Multinomial Latent Logistic Regression



$\label{eq:Zhe Xu} Zhe~Xu$ Faculty of Engineering and Information Technology $\mbox{University of Technology, Sydney}$

A thesis submitted for the degree of $Doctor\ of\ Philosophy$ November 2016

Certificate of Original Authorship

I certify that the work in this thesis has not previously been submitted for a degree nor has it been submitted as part of requirements for a degree except as fully acknowledged within the text.

I also certify that the thesis has been written by me. Any help that I have received in my research work and the preparation of the thesis itself has been acknowledged. In addition, I certify that all information sources and literature used are indicated in the thesis.

Student: Zhe Xu Date: 21/10/2016 I would like to dedicate this thesis to my loving parents $Nan\ Huang\ {\rm and}\ Yuan\ Xu$

Acknowledgements

I would like to take this good opportunity to appreciate my advisors, colleagues, friends and also my family for their significant help during my doctoral study in University of Technology, Sydney.

First of all, I would like to express my sincere appreciation and deep gratitude to my advisor supervisor **Prof. Dacheng Tao** for his unlimited patience, generous support, and supportive guidance. I'm particularly impressed by his incredible enthusiasm and high standard in academic research, which encourage me to breakthrough my own setting limits and submit papers to the leading journals or conferences in my research field.

I would also like to thank my advisor **Prof. Ya Zhang** from Shanghai Jiao Tong University. She always gives me plenty of freedom to explore and timely constructive suggestions to help me out of difficulties. Without the effect by her, Prof. Xiaokang Yang and Prof. Chengqi Zhang, I would not have the opportunity to study here in UTS as a dual-degree PhD student.

I have been fortunate to work in UTS and Centre for Quantum Computation and Intelligent Systems (QCIS) directed by Prof. Chengqi Zhang. QCIS provides full support for me to attend top conferences including ECCV, ICCV and KDD, where I got the opportunities to learn from many world-famous experts. It's really a pleasure for me to work in thus a great team and around so many brilliant minds in QCIS. Studying in QCIS and also UTS will be a fantastic memory that I will never forget.

I am also deeply indebted to Dr. Jun Zhu who led me into the field of computer vision. He shows me how interesting my research objective is, which encourages me constantly during the journey of exploration in the following years. Moreover, I also want to give special thanks to my excellent collaborators: Zhibin Hong and Shaoli Huang for their brilliant work and timely support, and also to my dear colleagues and friends I met in QCIS: Dr. Bozhong Liu, Chunyang Liu, Meng Fang, Tongliang Liu, Mingming Gong, Maoying Qiao, Qiang Li, Runxin Wang, Changxing Ding, Zhiguo Long, Caishi Fang, Wei Bian, Shirui Pan, Yong Luo, Xiao Liu, Dianshuang Wu, Weilong Hou, Chang Xu, Chen Gong, Sujuan Hou, Haishuang Wang, Jia Wu, Wei Yang, Qin Zhang, Yali Du, Hao Xiong, Jiankang Deng, Xiao Liu, Peng Hao, Liu Liu, Guodong Long, Jing Jiang, Peng Zhang, Barbara Munday, Prof. Bo Du, Prof. Xianhua Ben, Prof. Wankou Yang, Prof. Shigang Liu, Prof. Xianhua Zeng, for the inspiring discussions, kind support and companionship.

I am also grateful to all the other friends: Guanbo Huang, Wei Xu, Weiyuan Chen, Xiaohang Ren, Zhiyi Tan, Jialin Li, Qing Wang, Weiyuan Chen, for their support and company during both joyful and stressful times.

Finally, I would like to express my deeply felt gratitude to my parents, who never excoriate me when I make mistakes but show me how to do it the right way, who never asks for anything but give me everything they have, who gives me such a wonderful place to grow up. It's you who make me the man who I am now. Thank you, from the bottom of my heart.

Abstract

We are arriving at the era of big data. The booming of data gives birth to more complicated research objectives, for which it is important to utilize the superior discriminative power brought by explicitly designed feature representations. However, training models based on these features usually requires detailed human annotations, which is being intractable due to the exponential growth of data scale.

A possible solution for this problem is to employ a restricted form of training data, while regarding the others as latent variables and performing latent variable inference during the training process. This solution is termed weakly supervised learning, which usually relies on the development of latent variable models. In this dissertation, we propose a novel latent variable model - multinomial latent logistic regression (MLLR), and present a set of applications on utilizing the proposed model on weakly supervised scenarios, which, at the same time, cover multiple practical issues in real-world applications.

We first derive the proposed MLLR in Chapter 3, together with theoretical analysis including the concave and convex property, optimization methods, and the comparison with existing latent variable models on structured outputs. Our key discovery is that by performing "maximization" over latent variables and "averaging" over output labels, MLLR is particularly effective when the latent variables have a large set of possible values or no well-defined graphical structure is existed, and when probabilistic analysis is preferred on the output predictions. Based on it, the following three sections will discuss the application of MLLR in a variety of tasks on weakly supervised learning.

In Chapter 4, we study the application of MLLR on a novel task of architectural style classification. Due to a unique property of this task that rich inter-class relationships between the recognizing classes make it difficult to describe a building using "hard" assignments of styles, MLLR is believed to be particularly effective due to its ability to produce probabilistic analysis on output predictions in weakly supervised scenarios. Experiments are conducted on a new self-collected dataset, where several interesting discoveries on architectural styles are presented together with the traditional classification task.

