tip was
345 retracted, leaving the droplet to settle, and fully wet the surface. During this settling process the
346 droplet was seen to wobble left and right in several drop tests indicating that new pores were being
347 wetted. This wobbling settled over time and the droplet reached a steady state. From this point
348 onwards, the wall contact angle was measured in the water phase at both calculation points.

349
350 The resulting wall contact angle is shown in Figure 14 averaged over three separate data ranges:

351 time, two calculation points, and at least three drops per specimen.



352
353 **Figure 14: Averaged wall contact angle, and its standard deviation, for Location A, B, C and D**

354 The wall contact angle overview shows a clear distinction between Location A, B and C, where an
355 iron ore slurry has ‘wetted-in’ the trough, and Location D, which did not interact with a slurry. It can
356 thus be reasoned that the release agent, once covering the whole of the spiral trough, has been
357 worn away by the iron ore slurry at Location A, B and C, whereas Location D still has this
358 hydrophobic layer applied. The wall contact angles and their standard deviations, averaged over
359 the wetted-in Locations (A, B and C) and the non-wetted-in Location D are given in Table 4.

	Trough surface	
	Wetted-in	Non-wetted-in
Wall contact angle (measured in the water phase)	88.14° (0.95)	99.20° (4.68)

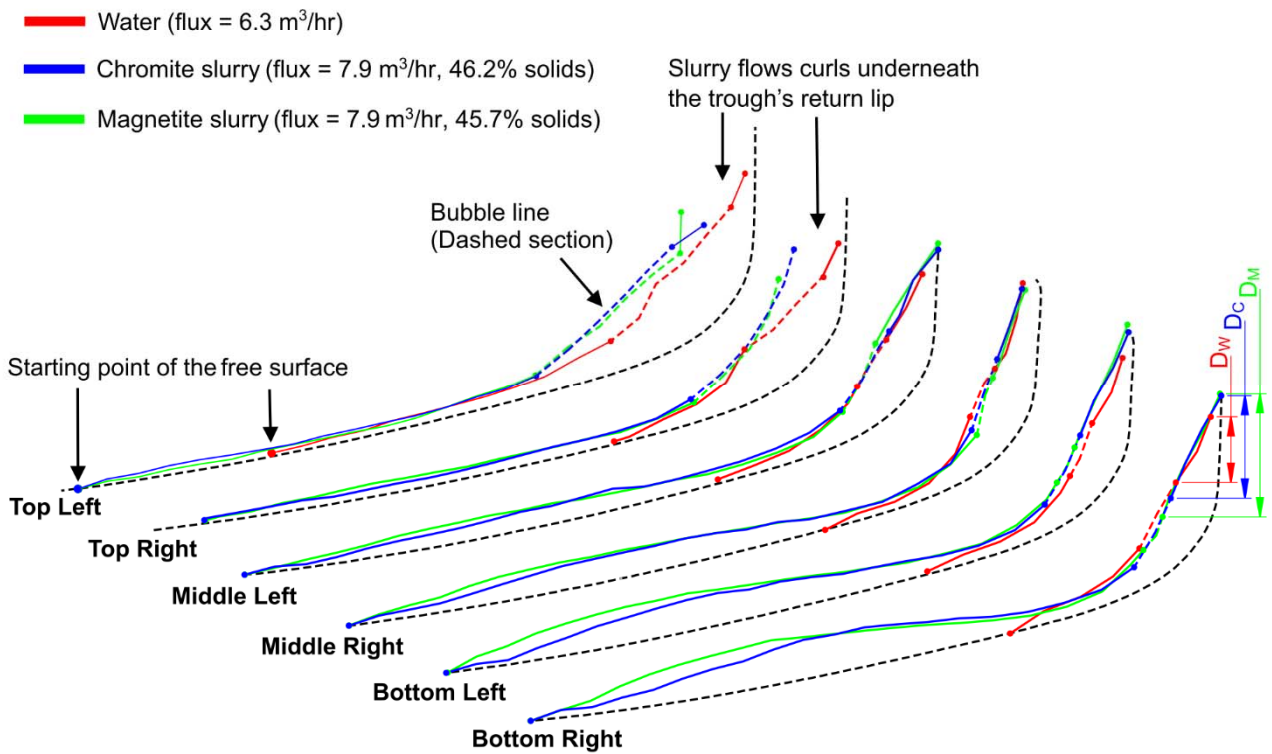
360
361 **Table 4: The wall contact angle of the wetted-in versus the non-wetted-in trough surface**

362 **3.3 Free surface and bubble line measurements**

363 **3.3.1 Water free surface**

364 The water free surface shapes at each of the six sampling locations are shown in red in Figure 15
365 overlaid onto the empty trough surface measurements. The portion of the trough with the smallest
366 radius will be referred to as the ‘inside’ of the trough, and the portion of the trough with the largest
367 radius is henceforth referred to as the ‘outside’ of the trough.

