

Article

# Designing Chip Feed High-Gain Millimetre Wave Resonant Cavity Antenna (RCA) Array and Optimization of Beam Steering Metasurface

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- Abstract: In this article, a chip-fed millimetre-wave high-gain antenna system with in-antenna power
- 2 combining capability is presented. A low-profile resonant cavity antenna (RCA) array is fed by multiple
- 3 spherical dielectric resonators (DRs), demonstrating its multi-feed capabilities. Each of the DR is fed
- 4 by two microstrip resonators on a planar circuit board. Printed superstrate is used in the proposed
- 5 RCA as the partially reflecting superstrate (PRS), which makes the antenna profile small. To increase
- 6 the directivity and gain, 2×2 RCA array is developed. The demonstrated design shows prominent peak
- <sub>7</sub> gain of 25.03 dBi, radiation efficiency of more than 80% and 3.38 GHz 3-dB gain-bandwidth while
- maintaining a low profile. To steer the beam of the demonstrated 2×2 RCA array in a wide angular
- range with low side-lobe-level, two planar all dielectrics passive beam steering metasurfaces have been
- designed and optimized. A detail analysis on the optimization procedure is presented in this article. This
- numerical investigation is vitally important for realizing beam steering metasurfaces with suppressed
- 2 side-lobe-level, wide bandwidth, excellent efficiency and less complexity.
- 3 Keywords: Beam steering; high gain antennas; metasurface; near-field; optimization.

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#### 1. Introduction

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The present day wireless communication is moving towards millimeter-wave band fre-15 quencies due to the requirements of increasing the number of users, high bandwidth and high data rates. However, millimeter-wave band has a limitation of high path loss which requires 17 high transmission power to compensate for this loss. The transistor-based amplifiers have 18 limited output power, thus, single amplifiers fail to provide the necessary output power for 19 the system. High output power can be supplied by combing powers from several amplifiers 20 in couplers, but the high coupler loss at millimeter-wave band compromises the benefit of 21 power combination. Instead of using couplers, phased array antenna topology can be used where each antenna of the array is fed from an amplifier and the total radiated power can be formed to be the combined power from each antenna element. This on-air power combining technique has the drawbacks of large heat production due to the closer location of the ampli-25 fiers in the phase array antenna system. Compared to these techniques, the in-antenna power combining method offers a more promising solution for transmitting high power [1], [2], [3], 27 [4]. In this technique, powers from multiple sources are concentrated inside a single antenna footprint, thus, eliminating the limitations of coupler losses or the losses from closely spaced 29 amplifiers in phased array topology. This in-antenna power combination technique is utilized in this work for a chip fed antenna system for millimeter-wave band. 31 32

The topology of the chips fabricated with standard processes, such as CMOS, are composed of two segments; the bottom segment of the chip is called Front-End-of-Line (FEOL) which is made with silicon and the active circuit elements are embedded in this segment. The top segment of the chip is called Back-End-of-Line (BEOL) which contained the passive circuit elements. The substrate (typically  $SiO_2$ ) and metallic elements of BEOL are connected to the

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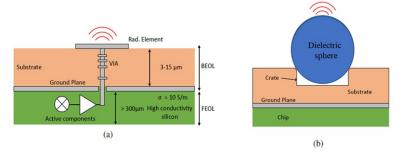
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active components of FEOL through a Vertical Interconnect Access (VIA). Figure 1 illustrates the configuration of a standard chip topology [5]. In this paper, a high gain antenna system is developed which can be directly mounted on the BEOL surface of the chip through a spherical dielectric resonator directly mounted on a shallow crate etched in the substrate of the BEOL (see Figure 1(b)) and fed from the active components located in FEOL through the VIA. In the proposed design, electromagnetic energy from several sources are combined inside an RCA array before transmitting through the radiating element of the antenna. The installation of a spherical resonator in the shallow crate ensures high positioning accuracy and stable attachment of the spherical resonator to the chip. This chip mounted spherical resonator acts as the feeding element of the proposed antenna system. Such an in-antenna power combing technique is highly efficient in millimeter-wave, low-loss high-power applications.



**Figure 1.** (a) Configuration of a standard chip. (b) Mounting the spherical dielectric resonator on a crate etched in the chip substrate.

There is a growing need to dynamically steer the beam of high-gain antennas. Among many applications in the existing and upcoming wireless communications, the most prominent application areas of high-gain beam steering antennas are automotive radar systems, point to point and point to multipoint communication terminals [6], and on-the-move connectivity [7].

Beam steering of high gain antennas can be accomplished by mechanically moving antenna components [8], liquid crystals [9], digitally controlled transmit arrays [10] [11], inplane translation of lenses with fixed antenna feeds [12], leaky-wave antennas [13], and phased array topology [14]. The phased array antenna topology provides quasi-continuous beam steering for high gain antennas at mm-wave frequencies, but it suffers from the limitations of high loss, poor efficiency and high cost [15] [16] [17].

Apart from the conventional mechanically movable reflector dishes and electronically steered phased arrays, recently, passive electromechanical beam steering systems have become popular due to their simplicity, wide-range steering and low cost [18] [8] [19]. A beam steering system utilizing planar phase transformation surfaces mounted in the far-field region (nearly eight wavelengths apart from the antenna aperture) of the fixed-beam antenna is reported in[18]. The topology of this phase transformation surface was motivated by optical Risley prism [20] and its microwave counterpart (dielectric wedges) [21]. The work in [8] demonstrated that the phase transformation metasurfaces can be placed in the near-field region instead of the far-field region of the fixed-beam antenna, and similar steering performance can be achieved with a lower height of the system. This novel technique introduced a new branch of beam steering development called near-field metasteering or otherwise known as metalenses. This methodology was later followed by [19] to develop two all-metallic phase transformation metasurfaces for high-power applications. [22] developed a phase gradient metasurface lens by placing a modulated circular disk unit cell on the top of the radiator to control the radiated beam, and this improved the gain with a decrease in beam width. [23] and [24] developed beam tilting system by using a phase modulated metasurface and negative indexed metasurface loading. A wide beam scanning metasurface with improved gain by controlling the beam of a substrate integrated slot array antenna was developed in [25]. [26] developed a bifocal Fresnel lens by using a polarization sensitive metasurface.

