

Animal models of compression spinal cord injury

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Abstract

Compression spinal cord injuries are a common cause of morbidity in people who experience a spinal cord injury (SCI). Either as a by-product of a traumatic injury or due to nontraumatic conditions such as cervical myelitis, compression injuries are growing in prevalence clinically and many attempts of animal replication have been described within the literature. These models, however, often focus on the traumatic side of injury or mimic short-term injuries that are not representative of the majority of compression SCI. Of this, nontraumatic spinal cord injuries are severely understudied and have an increased prevalence in elderly populations, adults, and children. Therefore, there is a need to critically evaluate the current animal models of compression SCI and their suitability as a method for clinically relevant data that can help reduce morbidity and mortality of SCI. In this review, we reviewed the established and emerging methods of animal models of compression SCI. These models are the clip, balloon, solid spacer, expanding polymer, remote, weight drop, calibrated forceps, screw, and strap methods. These methods showed that there is a large reliance on the use of laminectomy to induce injury. Furthermore, the age range of many studies does not reflect the elderly and young populations that commonly suffer from compression injuries. It is therefore important to have techniques and methods that are able to minimize secondary effects of the surgeries, and are representative of the clinical cases seen so that treatments and interventions can be developed that are specific.

KEYWORDS

age related, compression, elderly, nontraumatic, pediatric, rodent

1 | INTRODUCTION

The global incidence of spinal cord injuries (SCIs) is estimated to be between 40 and 80 cases per million, with an average of between 250 and 500 thousand new cases per year (WHO, 2013). In the adult population, a substantial proportion of SCI is due to traumatic causes such as motor-related injury, sporting accidents, falls, or violence, while a smaller yet growing proportion (incidence of 26.3 cases per

million) of spinal damage is due to nontraumatic causes (Müller-Jensen et al., 2021; New, 2019; New et al., 2014; WHO, 2013). There are also significant age-related differences in the causes of SCI, with the young and the elderly more likely to have a higher proportion of nontraumatic spinal cord injury (NTSCI) (Smith et al., 2017).

NTSCI can further be classified as compressive (tumors (benign/malignant), metastases, malformations, abscess, bleeding, spondylitis, and disk herniation/spinal stenosis) or non-compressive

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inflammatory/infections, immunological (e.g., multiple sclerosis), vascular (e.g., infarction), metabolic (e.g., vitamin deficiency), toxins, physical (e.g., postradiation myelopathy) (Adams & Salam-Adams, 1991; Müller-Jensen et al., 2021). It is important to acknowledge that the terminology for describing these types of SCI is not standardized. For the purpose of this review the term “NTSCI” will be used to differentiate from animal models that rely on a mechanical impact to produce a traumatic injury and “compression” to describe the primary mode of injury where the spinal cord is deformed due to the application of sustained pressure of varying duration rather than an acute impact of varying force. Other descriptive terms used clinically may include spinal cord dysfunction (SCDys) or compressive myelopathy. NTSCI has received relatively little attention compared to traumatic SCI, with considerable variation in approaches to research. As a result, there is a lack of robust animal models to investigate causes, pathophysiology, and intervention strategies.

Most current NTSCI research focuses on compressive type injuries as they have the highest incidence, and many animal models of NTSCI focus on acute compression injuries as a confounding factor of traumatic injury (De Martino et al., 2019; New et al., 2017). In a 2017 review of all animal models of SCI, 94.5% were modeled using mechanical traumatic injury while the remaining 5.5% were modeled using nonmechanical injury (Sharif-Alhoseini et al., 2017). Currently, only about 17% of all SCI publications include “compression” and <5% of those refer to animal models. There is a limited number of methods to reproduce compressive SCI in animals. The most common method used is clip compression, making up over 50% of all compression models (Sharif-Alhoseini et al., 2017). This is followed by balloon compression models and then several less utilized methods such as screw compression, solid spacer compression, weight drop compression, remote compression, expanding polymers, and spinal cord strapping (Cheriyian et al., 2014; Muir & Webb, 2000; New, 2019; Sharif-Alhoseini et al., 2017; Zhang et al., 2014). These models can be used to investigate specific aspects of spinal cord compression but may not entirely cover the broad range of compressive NTSCI seen clinically (Kang et al., 2018; New, 2019).

In this review, each of these animal models of spinal cord compression will be evaluated for their use in modeling human spinal cord compression injury and their future potential for accurate and useful intervention techniques in NTSCI.

2 | TYPES OF COMPRESSION MODELING

2.1 | Models requiring laminectomy

2.1.1 | The limitation of laminectomy

All the techniques described below have the same limited consideration. They all require at least a partial laminectomy to be undertaken to allow access to the spinal cord. The main limitations of these methods are the impedance and removal of spinal processes

Significance

While the majority of spinal cord injuries (SCIs) are caused by acute mechanical trauma there are also a proportion caused by chronic spinal cord compression. The current trend of SCI shows an increase in compression SCI in all ages, but especially in the very young and the elderly. There is relatively little research undertaken in animals for compression SCI compared to trauma-related SCI. In this review paper, we described current animal models of compressive SCI and evaluated their broader applications. Models that are reproducible, uncomplicated, and adaptable across species and ages have the most potential for translational research.

and lamina and alterations to the fluid dynamics of the spinal cord (Cheriyian et al., 2014; Do Espírito Santo et al., 2019; Xu et al., 2008; Zhang et al., 2014). By removing any part of the lamina whether extensive or minimal, the fluid dynamics of the spinal cord are changed. Laminectomies may also cause alterations to the degree of spinal cord compression due to the increased space at or near the injury site. The location of the laminectomy compared to the injury site may change the biomechanics of the injury, especially if in close proximity. The damaged cord may then “bulge” into the space created. Laminectomy and laminoplasty are in fact treatment options for spinal compression caused by cervical myelopathy (Liu et al., 2016). However, there are two methods of spinal cord compression that overcome this limitation by avoiding the necessity for a laminectomy which will be described in the following section.

