

Numerical Modelling of the Gas Dynamics of a Prototype Free-Piston Engine

Gregory Paul Gibbes

Submitted in fulfilment of the degree of

Doctor of Philosophy

University of Technology, Sydney

Australia

2011

keywords: free-piston, 1D gas dynamics, two-stroke, specific heat, chemical equilibrium, charging, scavenging, tuning

CERTIFICATE OF AUTHORSHIP/ORIGINALITY

I certify that the work in this thesis has not previously been submitted for a degree nor has it been submitted as part of requirements for a degree except as fully acknowledged within the text.

I also certify that the thesis has been written by me. Any help that I have received in my research work and the preparation of the thesis itself has been acknowledged. In addition, I certify that all information sources and literature used are indicated in the thesis.

.....

.....

ACKNOWLEDGEMENTS

I would first like to acknowledge the men who created Pempek Engine project. Edward Wechner, who designed most of engine's hardware, and Bert Van Der Broek for his company's provision of the Pempek scholarship and for his leadership. Thanks also goes to Douglas Carter who designed the electrical systems, and who was a constant, friendly, professional source of ideas and fruitful discussion. Thanks to Slobadan Ilic, who was likewise a friendly and helpful member of the small Pempek engine team, and who worked tirelessly to manufacture and assemble much of the engine. I was glad for his encouragement, advice, and readiness to share information.

My supervisor Guang Hong has been supportive over this long road, and has provided much guidance, insight and advice which, I hope, has borne fruit in making this thesis more useful to others. Thank you for your hard work to support me, even when we didn't always agree. I am in your debt.

Thanks also to Phyllis Agius for her ready helpfulness in all postgraduate student matters, both to me and numerous other students.

Thanks to Matt Gaston, Peter Brady and John Reizes who were always generous with their time, as I learned the art of CFD modelling early in this project.

Thanks go to the many people who I have learned from but never met except through the pages of technical papers and text books. In particular, I would like to acknowledge the late Gordon P. Blair, whose method of modelling 1D gas dynamics I have adapted for this work. Thanks to Samuel J. Kirkpatrick who's carefully published experimental work was invaluable to me in validating my code. Thanks also to John D. Anderson Jr. from whom I learned much about compressible flow; and Markus Klein and Gary L. Borman in the field combustion modelling.

Thanks to Randy Lewis, a kindred spirit in the joys 1D gas dynamic modelling, who provided valuable feedback for the material which appears in Chapter 4.

Thanks to my research friends here at UTS from all corners of the globe: Janitha Wijesinghe, Reza Fathollahzadeh, Fabio Cumbe, Wade Smith, Ulrike Dackermann, Debbie Marsh, Fook Choi, Minh Nguyen, Kifayah Amar, Dang Ho, Thanh Nguyen, Jiping Niu, Wen Xing, Zhinous Zabihi, Xiaohang Pang, Ibrahim El-Saliby and Sherub Phuntsho.

ABSTRACT

Free-piston internal combustion engines found commercial success as air compressors in the 1920's and 1930's, and afterward as gas turbine gasifiers for stationary applications. Since that time they have failed to see commercial application, however in the last decade or so there has been a resurgence of interest in free-piston engines because of their ostensible simplicity and in the flexibility afforded by an unconstrained piston.

This thesis reports the testing and modelling on a free-piston engine by *Pempek Systems Pty. Ltd.* It is an opposed cylinder, electric machine, operating on a two stroke cycle with direct fuel injection. Analysis of experimental cylinder pressure shows that while compression ignition is suitably fast and reliable, the Pempek engine suffers from (among other things) low charging efficiency. The aim of the modelling work is to understand the reasons for this, and to investigate design options for improvement.

A comprehensive, generally applicable 1D gas dynamics engine model has been developed. The important features of this model are described in some detail. While the model builds on existing methods, a number of unique contributions have been made. A chemical equilibrium code was developed which is computationally efficient and flexible. The 1D gas dynamics method is based on a method developed at *Queens University, Belfast (QUB)* in the early 1990's but has been thoroughly re-worked in the way it handles friction, gas property changes and heat transfer. The originally first order accurate method has been changed to second order, and a way of preserving full mass conservation has been developed. An unsteady heat transfer model is proposed. A comprehensive boundary solution is presented, which has relevance to all 1D gas dynamics models. The gas dynamics model is validated against extensive single shot data from QUB, and also against some experimental engine-run data.