Phase transformation metasurfaces located in the near-field region can steer the beam 78 within a large conical region. These methods are efficient, suitable for high-power applications and are low in cost. However, very limited literature is found on optimizing the metasurfaces 80 for more improved performance. Motivated by the future prospects of beam steering high gain high power chip-fed antennas and the limited research in optimization of metasurfaces, this 82 article presents an all dielectric metasurface designed and optimized for millimeter wave band applications. The all dielectric topology offers the benefit of low loss, design simplicity, ease of fabrication and low cost. Moreover, the phase transformation is achieved by implementing a 85 series of holes with varying radius in the dielectric slabs instead of varying the height of the dielectric. This method significantly reduces the height of the metasurafce. The demonstrated optimization technique offers a promising solution for designing metasurafces with better beam steering performance with reduced side-lobe-level, large bandwidth and high efficiency. 89

# 90 2. Antenna Topology and Design

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#### 2.1. Configuration of the Antenna

Figure 2 shows the configuration of the proposed antenna. The proposed antenna is an RCA with printed superstrate. A partially reflecting superstrate (PRS) modifies the phase front of the transmitted wave and thus improves the directivity of the antenna. Superstrates are classified as printed and non-printed; non-printed superstrates are constructed by dielectrics where phase correction is implemented by varying the permittivity [27] or the thickness [28] of the dielectrics while printed superstrates are constructed by printing metallic patterns on the dielectric [29]. In the demonstrated design, a printed superstrate is used where disk shaped metallic patters are printed on the dielectric. The RCA is fed by a 2×2 square microstrip patch array. These square patches are printed on a middle board. The substrate of the middle board is Rogers RT5880. The bottom surface of the middle board has cladding which serves as the ground plane for the RCA. Square coupling slots are etched in the cladding exactly underneath each patch to provide electromagnetic coupling between the patch radiator and the dielectric sphere. For proper alignment of the spheres with respect to the middle board, holes are drilled in the dielectric and through the square patches.

In the demonstrated design, four alumina spheres are used as the feeding elements of the antenna where the spheres are mounted in thin circuit board. Spherical DRs are an effective method for feeding such types of millimeter-wave chip-fed antennas because of their perpendicular radiation, excellent radiation efficiency and precise alignment to the circuit board [30], [31]. The selected material for the bottom circuit board is Ultralam 3850. Circular crates etched in the circuit board hold the spheres. The alumina spheres have a 3 mm diameter, and each resonates at 34.5 GHz. Four open-ended  $\lambda/4$  microstrip resonators are used to excite each sphere, where  $\lambda$  is the guided wavelength. Among four microstrip resonators of each sphere, an opposite set of microstrip resonators are fed in opposite phases with the same magnitudes. For impedance matching, each microstrip resonator is shorted to ground through a pair of via holes. From the demonstrated antenna topology, it is explicit that there is a total of sixteen microstrip resonators to feed the RCA, thus, power from sixteen sources is combined inside the cavity of the RCA and radiates through the PRS. In actual chip feed applications, the circuit board will be the substrate of the BEOL and each microstrip resonator will be directly fed from a power source located in the FEOL through VIA. So, it can be concluded that the proposed design can be an efficient form of in-antenna power combing technique for chip feed integrations.

Parameter	Value (mm)	Parameter	Value (mm)	Parameter	Value (mm)
A	11.314	В	1.575	С	1.138
E	0.375	F	1.3735	G	1.592
Н	0.31	I	0.85	J	1.338
K	0.125	L	3	M	2.82
N	3.92	О	35	P	1.8546
Q	0.4	R	1.48	D1	2.667
D2	2.663	D3	2.62	D4	2.04
D5	0.68	T1	2.835	T2	8.506
Т3	14.176	T4	19.847	T5	25.517

Table 1: Dimension of the antenna element.

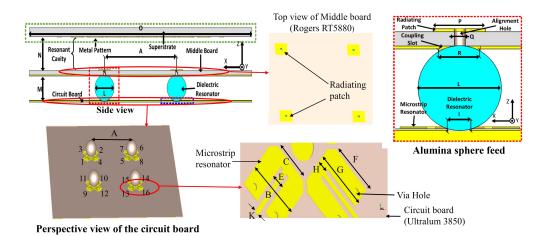


Figure 2. Geometry of the proposed antenna.

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The superstrate of the RCA is shown in Figure 3. The dielectric material for the superstrate is TMM4 whose bottom surface has a printed pattern that consists of circular metallic disks with gradually reduced diameters from center towards the edge. This configuration imposes more phase delay to the field at the center of the superstrate compared to the edge, incorporating a uniform phase front and enhancing directivity.

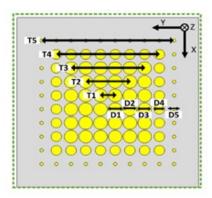


Figure 3. Printed superstrate.

Computational analysis of the RCA was accomplished in CST Microwave Studio 2020. The dimensions of the antenna element and superstrate, presented in Figure 2 and Figure 3, are shown in Table 1.

The properties of the different dielectric materials used in different parts of the antenna are mentioned in Table 2.

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Material Dielectric Constant Loss Tangent Component Thickness/ Diameter (mm) 0.0002 3 9.98 Sphere Alumina Ultralum 3850 2.9 0.0025 Circuit board 0.05 Rogers RT5880 2.2 0.0009 Middle board 0.508 TMM4 0.002 Superstrate 4.7 1.03

Table 2: Properties of the dielectric materials.

## 2.2. Performance Characterization

Figure 4 demonstrates the simulated active S-parameters (magnitude of input reflection coefficient) of the input ports. There are in total 16 input reflection co-efficient results for 16 ports (excited with  $50-\Omega$  discrete ports), but for clarity 7 results are shown in Figure 4 as the results for some ports are exactly similar. The active S-parameters results reveal that this multi-fed RCA maintains impedance matching over a wide bandwidth.

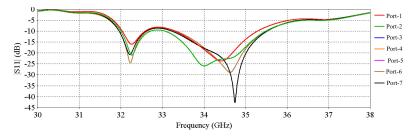


Figure 4. S-parameters of the input ports.

Figure 5 demonstrates the magnitude and phase response of the printed PRS. Here the results for cut plane on X direction is shown, due to symmetry in other plane, it gives the similar results, so not presented here to avoid the repetition.

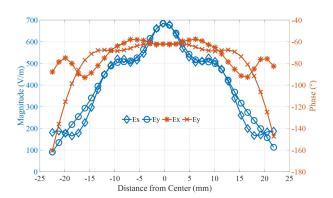


Figure 5. E-Field magnitude and phase response of the printed PRS in X-cut plane.

Figure 6 shows that the antenna achieves a peak directivity of 20.83 dBi at 34.5 GHz. The 3-dB directivity bandwidth is 3.77 GHz (32.63-36.4 GHz). From Figure 6, it is observed that the antenna achieves a peak gain of 20.33 dBi at 34.5 GHz with 3-dB gain bandwidth of 3.02 GHz (32.84-35.86 GHz). Figure 7 shows the side-lobe-level (SLL) of the antenna in two orthogonal planes (phi = 0  $^{\circ}$  and phi = 90  $^{\circ}$  planes).

