

An analysis of causative factors for road accidents using partition around medoids and hierarchical clustering techniques

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Abstract

Insufficient progress in the development of national highways and state highways, coupled with a lack of public awareness regarding road safety, has resulted in prevalent traffic congestion and a high rate of accidents. Understanding the dominant and contributing factors that may influence road traffic accident severity is essential. This study identified the primary causes and the most significant target-specific causative factors for road accident severity. A modified partitioning around medoids model determined the dominant road accident features. These clustering algorithms will extract hidden information from the road accident data and generate new features for our implementation. Then, the proposed method is compared with the other state-of-the-art clustering techniques with three performance metrics: the silhouette coefficient, the Davies–Bouldin index, and the Calinski–Harabasz index. This article's main contribution is analyzing six different scenarios (different angles of the problem) concerning grievous and non-injury accidents. This analysis provides deeper insights into the problem and can assist transport authorities in Tamil Nadu, India, in deriving new rules for road traffic. The output of different scenarios is compared with hierarchical clustering, and the overall clustering of the proposed method is compared with other clustering algorithms. Finally, it is proven that the proposed method outperforms other recently developed techniques.

KEY WORDS

accidents, Calinski–Harabasz index, Davies–Bouldin index, DBSCAN, hierachal clustering, K-means, OPTICS, PAM clustering, road safety, silhouette coefficient

1 | INTRODUCTION

Road accidents are a global concern, contributing significantly to mortality, disability, and economic burdens. India, in particular, experiences high traffic fatalities, with at least one in ten global traffic deaths attributed to the country.

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The impact of road accidents is far-reaching, affecting victims, families, and the economy due to premature deaths, injuries, disabilities, and lost income potential. Preventing accidents is crucial, but fatalities still occur despite everyone's best efforts. Therefore, data mining techniques, especially clustering algorithms, offer a promising avenue to uncover valuable insights from massive traffic accident datasets. Data mining, also known as knowledge discovery in data, enables the extraction of patterns and essential information from vast datasets. Unlike business intelligence, which focuses on analyzing business data, data mining employs various methods and algorithms to identify relationships and patterns within the data.

In the context of road accidents, data mining can assist in predicting future accident patterns based on historical data. For this research, the authors utilized clustering analysis to make predictions about road accidents, explicitly focusing on fatal accidents. Clustering analysis is one of the techniques used to study the contributory factors of road traffic accidents (RTAs). For identifying the contributing factors of RTAs, different clustering algorithms were proposed in the literature. The K-medoids method¹ is used to determine the critical pre-crash events at T-and four-legged junctions, which can be used to verify the safety of autonomous driving systems. The data set consists of 1056 junction crashes in the UK and resulted in 13 T-junction clusters and 64-legged junction clusters.¹

The authors studied a cluster analysis of the accident-prone areas in Semarang city to find an area's vulnerability.² According to their findings, Semarang's highest level of accidents mainly occurred on weekdays. Data in New Mexico were considered to inspect the injury severity in intersection-related crashes for two-year crashes. The k-means cluster technique was used to cluster the road data. The hierarchical Bayesian random intercept models were developed to identify the contributing factors in every cluster. The findings reveal how the number of crash-level, vehicle/driver-level, and cross-level interactions significantly impact driver injury severity and how these findings help prevent crashes. They examine the understanding of crash potentials among teen drivers using a huge dataset (information on roughly 88,000 respondents) of teen survey data obtained in Texas. Taxicab correspondence analysis was used to analyze the data and discovered that males with provisional or unrestricted licenses are among the highest risk groups.

The authors concentrated on identifying potential factors that may be linked to varying levels of pedestrian injury severity resulting from train-pedestrian collisions (excluding suicides) at highway-rail grade crossings (HRGCs).³ To conduct their analysis, they utilized 10-year data from the Federal Railroad Administration and employed latent class clustering (LCC) as a method of clustering analysis. Results showed that regardless of the HRGCs' parameters, higher train speed was linked to a higher risk of severe injury. All other factors elevated pedestrian injury severity levels, with differing effects in different clusters.

Traditional statistical models in road safety research have limitations in handling complex datasets, leading researchers to adopt machine learning (ML) approaches. Clustering and classification algorithms like K-means, support vector machines, and decision trees are commonly used for accident severity prediction. However, more comparative analysis and exploration of hierarchical clustering's potential in road safety research must be done. In the related works section, a detailed literature survey has been done. From the literature survey, we found that all the proposed clustering algorithms applied to the entire dataset and then found the grouping based on the homogeneity of the attributes. The main contribution of this article is to analyze six different scenarios (different angles of the problem) in the road accidents dataset, which will help us analyze the more profound insights into the problem and help the transport authorities in Tamil Nadu, India, derive new rules for road traffic. To achieve this, the proposed work analyses causative factors for road accidents in Tamil Nadu using partitioning around medoids (PAM) and hierarchical clustering algorithms, and then it will be compared with other state-of-the-art methods. The flow diagram for the proposed method is given in Figure 1.

The article is organized as follows: In Section 2, we discuss the related works and address the gaps identified. In Section 3, we discuss the methodologies used in this research, such as Gower distance, silhouette width, PAM clustering, and hierarchical clustering. The performance analysis of the proposed methods with others is discussed in Section 5, and finally, a conclusion is given in Section 6.

2 | RELATED WORKS

Recently, many researchers have been contributing traditional statistical model-based methods used to predict accident fatality and severity. Some of the conventional statistical model-based techniques are the logit model,⁴ logic model approach,^{5,6} and ordered probit model⁷ to predict accident fatality and severity in terms of independent and dependent accident factors like bad road conditions, weather conditions, lack of traffic indication, drunken and driving,

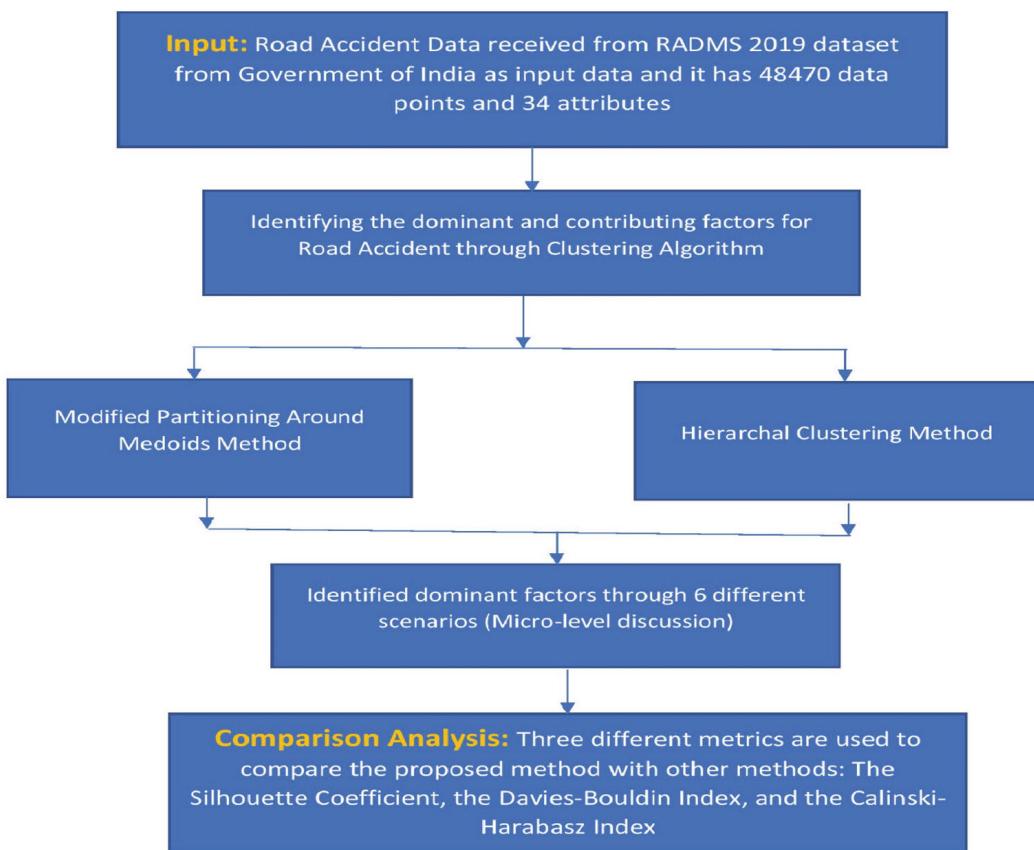


FIGURE 1 The flow diagram for the proposed method.