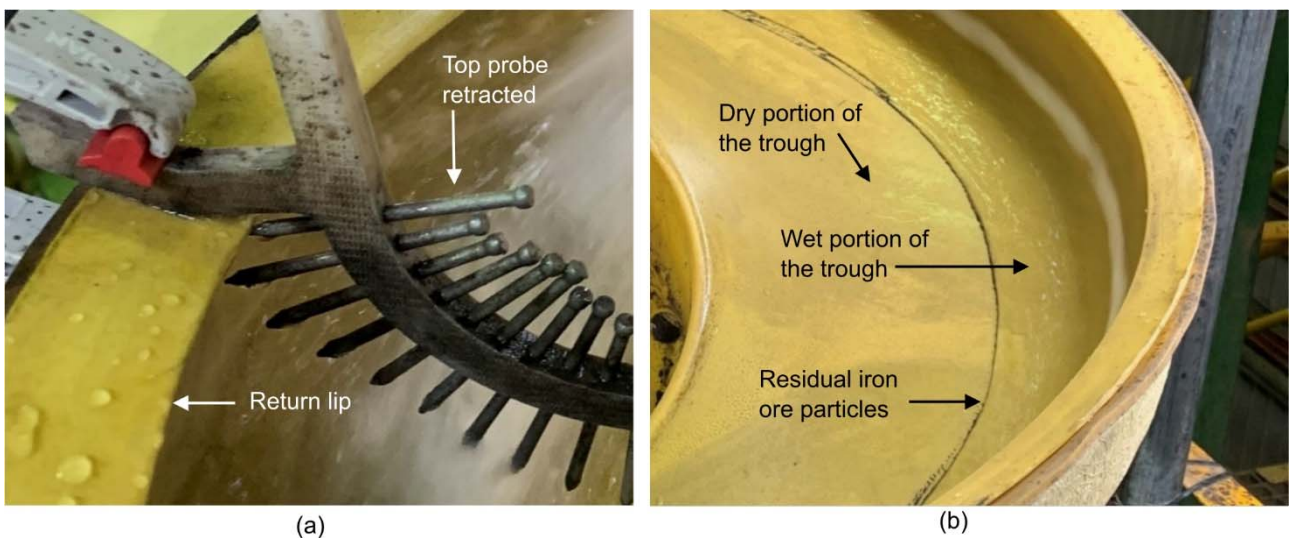
368



369

370 **Figure 15: Free surface at the six sampling locations including the position and width of the bubble line for a water**
 371 **flow, a Chromite slurry, and a Magnetite slurry**

372 The Top Left and Top Right profiles show an open free surface at the outside of the trough. As the
 373 water and slurries flowed from the feed box onto the trough, the free curve curled up underneath
 374 the trough's overhanging return lip, visible in Figure 16 (a) by a clearly retracted top probe. As the
 375 flow turbulence reduces when moving down the spiral, this effect disappeared in later sampling
 376 locations.



377

378

379

380

Figure 16: Water curling underneath the return lip at the Top Left sampling location (a). Partial wetting of the
trough (b)

381

The free surface measurements indicate that the water-only flow wets roughly half of the trough's

382 'horizontal' surface, near the outside of the trough. Figure 16 (b) clearly shows the dry and wet
383 portions of the trough during the water-only test. The location of the start of the water free surface
384 was marked by a black line resulting from residual iron ore particles being separated out of the
385 water phase. The starting point of the water surface, indicated in Figure 15, only changes before
386 the Middle Left sampling location and remains roughly consistent after that. This observation is
387 useful in numerical fluid flow simulations, as it permits the use of a shortened fluid model, ending at
388 the Middle Left sampling location.

389

390 Since the release agent was worn away through the wetting-in process, the release agent could
391 not be the cause of the location of the wet-dry interface. In fact, after the free surface
392 measurements were completed, attempts were made to wet the dry portion by intrusively altering
393 the flow by placing an obstacle in its path. Once the obstacle was removed, the location of the wet-
394 dry interface reverted to its previous location over time. It can thus be concluded that the
395 incomplete wetting of the trough in a water-only flow is a feature of the flow behaviour and should
396 therefore also be present in the results of computational fluid flow analyses.

397 **3.3.2 Slurry free surface**

398 The shape of the free surface of the Chromite and Magnetite slurries are shown in Figure 15 as
399 blue and green lines respectively. The results of the empty trough surface measurements have
400 also been incorporated into Figure 15. The start of the slurries' free surface is at the far inside of
401 the trough and the complete spiral trough's surface is covered by the slurries. The separation
402 effects of a spiral are evident by the continuous, and very similar, build-up of particles for both
403 slurries near the inside of the trough. When moving from the inside towards the outside of the
404 trough, Figure 15 clearly shows that the shape of the free surface of both slurries conform to that of
405 the water free surface after a certain radius. A spiral separates a slurry into different streams of
406 particles, where the larger and heavier particles move towards the inside of the trough, and the
407 smaller and lighter particles move to the outside of the trough. It is thus believed that the free
408 surface after a certain radius is no longer dominated by the effects of interacting particles but
409 instead the water phase determines the shape of the free surface. It can thus be reasoned that the
410 fluid flow after a certain radius is not governed by particles but instead relies on the fluid flow profile

411 of water alone.