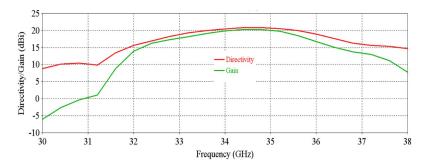


Figure 6. Directivity and gain vs frequency of the antenna.

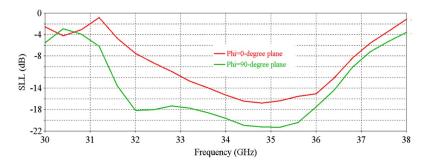


Figure 7. SLL vs frequency of the antenna.

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The simulated efficiency of the antenna is shown in Figure 8. It can be seen that the antenna maintains more than 70% radiation efficiency from 32 GHz to 35.5 GHz. At 34 GHz, the efficiency of nearly 90% is observed. Figure 9 shows the 3-D radiation pattern at 32, 34 and 36 GHz. It shows that the maximum radiation is pointing towards broadside with side-lobe-levels below 8 dB.

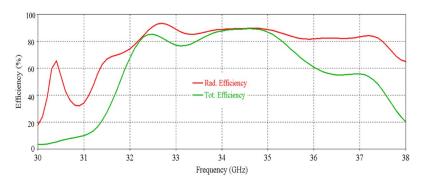


Figure 8. Efficiency vs frequency of the antenna.

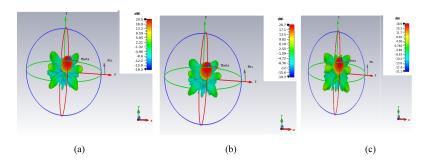


Figure 9. 3-D patterns- (a) 32 GHz, (b) 34 GHz, (c) 36 GHz.

From the above numerical analysis, it is revealed that the antenna achieves excellent matching bandwidth, 3-dB directivity bandwidth (3.77 GHz), 3-dB gain bandwidth (3.02 GHz) and promising efficiency in the entire operating band (32 GHz to 35.5 GHz).

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## 3. Phased Array Topology

For increasing the directivity and bandwidth, RCA array technology is implemented. In this work, a  $2\times2$  RCA array is used. The top view of the RCA array configuration is illustrated in Figure 10. In the demonstrated RCA array topology, different elements of the array are combined into the same substrate, thus, simplifying the assembly and the feeding. In the proposed array technology, two outermost columns and rows of the metallic disks of each element of the supserstrate are overlapped (Figure 10(a)), which substantially reduces the grating lobes. Here, the dimensions of each array elements are the same as the previous single element antenna as shown in Figure 3 and Table 1. The separation between the spheres (A) is slightly increased to 11.34 mm to maintain equal distance between consecutive spheres. The footprint of the antenna is 57.68 mm  $\times$  57.68 mm. Figure 10(b) shows the dielectric spheres of the array. There are in total 16 spheres and each fed from two vertical microstrip resonators. So, there are in total 32 input/output ports for this  $2\times2$  RCA array.

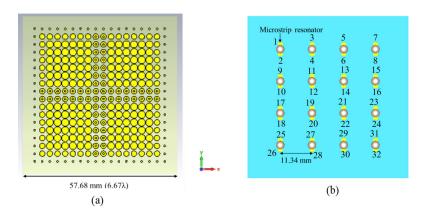
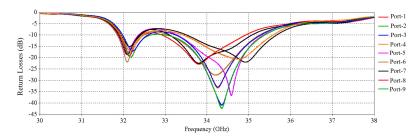


Figure 10. 2×2 RCA array-(a) top view, (b) feed topology.

## 3.1. Performance of the RCA Array

The numerical performance of the RCA array is investigated in CST Microwave Studio 2020. Figure 11 shows the simulated active input match at each port. There are in total 32 results for 32 ports, but for clarity 9 results are shown in Figure 11 as some results are exactly similar, so these are skipped here. The S-parameter results indicate good matching from 31.8 to 35.5 GHz, except some relatively poor matching for some ports at 33 GHz.



**Figure 11.** S-parameters of the 2×2 RCA array.

Figure 12 shows that the antenna achieves a peak directivity of 25.6 dBi at 34.5 GHz, whereas for a single element, the directivity was 20.83 dBi. So, the directivity has been increased by 4.77 dB. The 3-dB directivity bandwidth of the  $2\times2$  RCA array is 3.85 GHz (32.37-36.22 GHz), whereas for individual elements, the 3-dB directivity bandwidth was 3.77 GHz. So, 3-dB directivity bandwidth has been increased by 0.08 GHz in the  $2\times2$  RCA array. From Figure 12, it is observed that the antenna achieves a peak gain of 25.03 dBi at 34.5 GHz with 3-dB gain bandwidth of 3.38 GHz (32.44-35.82 GHz). For a single element, the peak gain was 20.83 dBi and 3-dB gain bandwidth was 3.02 GHz. So, the peak gain is increased by 4.2 dB and 3-dB gain bandwidth is increased by 0.36 GHz. Figure 13 demonstrates the excellent side-lobe-level (SLL) of the RCA array in two orthogonal planes (phi =  $0^{\circ}$  and phi =  $90^{\circ}$  planes).

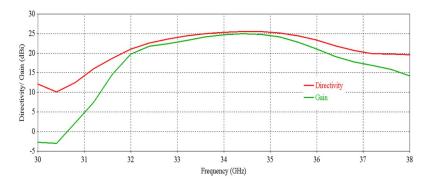


Figure 12. Directivity and gain vs frequency of the 2×2 RCA array.

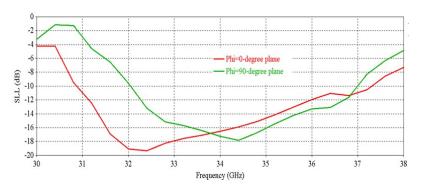
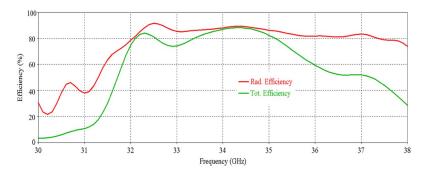


Figure 13. Side-lobe-level (SLL) vs frequency of the 2×2 RCA array.

The simulated efficiency of the RCA array is shown in Figure 14. It can be seen that the antenna maintains a radiation efficiency of more than 80% from 32.1 GHz to 37.3 GHz. A decrease in total efficiency is seen at 33 GHz and after 35 GHz, and this is due to poor matching at these frequencies.



**Figure 14.** Efficiency vs frequency of the 2×2 RCA array.

The E-field distribution of the RCA array is shown in Figure 15. There is overlapping hotspots between array elements, which indicates good radiation characteristics of the array.