2.1.2 | Clip compression

Clip compression (Figure 1) is an acute compression that reflects a sudden and short compression of the spinal cord such as an injury caused after a vertebral bone fracture. Developed by Rivlin and Tator, this method used a repurposed aneurysm clip to compress the spinal cord of rats using 180g of force for varying times (1978). This study aimed to understand the importance of time and decompression from the incidence of the injury. This method has since been developed and used to induce varying levels of acute compressive SCI in rats and mice. Most commonly the procedure includes thoracic laminectomy (Chamankhah et al., 2013; Lanza et al., 2018; Sajad et al., 2021) followed by the application of a clip to exert extradural compression of the spinal cord. Typically, clips are applied for 30 s to 1 min before release and use 20–180g of force for compression (Chamankhah et al., 2013; Lanza et al., 2018; Sajad et al., 2021). The clips used for compression are often an aneurysm or vascular clips but may also be custom designed (Do Espírito Santo et al., 2019; Gao et al., 2019; Wang et al., 2021; Zhang et al., 2021).

Clip compression is a simple and effective method that results in an acute compression SCI. By altering the time and force of the clip this model also produces a graded injury (Do Espírito Santo et al., 2019; Rivlin & Tator, 1978; Sajad et al., 2021; Wang et al., 2021; Zhang et al., 2021). This model further provides an excellent histological example of injury to the spinal cord (Hassannejad et al., 2019; Zhang et al., 2021). This is important as it allows quantification and visualization of the damage in the spinal cord, aiding discussion about the corresponding motor deficits. Using a clip also allows for changes in compression angle so that both the anterior-posterior and lateral spinal cord compression injuries can be replicated (Wang et al., 2021). These all make for a relatively simple reproducible procedure that creates good histological outcomes.

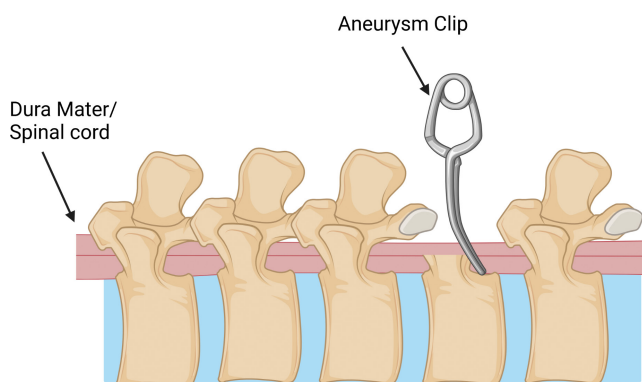


FIGURE 1 Schematic of spinal cord injury compression model using an aneurysm clip on the exposed spinal cord post-laminectomy. The spinal cord sits between the two prongs of the aneurysm clip and compresses the spinal cord laterally for a short time before being removed. Created with [BioRender.com](https://www.biorender.com).

However, clip compression is limited in its use as an accurate NTSCI model in a few ways. Clip compression may be better defined as an acute traumatic injury using compression rather than a model of NTSCI due to compression. This is reflected in the literature as it is sometimes referred to as a traumatic injury (Gao et al., 2019; Hassannejad et al., 2019). While this is not a poor characteristic of the procedure, it makes it unsuitable for modeling chronic compression SCI such as those caused by tumors or spondylitis (Müller-Jensen et al., 2021). Moreover, clip compressions of spinal cord have been described only for adult animals and may not be suitable for use in young or old animals. This limits the potential to transfer accurate data about NTSCI to humans, as they most commonly occur in the very young and the elderly populations (Müller-Jensen et al., 2021; New et al., 2013).

2.1.3 | Balloon compression

Balloon compression (Figure 2) is a short-term compressive injury that increases pressure significantly for a short time above the dura mater of the spinal cord and below the spinal processes. Balloon compression is a popular method among scientists as it mimics a compression injury and decompression of the spinal cord, simulating the removal of a tumor, cervical myelitis, and the like. Tarlov first described this method in 1957 when he inserted an inflatable catheter into the vertebral canal above the spinal cords and inflated it for varying amounts of time (1957). Since the initial study, this method of spinal cord compression has been used sporadically to induce spinal cord compression in animals such as dogs, rabbits, and rodents (Krupa et al., 2020; Lim et al., 2007; Murgoci et al., 2019;