412

413 Since the shape of the slurries' free surface continuously changes when moving down the spiral,
414 no shortened fluid model would be representable when conducting a CFD simulation of a slurry
415 flow.

416 3.3.3 Bubble line analysis

417 The dashed section of the free surfaces in Figure 15 indicates the position and width of the bubble
418 line. The width and position of the bubble line sees a large change before, and minimal change
419 after the Middle Left sampling location for both the water-only and two slurry flows. Additionally, the
420 position and size of the bubble line are similar for all three flows, further supporting the fact that
421 water dynamics are determining the flow behaviour near the outside of the trough. The consistency
422 of the bubble line location and positions after the Middle Left sampling location further supports the
423 use of a shortened model in a fluid flow simulation of a water-only flow.

424

425 The vertical distance from the top of the water free surface to the start of the bubble line, indicated
426 in Figure 15, for each flow is listed in Table 5 for the last four locations.

	Vertical distance from the highest point of the free surface to the highest point of the bubble line		
	Water (D_w)	Chromite slurry (D_c)	Magnetite slurry (D_m)
Middle Left	20.8 mm	25.9 mm	31.8 mm
Middle Right	27.2 mm	22.4 mm	28.1 mm
Bottom Left	21.0 mm	33.2 mm	29.3 mm
Bottom Right	20.8 mm	32.5 mm	39.0 mm
Average (standard dev)	22.5 (2.7) mm	28.5 (4.5) mm	32.1 (4.2) mm

427

428 **Table 5: The bubble line position relative to the free surface shape for each flow**

429 These measurements are in line with the observations of Palmer & Weldon where the bubble line
430 was found to be located roughly 20 to 30mm below the highest point of the free surface [2].