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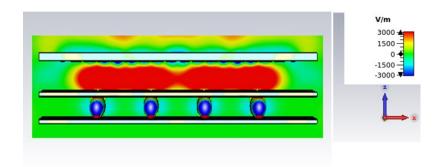


Figure 15. E-field distribution of the 2×2 RCA array at 34.5 GHz.

The far-field radiation pattern of the RCA array at 34.5 GHz is shown in Figure 16. It is exhibited that the maximum radiation pointing towards broadside is 25.5 dBi with side-lobelevels lower than 15.7 dB.

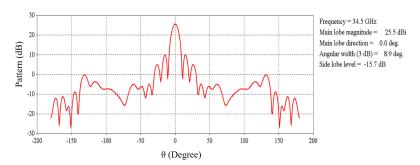


Figure 16. Radiation pattern of the 2×2 RCA array at 34.5 GHz.

# 4. Beam Steering Metasurface Design

To tilt the beam at the desired angle, a planar phase gradient all dielectric metasurface is designed. In the demonstrated design, a pair of planar near-field phase gradient metasurfaces are utilized to steer the beam. When two metasurfaces are rotated together in the same direction keeping no change to their relative positions, a conical scan of the main beam occurred. On the other hand, the beam is steered in the elevation plane only when both metasurfaces are rotated with the same angle in the opposite direction to each other. So, beam steering is possible in any direction within the cone by changing the relative position of the metasurfaces [32].

# 4.1. Unit Cell Model

Figure 17 shows the unit cell of the proposed metasurface. The unit cell is a square dielectric block having width w and thickness t, all four different dielectric materials combinedly form the whole metasurface structure with a thickness of 4.5 mm. A circular through hole with radius t is made in the middle of the dielectric, by varying the radius of the hole, the effective dielectric constant of the cell can be changed which in turn changes the phase shift of the electromagnetic wave passing through the dielectric block. With the combination of different dielectric materials and radiuses of the holes, a full 360° phase shift can be achieved through this cell configuration. In this design, four different dielectric materials are used to achieve the 360° phase-shift range, which are:

211 360° phase-shift range, which are: PREPERM ABS300 ( $\epsilon_r = 3$ ,  $\tan \delta = 0.0046$ ) PREPERM ABS450 ( $\epsilon_r = 4.5$ ,  $\tan \delta = 0.0042$ ) PREPERM ABS650 ( $\epsilon_r = 6.5$ ,  $\tan \delta = 0.0035$ ) PREPERM ABS1000 ( $\epsilon_r = 10$ ,  $\tan \delta = 0.003$ )

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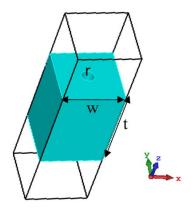
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**Figure 17.** Unit Cell of the proposed metasurface (w = 2.85mm, t = 4.5mm).

These dielectric materials are used to realize the near field phase gradient metasurface. Normalized phase achieved with these four dielectric materials with varying radiuses of through holes between 0.1 mm to 1.4 mm are plotted in Figure 18.

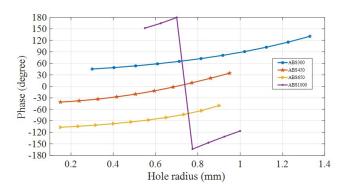


Figure 18. Unit cell normalized phases.

# 4.2. Metasurface Development from Unit Cell Model

The proposed metasurface is a near-field phase gradient metasurface which is designed for the tilt angle of 20°. From the theory of phase gradient metasurface, it is known that to obtain a beam tilt of  $\theta$ ° at a wavelenth of  $\lambda_0$  in a 1-D array, the progressive phase delay  $\Delta \phi$  required between adjacent elements is given by the following relationship [8], [32] -

$$\Delta \phi = \frac{2\pi}{\lambda_0} dsin\theta....(1)$$

where d is the center-to-center distance between adjacent cells. So, to tilt a normal beam by 20°, a metasurface requires a progressive phase shift ( $\Delta$   $\phi$ ) of 41° between adjacent cells for the cell width (d) of  $\lambda$ /3. In the designed metasurface, a total of 20 × 20 cells are used to cover the entire surface of the antenna. Figure 19 shows the metasurface configuration, the phase gradient between adjacent cell along x-axis is 41°, while along y-axis, no phase gradient is introduced. It is exhibited that the metasurface is aperiodic in configuration.

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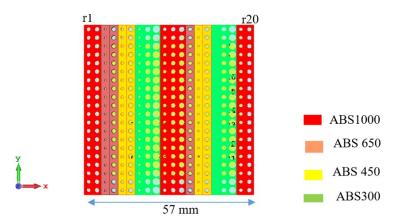


Figure 19. Metasurface configuration.

The radius of the holes (in mm) of all unit cells of the metasurface for each row from 1 to 20 are as follows: r1 = 0.74; r2 = 0.85; r3 = 0.35; r4 = 0.78; r5 = 0.5; r6 = 0.8; r7 = 0.5; r8 = 1; r9 = 1.32; r10 = 0.66; r11 = 0.84; r12 = 1; r13 = 0.7; r14 = 0.35; r15 = 0.72; r16 = 0.2; r17 = 0.85; r18 = 1.25; r19 = 0.66; r20 = 0.8.

To make the metasurface structure periodic, the phase gradient between adjacent cells is set to  $40^\circ$  keeping the overall size same as the aperiodic metasurface ( $20 \times 20$  cells). The steering angle of this metasurface will remain the same as before (i.e.,  $20^\circ$ ). Figure 20 shows the periodic metasurface configuration. The radius (in mm) of the holes of the periodic metasurface unit cells are: r1=0.55; r2=0.75; r3=0.94; r4=0.56; r5=0.91; r6=0.62; r7=0.94; r8=0.81; r9=1.22; r10=0.55; r11=0.75; r12=0.94; r13=0.56; r14=0.91; r15=0.62; r16=0.94; r17=0.81; r18=1.22; r19=0.55; r20=0.75. It is noticed that r1-r9 are unique radiuses that repeat periodically.

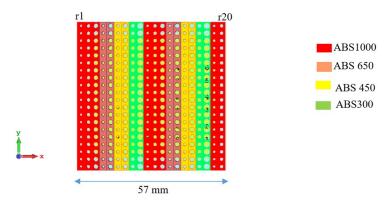


Figure 20. Periodic metasurface configuration.