children driving, vehicle problem, driver's attitude and so on. The following provides an overview of several studies that utilize clustering and data mining techniques in road safety research. These studies investigate various aspects, such as identifying risky driving behaviors, understanding the relationship between dangerous behaviors and accidents, analyzing injury patterns, and predicting accident causes. Applying clustering and data mining methods in these studies has yielded valuable insights and contributed to developing effective road safety strategies. Lastrucci et al.⁸ utilized cluster analysis to identify risky driving behaviors among adolescent drivers in Italy and their association with RTAs. This approach allowed them to identify distinct patterns of risky behaviors and their impact on accident occurrence, providing valuable insights for targeted intervention strategies. Similarly, Hassanzadeh et al.⁹ investigated motorcycle riders' riding patterns and risky behaviors in a specific district in Iran using regression analytic methods. This analysis helped them understand the relationships between dangerous behaviors and other factors, contributing to a better understanding of the risk factors involved in motorcycle accidents. Fueyo et al.¹⁰ focused on accident injury patterns, employing unsupervised clustering algorithms on crash data. By classifying seriously injured individuals into clusters, the study opened new possibilities for vehicle safety, potentially leading to improved safety features. In the survey of medical expenses and costs related to motor vehicle crashes in Puerto Rico,¹¹ K-means clustering played a crucial role in grouping the data, facilitating the identification of the best cluster that maximized distance among groups and minimized distance within groups. This approach contributed to a better understanding of the factors influencing medical expenses and costs associated with injuries in road accidents. Moreover, the survey of data mining methods for road accident analysis¹² presented various clustering and classification methodologies, with the self-organization map (SOM) being used to uncover multiple patterns and predict accident causes. The application of SOM led to improved analysis accuracy compared to k-means clustering, demonstrating the effectiveness of SOM in handling road accident data. In the context of road accidents in Haridwar,¹³ India, Sachin Kumar et al. proposed a data mining technique that employed LCC and the k-mode clustering technique to reduce heterogeneity in the dataset. This approach helped reveal crucial facts about the accidents and paved the way for better solutions and targeted interventions. Furthermore, Kim and Yamashita¹⁴ discussed the utility of K-means clustering in safety research and its application in analyzing spatial patterns of pedestrian-involved

crashes in Honolulu. They suggested that both K-means and hierarchical clustering techniques are valuable tools in the arsenal of spatial analytic methods for road safety research. Clustering techniques are not only used in predicting road accident severity, but they can also be used in several other fields like management, arts, engineering, and medicine.¹⁵

More recently, Sivasankaran and Balasubramanian²⁶ studied the patterns in road crashes in Tamil Nadu from 2009 to 2017 reported in the Road Accidents Database Management System (RADMS) to explore the injury severity levels of bicycle-vehicle crashes. Latent Class Clustering (LCC) models and binary logit models were combined to identify significant factors in demographics, vehicle, and environmental causes for the crashes. Sivasankaran and Balasubramanian²⁷ used the same RADMS database to identify associations between pedestrian hit-and-run causes. The same team used Multiple Correspondence Analysis (MCA)^{28,29} to identify associations between various contributing factors of pedestrian crashes. Pedestrians of 25–34 age group were associated with crashes at traffic signals where the drivers exhibited non-respect for the right way of rules. In addition, driving violations such as driving against traffic flow and risky driving behaviours such as changing lanes without due care and dangerous overtaking were associated with pedestrian-vehicle crashes.²⁹ Similar studies were conducted, where the factors associated with the overspeeding risky behaviour of drivers were studied using logistic regression.³⁰ With a majority of crash fatalities in Tamil Nadu involving motorcycles,³¹ ordered logit model was used to identify significant contributing factors in single vehicle motorcycle fatalities.³² In road safety research, traditional statistical model-based techniques have long been utilized to predict accident fatalities and severity. However, conventional statistical models have limitations, particularly in dealing with complex and multidimensional datasets. Nowadays, most researchers have turned to ML approaches to overcome these challenges due to their predictive superiority, efficiency, and ability to handle informative datasets. The notable works are given as follows: Kwon et al.,²³ used decision trees and Nave Bayes to classify road accidents, and the data were collected between 2004 and 2010; they also compared the classification results with linear regression. Sharma et al.²⁴ demonstrated the road accident prediction through a support vector machine and multi-layered perceptron; they considered only two parameters, namely, drunken and driving and speed of the vehicle. AlMamlook et al.²⁵ utilized Nave Bayes, AdaBoost, random forest, and logistic regression methods for road accident predictions. Ester et al.,²⁶ proposed a density-based algorithm for discovering clusters in large spatial databases with noise (DBSCAN) for clustering, and Ankerst et al.,²⁷ proposed ordering points to identify the clustering structure (OPTICS) clustering algorithms.

ML has applications in various domains, including construction, occupational accidents, agriculture, education, sentiment analysis, banking, and insurance. Data mining, ML, and deep learning algorithms have been extensively used in road accident prediction. Notable clustering and classification algorithms have been employed to build accident severity models, such as K-means, support vector machines, K-nearest neighbors, decision trees, artificial neural networks, convolutional neural networks, and logistic regression. The literature needs a comprehensive comparative analysis of different clustering algorithms' performance and standardized evaluation metrics. From the literature survey, we found that all the proposed clustering algorithms applied to the entire dataset and then found the clustering based on the homogeneity of the attributes. The significant contribution of this article is to analyze six different scenarios (different angles of the problem) in the road accidents dataset, which will help us analyze the more profound insights into the problem and help the transport authorities in Tamil Nadu, India, derive new rules for road traffic. To achieve this, the proposed work analyses causative factors for road accidents in Tamil Nadu using PAM and hierarchical clustering algorithms, and then it will be compared with other state-of-the-art methods.

3 | METHODOLOGY

3.1 | Dataset

This article uses the road accident data management system (RADMS) data and GIS-based software for collecting, comparing, and analyzing road accident data for testing. This database is maintained by the State Transport Planning Commission of Tamil Nadu and is the official source that offers complete information on accident circumstances (please refer: <https://data.gov.in/catalog/road-accidents-india-2019>). Trained police officials compile the crash data across the state with the same instruction manual. The World Health Organization has also advocated using RADMS as an ideal system for nations lacking databases that store accident data. The RADMS 2019 dataset has 48,470 data points and 34 attributes; another dataset contains 2821 data points with 32 attributes.

3.2 | Maintaining the integrity of the specifications

Accidents involving grievous injuries and vehicle damage only (non-injury) on national and state highways of Tamil Nadu state in India in 2019 have been considered. Table 1 illustrates the data spread across the various variables for the RADMS dataset.