The 1D gas dynamics engine model is used to assess the viability of utilising exhaust pipe tuning to drive the charging process of the Pempek engine. Simulation results show that it is possible to charge the engine using exhaust gas dynamics alone.

.....

PREFACE

At a stand at the World Energy Congress 2004 in Sydney I met Bert Van Der Broek and Edward Wechner and was introduced to the Pempek free-piston engine. Ed explained to me the fascinating features of his new engine design and invited me to visit the workshop to see some prototype testing. This was the start of my association with Pempek Systems, which led to a final year project exploring the scavenging of the engine, then on to this PhD in a similar vein.

Pempek Systems had done what few research groups had yet achieved – they had built and run a full scale electric free-piston engine, demonstrating unequivocally that generator based piston motion control was accurate and robust. Their working prototype was an excellent platform from which to launch a theoretical investigation - which was aimed at providing tools to interpret results, and doing predictive modelling to guide future directions of the project.

A little should be said about the contents of this thesis which follow from the requirements of the project. There are two main topics addressed. The first is the developing technology of free-piston engines. This is the subject of the first two chapters. The second topic is that of engine modelling and makes up the middle part of the thesis. Even though the modelling was developed for the Pempek project, it is nonetheless broadly applicable to all IC engines and even to other fields. Thus, the sections on modelling can be read profitably without concern for the preceding chapters on free-piston engine technology. Likewise, readers with little interest in physics and methods of modelling will be able to read the sections reporting free-piston engine technology. The final section of the thesis takes the engine model and looks at two possible design variations for the Pempek engine.

- Synopsis -

Chapter 1 - Free-piston Engines – overview of developments

Surveys the current state of the art in free-piston engine technology. The survey shows that despite the relative immaturity of the field, promising solutions have been found for the main difficulties, such as piston motion control.

Chapter 2 - Pempek free-piston engine – details and experimental results

Describes the Pempek free-piston engine project in some detail, highlighting the successful piston motion control, and describing some of the difficulties that were faced, in particular low combustion energy and high compressor power

consumption. In order to explore the potential for lower compressor pressure, it was deemed necessary to analyse the gas dynamics of inlet and exhaust systems. This is the motivation for the modelling work which follows.

Chapter 3 - Thermodynamic and gas property models

Describes three key components of the engine model – namely the single zone thermodynamic cylinder model, the gas property model and the chemical equilibrium model.

Chapter 4 - Unsteady 1D gas dynamics model

Describes the unsteady gas dynamics model, which was based on an existing method, but with several modifications. Concludes with some simple validation cases.

Chapter 5 - Other sub models

Describes miscellaneous other parts of the engine model which were not covered in the previous two chapters.

Chapter 6 - The engine model – integrating all sub models

Explains the integration of all the sub models into the overall engine model

Chapter 7 - Validations using experimental results

Validates the gas dynamics model against a suit of single shot experiments, and also a superficial comparison to measured data from the Pempek engine.

Chapter 8 - Predictive modelling

Applies the gas dynamics model to the original Pempek engine but with a modified low pressure compressor, and a tuned exhaust pipe. Simulation results show that low compressor pressure operation is possible. Next, a radical design modification is proposed, and the gas dynamics model is used to test the viability of un-boosted charging. These two applications of the gas dynamics model demonstrate the usefulness of the model, and the sort of design options that are available for free-piston engines to take advantage of gas dynamics to improve and control charging.

Chapter 9 - Summary and conclusion

Summarises the specific findings for the Pempek project, summarises the model scope and usefulness, and lists the unique contributions of the thesis. A list of suggested further work is also included.

Appendices

A wide range of material with further details of free-piston engine projects and the engine model.

Appendix I	Review of recent free-piston engine projects
Appendix II	Specific heats of a reacting mixture
Appendix III	Further applications of the energy equation
Appendix IV	Tables of Thermodynamic Properties
Appendix V	Method for Calculating Chemical Equilibrium of Combustion Products
Appendix VI	Derivation of fundamental one dimensional unsteady gas equation
Appendix VII	Derivation of Boundary Flow Equations
Appendix VIII	Model Data Structures
Appendix IX	2 nd Order Interpolation – further details
Appendix X	Re-meshing Criteria and Method
Appendix XI	Single Shot Experiments Cross Reference
Appendix XII	Derivation of normal shock equations
Appendix XIII	Rayleigh and Fanno Flow
Appendix XIV	Graphical user interface screen shots
Appendix XV	Table of contents of data CD

.....