# 4.3. Period and Aperiodic Metasurfaces Performance Comparison

The performance of the periodic and aperiodic metasurfaces are compared to evaluate which metasurface gives better results for the demonstrated antenna. The performance is examined both with one metasurface and two metasurfaces. For performance prediction and parameter tunning, an array of horizontal electric dipoles (HEDs) is used as a feeding base antenna, which needs relatively less computational resources whilst having nearly the same radiation characteristics as RCA. Figure 21 shows an HED array with one metasurface and two metasurfaces. For the one metasurface configuration, the distance from HED array to metasurface is kept at 8.7 mm and for two metasurfaces configuration, the distance from HED array to metasurface-1 is kept at 8.7 mm and the distance between metasurfaces is kept at 8.7 mm. It can be noted that when the two metasurfaces are aligned in the same direction, maximum beam tilting is realized, while no beam tilting is achieved when they are aligned in the opposite direction.

Configuration	SLL (dB)	Directivity (dB)
HED array only	-13.2	26.7
One periodic metasurface	-9.5	25.9
One aperiodic metasurface	-7.4	24.9
Two periodic metasurfaces aligned in same direction	-4	21.9
Two aperiodic metasurfaces aligned in same direction	-3.4	21.7
Two periodic metasurfaces aligned in opposite direction	-6.1	24.1
Two aperiodic metasurfaces aligned in opposite direction	-5.5	23.1

Table 3: Period and aperiodic metasurfaces performance comparison.

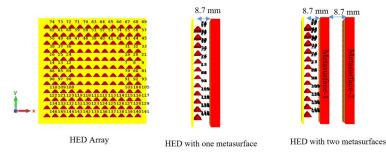


Figure 21. HED array and metasurfaces.

Figure 22 shows the radiation pattern at 34.5 GHz for HED array and two metasurfaces aligned opposite to each other, the patterns are plotted both for periodic and aperiodic metasurfaces for comparison.

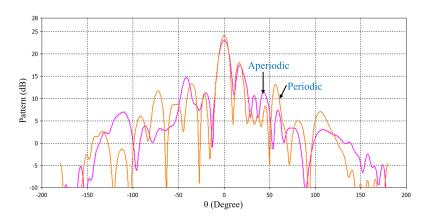


Figure 22. Pattern at 34.5 GHz for HED array and two metasurfaces aligned opposite to each other.

The details simulated performance of the periodic and aperiodic metasurfaces are shown in Table 3. In this comparison, the directivity and side-lobe-level (SLL) are taken into consideration. It can be seen that for both one metasurface and two metasurfaces (aligned in same direction for maximum beam tilting and in opposite direction for  $0^{\circ}$  beam tilting cases), periodic metasurface gives higher directivity and lower SLL. In the demonstrated work design, periodic metasurface configuration is used due to its better performance over the aperiodic one.

## 5. Metasurface Optimization

To increase the directivity and reduce the side-lobe-level (SLL), the metasurface is optimized by using the optimization algorithms of CST Microwave Studio. The radius of the holes of the metasurface cells are optimized keeping the width and thickness constant. Later, the performance of the RCA array is computed with the optimized metasurface and compared with the unoptimized metasurface performance.

## 5.1. Optimization Procedure

The optimization is conducted with supercell [33] and periodic boundary conditions that mimics an infinitely extended metasurface. Supercell is the combination of unit cells that are repeated periodically to form the metasurface. In the demonstrated metasurface, the combination of the first nine-unit cells is the supercell which is shown in Figure 23. "CMA Evolution Strategy" algorithm of CST was used for the optimization. The radius of the holes (r1, r2, r3, r4, r5, r6, r7, r8 and r9) of the unit cells were used as the optimization parameters in the algorithm. In the optimizer, the radius limit was set at 0.1-1.4 mm.

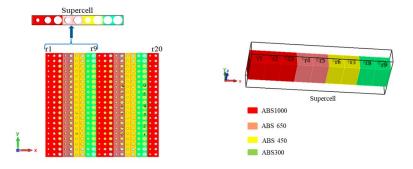


Figure 23. Supercell of the metasurface.

The step-by-step procedure of the optimization is described as follows-

**Step-1:** The supercell was simulated in CST MWS under periodic boundary condition with Floquet port excitation [33]. For this simulation, the supercell was excited with a broadside TE (00) mode propagating along the z-axis. From Floquet analysis, it was exhibited that this supercell supports fourteen propagating TE modes, out of which seven are transmitting and seven are reflecting. Figure 24 exhibits the fourteen propagating TE modes. Among these modes, SZmax(5), Zmin(1) is the main propagating mode which will be maximised. The other modes are either reflections or deflection in unwanted directions and need to be suppressed.

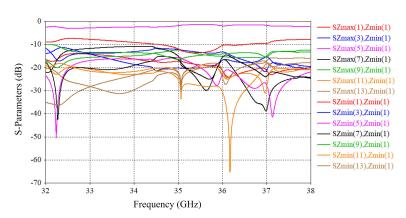


Figure 24. Transmission and reflection modes of the Supercell in Floquet analysis.

**Step-2:** In the optimization settings, a target value, frequency range of interest and weight were assigned to each mode. Maximum weight was assigned for the desired mode. For grating modes, the weights were distributed to target the worst grating lobes selectively. Thus, a higher weight value was assigned to the grating modes with high magnitude. The weight values were gradually reduced for a corresponding reduction in the magnitude of the grating modes. Figure 25 depicts the assigned goal for each mode.

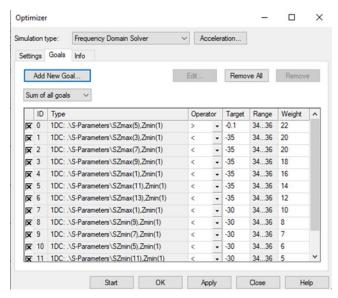


Figure 25. Optimizer settings in CST.

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**Step-3:** The optimizer aims to minimize the goal function value at each iteration. Once the goal function was sufficiently reduced and did not change significantly for at least 10 to 15 runs, then the algorithm was terminated manually. The parameters corresponding to the current best goal function value gives the best performance (enhances the desired mode and suppresses the unwanted modes). The best parameter values (radius of the holes) found from the optimizer were used to form the optimized metasurface which intended to give better performance in terms of directivity and side-lobe-level. The optimizer result is shown in Figure 26. The radius of the holes before and after the optimization are shown in Table 4, which shows significant change in the hole radius.

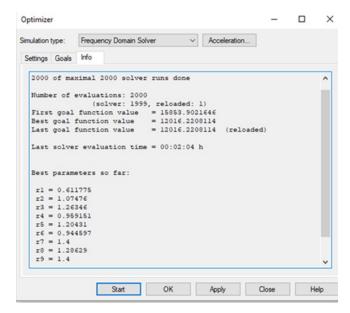


Figure 26. Computed result of the optimizer in CST Microwave studio.