3.3 | Techniques used

Clustering algorithms and techniques play an essential role in analyzing traffic accidents. They can identify groups of people on the road, vehicles, environmental factors, and other such attributes, which would help arrive at conclusions and appropriate countermeasures well.¹⁴

3.3.1 | Gower distance

Choosing the right metric to calculate the distance between two data points, especially while clustering the data, is very important. The RADMS data has both numerical and categorical attributes, hence mixed data. Mixed data have unique metrics for calculating the distance between data points. Gower distance is one such metric used on diverse data.²⁸ Gower distance is a dissimilarity-based distance metric computed as the mean of partial dissimilarities between data points. In the R programming language used for this study, the daisy function has been used to compute Gower distance. For calculating the Gower distance matrix, the daisy function does the following—each variable (column) or attribute is standardized by subtracting the minimum of the column from each data point and then dividing each data point by the range of the corresponding attribute. This standardization of each variable scales the data such that the range becomes [0, 1]. We compute a measure for each pair of data. If these data are numeric, the measure is the absolute value of the difference divided by the range. If the data is not numeric, the measure takes the value of 1 if the data points are different or 0 if the data points are the same. Gower distance is the average of all these measures.

3.3.2 | Silhouette width

Silhouette analysis decides the optimum number of data clusters.²⁹ The silhouette value describes how similar an object is to its cluster compared to others. The silhouette plot, which represents the same, has the number of clusters on the x-axis and silhouette width on the y-axis, which is given in Figure 2A,B. The higher the silhouette width, the better would be the clustering. silhouette width values lie in the range of -1 and 1. A value of 1 indicates a considerable distance from this sample to its neighboring clusters. A value of 0 indicates that the sample lies on the boundary of two clusters.

The optimum number of clusters is chosen with the help of the silhouette plot and used in the PAM algorithm, which is given in Figure 2 with two data subsets, namely, grievous injury subset (Figure 2A) and no injury subset (Figure 2B). Moreover, a negative value indicates that the sample has been classified into the wrong cluster.

3.3.3 | Partition around medoids clustering

The partition around medoids (PAM) clustering algorithm finds objects called medoids around which clusters are built. PAM aims to minimize the average dissimilarity of data points to their closest medoid. The similarity coefficient can evaluate the similarity between the various attributes.³⁰ If the value of the similarity coefficient is high, then the similarity between the attributes is more elevated. Otherwise, dissimilarity is more significant. In this case, the dissimilarity can

be estimated by using the relation $S_{ij} = \left(\frac{a[\sin(\frac{ax}{2n})+d]}{[a \sin(\frac{ax}{2n})+b+c+ad]} \right)$ for $i \neq j$, where a is the number of attributes which is equally importance between the clusters i and j ; b is the number of attributes which are required in cluster i and not in j ; c is the number of attributes which are required in cluster j but not in i , d is the number of attributes which is neither needed for cluster i nor j , and n is the total number of attributes. Equivalently, the sum of dissimilarities can also be minimized.³¹ The algorithm has two phases: a build phase and a swap phase. The “ k ” medoids are selected during the build phase, and

TABLE 1 Sample data for the road accident data management system (RADMS).

Category	Frequency	Category	Frequency
Accident severity		Police present	
Grievous injury	1643	No	2108
No injury	1178	Yes	713
Accident day		Shoulder	
Sunday	456	Yes	2821
Monday	417	Footpath	
Tuesday	416	No	940
Wednesday	373	Yes	1881
Thursday	366	Structure narrowing	
Friday	369	No	2774
Saturday	424	Yes	47
Collision type		Other features involved	
Head on	1095	Tree	6
Hit pedestrian	437	Animals	17
Hit from rear	584	Fixed objects	29
Hit animal	11	Posts	9
Hit from side	264	Advertising boards	2
Hit tree	17	Not applicable	2758
Sideswipe	24	Location type	
Skidding	100	Corporation	524
Rain off-road	16	Municipality	968
Overturning	23	Panchayat	1329
Overturning-no collision	4	Landmark 1	
Hit object on the road	38	Near school/college	230
Hit object off-road	25	Near/inside a village	255
Hit parked vehicle	22	Near factory/industrial area	85
Others	161	Near religious place	88
Central divider		Near recreation place/cinema	23
No	1045	In bazaar	158
Yes	1776	Residential area	114
Junction type		Near hospital	116
T-junction	189	Open area	187
Staggered junction	2	Near bus stop	771
Y-junction	26	Near petrol pump	177
Cross junction	93	At pedestrian crossing	23
Roundabout junction	10	Narrow bridge or culvert	17
Junction with more than 4 arms	29	Near office complex	97
Bridge (flyover)	17	Near beach	7
Rail crossing-manned	4	Near bridge	205
Not a junction	2451	Junction	195

(Continues)

TABLE 1 (Continued)

Category	Frequency	Category	Frequency
Junction control		Near railway station	10
Not a junction	2068	Near traffic signal	45
Police officer	16	Near tollgate	18
Traffic signals	46	Rural-Urban	
Flashing signal	31	Rural	2233
Stop sign	18	Urban	588
Give way sign	42	Hit run	
No control	600	No	2640
Road category		Yes	181
National highway	1054	Collision type code	
State highway	1767	Pedestrian accident	517
Light condition		Single vehicle accident	217
Daylight	1775	Single vehicle: collision with a fixed object	29
Twilight	245	Vehicles at perpendicular direction without turning	32
Darkness-no street lights	174	Accident between vehicles from opposite direction	533
Darkness street lights on	460	determine factors and identify high-risk	319
Darkness with poor street light	167	Accidents between vehicles from the same direction and where one is turning	121
Weather code		Accidents between vehicles from opposite directions and where one is turning	75
Fine	2718	An accident between vehicles in the perpendicular direction and where one is turning	52
Cloudy	48	Accident due to driver error	926
Light rain	9	Collision description code	
Heavy rain	8	Junction-pedestrian crossing from left to right	38
Flooding of causeways/rivulets	2	Vehicle turning left	17
Hail/sleet	1	Junction-pedestrian crossing from right to left	25
Smoke/dust	1	Pedestrian crossing from left to right	90
Strong wind	2	Pedestrian crossing from right to left	61
Very cold	15	Pedestrian standing on the road	74
Very hot	17	Pedestrian walking along the road	168
Surface type		Pedestrian on shoulder/footpath	61
Tarred (bitumen)	2300	Vehicle turning right	5
Concrete	372	Vehicle at a junction	5
Metaled (WBM)	37	Vehicle skidding	75
Kuttcha	112	Loss of control	100
Road condition		A passenger fell inside the vehicle	1

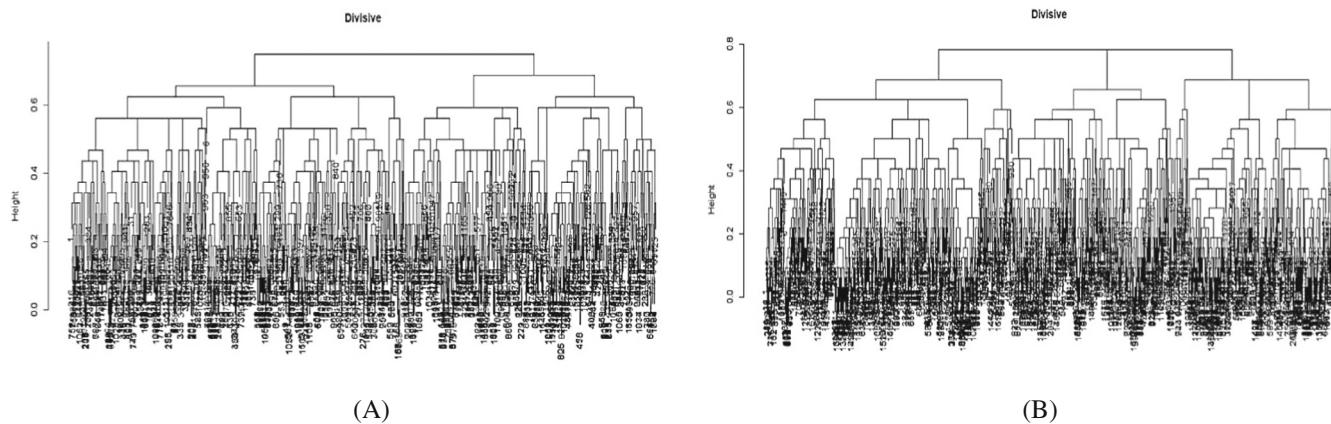


FIGURE 2 The optimum number of clusters using the silhouette plot for grievous injury and no injury. (A) Grievous injury subset. (B) No injury subset.