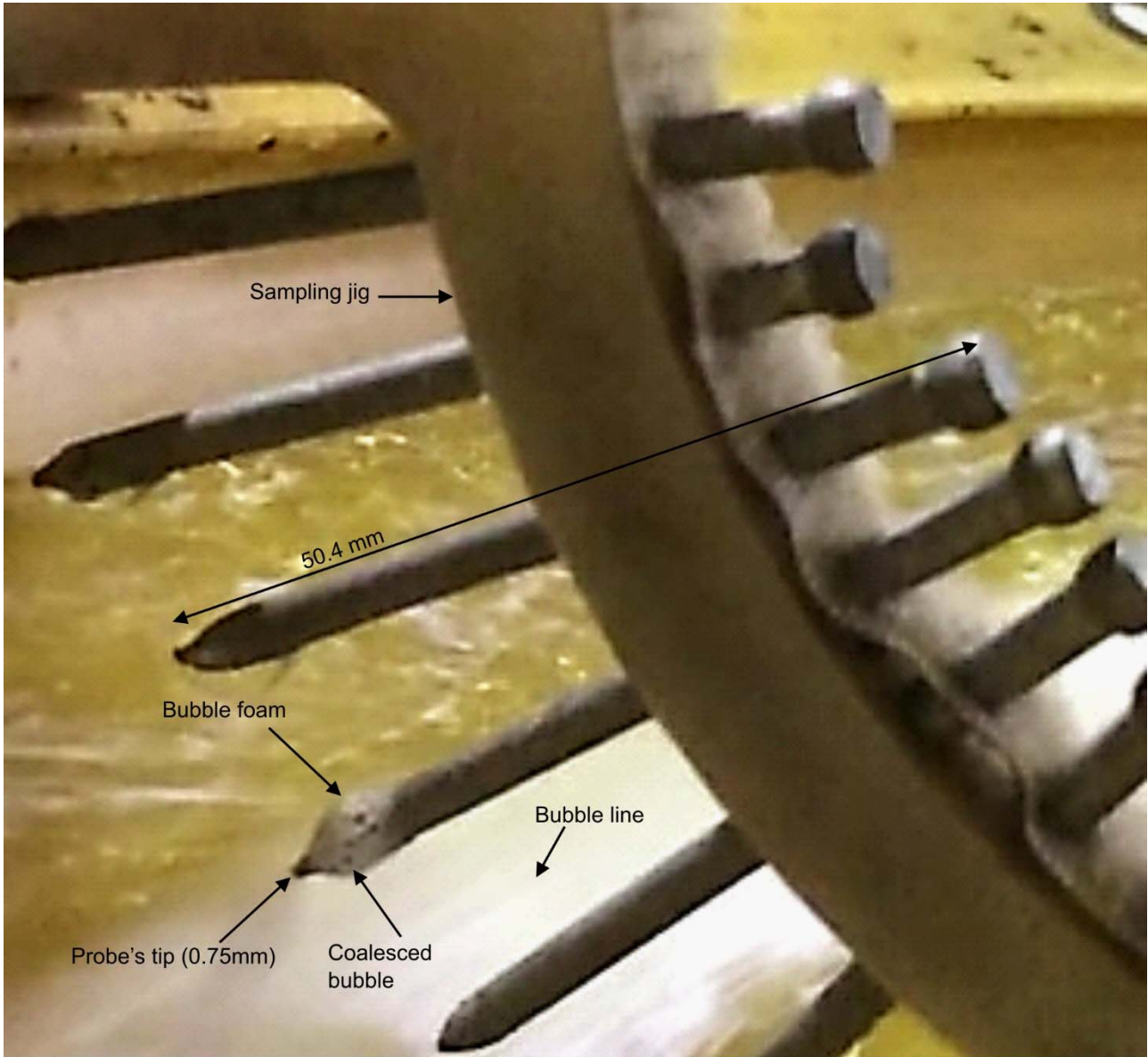
431

432 An estimate of the size of the bubbles in the bubble line was challenging due to bubble
433 coalescence and bubble bursting effects. A rough estimate was achieved by comparing the
434 bubbles, when washed up onto the probes, to the known diameter of the probe tip before the
435 bubbles dislodged again. Figure 17 shows a still image from the video footage taken during the

436 water-only flow experiments where the bubbles have accumulated on the probe tip. The tip of the
437 probe has a diameter of 0.75 mm, or 750 μm , and bubbles can be seen to have coalesced into
438 larger sized bubbles. The smallest of these larger bubbles is still visible as indicated in Figure 17.
439 The smallest bubble is estimated to be $1/3^{\text{rd}}$ of the diameter of the probe's tip, resulting in a
440 diameter of 250 μm for the coalesced bubbles. Still, these coalesced bubbles are surrounded by
441 far smaller bubbles, only visible as a white foam on the probe tip in Figure 17. This leads to the
442 estimate that the bubble size dominating the bubble line is an order of magnitude smaller than the
443 largest visible coalesced bubble, resulting in a dominant bubble diameter of 25 μm .

444

445 Noteworthy during all experiments is the fact that no noticeable difference in bubble line velocity to
446 the water or slurry phase velocity was found. Furthermore, the observed coalescing of bubbles on
447 the probe's tip only occurred sporadically as newly washed-up bubbles encountered previously
448 washed-up stationary bubbles. This indicated that the bubbles in the bubble line form a foam and
449 bubbles do not easily coalesce. This observation was further supported by the absence of a large
450 bubble size difference within in the bubble line.

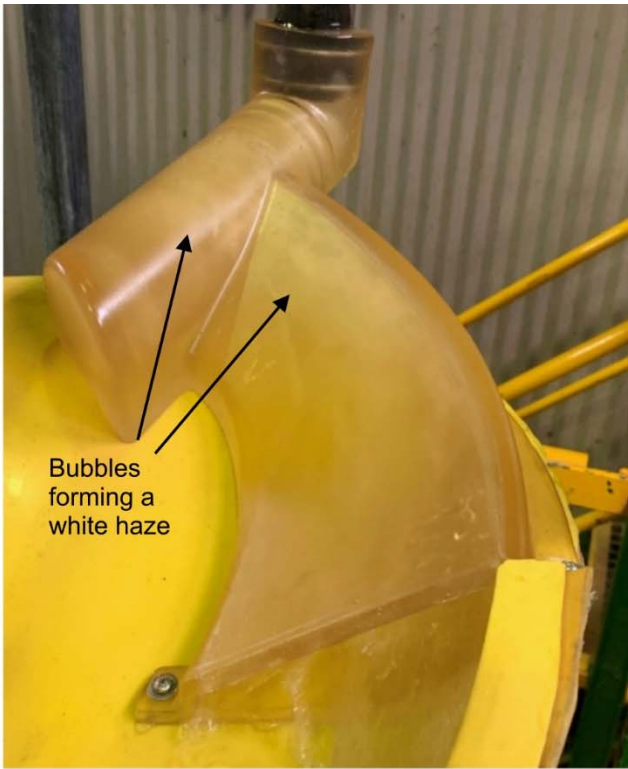


452

453 **Figure 17: Still image from video footage of the experiment showing the temporary accumulation of bubbles on**
 454 **the probe's tip**

455 **3.5 Bubble origin assessment**

456 Visualisation through the translucent feed box made it clear that the flow entering the feed box
 457 contained many suspended bubbles. This was most clearly visible as a white haze throughout the
 458 feed box during the water-only experiments as shown in Figure 18, with Figure 19 illustrating the
 459 viewpoint used. The presence of suspended bubbles was traced further upstream in the spiral's
 460 water supply system, as shown in Figure 20.