TABLE OF CONTENTS

Abstract	vii
Preface	ix
Table of Contents	xiii
List of Figures	xvii
List of Tables	xxvii
Nomenclature	xxix
Acronyms	xxxiii
Chapter 1 Free-piston Engines – overview of developments	1
1.1 Introduction	2
1.2 Summary of free-piston projects	4
1.3 Piston Motion Control	6
1.4 Discussion on free-piston engines state of the art	9
1.5 Free-piston Engine Modelling	11
Chapter 2 Pempek free-piston engine – details and experimental results	19
2.1 Overview of the project	19
2.2 Details of the engine	21
2.3 Cylinder pressure analysis	27
2.4 Compressor analysis	31
2.5 Summary	33
Chapter 3 Thermodynamic and gas property models	37
3.1 Thermodynamic control volume model	38
3.2 Gas mixture property model	45
3.3 Reacting gas mixture model	49
Chapter 4 Unsteady 1D gas dynamics model	55
4.1 Introduction	55
4.2 Theoretical Basis	61
4.3 Wave Propagation	63
4.4 Flow Boundary solution	68

4.5	Mass and thermal energy transport	79
4.6	Validation using analytical results	83
4.7	Summary	89
Chapter 5	Other sub models	91
5.1	Duct friction and heat transfer.....	92
5.2	Combustion cylinder models.....	105
5.3	Separated flow model.....	112
5.4	Flow area coefficient maps	115
5.5	Multi body dynamics.....	117
Chapter 6	The engine model – integrating all sub models	123
6.1	Overview of model building blocks.....	124
6.2	Calculation sequence for a complete time-step evaluation	125
6.3	Programing details of the engine model.....	127
Chapter 7	Validations using experimental results	129
7.1	Description of the single shot tests.....	130
7.2	Slide valve tests.....	134
7.3	P1 driven simulation	141
7.4	Straight pipe shots	142
7.5	Converging flow	147
7.6	Diverging flow	150
7.7	Modelling the Pempek engine.....	161
Chapter 8	Predictive modelling	171
8.1	Optimising the existing layout	172
8.2	Port admission layout.....	175
8.3	Gas dynamics driven scavenging	178
8.4	Conclusion	183
Chapter 9	Summary and conclusion	185
9.1	Findings for the Pempek project	186
9.2	The model, its scope and usefulness	187
9.3	Unique contributions to modelling art	188
9.4	Contribution to free-piston engine research.....	190
9.5	Further Work.....	191

Publications	193
References	195
Appendices	207
Appendix I Review of recent free-piston engine projects.....	209
Appendix II Specific heats of a reacting mixture.....	235
Appendix III Further applications of the energy equation	237
Appendix IV Tables of Thermodynamic Properties	241
Appendix V Method for Calculating Chemical Equilibrium of Combustion Products ...	247
Appendix VI Derivation of fundamental one dimensional unsteady gas equation	255
Appendix VII Derivation of Boundary Flow Equations	259
Appendix VIII Model Data Structures	263
Appendix IX 2 nd Order Interpolation – further details	269
Appendix X Re-meshing Criteria and Method	271
Appendix XI Single Shot Experiments Cross Reference.....	273
Appendix XII Derivation of normal shock equations	275
Appendix XIII Rayleigh and Fanno Flow.....	281
Appendix XIV Graphical user interface screen shots	285
Appendix XV Table of contents of data CD	291

.....

LIST OF FIGURES

Figure 1-1 Various free-piston engine layouts	2
Figure 1-2 Two control methodologies	8
Figure 1-3 Scavenging modes analysed by Goldsborough [58].....	15
Figure 1-4 Simulated 1D model compared to experiment for pressure in exhaust pipe. Larimi et al [74].....	17
Figure 2-1 Spark ignition prototype	20
Figure 2-2 Cross section of engine module (shown vertically).....	22
Figure 2-3 Typical exhaust valve actuator trajectory	23
Figure 2-4 Real vs. target mover velocity	25
Figure 2-5 Example engine run indicated work (efficiency indicated by black markers).....	26
Figure 2-6 Sample indicator plot – fired cycle.....	27
Figure 2-7 Sample indicator plot - motored cycle.....	27
Figure 2-8 Apparent heat release.....	28
Figure 2-9 Cylinder and compressor pressure during scavenging	29
Figure 2-10 Comparison of cylinder pressure with and without exhaust pipe	30
Figure 2-11 Indicator plot of compressor	31
Figure 2-12 Proposed advanced passive inlet valve design [96].....	32
Figure 3-1 Numerical solution of the energy equation.....	40
Figure 3-2 Pressure history and error for various time steps.....	42
Figure 3-3 Prescribed fuel burn rate and cylinder volume	43
Figure 3-4 Pressure and temperature for combustion case.....	43
Figure 3-5 Error for various time steps	44
Figure 3-6 Specific heat C_p of common exhaust gas species	45
Figure 3-7 Typical pressure error incurred for setting $\gamma=1.4$	45
Figure 3-8 Variation of γ^* with temperature and equivalence ratio for unburned and burned mixture	47