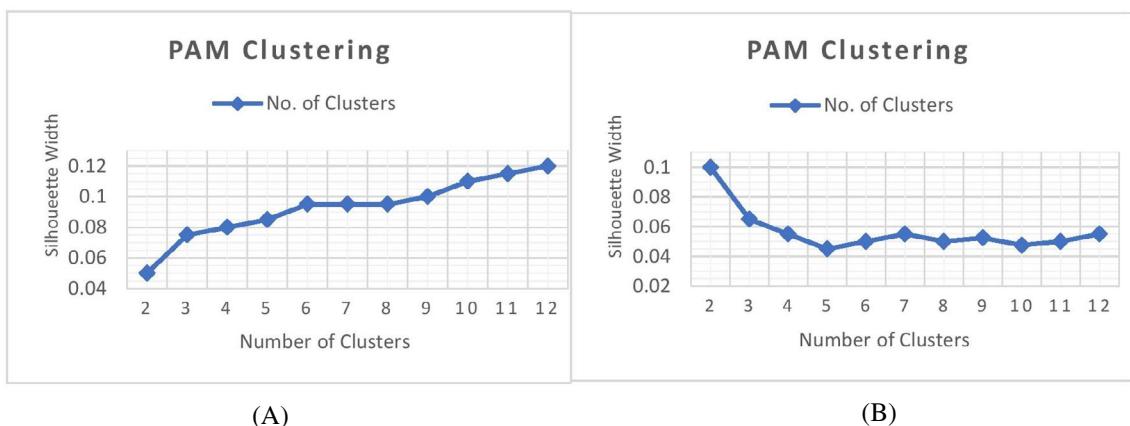


FIGURE 3 The dendograms for grievous injury and no injury. (A) Grievous injury subset. (B) No injury subset.

clusters are improved in the swap phase by exchanging selected medoids with better replacements from the non-medoids, if any. It is a more robust version of K-means. PAM clustering is more potent because it accepts a dissimilarity matrix and minimizes the sum of dissimilarities instead of the sum of squares of Euclidean distances. Figure 3 describes dendograms for the grievous injury (Figure 3A) and the no injury (Figure 3B) cases.

The main advantages of the PAM clustering algorithm over the other clustering algorithms are (i) PAM can effectively deal with noisy and outliers information present in the given dataset, (ii) PAM uses medoid to partition attributes into clusters rather than centroids, and (iii) PAM achieves clustering on overall data rather than on selected samples from the given dataset.

3.3.4 | Hierarchical (divisive) clustering

The clustering obtained by using hierarchical clustering consists of two approaches, namely, agglomerative and divisive clustering algorithms. Agglomerative clustering follows a bottom-up approach, where the individual data points are considered as “n” clusters, like a cluster on their own. Then, it finds similarities between them and groups them.³² All the data points aggregate and form one final cluster in the end. The divisive clustering algorithm follows the top-down approach. The real data is one cluster, divided into sub-clusters until the end of the splits are the data points. Dendograms are an essential tool that helps decide which of the two approaches in hierarchical clustering can be chosen by gauging the amount of balance/imbalance in the graph. A balanced dendrogram would indicate that that particular algorithm can

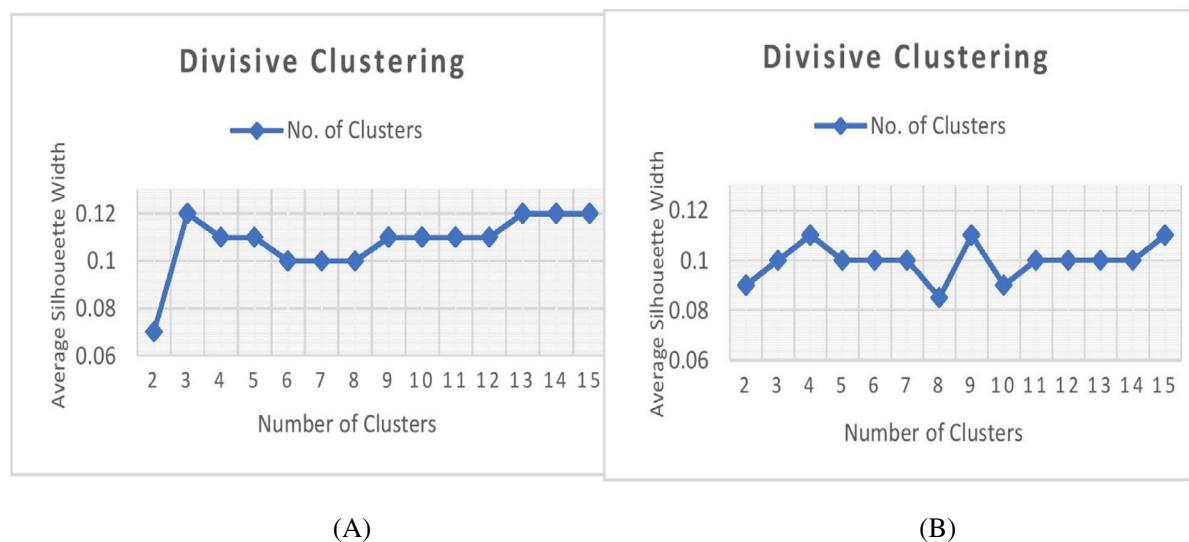


FIGURE 4 The hierarchical clustering for grievous injury and no injury. (A) Grievous injury subset. (B) No injury subset.

cluster the data better. Figure 4 explains the number of hierarchical clustering obtained by using the silhouette dataset for the grievous injury (Figure 4A) and the no injury (Figure 4B) cases.

4 | PERFORMANCE ANALYSIS OF THE PROPOSED PAM AND HIERARCHICAL CLUSTERING

The results can be split upon analyzing the data into six unique scenarios, four for grievous injuries and two for no injuries subsets. Each scenario consists of PAM clusters and the relevant cluster from Hierarchical clustering, which validates those results. Some scenarios are described in some clusters of PAM, which are unique and not shown by the hierarchical clustering method. All the factors in hierarchical clustering are common to the clusters of both algorithms, but PAM clusters give more details that are not described by the clusters of hierarchical clustering. This makes PAM a more robust algorithm. The total number of accidents with grievous injuries is 1643, and no injuries are 1178. Figure 5 represents the number of PAM clustering obtained by using the silhouette dataset for the grievous injury (Figure 5A) and the no injury (Figure 5B) cases.