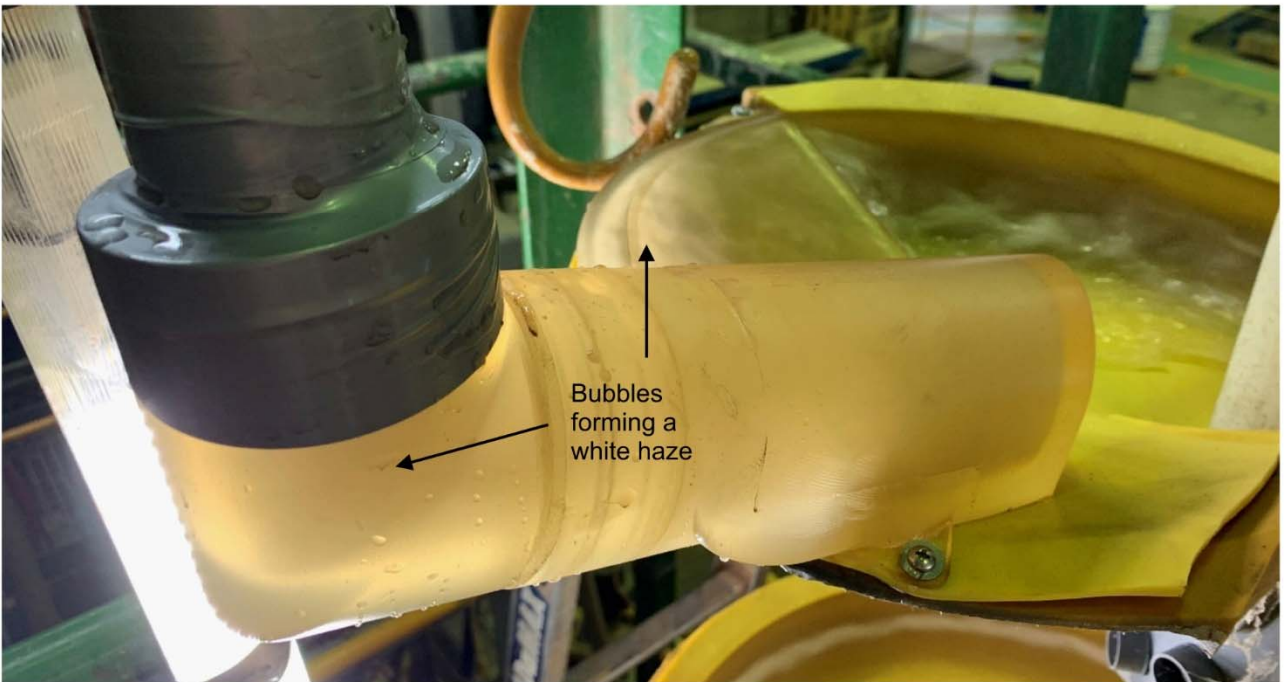
Bubbles forming a white haze

(a)



Bubbles forming a white haze

(b)



Bubbles forming a white haze

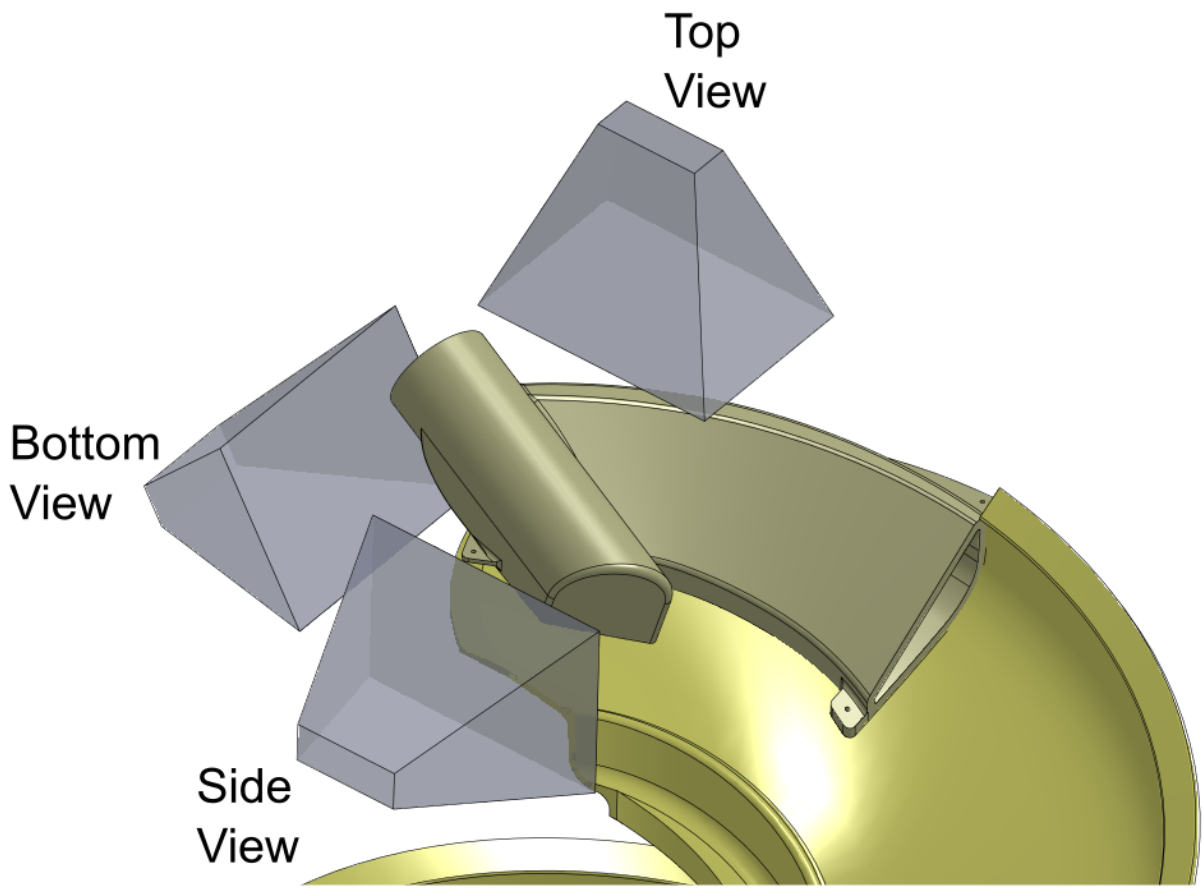
(c)