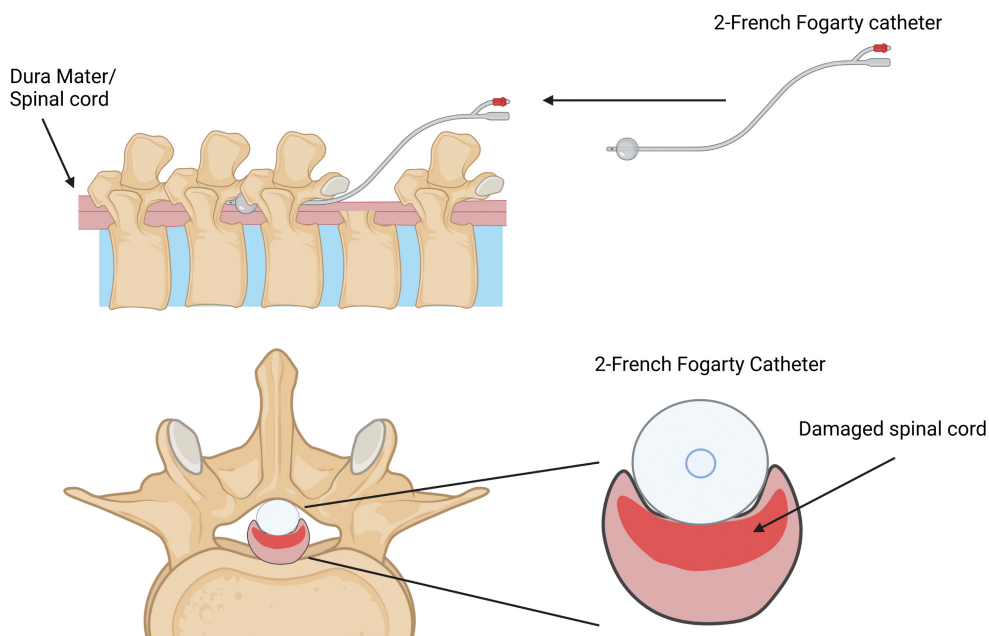


FIGURE 2 Schematic of balloon compression model with a 2-French Fogarty catheter and the inflatable “balloon” tip. The catheter is maneuvered under the spinal column and above the dura upstream from the laminectomy, before being inflated. Created with [BioRender.com](https://www.biorender.com).

Ruzicka et al., 2017; Yang et al., 2017). Most studies now use either a rabbit or rodent model when inducing a compression injury. The standard procedure uses a “2-French Fogarty” catheter which has a balloon-like tip, which is then inserted into the spinal canal and above the dura as the means for compression injury (Krupa et al., 2020). A laminectomy is needed to insert the catheter but does not need to be positioned directly over the intended injury site. Instead, it may be several segments away and the catheter is then introduced until it reaches the required spinal level before inflation (Krupa et al., 2020; Lim et al., 2007; Ruzicka et al., 2017). A graded injury can be obtained by varying the volume of filling solution from 12 to 50 μ l saline solution and by varying the inflation time before decompression. This is most commonly 5–10 min (Krupa et al., 2020; Lim et al., 2007; Ruzicka et al., 2017) but inflated “balloons” may be left in post-surgery for up to 4 weeks (Yang et al., 2017). It has been suggested that the balloon method is not actually best for rodents due to their small subarachnoid space (Vanický et al., 2001) but nevertheless it has been used quite extensively in both rats and mice and has also been employed in several larger species including rabbits (Yang et al., 2017), dogs (Lim et al., 2007; Tarlov, 1957), and goats (Jiang et al., 2016).

The balloon method is also relatively simple and easy to implement, and this model has the advantage of allowing for the decompression of the injury after time which is clinically relevant.

Nevertheless, the balloon model causes more of an acute compressive injury (Cheriyian et al., 2014). While the compressive injury does occur, followed by loss of function in the animals, it does not accurately reflect the changes in compression over a prolonged period. Almost all the balloon models describe a short compressive injury time of 5 min before removal of the balloon. Therefore, while this model helps research clinical acute compression injuries, its use in NTSCI is limited. Additionally, all

reported balloon compressions have been undertaken in adult animals only. Even the smallest balloon catheters used for this method, are too large for use on younger rodents as they are too large for their spinal column.

2.1.4 | Solid spacer compression

A solid spacer compression (Figure 3) is used to mimic compression injuries by inserting a solid wedge-shaped object into the epidural space. This process is done by performing a laminectomy above the level of the desired injury and then moving the spacer into position above the dura and below the intact lamina. This procedure can occlude the spinal column at varying levels depending on the dimensions of the spacer, where 50% occlusion is the first instance of visual motor deficit (Dimar et al., 1999). After insertion of the spacer, it can be left in the epidural space for a prolonged period and has the potential to be removed via surgery if desired (Batchelor et al., 2010). The initial use for the spacer was to test the impact of contusion injury and compression using a Teflon spacer in a rat model of SCI (Dimar et al., 1999). This has since been modified to either a poly (methyl methacrylate) plastic or polycarbonate rod spacer in rats (Batchelor et al., 2010; Schiaveto-de-Souza et al., 2013) and in mice (Kubota et al., 2012).