## 5.2. Performance Investigation of the Optimized Metasurface

The performance of the optimized metasurface was numerically investigated and compared with the unoptimized metasurface performance. For performance estimation, HED array was used instead of the actual RCA array to save computation time. The performance was computed when the two metasurfaces were aligned in the same direction (maximum beam

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Cell	Hole radius (mm) before optimization	Hole radius (mm) after optimization	% Change
1	0.55	0.61	10.91
2	0.75	1.07	42.67
3	0.94	1.26	34.04
4	0.56	0.96	71.42
5	0.91	1.2	31.87
6	0.62	0.94	51.61
7	0.94	1.4	48.94
8	0.81	1.3	60.49
9	1.22	1.4	14.75

Table 4: Radius of the Holes Before and After Optimization.

titling) and when they were aligned in the opposite direction ( $0^{\circ}$  beam titling). For simulation with HED array, the distance from HED array to metasurface-1 was kept at 9.83 mm and the distance between metasurfaces was kept at 5 mm (From parametric analysis, it was found that these distances give better performance).

Figure 27 shows the SLL vs frequency of the HED array with two optimized metasurfaces as well as two unoptimized metasurfaces. It can be noticed that when the two metasurfaces are aligned in the opposite direction (0° beam titling), notable improvement in SLL is visible at 33.6-36 GHz for the optimized metasurface, although the minimum value of SLL is better for the unoptimized metasurface, the overall SLL in the entire frequency band is better for the optimized metasurface. For maximum beam titling, significant improvement in SLL is visible at 33.2-36 GHz for the optimized metasurface.

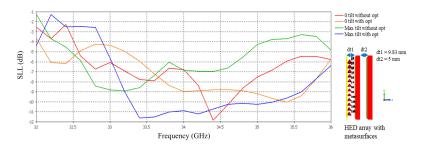


Figure 27. SLL vs frequency before and after optimization tested with HED array.

Figure 28 shows the far-field radiation pattern at  $34.5~\mathrm{GHz}$  of the HED array with two optimized metasurfaces as well as two unoptimized metasurfaces for maximum and  $0^\circ$  beam tilting. An improvement in maximum directivity is visible with the optimized metasurface, this improvement is more significant for maximum beam tilting, i.e., when the two metasurfaces are aligned in the same direction.

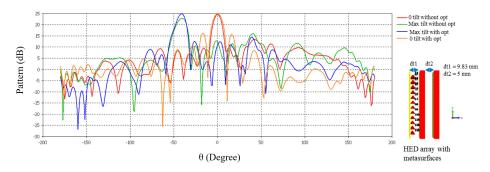


Figure 28. Far-field pattern at 34.5 GHz before and after optimization tested with HED array.

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# 6. Testing the Optimized Metasurface Performance with RCA Array

The performance estimation of the optimized metasurface with HED array has revealed the improvement in directivity and SLL for beam tilting operation. Now, the optimized metasurface is used with the designed  $2 \times 2$  RCA array and beam steering performance is investigated. Performance investigations for maximum beam tilting (when the metasurfaces are aligned in same direction) and  $0^{\circ}$  beam tilting (when the metasurfaces are aligned in opposite direction) are analysed.

#### 6.1. RCA Array with Maximum Beam Tilting Metasurface

Figure 29 depicts the designed sphere-fed RCA array and two optimized metasurfaces aligned in the same direction incorporating maximum beam tilting. The distance from the PRS of the RCA array to metasurface-1 is 9.83 mm and the distance between the metasurfaces is 5 mm.

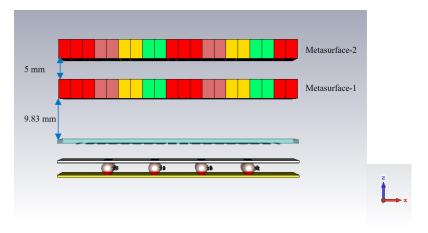


Figure 29. RCA array with two optimized metasurfaces aligned in same direction.

Figure 30 shows the active S-parameters of the ports of the RCA array with optimized metasurfaces, there are total 32 results for 32 ports. For clarity 9 results are shown here, some results are exactly similar, so these are skipped. Comparing with Figure 11 it is observed that at higher frequencies, the reflection at some ports is increased with the metasurfaces.

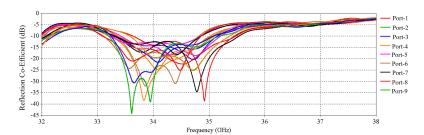


Figure 30. S-parameters of the RCA array with optimized metasurfaces.

Figure 31 shows the directivity and gain vs frequency of the RCA array with two optimized metasurfaces oriented for maximum beam tilting. It is observed that the 3-dB directivity bandwidth is 1.94 GHz (33.59-35.53 GHz) and 3-dB gain bandwidth is 1.68 GHz (33.66-35.34 GHz).

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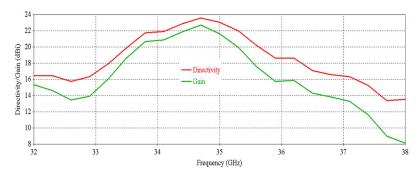
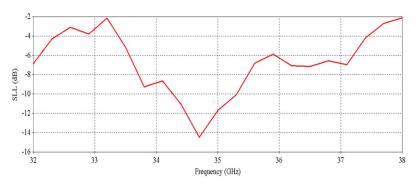


Figure 31. Directivity and gain vs frequency of the RCA array with optimized metasurfaces.

Figures 32 and Figures 33 illustrate the results of SLL vs. frequency and efficiency vs. frequency, respectively for maximum beam tilting. Promising SLL and efficiency can be observed from these results. In Figures 33, a decrease in total efficiency at higher frequencies occurs due to the poor matching at higher band as can be seen from Figure 30.



 $\textbf{Figure 32.} \ \textbf{SLL} \ \textbf{vs.} \ \textbf{Frequency of the RCA array with optimized metasurfaces.}$ 

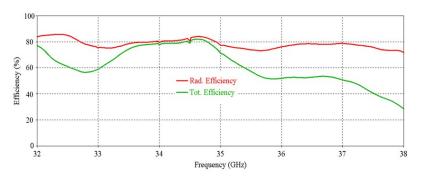
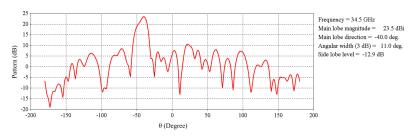


Figure 33. Efficiency vs. Frequency of the RCA array with optimized metasurfaces.

Figure 34 illustrates far-field radiation pattern at 34.5 GHz, the main beam is tilted to  $40^{\circ}$  as expected.



**Figure 34.** Far-field radiation pattern at 34.5 GHz of the RCA array with optimized metasurfaces for maximum beam tiling.