461

462

463

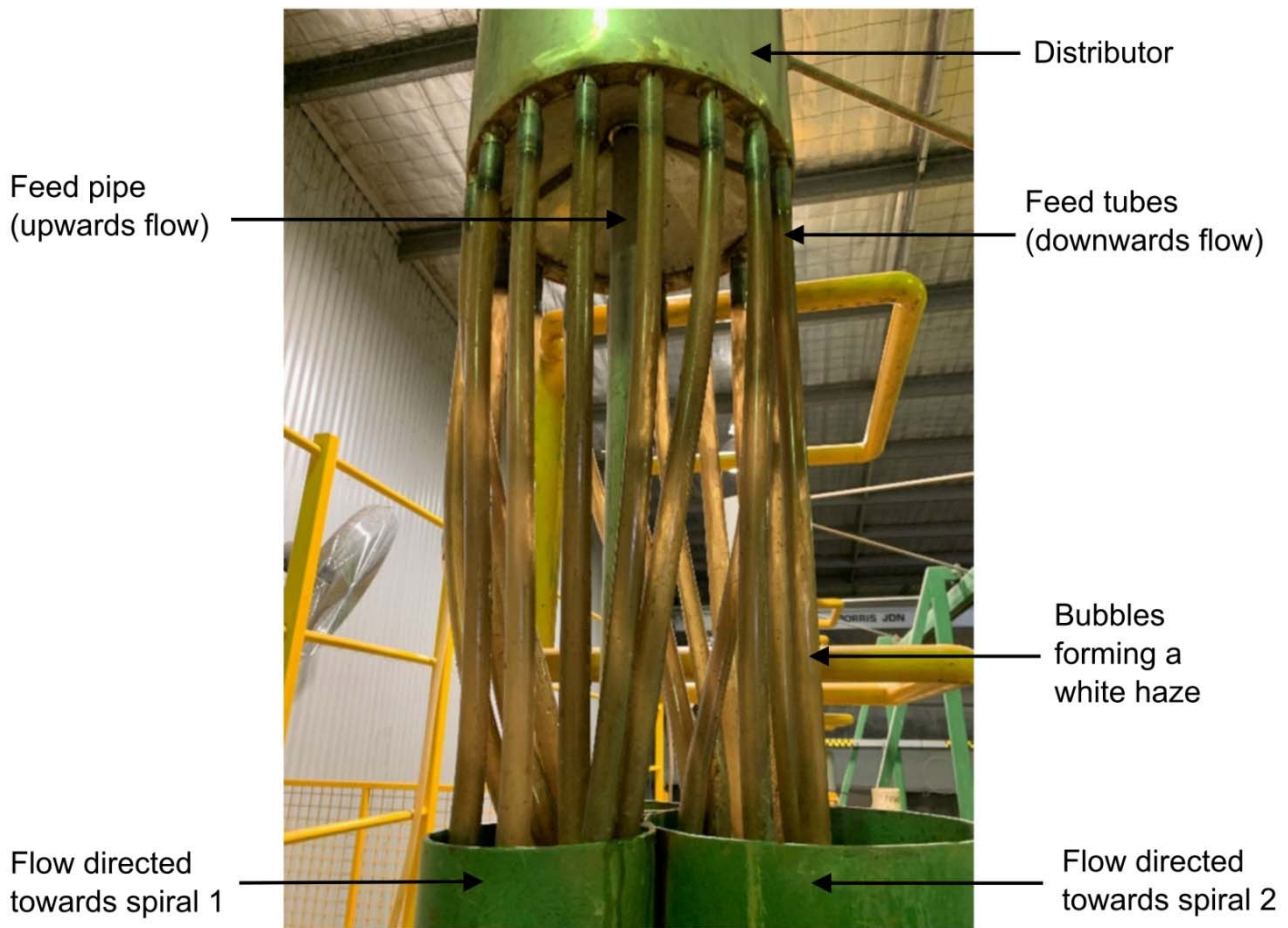
Figure 18: Top view (a), bottom view (b) and side view (c) of the flow through the feed box showing a large quantity of suspended bubbles as a white haze