2.1.5 | Expanding polymer models

Similarly, an expanding polymer (Figure 4) inserted underneath the cervical spinal cord was first described by Kim et al. (2004). This method used a sheet of polymer that would

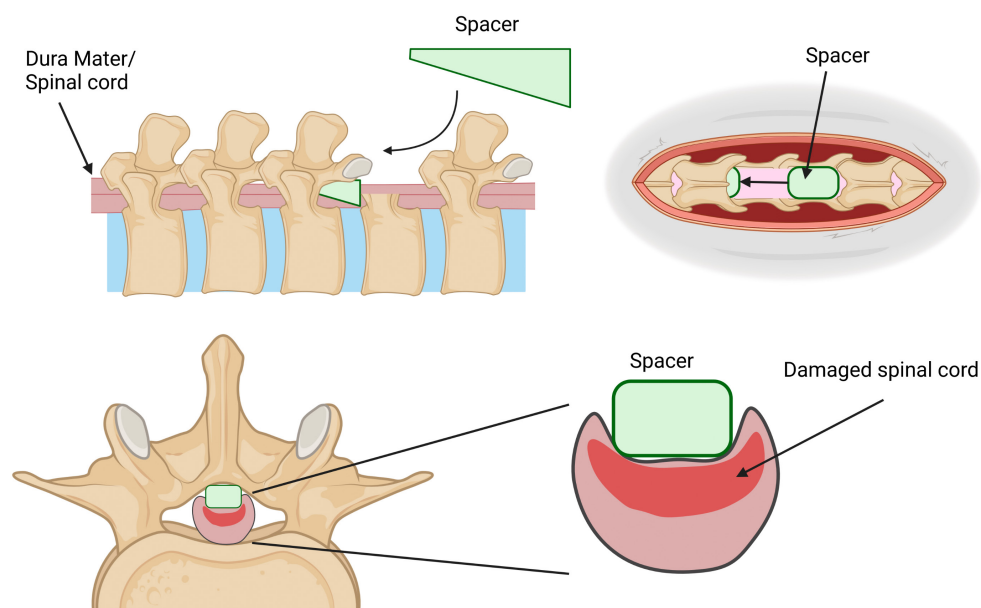


FIGURE 3 Schematic of solid spacer model using a wedged shape spacer which is inserted between the dorsal spinal column and dura of the spinal cord after a laminectomy. The spacer can be left in for days-weeks. Created with [BioRender.com](https://www.biorender.com).

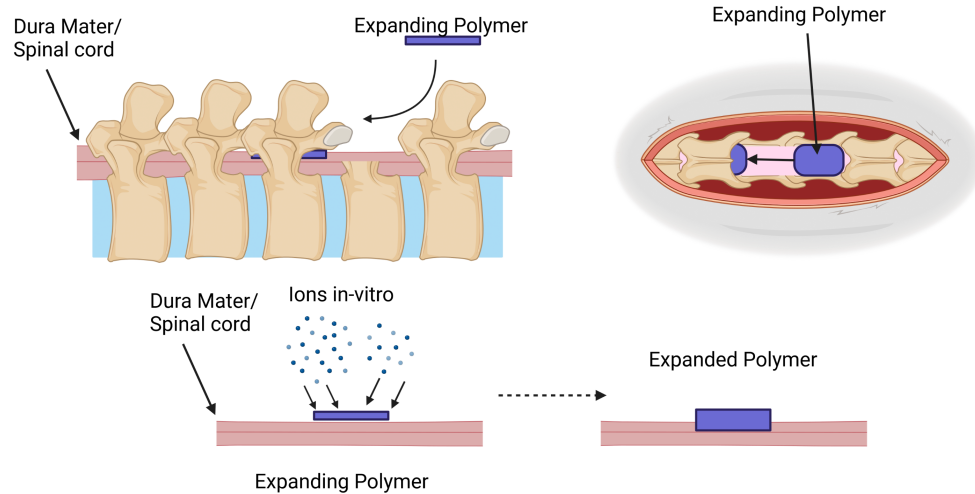


FIGURE 4 Schematic of expanding polymer with a thin strip of polymer inserted between the posterior spinal column and dura of the spinal cord after a laminectomy. The spacer expands in situ over time to create a growing spinal cord injury that slowly compresses the spinal cord. Created with [BioRender.com](https://www.biorender.com).

expand and sit in situ for 25 weeks between the spinal cord and spinal column. This reproduces a chronic compressive injury that mimics delayed cervical myelopathy. Since then, this method has been enhanced by using different sized polymers, and several types of polymers to try and create a more accurate and repeatable experiment. One such method used a water-absorbing polymer that hooks around the spinal cord at the C5/6 region and absorbs water over the desired time of up to 24 h (Ijima et al., 2017; Long et al., 2013). Additionally, Karadimas et al. have used a different type of polymer that absorbs phosphate anions in situ and encourages the formation of new bone in the area to replicate the same chronic compression seen clinically in myelopathy (2013, 2015). These polymers require a laminectomy to implant and are left in for days to weeks depending on the study. They have been able to show that there is a variable loss of large motor neurons using this method, but with a range of spinal cord occlusion that is hard to replicate (Karadimas et al., 2015). This method currently lacks the ability and definitive measurements to be a succinct reproducible model that can accurately replicate injury at the same level each time (Ijima et al., 2017). It is unclear whether this model could be a reliable model for spinal cord compression, even though it can accurately mimic the chronic increase and sustained compression that is missing from other models.