Figure 3-9 Equilibrium species mass fractions of a fuel-air mixture at various temperatures and pressure	52
Figure 3-10 Equilibrium species mass fractions of a fuel air mixture with varying fuel to oxygen ratio.....	52
Figure 4-1 Evolving mass flow rate into an idealised duct	55
Figure 4-2 A right travelling pressure wave.....	61
Figure 4-3 Oppositely moving pressure waves	62
Figure 4-4 Advancing pressure waves by one time step	63
Figure 4-5 Second order interpolation of pressure waves.....	64
Figure 4-6 Modifying pressure waves to account for heat transfer and mass conservation.....	65
Figure 4-7 Re-meshing a duct	67
Figure 4-8 Detection of a travelling shock.....	67
Figure 4-9 Duct cell boundary nodes in space and time	68
Figure 4-10 Variation of gas properties around a node in space and time	68
Figure 4-11 Catalogue of all flow types considered.....	70
Figure 4-12 A typical flow boundary showing all flow properties	72
Figure 4-13 Mass and thermal transport.....	79
Figure 4-14 Calculating boundary flow properties	81
Figure 4-15 Temperature transport with different mixing coefficients.....	82
Figure 4-16 Standard shock tube results	84
Figure 4-17 Shock tube with mass conservation.....	85
Figure 4-18 Shock tube comparison between first and second order wave interpolation.....	86
Figure 4-19 Fanno flow.....	87
Figure 4-20 Rayleigh flow	87
Figure 4-21 Smearing of a triangular pulse traversing 100 mesh spaces	88
Figure 5-1 Coefficient of friction for flow over a flat plate [90].....	92

Figure 5-2 Fluid element experiencing friction.....	93
Figure 5-3 Fluid element experiencing heat transfer.....	95
Figure 5-4 Heat transfer model compared to Dittus-Boelter for steady flow.....	99
Figure 5-5 Heat transfer model turbulent kinetic energy for different turbulence length scales.....	99
Figure 5-6 Heat transfer model for a turbulence generating inlet	100
Figure 5-7 Heat transfer model compared to Dittus-Boelter for low speed flow....	100
Figure 5-8 Heat transfer model for different cell spacing	101
Figure 5-9 Heat transfer modelled for single shot using different turbulence length scales.....	102
Figure 5-10 Heat transfer modelled for single shot using different timestep size...	103
Figure 5-11 Sketch of piston-cylinder crevice	106
Figure 5-12 Blowby CFD model mesh	107
Figure 5-13 Blowby correlation	108
Figure 5-14 Finding fuel injection enthalpy.....	109
Figure 5-15 Spark ignition combustion rate model.....	110
Figure 5-16 Compression ignition combustion rate model	111
Figure 5-17 Control volume for applying the momentum equation to a diffusing flow	112
Figure 5-18 Modified area ratio for tapered ducts.....	114
Figure 5-19 Example flow area coefficient map	116
Figure 5-20 Cutaway of FP3 showing moving parts.....	117
Figure 5-21 Forces on the mover	117
Figure 5-22 Forces on the exhaust valves	118
Figure 5-23 Aero force coefficients for normal flow through exhaust and inlet valves	119
Figure 5-24 Forces on the passive inlet valves.....	120
Figure 5-25 Typical collision trajectory	122