464

465 **Figure 19: Viewpoints used in Figure 18**

466



467

468 **Figure 20: View of the flow through after the distributor showing a large quantity of suspended bubbles as a**
 469 **white haze**

470 As multiple spirals were fed by a single feed source, the inlet flow was split using a so-called
 471 ‘distributor’, as indicated in Figure 20, raised high above the spiral’s feed box entry level. The
 472 pumped, upwards flow from the feed pipe entered the distributor and created a small water
 473 fountain therein to dissipate any pump variability in the flow. The water subsequently settled in the
 474 distributor and drained through a series of feed tubes which took the flow down to two spirals,
 475 thereby splitting the flow. The translucent nature of the feed tubes shows that many suspended
 476 bubbles were present in the downwards flow from the distributor. The bubble’s origin is then likely
 477 caused by air being entrained through the fountain-like flow spreading in the distributor.

478

479 The suspended bubbled in the spiral’s supply system finding clearly shows that a realistic
 480 computational fluid flow analysis should include bubbles entering the fluid domain, using the
 481 previously determined bubble size. To the best of the authors’ knowledge, no such bubble phase
 482 has been included in fluid analysis efforts so far.

483 **4 Discussion**

484 The porosity of the polyurethane wear layer of the spiral trough has been shown to be an issue in
485 roughness measurements. Although all roughness values show a lower value for the wetted-in
486 compared with the non-wetted-in surface, the large differences in porosity amongst the specimens,
487 evident by a large standard deviation, overshadows possible roughness differences resulting from
488 the wetting-in process. The Maximum Roughness Height (Rz) metric best alleviates this issue,
489 making the wetted-in roughness value of 138.4 μm the most representative roughness value of a
490 spiral trough. Microscopic imaging revealed that the porosity is not limited to the top of the wear
491 layer surface but is also spread through the thickness of the specimen.

492
493 A clear distinction between the wetted-in and the non-wetted-in trough surface was found through
494 the wall contact angle measurements. The wetted-in trough surface has a lower wall contact angle
495 of 88.14°, measured in the water phase, compared with that of the non-wetted-in surface. The
496 lower wall contact angle is clear evidence of the removal of the hydrophobic release agent layer on
497 the spiral trough surface through the wetting-in process.

498
499 Overall, if a spiral manufacturer aims to reduce or eliminate the wetting-in process during spiral
500 commissioning, which would save time and money for both the spiral manufacturer and the client,
501 the wall contact angle, more so than the surface roughness, should be aimed to be corrected
502 during or after the manufacturing process. Although these experiments were conducted on a CS1
503 model spiral, the common usage of polyurethane as a wear layer in spirals allows the results to be
504 applied to different spiral models and makes.

505
506 Measurements were taken of the water free surface and bubble line position and width using a
507 customised jig at six sampling locations along the spiral trough. The same jig was also utilised to
508 measure the empty spiral trough at the same sampling locations. These free surface
509 measurements can be used directly or, in the case of different spiral makes and models, can be
510 used quantitatively to validate a CFD model. Ideally other spiral makes and model could be
511 subjected to the same measurement techniques. Future improvements in 3D scanning could

512 potentially simplify the measurement of the free surface shape.

513

514 A novel comparison of the free surface of water-only and two slurry flows was presented which
515 showed that the free surface shape of the slurries coincides with that of the water free surface
516 shape after a certain spiral radius. This showed that particle interaction drives the free surface
517 shape at lower radii whereas the water phase dominates the free surface shape at larger radii. This
518 finding has potential consequences for the forces a moving slurry exerts on the spiral surface, a
519 key parameter in spiral design, as the centripetal forces caused by the moving slurry are likely
520 dominated by the water phase at larger spiral radii. More research efforts are recommended to
521 deepen the understanding of this finding.

522

523 It was shown that the start of the water free surface changes rapidly after the feed box but reach a
524 steady state after 1.25 turns down the spiral in the case of the water-only flow. This finding would
525 allow a smaller fluid flow domain in a water-only CFD simulation, which will reduce the required
526 mesh size thus leading to valuable computational savings in such a CFD analysis. Given the ever-
527 changing free surface shape of slurries, no such domain reductions can be recommended when
528 assessing a realistic slurry flow in an existing spiral model. Still, it is expected that the change in
529 the free surface shape due to particle stratification and particle build-up will plateau since particles
530 settled out of the flow or have otherwise found their preferred location. The distance from the feed
531 box to the point of a constant free surface shape would aid in determining the length, referred to
532 commonly as the 'number of turns' of a new spiral model and could be a subject of further
533 research.