2.1.6 | Weight drop compression

The weight drop model of SCI (Figure 5) is commonly used to induce a contusion injury that mimics a traumatic injury (Sharif-Alhoseini et al., 2017). However, some researchers have suggested its use as a compression model in conjunction with the

contusion model to replicate the compression created from edema after injury (Dimar et al., 1999; Kim et al., 2019; Lau et al., 2013). This model uses multiple animal models, such as rodents and pigs, commonly at adult age (Cheriyani et al., 2014; Sharif-Alhoseini et al., 2017). This procedure opens the animal's spinal column via laminectomy and drops a weighted (30–50 g) rod from a fixed height onto the exposed spinal cord (Gruner, 1992; Stokes, 1992). To induce compression, the rod is additionally held down with an increased mass (50–100 g) for up to 15 min on the exposed cord (Gruner, 1992; Scheff et al., 2003; Stokes, 1992). This model may also skip the weight drop and compress the exposed spinal cord with the weighted rod from the start (Scheff et al., 2003). After the injury, the animal is sutured and allowed to recover while motor deficits are observed (Gruner, 1992; Scheff et al., 2003; Stokes, 1992). There are many models of weight drop, most commonly the Ohio state method, The NYU method, and the Infinite Horizons impact method (Cheriyani et al., 2014; Gruner, 1992; Scheff et al., 2003; Stokes, 1992). These methods were all created to model contusion injuries. Still, they may have the potential to be converted into compression models, mainly when controlled by a consistent force for a prolonged period that does not involve the weight to “drop.”

2.1.7 | Forceps compression

Other models of compression injury include forceps compression (Figure 6) (Blight, 1991). Following a laminectomy, forceps compression involves using calibrated forceps separated by a spacer at different lengths (0.25 mm (mild), 0.4 mm (intermediate), 0.55 mm (severe)) to compress the spinal cord for 15 s and induce a compressive SCI (Blight, 1991; Luo et al., 2002; McDonough et al., 2015; Plemel et al., 2008; Vaughn et al., 2013). This method

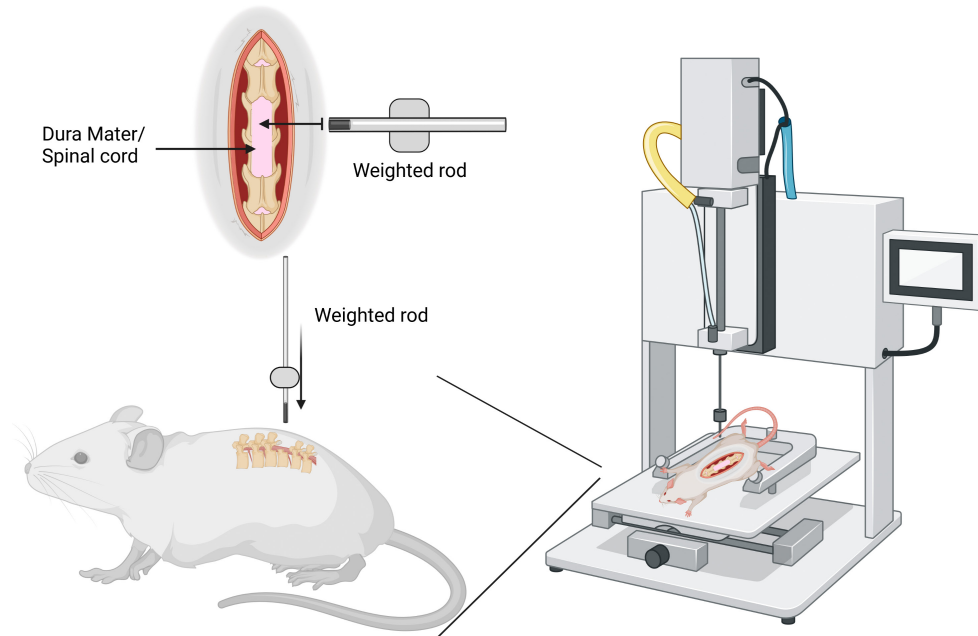


FIGURE 5 Schematic of the weight drop method using a mechanical impactor. The weighted rod drops on the exposed spinal cord from a set height and will displace the cord a varying degree and time depending on the model of weight drop used. Created with [BioRender.com](https://www.biorender.com).

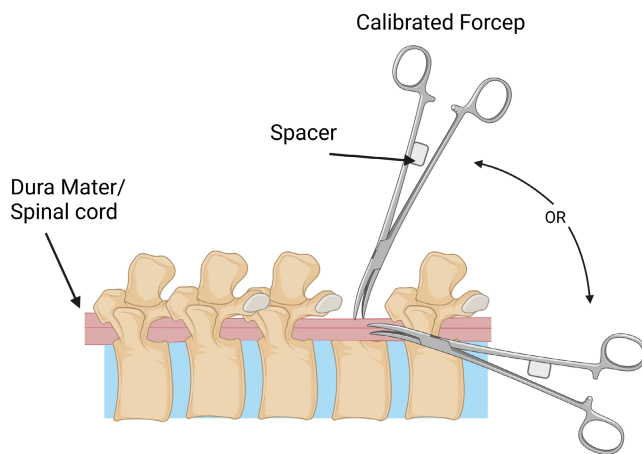


FIGURE 6 Schematic of calibrated forceps model for compression spinal cord injury. The forceps are modified to have a spacer between the handles so that the compression of the spinal cord is consistent. This procedure can be done from the posterior plane or lateral plane of the spinal cord post-laminectomy. Created with [BioRender.com](https://www.biorender.com).

was initially designed to mimic mild compression injuries but has evolved to induce a graded level of injury that can be measured (Blight, 1991; McDonough et al., 2015) and might also be better described as an acute traumatic injury using compression. While this method can provide a consistent injury, some discrepancy in the actual ability for this model to record the injury parameters accurately has been reported (Cheriyen et al., 2014). Therefore, while forceps compression is an inexpensive and straightforward method of NTSCI, variability in its accuracy, reliability for accurate replication and modeling needs to be considered.