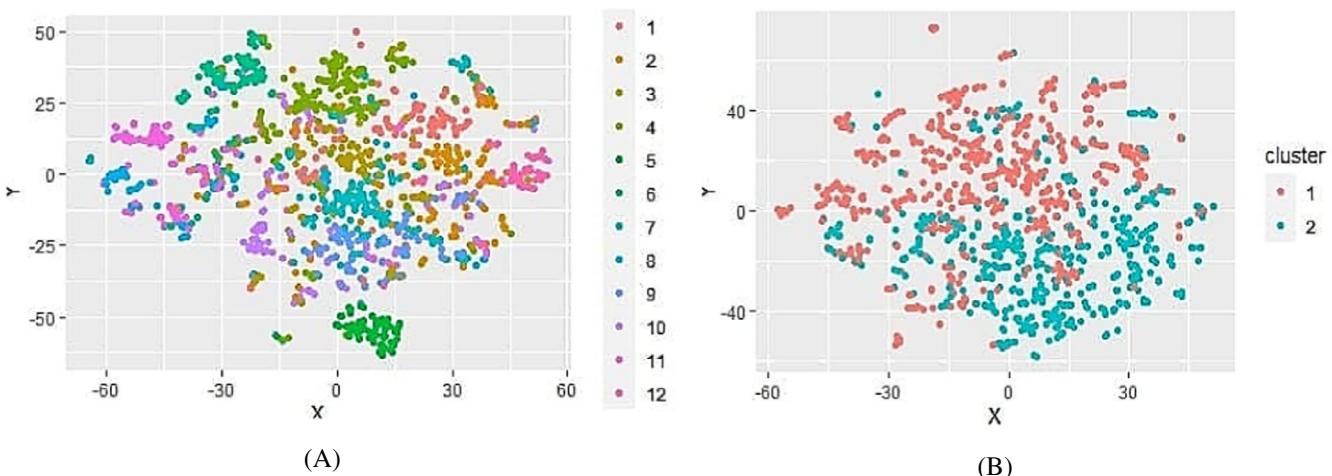


FIGURE 5 The PAM clusters for grievous injury and no injury. (A) Grievous injury subset. (B) No injury subset.

4.1 | Grievous injuries

In this section, we have discussed the results of the unique and utilizing factors in five different scenarios, which are given below:

4.1.1 | Scenario 1

“Give way sign present, paved shoulder, flat roads, taking inattentive turn.”

PAM clusters in this scenario: Cluster 1 (size = 165 accidents), Cluster 3 (size = 115 accidents), Cluster 10 (size = 101 accidents).

Hierarchical clusters validating this scenario: Cluster 1 (size = 713 accidents) list of uniting factors: Junction control, shoulder type, and road vertical characteristics.

List of unique factors: collision type, road category, traffic restriction, road narrow row, location type, landmark, collision type code, collision description code.

In PAM clustering, two collision types occurred: hit pedestrian (Cluster 1 = 30.9%) and hit from rear (Cluster 3 = 66.08%, Cluster 10 = 48.51%). Accidents involving hitting a pedestrian mostly happen on state highways (75.15%), where the roads are narrow (87.27%), with two-way traffic (81.21%) in the absence of police (95.15%), and heavy vehicles prohibited from entering (67.88%). Specifically, these accidents happened near bus stops (35.15%) in municipality areas (80.61%), and drivers collided with pedestrians who were walking along the road (20.61%). We infer that narrow roads and pedestrians walking along the roads are the misleading use of the accidents here. The presence of police creating awareness among the public to use footpaths, making traffic movement one-way on narrow roads, and initiating road widening activities wherever necessary can be suitable countermeasures to bring down accidents of this type.

Accidents involving collisions from the rear occur on national (Cluster 3 = 80%) and state (Cluster 10 = 78.3%) highways. There was no traffic restriction (58.26%). The national highways were near a panchayat (74.78%) area, and accidents occurred near a bridge (22.61%). Police were not present (82.61%), which leads us to suggest installing some police force, traffic rules, and signages so that entering or leaving the national highway can be smoother and without the risk of any accidents. The state highways were near a municipality (76.24%), and the accidents occurred near a school/college (24.75%). Careless driving (95.05%) was reported to describe the collision. Installing a police force to control and curb careless driving can help reduce these accidents.

In hierarchical clustering, the location was not a junction (81.48%), and if it was, there was not any control present (14.30%), or there was a give way sign (1.40%). The roads had paved shoulders (89.60%) and were flat (97.89%). All these factors are shared between PAM and hierarchical clusters, while PAM clusters further give more details as described above. Table 2 provides an in-depth analysis of Scenario 1: “Give way sign present, paved shoulder, Flat roads, taking inattentive turn” for grievous injury.

4.1.2 | Scenario 2

“Traffic signals, darkness with street lights, paved and unpaved shoulders, roads are flat or have a gentle incline, dangerous overtaking, driving against the flow of traffic, and happening in urban areas.”

PAM clusters in this scenario: Cluster 6 (size = 125 accidents), Cluster 8 (size = 94 accidents), and Cluster 11 (size = 131 accidents).

Hierarchical clusters validating this scenario: Cluster 2 (size = 463 accidents) list of uniting factors: Junction control, road vertical characteristics, accident cause, rural/urban.

List of unique factors: collision type, light condition, traffic restriction, landmark, collision type code, collision description code.

In PAM clustering, three collision types took place—hit from the side (34.4%), head on (74.5%), and hit from the rear (51.15%). The accidents involving hitting from the side happened in daylight (70.4%), with speed restrictions (88.8%) present, near a traffic signal (17.6%), and the cause reported was careless driving (62.4%). It can be inferred that a sweep from the side could have taken place near the traffic signal despite the restrictions present. A suitable remedy that can be suggested would be to install rumble strips at regular intervals before the signal, as this can help slow vehicles and increase caution.

The accidents involving head-on collisions happened in darkness with street lights on (59.6%), with the entry of heavy vehicles prohibited (78.7%), and in a bazaar area (31.9%). Countermeasures for this situation include widening the

TABLE 2 In-depth analysis of Scenario 1 (give way sign present, paved shoulder, flat roads, taking in-attentive turn) for grievous injury.

	HC-1	PAM-1	PAM-3	PAM-10
Uniting factors				
Junction control	No control (22.03%)	Not a junction (86.1%)	Not a junction (69.56%)	No control (59.4%)
Shoulder type	Paved (89.60%)	Paved (90.3%)	Paved (90.43%)	Unpaved (64.35%)
Road vertical characteristics	Flat (97.89%)	Flat (99.39%)	Flat (98.26%)	Flat (97.03%)
Unique factors				
Collision type	–	Hit pedestrian (30.9%)	Hit from the rear (66.08%)	Hit from rear (48.51%)
Road category	–	State highways (75.15%)	National highways (80%)	State highways (78.3%)
Traffic restriction	–	Entry of heavy vehicles prohibited (67.88%)	None (58.26%)	None (80.2%)
Road narrow	–	Yes (87.27%)	No (86.14%)	No (82.61%)
Location type	–	Municipality (80.61%)	Panchayat (74.78%)	Municipality (76.24%)
Landmark	–	Near bus stop (35.15%)	Near a bridge (22.61%)	Near a school/college (24.75%)
Collision type code	–	Category of pedestrian walking, crossing or standing on/along the road, shoulder or at a junction (42.42%)	Type of vehicle overtaking to the right/left, rear-end collision, when changing the lane to left/right, when making U-turn to the right/left, sight swipe to right/left, sight swipe from opposite direction—right side/left side (53.04%)	Category of rash/careless/drunken driving or disobeying traffic rule (61.4%)
Collision description code	–	Pedestrians walking along the road (20.6%)	Rear-end collision (45.22%)	Careless driving (52.48%)

roads and placing barricades so that speed will automatically be slowed down. The accidents involving hits from the rear happened in daylight (83.2%), with the entry of heavy vehicles prohibited (76.3%) and near bus stops (22.9%). In such a situation, a suitable countermeasure is having designated parking spaces and imposing fines for parking in a no parking area.