Figure 6-1 Integration of sub models to make an engine model	123
Figure 7-1 Straight pipe.....	130
Figure 7-2 Straight pipe with density discontinuity	131
Figure 7-3 Sudden contraction.....	131
Figure 7-4 Convergent taper	131
Figure 7-5 Sudden enlargement	132
Figure 7-6 Divergent taper	132
Figure 7-7 Short megaphone.....	132
Figure 7-8 Long megaphone	132
Figure 7-9 Flow area coefficients used for slide valve	135
Figure 7-10 Slide valve $P_{rel}=1.5$ bar, $T_{rel}=293$ K.....	136
Figure 7-11 Slide valve $P_{rel}=1.5$ bar, $T_{rel}=293$ K, air in cylinder, CO ₂ in pipe.....	136
Figure 7-12 Slide valve $P_{rel}=1.5$ bar, $T_{rel}=293$ K, CO ₂ in cylinder, air in pipe.....	136
Figure 7-13 Slide valve $P_{rel}=2.4$ bar, $T_{rel}=293$ K.....	137
Figure 7-14 Slide valve $P_{rel}=2.4$ bar, $T_{rel}=293$ K, air in cylinder, CO ₂ in pipe.....	137
Figure 7-15 Slide valve $P_{rel}=2.4$ bar, $T_{rel}=293$ K, CO ₂ in cylinder, air in pipe.....	137
Figure 7-16 Slide valve $P_{rel}=2$ bar, $T_{rel}=623$ K.....	138
Figure 7-17 Slide valve $P_{rel}=5$ bar, $T_{rel}=623$ K.....	138
Figure 7-18 Slide valve $P_{rel}=0.5$ bar, $T_{rel}=293$ K.....	138
Figure 7-19 Slide valve $P_{rel}=0.8$ bar, $T_{rel}=293$ K.....	139
Figure 7-20 Slide valve $P_{rel}=0.5$ bar, $T_{rel}=293$ K short pipe shot	139
Figure 7-21 Slide valve $P_{rel}=0.8$ bar, $T_{rel}=293$ K short pipe shot	139
Figure 7-22 Slide valve $P_{rel}=2.4$ bar, $T_{rel}=293$ K short pipe shot	140
Figure 7-23 Straight pipe P2, $P_{rel}=0.5$ bar, $T_{rel}=293$ K.....	143
Figure 7-24 Straight pipe P2, $P_{rel}=0.8$ bar, $T_{rel}=293$ K.....	143
Figure 7-25 Straight pipe P2, $P_{rel}=1.5$ bar, $T_{rel}=293$ K.....	143
Figure 7-26 Straight pipe P2, $P_{rel}=2.4$ bar, $T_{rel}=293$ K.....	144

Figure 7-27 Density discontinuity P3, CCC, $P_{rel}=2.4$ bar, $T_{rel}=293$ K, closed end .	144
Figure 7-28 Density discontinuity P1, AAC, $P_{rel}=1.5$ bar, $T_{rel}=293$ K.....	144
Figure 7-29 Density discontinuity P3, AAC, $P_{rel}=1.5$ bar, $T_{rel}=293$ K.....	144
Figure 7-30 Density discontinuity P1, AAC, $P_{rel}=2.4$ bar, $T_{rel}=293$ K.....	145
Figure 7-31 Density discontinuity P3, AAC, $P_{rel}=2.4$ bar, $T_{rel}=293$ K.....	145
Figure 7-32 Density discontinuity P1, CCA, $P_{rel}=1.5$ bar, $T_{rel}=293$ K.....	145
Figure 7-33 Density discontinuity P3, CCA, $P_{rel}=1.5$ bar, $T_{rel}=293$ K.....	145
Figure 7-34 Density discontinuity P1, CCA, $P_{rel}=2.4$ bar, $T_{rel}=293$ K.....	146
Figure 7-35 Density discontinuity P3, CCA, $P_{rel}=2.4$ bar, $T_{rel}=293$ K.....	146
Figure 7-36 Flow area coefficients used for sudden area change	147
Figure 7-37 Sudden contraction 53mm P1, $P_{rel}=2.4$ bar, $T_{rel}=293$ K	148
Figure 7-38 Convergent taper 53mm P1, $P_{rel}=2.4$ bar, $T_{rel}=293$ K.....	148
Figure 7-39 Sudden contraction 53mm, P3, $P_{rel}=2.4$ bar, $T_{rel}=293$ K	148
Figure 7-40 Convergent taper 53mm, P3, $P_{rel}=2.4$ bar, $T_{rel}=293$ K.....	148
Figure 7-41 Sudden contraction 80.2mm, P1, $P_{rel}=2.4$ bar, $T_{rel}=293$ K	149
Figure 7-42 Convergent taper 80.2mm, P1, $P_{rel}=2.4$ bar, $T_{rel}=293$ K.....	149
Figure 7-43 Sudden contraction 80.2mm, P3, $P_{rel}=2.4$ bar, $T_{rel}=293$ K	149
Figure 7-44 Convergent taper 80.2mm, P3, $P_{rel}=2.4$ bar, $T_{rel}=293$ K.....	149
Figure 7-45 Sudden enlargement 53mm, P1, $P_{rel}=1.5$ bar, $T_{rel}=293$ K	152
Figure 7-46 Divergent taper 53mm, P1, $P_{rel}=1.5$ bar, $T_{rel}=293$ K	152
Figure 7-47 Sudden enlargement/ Divergent taper 53mm, P3, $P_{rel} =1.5$ bar, $T_{rel}=293$ K.....	152
Figure 7-48 Sudden enlargement 53mm, P1, $P_{rel}=2.4$ bar, $T_{rel}=293$ K	153
Figure 7-49 Divergent taper 53mm, P1, $P_{rel}=2.4$ bar, $T_{rel}=293$ K	153
Figure 7-50 Sudden enlargement/ Divergent taper 53mm, P3, $P_{rel} =2.4$ bar, $T_{rel}=293$ K.....	153
Figure 7-51 Sudden enlargement 80.2mm, P1, $P_{rel}=1.5$ bar, $T_{rel}=293$ K	154
Figure 7-52 Divergent taper 80.2mm, P1, $P_{rel}=1.5$ bar, $T_{rel}=293$ K	154