2.2 | Models not requiring laminectomy

2.2.1 | Screw compression

The screw compression model (Figure 7) is a relatively new chronic compression model, with its first reference being in 2008 by Xu and associates (2008). This model uses a small plastic, or titanium screw with a flat bottom (pitch of 0.5 mm, a diameter of 3 mm, and a height of 9 mm) drilled through the lamina at the desired region after removing the spinous process (Sun et al., 2016). This screw is then left slightly exposed or sutured over until the following procedures (Lee et al., 2012; Sun et al., 2017; Xu et al., 2008). At each time interval, the screw is turned to increase compression between 0.1 and 0.5 mm each turn, commonly occurring every 7 to 14 days for up to 2 months (Jiang et al., 2016; Lee et al., 2012; Sun et al., 2016, 2017; Xin et al., 2020; Xu et al., 2008). This incrementally increases compression over time to mimic injuries such as tumors or cervical myelitis (Lee et al., 2012). Over the several weeks of study with the screw-in, measurements of spinal deficits are recorded before sacrifice. After sacrifice, histological and pathological measurements are done to assess the extent of the injury (Sun et al., 2017; Xin et al., 2020). In conjunction with motor deficits observed before sacrifice, this measurement measures the extent of the injury and how compression affects the spinal cord. Intervention can be done after removing the screw to test further recovery after such an injury but has yet to be explored in literature.

There are many benefits of the screw compression model in replicating and reproducing NTSCI and compression. This model allows for sustained and increasing compression over a prolonged period that accurately reflects the morphology of a compression

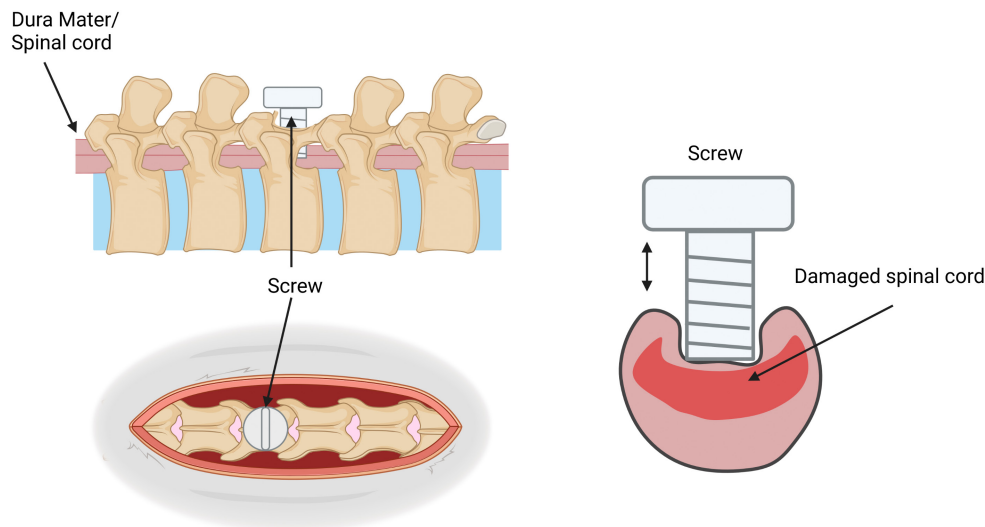


FIGURE 7 Schematic of the screw method of NTSCI where a screw goes through the lamina of the spinal column and compresses the spinal cord. The screw can be adjusted incrementally over a period of days to weeks. Created with [BioRender.com](https://www.biorender.com).

growth such as a tumor, spondylitis, metastasis, and many more (Lee et al., 2012; Sun et al., 2016). This model further improves upon other methods as it does not remove the lamina as part of the operation, meaning that the fluid dynamics of the spinal cord are not altered in a way that may affect results as seen in other methods of spinal cord compression (Xu et al., 2008). Even with the removal of the screw, compression can be relieved while leaving in a small part of the screw to block off the opening in the lamina of the spinal cord (Xin et al., 2020).

There is a concern that the exposed screw or recurrent opening of the wound to tighten concealed screws has the potential for increased infection compared to most of the other models. None of the published articles describing the screw method addressed the morbidity and mortality rates due to infection and while this does not detract from the potential of this model there may be ethical implications that should be taken into account. Additionally, due to the underdevelopment and softness of the spinal bone in neonatal rodents, it is unlikely that this method would be suitable for use on younger aged rodents, limiting its potential for use in mimicking child NTSCI.

2.2.2 | Spinal cord strapping

Spinal cord strapping (Figure 8) is a minimally invasive spinal cord compression injury that replicated NTSCI due to increasing pressure in the spinal column (da Costa et al., 2008). This model is sparse in the literature, most likely due to this method's surgical specificity and complexity. This technique requires a suture to pass through the dermal layers and between the gap of the spinal column. The suture attached to a hooked needle must then wrap under the spinal cord/dura mater and exit the derma without damaging the dura mater and accompanying blood vessels to begin the compression (da Costa et al., 2008). The suture is then attached to a pulley system device developed specifically in the laboratory of the creators Costa et al., to be used for graded

injury using different weights to compress the spinal cord against the posterior spinal column (da Costa et al., 2008). This model allows for a minimally invasive and safe surgery when done right. It can create a graded injury that represents clinical NTSCI of mild, intermediate, and severe cases while minimizing the risk of undesired side effects due to surgery (Cheriyana et al., 2014; da Costa et al., 2008). However, this model is limited in its ability to create a consistent injury and its accessibility for reproduction is an unvalidated method of NTSCI replication (Cheriyana et al., 2014).