In hierarchical clustering, it was found that the road's vertical characteristics were flat (97.40%) or had a gentle incline (1.94%). The accident causes reported were injuries due to human error (67.38%), dangerous overtaking (15.98%), inattentive turn (9.07%), and driving against the flow of traffic (3.45%). Accidents majorly occurred in urban (88.76%) areas where either junction was not involved (71.49%), no control (22.03%) was present at the junction, or there was a traffic signal (3.45%). All these factors are shared between PAM and hierarchical clusters, whereas PAM clusters further give more details as described above. This makes PAM a more robust algorithm. Table 3 provides an in-depth analysis of Scenario 2: "Traffic signals, darkness with street lights, paved and unpaved shoulders, roads are flat or have a gentle incline, dangerous overtaking, driving against the flow of traffic, and happening in urban areas" for grievous injury.

4.1.3 | Scenario 3

"Central divider absent, no junction control, paved shoulder, non-respect of rights of way, pedestrians involved, fault of the driver or driver of another vehicle."

PAM clusters in this scenario: Cluster 2 (size = 176 accidents), Cluster 5 (size = 91 accidents), Cluster 9 (size = 125 accidents), Cluster 12 (size = 81 accidents).

TABLE 3 In-depth analysis of Scenario 2 (traffic signals, darkness with street lights, paved and unpaved shoulders, roads are flat or have a gentle incline, dangerous overtaking, driving against the flow of traffic, and happening in urban areas) for grievous injury.

Rural/urban	Urban (88.76%)	Urban (99.2%)	Urban (95.74%)	Urban (92.37%)
Unique factors				
Collision type	–	Hit from side (34.4%)	Head on (74.5%)	Hit from rear (51.15%)
Light condition	–	Daylight (70.4%)	Darkness with street lights on (59.6%)	Daylight (83.2%)
Traffic restriction	–	Speed restrictions (88.8%)	Entry of heavy vehicles prohibited (78.7%)	Entry of heavy vehicles prohibited (76.3%)
Landmark	–	Near a traffic signal (17.6%)	In a bazaar area (31.9%)	Near bus stop (22.9%)
Collision type code	–	Category of rash/careless/drunken driving or disobeying traffic rule (74.4%)	Type of collision during overtaking or while making a U-turn/head-collision (59.6%)	Category of vehicle overtaking to the right/left, rear-end collision, when changing the lane to left/right, when making U-turn to the right/left, sight swipe to right/left, sight swipe from opposite direction—right side/left side (48.09%)
Collision description code	–	Careless driving (62.4%)	Head on (54.26%)	Rear-end collision (42.75%)

Hierarchical clusters validating this scenario: Cluster 3 (size = 467 accidents) list of uniting factors: Central divider, junction control, shoulder type, accident cause, contributory factor.

List of unique factors: collision type, road category, location type, traffic movement, traffic restriction, police present, footpath, landmark, collision type code, and collision description code.

Clusters resulting from PAM clustering can be divided into two cases based on the collision type: hit pedestrian (60.23%, 66.67%) in clusters 2 and 12, and head-on collision (96.7%, 72%) in clusters 5 and 9. Accidents involving hitting a pedestrian happened on state highways (67.05%, 60.5%) in panchayat areas (73.3%, 95.1%), with two-way traffic (89.2%, 98.8%) and footpaths present (76.7%, 76.54%). When these accidents took place near bus stops (39.2%), we observed that there was no restriction on traffic (59.66%), and pedestrians were walking along the road (30.68%). Simultaneously, when accidents occurred near a bridge (46.91%), pedestrians were crossing the road from left to right (29.63%). There was a restriction on the entry of heavy vehicles (87.65%). We infer from our findings that there is some inconvenience for pedestrians. Hence, a crossing signal, a traffic signal at the end of the bridge, or a skywalk (before or after the bridge) for the pedestrians to cross can be some countermeasures to mitigate these accidents.

Head-on collisions occurred on national (89%) and state (76%) highways. On a national highway, they came under a municipality area (98.9%). The roads had one-way traffic (98.9%) and did not have footpaths (71.43%). Careless driving (85.71%) was reported as a description of the collision. These accidents happened near a bus stop (34.1%). We infer from this situation that drivers/riders could have been more careful. Considering the state highway accidents, the factors were more alarming. Happening mainly in panchayat areas (76.8%), the roads had two-way traffic (89.6%) with no footpath (98.4%) present and head-on collisions (56%) reported as the collision description. A commonly occurring landmark was near a bus stop (35.2%). Imposing speed limits, fines for violations, widening roads, and building a bus bay wherever necessary can help reduce these accidents. Two-way traffic can be converted into one-way traffic if the roads are very narrow. Installing street lights on narrow main roads of villages can also contribute to reducing these accidents.

Hierarchical clustering found that the roads had a paved shoulder (62.31%) and the central divider was absent (91.01%). Accident sites were not junctions (69.16%); in cases where they were junctions, there was no control (27.19%) at the junction. The accident cause was reported as injured in accidents due to human error (95.29%), and the contributory factor was the fault of the driver/rider (95.93%). All these factors are shared between PAM and hierarchical clusters, whereas PAM clusters further give more details as described above. Table 4 provides an in-depth analysis of Scenario 3: “Central

TABLE 4 In-depth analysis of Scenario-3 (central divider absent, no junction control, paved shoulder, non-respect of rights of way, pedestrians involved, fault of the driver, or driver of another vehicle) for grievous injury.

	HC-3	PAM-2	PAM-5	PAM-9	PAM-12	PAM-14
Uniting factors						
Central divider	No (91.01%)	Yes (68.18%)	No (89.01%)	No (96%)	No (87.64%)	
Junction control	Not a junction (69.16%)	Not a junction (62.5%)	Not a junction (98.9%)	Not a junction (74.4%)	Not a junction (86.42%)	
Shoulder type	Paved (62.31%)	Paved (78.41%)	Paved (98.9%)	Unpaved (56.8%)	Paved (77.78%)	
Accident cause	Injured in accidents due to human error (95.29%)	High speed (95.45%)	High speed (86.81%)	High speed (96.8%)	High speed (96.3%)	
Contributory factor	The fault of the driver/rider (95.93%)	Fault of driver/rider (96.02%)	Aggressive driving (78.02%)	The fault of the driver/rider (96.8%)	The fault of the driver/rider (97.53%)	Fault of driver/rider (97.53%)
Unique factors						
Collision type	–	Hit pedestrian (60.23%)	Head on (96.7%)	Head on (72%)	Hit pedestrian (66.67%)	
Road category	–	State high ways (67.05%)	National high ways (89%)	State highways (76%)	State highways (60.5%)	
Location type	–	Panchayat (73.3%)	Municipality (98.9%)	Panchayat (76.8%)	Panchayat (95.1%)	
Traffic movement	–	Two-way traffic (89.2%)	One-way traffic (88.9%)	Two-way traffic (89.6%)	Two-way traffic (98.8%)	
Traffic restriction	–	None (59.66%)	None (93.4%)	Entry of heavy vehicles prohibited (62.4%)	Entry of heavy vehicles prohibited (87.65%)	
Police present	–	Yes (59.1%)	No (95.6%)	No (65.6%)	Yes (80.25%)	
Footpath	–	Yes (76.7%)	No (71.43%)	No (98.4%)	Yes (76.54%)	
Landmark	–	Near bus stop (39.2%)	Near bus stop (34.1%)	Near bus stop (35.2%)	Near a bridge (46.91%)	
Collision type code	–	Category of pedestrian walking, crossing, or standing on/along the road, shoulder, or at a junction (71.02%)	Category of rash/careless/drunken driving or disobeying traffic rule (86.8%)	Category of collision during overtaking or while making a U-turn/head on collision (60.8%)	Category of pedestrian walking, crossing, or standing on/along the road, shoulder, or at a junction (70.37%)	
Collision description code	–	Pedestrians walking along the road (30.7%)	Careless driving (85.71%)	Head on (56%)	Pedestrians crossing from left to right (29.63%)	

divider absent, no junction control, paved shoulder, non-respect of rights of way, pedestrians involved, fault of the driver or driver of another vehicle" for grievous injury.