534

535 The bubble line also changes very little after 1.25 spiral turns from the exit of the feed box, both in
536 position and width, for all three fluids. This further supports the case for a shortened fluid flow
537 domain for the CFD simulation of a water-only flow. The position of the bubble line was found to be
538 between 26 and 33 mm below the highest point of the water free surface, which aligns with other
539 researchers' findings. Although challenging to measure experimentally, the best bubble size
540 estimate, 25 μm , was found by relating the bubbles to the know size of a sampling probe.

541 Improved methods of bubble size measurement are a research topic worth pursuing. The bubbles
542 were found to be reluctant to coalesce, forming a foam, and were observed to have a small
543 difference in bubble size.

544
545 Finally, a translucent feed box showed that the inlet water flow already contains a significant
546 quantity of suspended bubbles. This finding makes the inclusion of a bubble phase, using the
547 estimated bubble size, essential in a fluid analysis of such a spiral flow.

548 **5 Conclusion**

549 This paper has presented an experimental analysis of water-flow and two slurries in a wetted-in,
550 gravity-driven helical mineral separator model that is currently in production to provide an
551 experimental baseline that can be used in the validation of researchers' CFD simulations of spirals.
552 The research conducted herein allowed the following conclusions to be drawn:

- 553 • The wall roughness and wall contact angle, two key wall properties not previously measured
554 but essential in any CFD simulation, were measured. The most representative wall roughness
555 metric was found to be the wall roughness height with a value of 138 μm . The wall contact
556 angle of the spiral trough surface was found to be 88.14°, measured in the water phase.
- 557 • Novel insights into the wetting-in process were gained as this process was found to affect the
558 wall contact angle to a far greater extent than it affects the surface roughness. A spiral's
559 commissioning costs, incurred by the wetting-in process, can thus be reduced if a correct wall
560 contact angle of the spiral trough is achieved during or after the spiral's manufacturing
561 process.
- 562 • The experiments showed that the free surface shape and the position and width of the bubble
563 line in a water-only flow reached a steady state after 1.25 spiral turns, which can significantly
564 improve the efficiency of a water-only flow CFD analysis but is not relevant to slurry flows due
565 to their ever-changing shape.
- 566 • As the use of polyurethane for the wear layer is common amongst spiral manufactures, these
567 findings are beneficial to spirals of different makes and models.
- 568 • The bubbles that form the often-encountered bubble line are estimated to be 25 μm in

569 diameter. The bubbles like originate from air entrainment in the distributor and many bubbles
570 were present at the inlet of the feed box. This finding indicates that a realistic computational
571 fluid flow analysis of the flow in mineral separation spirals should include bubbles entering the
572 fluid domain.

573 Future work will use the observations and measurements presented, and the measured shape of
574 the empty spiral trough surface to inform the modelling choices and settings of a generalised
575 gravity-driven helical mineral separator fluid flow CFD simulation. The free surface and bubble line
576 locations and widths will be used to validate the outcomes of these CFD analysis.

577 **6 Declarations**

578 **6.1 Funding**

579 The research study described herein is supported by an Australian Government Research Training
580 Program Scholarship and is co-funded by the Department of Industry, Innovation and Science
581 (Innovative Manufacturing CRC Ltd), the University of Technology Sydney (UTS) and Downer, via
582 its subsidiary Mineral Technologies Pty Ltd (IMCRC/MTC/290418). The funding bodies were not
583 involved in the study design; in the collection, analysis and interpretation of data; in the writing of
584 the report; or in the decision to submit the article for publication.

585 **6.2 Conflicts of interest/Competing interests**

586 Thomas Romeijn is employed by Mineral Technologies whilst being a research student at the
587 University of Technology Sydney (UTS). This research paper reports experimental data on the
588 properties of a CS1 spiral to inform other researchers simulating spiral flows using CFD of
589 essential wall, flow and fluid domain properties. Care has been taken to avoid any value judgement
590 on the mineral separation performance of the CS1 spiral versus other spiral makes and models,
591 thereby avoiding a conflict of interest while enhancing the knowledge of key simulation parameters.

592 **7 Acknowledgment**

593 The research study described herein is supported by an Australian Government Research Training
594 Program Scholarship and is a collaboration between the University of Technology Sydney (UTS),
595 the Innovative Manufacturing Cooperative Research Centre (IMCRC) and Downer, via its

596 subsidiary Mineral Technologies under Grant [IMCRC/MTC/290418]. Thank you to UTS:Rapido,
597 particularly, Hervé Harvard for establishing the research activity. The researchers would like to
598 thank Samuel Gallagher, Myoung Jun Park and Professor Hokyong Shon for their contribution to
599 the findings described in this paper. A special thank-you goes out to David Myint at ATA Scientific
600 for allowing the use of the state-of-the-art tensiometer. The authors appreciate the efforts of David
601 Su in conducting experiments especially his ideas for future avenues of testing. In addition, the
602 many brainstorming sessions with and guidance of Professor David Fletcher are greatly
603 appreciated.

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