2.2.3 | Remote compression model

A more recent compression model that can be operated remotely has been established by Li and colleagues (2022). In this model, a Bluetooth-controlled device (Figure 9) comprised of an in-situ component to compress the spinal cord, and a sub-cutaneous part to receive transmissions is implanted between the C2/3 region of adult male Han sheep. While the sheep lay in a supine position, the compressive device was screwed into the front or anterior side of the vertebral column such that the rod sat between the C2 and C3 intravertebral disk space. In this position, the rod is used to compress the spinal cord positioned above it. After the procedure, the spinal cord was compressed 0.1 mm every 2 days for 10 or 20 weeks, with one 20-week group receiving decompression after the experimental time. This is the first described method of its kind which provided clinically relevant information about chronic cervical compressive myelopathy, that not only reproduced chronic compression in situ over a prolonged time but was also less invasive and can be decompressed at any time (Li et al., 2022). However, while this model shows exciting potential, an animal model of this experiment that would allow for greater replication more efficiently would be far more beneficial to the broader research community, as sheep are harder and more expensive to house than other animals such as dogs or rodents.

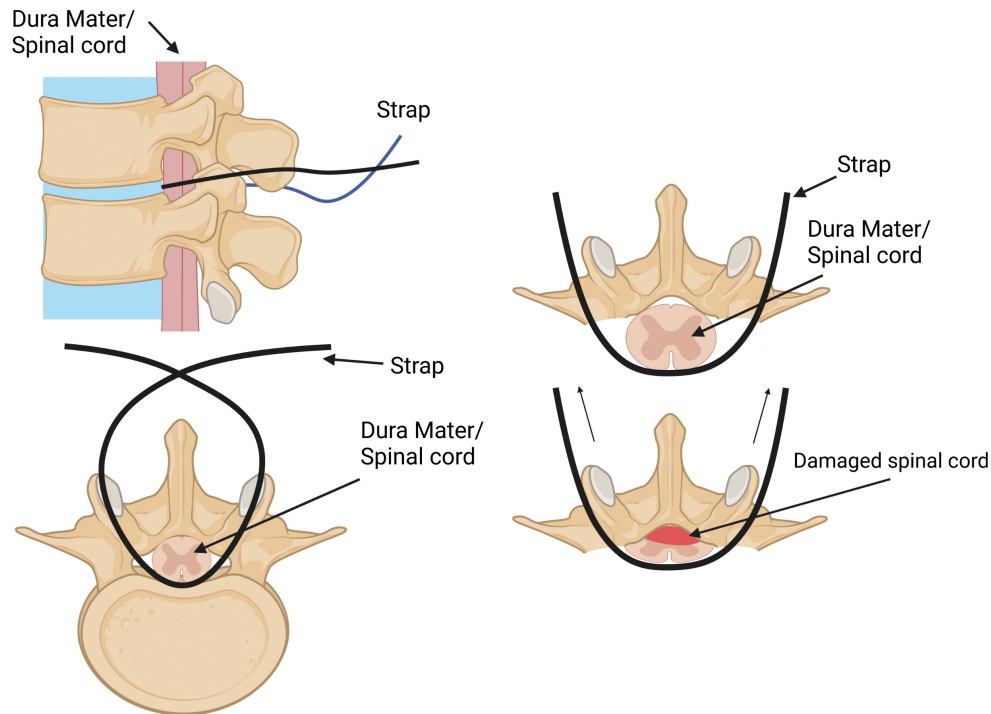


FIGURE 8 Schematic of the strap method of compressive spinal cord injuries. The thread passed through the dermal layers and wraps under the spinal cord before exiting the derma. The straps are then attached to weights that pull the spinal cord up and compress it against the posterior spinal column. Created with [BioRender.com](https://www.biorender.com).

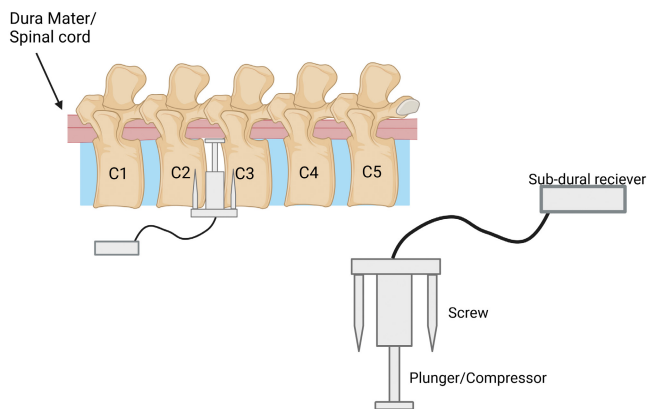


FIGURE 9 Schematic of Bluetooth compression model in sheep. The compression device is screwed into the anterior C2-C3 spinal column after removal of the intervertebral disk. The device then increases compression on the spinal cord using a Bluetooth-controlled plunger that can be incrementally increased. Created with [BioRender.com](https://www.biorender.com).