Figure 7-53 Sudden enlargement/ Divergent taper 80.2mm, P3, $P_{rel} = 1.5\text{bar}$, $T_{rel} = 293\text{K}$	154
Figure 7-54 Sudden enlargement 80.2mm, P1, $P_{rel} = 2.4\text{bar}$, $T_{rel} = 293\text{K}$	155
Figure 7-55 Divergent taper 80.2mm, P1, $P_{rel} = 2.4\text{bar}$, $T_{rel} = 293\text{K}$	155
Figure 7-56 Sudden enlargement/ Divergent taper 80.2mm, P3, $P_{rel} = 2.4\text{bar}$, $T_{rel} = 293\text{K}$	155
Figure 7-57 Divergent taper 80.2mm, P2, $P_{rel} = 2.4\text{bar}$, $T_{rel} = 293\text{K}$	156
Figure 7-58 Divergent taper 105.6mm, P1, $P_{rel} = 2.4\text{bar}$, $T_{rel} = 293\text{K}$	156
Figure 7-59 Divergent taper 105.6mm, P2, $P_{rel} = 2.4\text{bar}$, $T_{rel} = 293\text{K}$	156
Figure 7-60 Divergent taper 105.6mm, P3, $P_{rel} = 2.4\text{bar}$, $T_{rel} = 293\text{K}$	157
Figure 7-61 Short Megaphone P1, $P_{rel} = 2.0\text{bar}$, $T_{rel} = 293\text{K}$	157
Figure 7-62 Long Megaphone P1, $P_{rel} = 2.0\text{bar}$, $T_{rel} = 293\text{K}$	157
Figure 7-63 Sudden contraction 53mm, P1, $P_{rel} = 0.5\text{bar}$, $T_{rel} = 293\text{K}$	158
Figure 7-64 Convergent taper 53mm, P1, $P_{rel} = 0.5\text{bar}$, $T_{rel} = 293\text{K}$	158
Figure 7-65 Sudden contraction / Convergent taper 53mm, P3, $P_{rel} = 0.5\text{bar}$, $T_{rel} = 293\text{K}$	158
Figure 7-66 Sudden contraction 53mm, P1, $P_{rel} = 0.8\text{bar}$, $T_{rel} = 293\text{K}$	159
Figure 7-67 Convergent taper 53mm, P1, $P_{rel} = 0.8\text{bar}$, $T_{rel} = 293\text{K}$	159
Figure 7-68 Sudden contraction / Convergent taper 53mm, P3, $P_{rel} = 0.8\text{bar}$, $T_{rel} = 293\text{K}$	159
Figure 7-69 Short Megaphone P1, $P_{rel} = 2.0\text{bar}$, $T_{rel} = 293\text{K}$, various simulation timesteps.....	160
Figure 7-70 Long Megaphone P1, $P_{rel} = 2.0\text{bar}$, $T_{rel} = 293\text{K}$, various simulation timesteps.....	160
Figure 7-71 Pempek engine inlet side ducting half section 3D view	161
Figure 7-72 Pempek engine 1D model layout.....	162
Figure 7-73 Motored engine comparison with experiment.....	163
Figure 7-74 Motored engine, indicator diagram	164
Figure 7-75 Motored engine, indicator diagram	164