4.1.4 | Scenario 4

"Central divider present, head-on collision, near bus stops" PAM clusters in this scenario:

Cluster 4 (size = 223 accidents), Cluster 7 (size = 216 accidents).

List of uniting factors: collision type, central divider, junction control, footpath, landmark.

List of unique factors: traffic restriction, location type, collision description code. This unique scenario is evident only in PAM clustering results and includes 2 clusters with accidents involving head-on collisions (59.64%, 82.87%). These accidents happened when central dividers (95.1%, 78.7%) and footpaths were present (91.03%, 80.56%), police were absent (91.48%, 74.54%), and also mostly near bus stops (30.04%, 38.42%). In municipality areas (61.43%), there was a restriction on entry of heavy vehicles (68.61%), but the collision took place due to rash driving (74.44%). Whereas in panchayat areas (72.68%), there was no traffic restriction (68.05%), and the description of the collision was head-on (68.05%). Based on the whole scenario, the countermeasures can be the presence of police in municipality areas and the imposition of some traffic restrictions in panchayat areas. Table 5 provides an in-depth analysis of Scenario 4: "Central divider present, head-on collision, near bus stops" for grievous injury.

4.2 | No injuries

In this section, we have discussed the results with two scenarios under the no injuries category, which are given below:

4.2.1 | Scenario 1

"Central divider present, footpath present, careless driving" PAM clusters in this scenario: Cluster 1 (size = 680 accidents).

Hierarchical clusters validating this scenario: Cluster 1 (size = 671 accidents) list of uniting factors: central divider, traffic movement, footpath, and collision description code.

List of unique factors: collision type, traffic restriction.

The PAM cluster has accidents involving hitting from the rear (30%) and with no traffic restrictions present (47.8%). The hierarchical cluster has accidents involving head-on collisions (30.99%) and hitting from the rear (22.21%), while the traffic restriction prohibited the entry of heavy vehicles (48.28%). The remaining factors gave the same results in both PAM and hierarchical clustering methods, as described here—central divider was present (PAM = 88.23%, HC = 96.42%), the footpath was present (PAM = 84.55%, HC = 94.48%), careless driving reported as collision description code (PAM = 28.1%, HC = 22.35%), two-way traffic (PAM = 81.03%, HC = 82.41%).

TABLE 5 In-depth analysis of Scenario-4 (central divider present, head-on collision, near bus stops) for grievous injury.

PAM-4		PAM-7
Uniting factors		
Collision type	Head on (59.64%)	Head on (82.87%)
Central divider	Yes (95.1%)	Yes (78.7%)
Junction control	Not a junction po (86.99%)	Not a junction (71.3%)
Footpath	Yes (91.03%)	Yes (80.56%)
Landmark	Near bus stop (30.04%)	Near bus stop (38.42%)
Unique factors		
Traffic restriction	Entry of heavy vehicles prohibited (68.61%)	None (68.05%)
Location type	Municipality (61.43%)	Panchayat (72.68%)
Collision description code	Rash driving (74.44%)	Head on (68.05%)

We infer that most of the factors are not leading us toward any causative severe factors, which could imply careless driving. Measures such as driver education during license issues, renewal, or vehicle registration at RTA offices and on hoardings and advertisements are a few countermeasures that could be brought into effect immediately to curb this category of accidents. Table 6 provides an in-depth analysis of Scenario 1: “Central divider present, footpath present, careless driving” for no injury data.

4.2.2 | Scenario 2

“Central divider absent, footpath present, head-on collision” PAM clusters in this scenario: Cluster 2 (size = 498 accidents).

Hierarchical clusters validating this scenario: Cluster 2 (size = 507 accidents) list of uniting factors: central divider, traffic restriction, footpath, and collision description code.

List of unique factors: collision type.

The PAM cluster has accidents involving head-on collisions (52%) and with an entry of heavy vehicles prohibited (52.41%).

The hierarchical cluster has accidents involving head-on collisions (42.60%) and hitting from the rear (22.23%), with no traffic restriction (44.97%). The remaining factors give the same results in both PAM and hierarchical clustering methods, as described here—central divider was absent (PAM = 71.5%, HC = 81.26%), footpath was absent (PAM = 72.9%, HC = 85.01%), head-on collision reported as collision description code (PAM = 28.11%, HC = 21.7%), two-way traffic (PAM = 86.75%, HC = 84.81%). We infer that footpaths and dividers are absent, which could be an essential factor responsible for such accident papers. Suitable countermeasures can be to make traffic one-way on roads that are seeing many such accidents and reduce some traffic. Table 7 provides an in-depth analysis of Scenario 2: “Central divider absent, footpath present, head-on collision” for no injury data.

TABLE 6 In-depth analysis of Scenario-1 (central divider present, footpath present, careless driving) for no injury.

	HC-1	PAM-1
Uniting factors		
Central divider	Yes (96.42%)	Yes (88.23%)
Traffic movement	Two-way traffic (82.41%)	Two-way traffic (81.03%)
Footpath	Yes (94.48%)	Yes (84.55%)
Collision description code	Careless driving (22.35%)	Careless driving (28.1%)
Unique factors		
Collision type	Head on (30.99%), hit from the rear (22.21%)	Hit from the rear (30%)
Traffic restriction	Entry of heavy vehicles prohibited (48.28%)	None (47.8%)

TABLE 7 In-depth analysis of Scenario-2 (central divider absent, footpath present, head-on collision) for no injury.

	HC-2	PAM-2
Uniting factors		
Central divider	No (81.26%)	No (71.5%)
Traffic movement	Two-way traffic (84.81%)	Two-way traffic (86.75%)
Footpath	No (85.01%)	No (71.5%)
Collision description code	Head on (21.7%)	Head on (28.11%)
Unique factors		
Collision type	Head on (42.60%) hit from rear (22.23%)	Head on (52%)
Traffic restriction	None (52.41%)	Entry of heavy vehicles prohibited (52.41%)