3 | DISCUSSION

3.1 | Age-related NTSCI

NTSCIs occur in all age groups due to many varied reasons. The most common age brackets that experience NTSCI are the very young and the elderly (Smith et al., 2017, 2022). While SCI in children represents <12% of all SCI globally, in Australia, 66% of SCI in

children are due to a nontraumatic cause (Galvin et al., 2013; Smith et al., 2017). This is important as children with NTSCI have a high morbidity rate, including motor deficits and lower quality of life when compared to other illnesses (Stettler et al., 2013). This further leads to lower life expectancy and an increased risk of other health complications for those affected (WHO, 2013). In addition, Stettler et al. (2013) found that in acute ischemic incidences in children, there were similar symptoms, recovery and overall outcomes compared to adults (Stettler et al., 2013).

It is essential to note the rising mean age for all SCI and the increasing prevalence of NTSCI in all age demographics (Noonan et al., 2012; Shepherd et al., 2021). While NTSCI does occur at all ages, most of the literature only reflects NTSCI models on adult-aged animals. As mentioned, the increasing age and high prevalence of NTSCI in both elderly and child populations are not reflected currently in animal modeling of SCI (Shepherd et al., 2021; Smith et al., 2017, 2022). There is an importance in reflecting the clinical symptoms and age groups that NTSCI occurs so that appropriate intervention strategy can be developed due to the difference in how the body adapts and responds at different ages to SCI (Sezer et al., 2015).

3.2 | Summary of models

The compressive SCI models discussed here are primarily well-established and clinically relevant models that mimic acute spinal

TABLE 1 Summary table of all described compression spinal cord injury models and their most common usages

Method	Level of injury	Injury duration	Common occlusion	Animal models	Pros	Cons
Clip	Cervical/thoracic	Seconds–minutes	30–90 g force	Rodent	Accurate, reproducible, graded injury, simple set up, decompression	Suitability for different ages, laminectomy, no prolonged compression model
Balloon	Thoracic	Seconds–minutes	15 μ l saline	Rodent/rabbit/dog/goat	Graded injury, usable on many animals, simple set up, decompression	Short compression model, suitability on small/young rodents, laminectomy
Spacer	Thoracic	Days–weeks	50% spinal cord	Rodent	Prolonged compression, graded injuries, simple, many devices can be used, used on all ages	Laminectomy, static pressure (no increase/decrease)
Expanding polymer	Cervical/thoracic	Weeks	Variable	Rodent	Slow compression model in situ, gradually increases compression	Laminectomy, minimal control of compression size, reproducibility
Weight drop	Thoracic	Seconds–minutes	30/40/50 g	Rodent/pig	Can readily change parameters of injury force/duration/pressure	Variability in the actual force applied, laminectomy, pressure instantly released
Calibrated forceps	Cervical/thoracic	Seconds–minutes	0.25–0.55 mm	Rodent	Inexpensive, graded injury, easy to perform	Laminectomy, discrepancy in ability to record injury parameters
Screw	Cervical/thoracic	Weeks	3.5–5.0 mm	Rodent/goat	Sustained and increasing compression injury, representative of many types of SCI	No reports of morbidity or mortality due to screw, possible risk of infection due to external exposure and repeated opening
Spinal cord strap	Thoracic	Seconds–minutes	Variable	Rodent	Minimally invasive, graded injury	Highly technical procedure, unvalidated method of SCI replication
Remote compression	Cervical	Weeks	7–14 mm	Sheep	In-vivo control of compression for prolonged periods of time and can be readily changed	Requires major surgery, only been done on large animals, not easily accessible to broader research community

cord compression (Table 1). However, the application of animal models for chronic NTSCI is not as prevalent. Screw compression and solid spacer compression provide a long-term compression injury that mimics what is seen clinically in tumors, spinal cord stenosis, spondylitis, and metastasis but are not yet well-established. These two robust approaches provide the most clinically relevant models for the investigation and intervention of long-term NTSCI. The weight drop compression model further provides good modeling of a compressive injury after a traumatic insult.

4 | CONCLUSION

Animal models of compressive SCI vary in their approach and in their complexity. While acute spinal cord compression is relatively easily modeled it is more difficult to establish a clinically relevant chronic spinal cord compression and even harder to model one that does not require a laminectomy or an extensively invasive technique to access the cord. In addition, most models of compression SCI have been trialed in adult animals which is not reflective of the rising population of NTSCI patients. Therefore, it is recommended that animal models of compression SCI are clearly identified as acute or chronic and that the emerging models with good potential be further tested and developed with the intent to minimize invasiveness to the animals and the spinal column, as well as be reflective of the age demographics most common in NTSCI.

DECLARATION OF TRANSPARENCY

The authors, reviewers and editors affirm that in accordance to the policies set by the *Journal of Neuroscience Research*, this manuscript presents an accurate and transparent account of the study being reported and that all critical details describing the methods and results are present.

AUTHOR CONTRIBUTIONS

The authors confirm contributions to this paper as follows: *Conceptualisation*, R.R., K.M., and C.G.; *Investigation*, R.R. and C.G.; *Writing – Original Draft*, R.R.; *Writing – Reviewing & Editing*, C.G. and K.M., *Supervision*, C.G. and K.M.

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CONFLICT OF INTEREST

The authors declare that there is no conflict of interest.

PEER REVIEW

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DATA AVAILABILITY STATEMENT

Data sharing is not applicable to this article as no new data were created or analysed in this study.

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