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6.2. RCA Array with Two Optimized Metasurfaces Aligned in Opposite Direction (0° Beam 350 351

Figure 35 shows the sphere-fed RCA array and two optimized metasurfaces aligned in opposite direction incorporating 0° beam tilting. The distance from the PRS of the RCA array to metasurface-1 is 9.83 mm and the distance between metasurfaces is 5 mm.

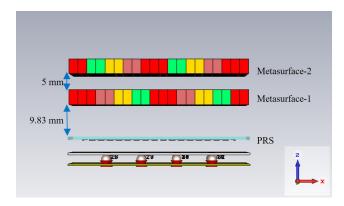


Figure 35. RCA array with two optimized metasurfaces aligned in the opposite direction.

Figure 35 shows the active S-parameters of the ports of the RCA array. Comparing with Figure 11, it is observed that at higher frequency band, the reflection at some ports is increased after using the metasurfaces. The results are similar to the previous results of Figure 30 where the metasurfaces were aligned for maximum beam tilting.

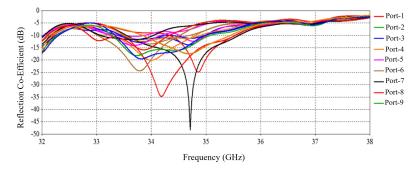
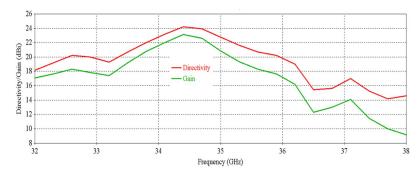


Figure 36. S-parameters of the RCA array with optimized metasurfaces aligned for 0-degree beam tilt.

Figure 37 shows the directivity and gain vs. frequency of the RCA array with two optimized 359 metasurfaces positioned for 0° beam tilting. It is observed that the 3-dB directivity bandwidth 360 is 1.9 GHz (33.59-35.49 GHz) and 3-dB gain bandwidth is 1.53 GHz (33.66-35.19 GHz).



**Figure 37.** Directivity and gain vs. frequency for 0° beam tilt.

Figure 38 and Figure 39 illustrate the results of SLL vs. frequency and efficiency vs. frequency, respectively. Satisfactory SLL and efficiency can be observed from these results. In Figure 39, a decrease in total efficiency at higher frequencies happens due to the poor matching at higher band as can be seen from Figure 36.

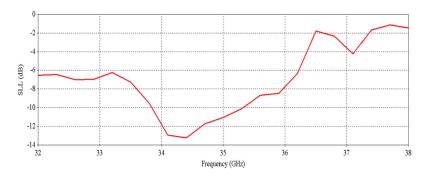


Figure 38. SLL vs. frequency for 0° beam tilt.

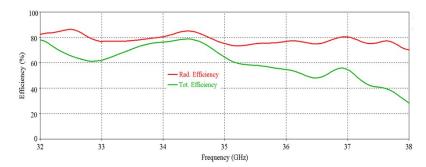


Figure 39. Efficiency vs. frequency for 0° beam tilt.

Figure 40 illustrates far-field radiation pattern at 34.5 GHz, the main beam is directed towards broadside as expected.

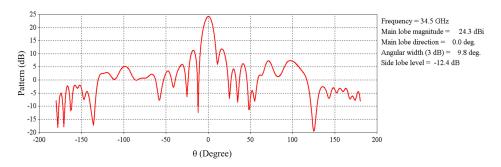


Figure 40. Far-field radiation pattern at 34.5 GHz for 0° beam tilt.

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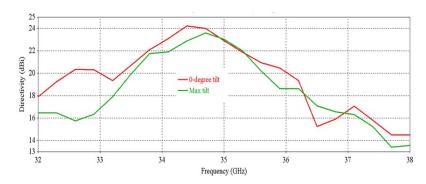
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6.3. Performance Comparison Between Maximum and 0° Tilt for Different Metasurface Orientations

The performance of the RCA array for two orientations of the metasurfaces (aligned in same direction for maximum beam tilting and aligned in opposite direction for  $0^{\circ}$  beam tilting) are compared to demonstrate the performance in different beam tilting positions.

Figure 41, Figure 42 and Figure 43 exhibit the performance comparison of directivity, gain and SLL, respectively for  $0^{\circ}$  and maximum beam tilting cases. The 3-dB directivity bandwidth is 1.94 GHz (33.59-35.53 GHz) for maximum beam tilting, whereas it is 1.9 GHz (33.59-35.49 GHz) for  $0^{\circ}$  beam tilting. It is exhibited that 3-dB directivity bandwidth is nearly the same for maximum and  $0^{\circ}$  beam tilting. 3-dB gain bandwidth is 1.68 GHz (33.66-35.34 GHz) for maximum beam tilting, whereas 3-dB gain bandwidth is 1.53 GHz (33.66-35.19 GHz) for  $0^{\circ}$  beam tilting. It is exhibited that 3-dB gain bandwidth is slightly higher for maximum beam tilting than  $0^{\circ}$  beam tilting. SLL comparison of Figure 43 indicates that  $0^{\circ}$  beam tilting orientation metasurface has better performance than maximum beam tilting metasurface at lower frequencies, but at higher frequencies maximum beam tilting has better SLL performance



**Figure 41.** Directivity comparison for  $0^{\circ}$  and maximum beam tilt.

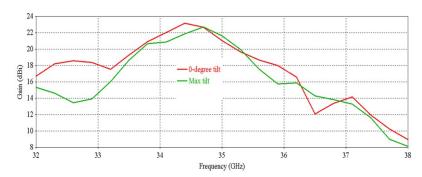
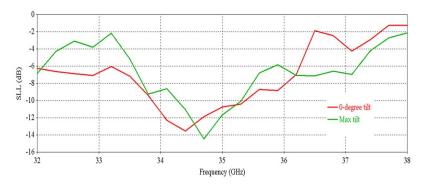


Figure 42. Gain comparison for 0° and maximum beam tilt.



**Figure 43.** SLL comparison for  $0^{\circ}$  and maximum beam tilt.

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Table 5 depicts the performance comparison of the proposed antenna with the state-of-the-art works. It can be noticed that the proposed antenna has the highest gain and it does not require any DC power supply due to the utilization of mechanical beam steering technique, moreover, the antenna has very good scanning angle. The most prominent features of our demonstrated system are its in-antenna power combining capability for chip-fed high power applications in millimeter-wave band, utilization of passive metasurface for the beam steering, the metasurface is 3D printable and has low thickness, excellent gain and scanning range. The optimized metasurface and the designed antenna provides an excellent system of microwave power combining and beam steering method.