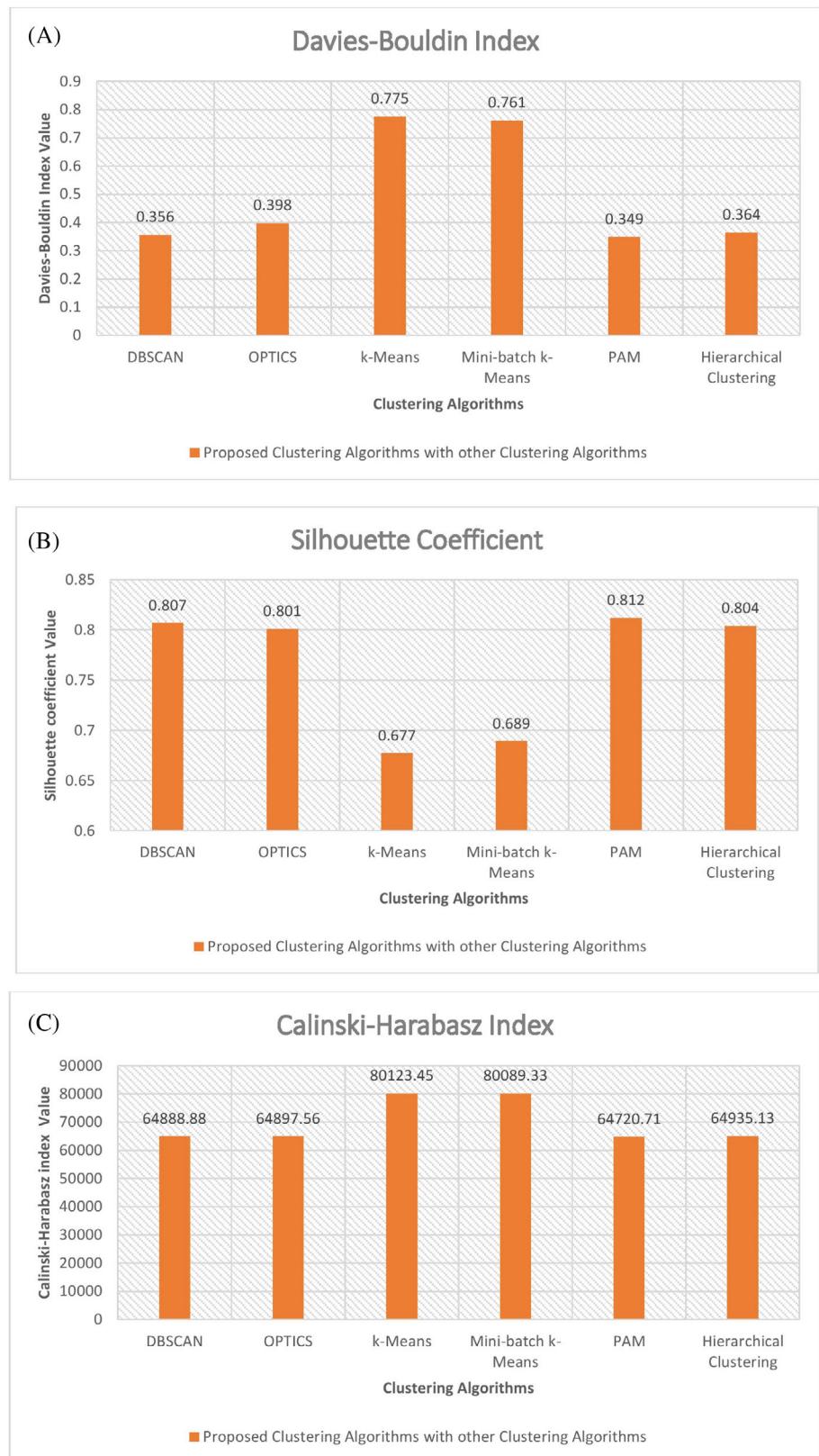


FIGURE 6 Performance analysis of the proposed method with other methods (A–C). (A) Davies–Bouldin index-based performance analysis of the proposed algorithms with other clustering algorithms. (B) Silhouette coefficient-based performance analysis of the proposed clustering algorithms with other clustering algorithms. (C) Calinski–Harabasz index-based performance analysis of the proposed algorithms with other clustering algorithms.

5 | PERFORMANCE ANALYSIS OF THE PROPOSED METHOD WITH OTHER STATE-OF-ART METHODS

The efficiency of the clustering algorithms can be measured by the internal cluster validation metric (ICVM) and the time complexity. In most of the clustering algorithms, the researchers measured only ICVM because it is sufficient to test the performance of the clustering algorithm. There are three performance metrics for evaluating the significance of the clustering algorithms available in the literature: the silhouette coefficient, the Davies–Bouldin index, and the Calinski–Harabasz index. Silhouette coefficient measures usually lie between -1 and $+1$. It measures how similar an attribute is to attributes in its own cluster compared to attributes in other clusters. Higher, the silhouette value is well matched to its own cluster and poorly matched to other clusters. The Calinski–Harabasz index or variance ratio criterion is the ratio of the sum of inter-cluster and intra-cluster dispersion for all clusters. If the Calinski–Harabasz index is higher, then the performance of the clustering is higher. Davies–Bouldin index is the internal evaluation scheme, where the validation of how well the clustering has been done is made using quantities and features inherent to the dataset. In contrast to Calinski–Harabasz, the lower the Davies–Bouldin index, the higher the clustering algorithm's performance.

The performance analysis of the proposed method with other methods is given in Figure 6 concerning all three metrics 6A–C.

For the purpose of the performance analysis, PAM and hierarchical clustering (HC) are estimated using the entire dataset. From Figure 6A–C, it is clearly found that the proposed PAM algorithm performs better than the other clustering algorithms.

6 | CONCLUSIONS

Tamil Nadu, a state of India, records the highest number of accidents. Compared to other states, Tamil Nadu ranks among the top three in all types of accidents, including those involving fatal, grievous, and mild injuries. Therefore, analyzing Tamil Nadu's accident data and finding countermeasures for every scenario can help Tamil Nadu and other states understand and prevent the current problems that cause accidents beforehand. PAM clustering is a relatively new but robust, hard clustering unsupervised algorithm. It randomly selects medoids from the dataset, calculates distances from data points around them (using a distance measure of our choice), finds a cost, and recalculates these distances as necessary. The algorithm works well with categorical variables, so we choose these from our dataset. Hierarchical clustering is also applied to the same dataset.

Our results show 14 different clusters that fall into six scenarios for our subset of data (accidents with the severity of grievous injuries and vehicle damage only (non-injury) on national and state highways), and we have suggested suitable countermeasures for each scenario. We used the Hierarchical clustering method (divisive approach) to validate the six scenarios' results. Again, the entire dataset has been used to obtain the clustering using PAM and hierarchical clustering, and then these values are compared with other state-of-the-art methods. From the performance analysis, the proposed methodology PAM performs better than the other clustering models. This article uses a novel and robust technique to contribute to solving a national issue of public interest. Our results and countermeasure suggestions will prove beneficial in mitigating rising accidents and saving more lives and property.

One limitation of the proposed PAM clustering algorithm is that it is unsuitable for large datasets due to its high computation requirements. Therefore, our study had to be restricted to a smaller subset of the data. Another limitation is that the algorithm produces new clusters each time it runs. We finalized our clusters after running the algorithm many times and observing a trend in the clusters and silhouette width. We then saved them to a file for further study. This study and algorithm can also be extended and used for any similar purpose involving unsupervised clustering.

AUTHOR CONTRIBUTIONS

Pendyala Manasa: Conceptualization (lead); data curation (equal); methodology (equal). **Pragya Ananth:** Conceptualization (equal); data curation (lead); formal analysis (supporting); writing – original draft (equal). **Priyadarshini Natarajan:** Conceptualization (supporting); formal analysis (supporting); supervision (equal); writing – review and editing (equal). **K. Somasundaram:** Formal analysis (supporting); investigation (lead); methodology (equal); supervision (equal); writing – review and editing (equal). **E. R. Rajkumar:** Methodology (supporting); software (supporting); supervision (equal); validation (equal). **Kattur Soundarapandian Ravichandran:** Formal analysis (supporting); investigation

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ACKNOWLEDGMENT

The authors wish to thank Tamil Nadu Police for providing permission and access to use the Road Accident Data Management System (RADMS) in this study. The authors gratefully acknowledge the Amrita ICTS Department, Amrita Vishwa Vidyapeetham, Coimbatore, for providing a high-performance computing facility for testing our algorithms. Open access publishing facilitated by University of Technology Sydney, as part of the Wiley - University of Technology Sydney agreement via the Council of Australian University Librarians.

CONFLICT OF INTEREST STATEMENT

No conflict of interest exists in our article.

PEER REVIEW

The peer review history for this article is available at <https://www.webofscience.com/api/gateway/wos/peer-review/10.1002/eng2.12793>.

DATA AVAILABILITY STATEMENT

<https://morth.nic.in/road-accident-in-india>

ETHICS STATEMENT

No ethical issues related to our work because our research involves anonymized records.

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How to cite this article: Manasa P, Ananth P, Natarajan P, et al. An analysis of causative factors for road accidents using partition around medoids and hierarchical clustering techniques. *Engineering Reports.* 2024;6(6):e12793. doi: [10.1002/eng2.12793](https://doi.org/10.1002/eng2.12793)