Figure 7-76 Fired engine comparison with experiment	165
Figure 7-77 Fired engine, indicator diagram.....	165
Figure 7-78 Fired engine, indicator diagram.....	166
Figure 7-79 Valve trajectories and mass flows	168
Figure 7-80 Cylinder mass and inlet mass	168
Figure 7-81 Cylinder species mass fractions.....	169
Figure 7-82 Cylinder temperature and specific heat ratio	169
Figure 8-1 Tuned exhaust pipe layout for existing engine	172
Figure 8-2 Results for optimised layout	173
Figure 8-3 Valve trajectories and mass flows (full power)	173
Figure 8-4 Cylinder mass and inlet mass (full power)	174
Figure 8-5 Cylinder species mass fractions (full power).....	174
Figure 8-6 Modification of Pempek engine for port admission	175
Figure 8-7 Contactless pistons with air bearings.....	177
Figure 8-8 Port admission engine model layout.....	178
Figure 8-9 General results for port admission layout.....	179
Figure 8-10 Port openings and mass flows (full power)	180
Figure 8-11 Cylinder pressure during scavenging (full power)	180
Figure 8-12 Modelled inlet and exhaust plenum pressure (full power)	180
Figure 8-13 Cylinder mass and inlet mass (full power)	181
Figure 8-14 Cycle temperatures	181
Figure 8-15 Cycle pressures.....	182
Figure 8-16 Cycle pressures during scavenging.....	182
Figure I-1 Junkers four-stage free-piston air compressor [8].....	210
Figure I-2 Partial cut-away diagram of the SIGMA Type GS-34 Free-Piston Gasifier [8]	211
Figure I-3 INNAS “Chiron” hydraulic free-piston engine [7]	212

Figure I-4 Tampere University of Technology hydraulic free-piston engine prototype “Emma2” [113]	213
Figure I-5 Third Generation prototype engine [114].....	214
Figure I-6 Cutaway view of the Toyohashi university of Technology hydraulic free-piston engine [63].....	215
Figure I-7 EPA six-cylinder four-stroke FPE [32].....	216
Figure I-8 West Virginia University, second generation linear engine prototype (2-stroke) [115]	218
Figure I-9 West Virginia University, four stroke concept [97].....	219
Figure I-10 First Sandia Free-piston Linear Alternator concept [116].....	220
Figure I-11 Sandia opposed piston layout [119]	221
Figure I-12 Sandia bounce chamber detail showing compressed air injection valves on the left and vent ports on the right [119]	222
Figure I-13 Sandia Opposed Piston Free-piston Engine [120].....	223
Figure I-14 Timeline of Sandia free-piston engine project [119].....	223
Figure I-15 FPEC prototype electric generator – opposed cylinder, two-stroke diesel with pneumatic exhaust valves [78]	224
Figure I-16 Korea Institute of Energy opposed cylinder engine [125]	225
Figure I-17 Four-stroke free-piston engine concept by Nanjing University of Science and Technology [128]	227
Figure I-18 German Aerospace Center free-piston prototype on test bench [60] ...	227
Figure I-19 Linear alternator built at WVU [34].....	228
Figure I-20 Sandia linear alternator design [117]	229
Figure I-21 Magnaquench linear alternator stator [117]	229
Figure I-22 University of Sheffield FPEC linear permanent magnet generator [122]	230
Figure I-23 Royal Institute of Technology Stockholm, Sweden transverse flux permanent magnet generator [40].....	230
Figure I-24 German Aerospace Center linear generator on the test stand [60].....	231

Figure I-25 Design concept for a miniature HCCI free-piston engine [112]	232
Figure I-26 Photo of Kvaerner test cylinder unit	233
Figure I-27 Liquid piston air compressor prototype (high inertance model) Vanderbilt University [73].....	234
Figure III-1 Variation of R with temperature for products of combustion in chemical equilibrium	240
Figure V-1 Heat release of n-octane at various equivalence ratios and temperatures	253
Figure VI-1 A fluid element influenced by a pressure wave.....	255
Figure VII-1 Schematic of a duct boundary.....	259
Figure IX-1 Interpolating discontinuous pressure waves.....	269
Figure IX-2 Handling the duct ends.....	270
Figure IX-3 Single cell ducts	270
Figure XII-1 Schematic of a normal shock	275
Figure XII-2 Travelling shock.....	280
Figure XIV-1 Main screen	286
Figure XIV-2 Edit Ducts screen.....	286
Figure XIV-3 Edit Volumes screen.....	287
Figure XIV-4 Edit Bodies screen	287
Figure XIV-5 Edit Area Coefficients screen.....	288
Figure XIV-6 Edit Functions screen	288
Figure XIV-7 Create Animated plot screen	289
Figure XIV-8 Example Animation screen grab (shock tube problem)	289
Figure XIV-9 History plot screen.....	290

.....