## 7. Antenna Performance with Closely Spaced Metasurfaces

The performance of the RCA array (with lossy feed distribution network) is assessed when the metasurfaces are placed very close to the antenna and closely placed near to each other. In this investigation, the distance from the PRS of the RCA array to first metasurface was kept at 0.5 mm and the gap between metasurfaces was kept at 0.5 mm. Metasurface orientation for  $0^{\circ}$  beam tilting scenario was observed. Figure 44 shows the antenna configuration with closely spaced metasurfaces

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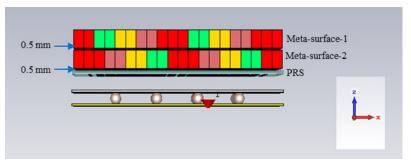
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Ref	Freq (GHz)	Steering	Scanning	Peak Gain	DC Power
		Technique	Angle (°)	(dBi)	
[8]	11	Mechanical	±46	19.4	No
[16]	5.5	PIN Diode	±36	7	Low
[19]	9.375	Mechanical	±20	-	No
[32]	35	Mechanical	±40	21.5	No
[34]	2.62	Water	±20	5.7	No
[35]	30	Mechanical	±39	16	No
[36]	11	Mechanical	±57	19.9	No
This work	35	Mechanical	±40	25.03	No

Table 5: Performance comparison of the proposed antenna with the state-of-the-art works.



**Figure 44.** RCA Array with lossy feed distribution network and closely spaced metasurfaces for 0° beam tilting.

Figure 45 shows the input reflection coefficient at the input port of the feed distribution network, which demonstrates very low reflection in the entire observed frequency band from 32 to 37 GHz.

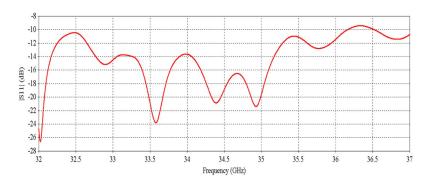


Figure 45. Input reflection coefficient of the RCA array with closely spaced metasurfaces.

The directivity and gain of the RCA array with closely spaced metasurfaces and fed through feed distribution network are illustrated in Figure 46. The 3-dB directivity bandwidth is 2.03 GHz (33.67-35.7 GHz) and 3-dB gain bandwidth is 1.76 GHz (33.76-35.52 GHz). These results are similar to the results when the metasurfaces were placed further apart than this closely spaced configuration (i.e., 9.83 mm from RCA array to metasurface-1 and 5 mm distance between metasurface-1 and metasurface-2).

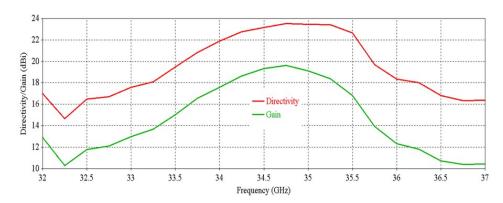


Figure 46. Directivity and gain vs frequency of the RCA array with closely spaced metasurfaces.

The SLL result shown in Figure 47 demonstrates that the side-lobe-level performance is poor for closely spaced metasurfaces configuration compared to the previous results.

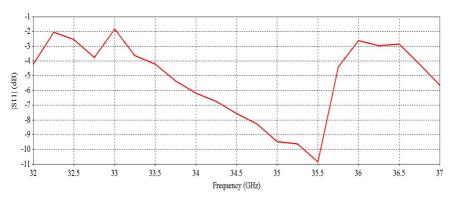
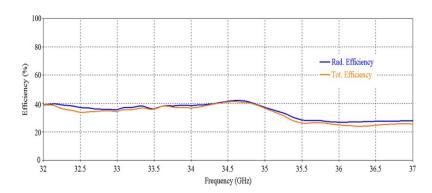


Figure 47. SLL vs frequency of the RCA array with closely spaced metasurfaces.

Figure 48 demonstrates the efficiency of the RCA array for closely spaced metasurfaces, which shows poor performance compared to the previous results.



 $\textbf{Figure 48.} \ Efficiency \ vs \ frequency \ of the \ RCA \ array \ with \ closely \ spaced \ metasurfaces.$ 

Figure 49 plots the far-field radiation pattern of the RCA array with closely spaced metasurfaces at 34.5 GHz, which shows the presence of high grating lobe.

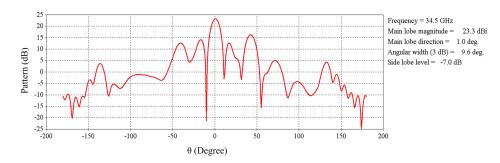


Figure 49. Pattern at 34.5 GHz of the RCA array with closely spaced metasurfaces.

So, it is explicit that a closely spaced metasurface configuration can be used with an appearance of high grating lobe and reduced efficiency. However, this configuration is useful where compact beam scanning system is required.

#### 417 8. Conclusions

The demonstrated RCA array can be a promising candidate for chip fed in-antenna power combining technique for millimeter-wave high gain and low-loss applications. The investi-419 gated planar dielectric phase gradient metasurface can steer the <mark>beam over a wide scanning</mark> 420 range. The explored technique is an effective solution for lightweight, low profile and low-cost 421 design of a passive beam steering system, which is free from thermal loss associated with active electronic components, non-linear distortion, and sensitivity to temperature variation. The explored optimization procedure of the metasurface is an important investigation for 4 24 designing an accurate wide angle and wideband beam steering system with the best achiev-425 able performance. The detail analysis of the Chip-fed RCA array with metasurface could be 426 promising source of information for designing a passive beam steering system having wide scanning range for a millimeter-wave high gain high power antenna system for electronic 428 sensing and spectral monitoring applications.

Author Contributions: Conceptualization, Abu Sadat Md. Sayem; Data curation, Abu Sadat Md. Sayem;
 Formal analysis, Abu Sadat Md. Sayem, Karu P. Esselle and Dushmantha Thalakotuna; Investigation, Abu Sadat Md. Sayem, Karu P. Esselle, Dushmantha Thalakotuna and Manik Attygalle; Methodology, Abu Sadat Md. Sayem; Project administration, Karu P. Esselle and Manik Attygalle; Resources, Karu P. Esselle, Dushmantha Thalakotuna and Manik Attygalle; Software, Abu Sadat Md. Sayem; Supervision, Karu P. Esselle, Dushmantha Thalakotuna and Manik Attygalle; Validation, Abu Sadat Md. Sayem, Karu P. Esselle, Dushmantha Thalakotuna and Manik Attygalle; Visualization, Abu Sadat Md. Sayem and Dushmantha Thalakotuna; Writing—original draft preparation, Abu Sadat Md. Sayem; Writing—review and editing, Abu Sadat Md. Sayem, Karu P. Esselle, Dushmantha Thalakotuna and Manik Attygalle. All authors have read and agreed to the published version of the manuscript.

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