LIST OF TABLES

Table 3-1 Thermodynamic cylinder model calculation sequence.....	41
Table 3-2 List of species considered in equilibrium calculation.....	50
Table 3-3 Equilibrium equations.....	51
Table 4-1 Shock tube setup	83
Table IV-1 Enthalpy of some combustion products.....	241
Table IV-2 Specific heat of some combustion products	242
Table IV-3 Properties of some fuels (various sources [30, 62, 107]).....	243
Table IV-4 Equilibrium equations.....	244
Table IV-5 Equilibrium constants for selected reactions	245
Table XIV-1 Cross reference figure numbers for single shot data.....	273

.....

NOMENCLATURE

Symbols

A	area (m ²)
a	speed of sound (m/s)
a_0	isentropic reference speed of sound (m/s)
a	acceleration (m/s ²)
a_A	moles of atomic element i.e. a_C, a_H, a_N, a_O (mol)
C	circumference or wetted perimeter of a duct (m)
C_f	Coefficient of friction (Fanning friction factor) (-)
C_h	Coefficient of heat transfer (W/m ² /K)
C_p, C_v	specific heat at constant pressure and constant volume (J/kg/K)
\hat{C}_p, \hat{C}_v	specific heat at constant pressure and constant volume (J/mol/K)
C_p^*, C_v^*	frozen specific heats (see Appendix II) (J/kg/K)
c	wave velocity (m/s)
$D_h = \frac{4A}{C}$	hydraulic diameter (m)
F	force (N)
H, \dot{H}	Enthalpy, enthalpy flow rate (J, J/s)
$h, \hat{h}, \Delta\hat{h}^o$	specific enthalpy, enthalpy of formation (J, J/kg, J/mol)
k	thermal conductivity (W/m/K)
L	Length
L_∞	Large eddy length
M	momentum (kg.m/s)
M	molar mass (g/mol)
m, \dot{m}	mass, mass flow rate (kg, kg/s)
\mathcal{N}	Total mixture moles (mol)
n_s	Species moles (mol)

P, P_0	pressure, reference pressure (absolute pressure, Pa)
\dot{Q}, \dot{q}	heat transfer rate (J/s, J/kg/s)
R	gas constant (J/kg/K)
\hat{R}	universal gas constant (8.314472 J/mol/K)
Re, Re_t	Reynolds Number, turbulent Reynolds number (-)
T	temperature (K)
T_0	isentropic reference temperature (K)
t	time (s)
u, u_0	fluid velocity, quiescent fluid velocity (m/s)
u'	turbulence intensity, RMS of fluctuating velocity (m/s)
U, u, \hat{u}	internal energy, specific internal energy (J, J/kg, J/mol)
v	velocity (m/s)
V, v	volume, specific volume (m^3 , m^3/kg)
\dot{W}, \dot{w}	work rate (J/s), specific work rate (J/kg/s),
$X = \left(\frac{P}{P_0} \right)^{\frac{\gamma-1}{2\gamma}}$	pressure amplitude ratio (-)
y_s	species mole fraction (-)
$\gamma = \frac{C_p}{C_v}$	ratio of specific heats (-)
$\gamma^* = \frac{C_p^*}{C_v^*}$	ratio of frozen specific heats (-)
μ	viscosity (N.s/m ²)
ν	Courant number (-)
ρ	density (kg/m ³)
[CO], [CO ₂] etc	species molar concentration (kmol/m ³)

Subscripts

<i>L</i>	leftward
<i>R</i>	rightward
<i>i</i>	iteration, incident
<i>f</i>	flow
<i>prev</i>	previous
<i>r</i>	reflected
<i>s</i>	species

.....

ACRONYMS

BDC	Bottom dead centre
BTDC	Before top dead centre
CFD	Computational Fluid Dynamics
FPEC	Free-piston Energy Converter, project name for a European free-piston engine consortium
HCCI	Homogenous Charge Compression Ignition
IMEP	Indicated mean effective pressure
QUB	Queens University Belfast
TDC	Top dead centre
WRT	With respect to

.....