In Chapter 5, we study the application of MLLR on an extreme case of weakly supervised learning for fine-grained visual categorization. The core challenge here is that the inter-class variance between subordinate categories is very limited, sometimes even lower than the intra-class variance. On the other hand, due to the non-convex objective function, latent variable models including MLLR are usually very sensitive to the initialization. To conquer these problems, we propose a novel multi-task co-localization strategy to perform warm start for MLLR, which in turn takes advantage of the small inter-class variance between subordinate categories by regarding them as related tasks. Experimental results on several benchmarks demonstrate the effectiveness of the proposed method, achieving comparable results with latest methods with stronger supervision.

In Chapter 6, we aim to further facilitate and scale weakly supervised learning via a novel knowledge transferring strategy, which introduces detailed domain knowledge from sophisticated methods trained on strongly supervised datasets. The proposed strategy is proved to be applicable in a much larger web scale, especially accounting for the ability of performing noise removal with the help of the transferred domain knowledge. A generalized MLLR is proposed to solve this problem using a combination of strongly and weakly supervised training data.

Contents

C	Contents				
Li	st of	Figure	es	xi	
Li	st of	Tables	;	xvii	
1	Inti	oducti	on	1	
	1.1	Backgr	round	1	
	1.2	Weakly	y Supervised Learning and Latent Variable Models	2	
		1.2.1	What is weakly supervised learning?	2	
		1.2.2	An intuitive example	4	
		1.2.3	Latent variable models with structured output or multi-		
			class prediction	5	
		1.2.4	Motivation of the proposed latent variable paradigm	7	
	1.3	Signific	cance and Organization	8	
2	Rel	ated W	$v_{ m ork}$	11	
	2.1	Latent	Variable Models with Structured Outputs	11	
		2.1.1	Hidden conditional random field	12	
		2.1.2	Latent structural support vector machine	13	
		2.1.3	Marginal structured support vector machine	14	
		2.1.4	Latent support vector machine	15	
		2.1.5	Weak-label structural support vector machine	15	
		2.1.6	Epsilon-extension model	16	
		2.1.7	Three-dimensional uncertainty model	17	

CONTENTS

	2.2	Optin	nization methods	18
		2.2.1	Concave-convex procedure	19
		2.2.2	Convex optimization solver	20
	2.3	Weakl	ly Supervised Learning	21
	2.4		Supervised Learning Approaches	23
	2.5		Grained Visual Categorization	24
		2.5.1	Feature representation	25
		2.5.2	Model design	25
		2.5.3	Training supervision	26
3	Mu	ltinom	ial Latent Logistic Regression	28
	3.1		luction	28
	3.2	Multin	nomial Latent Logistic Regression	30
		3.2.1	Multinomial logistic regression	30
		3.2.2	Latent variables	31
		3.2.3	Concave-convex procedure	33
		3.2.4	Gradient descent	35
		3.2.5	Coordinate descent using one-dimensional Newton direc-	
			tions with latent variables	36
		3.2.6	Generalization to Structured Outputs	41
	3.3	Conne	ection and Difference between MLLR and Existing Methods	42
		3.3.1	Maximization vs. marginalization over h	42
		3.3.2	Max-margin vs. log-likelihood over y	43
		3.3.3	Regularizer	44
	3.4	Exper	iment	45
		3.4.1	Handwritten digit recognition	45
		3.4.2	PASCAL action classification	48
		3.4.3	Sport action recognition	49
		3.4.4	Animal classification	50
	3.5	Summ	nary	54
4	ML	LR for	Architectural Style Classification	55
	4.1	Introd	luction	55

CONTENTS

	4.2	Archit	sectural Style Dataset	58
	4.3	Model	Description	60
		4.3.1	Deformable part-based model	60
		4.3.2	Latent SVM	64
		4.3.3	DPM-MLLR framework	65
	4.4	Exper	${ m iment}$	67
		4.4.1	Classification task	71
		4.4.2	Inter-class relationships between styles	71
		4.4.3	Individual building analysis	72
	4.5	Summ	nary	73
5	ML	LR for	Fine-grained Categorization	7 6
	5.1	Introd	luction	76
	5.2	Gener	al Initialization Strategies for MLLR	80
	5.3	Initial	ization via Multi-task Co-localization	81
		5.3.1	Preliminary	83
		5.3.2	Co-localization by discriminative clustering	84
		5.3.3	Multi-task discriminative clustering	85
		5.3.4	Optimization	86
		5.3.5	Fine-grained classifiers	87
	5.4	Exper	iment	88
		5.4.1	Dataset and implementation details	88
		5.4.2	Localization results	89
		5.4.3	Classification results	92
	5.5	Summ	nary	98
6	ML	LR for	Webly Supervised Learning	99
	6.1	Introd	luction	99
	6.2	Webly	Supervised Learning via Deep Domain Adaptation	102
		6.2.1	Preliminary	102
		6.2.2	Objective function via generalized MLLR	103
		6.2.3	Knowledge extraction on the strongly supervised dataset $% \left(1\right) =\left(1\right) \left(1$	104
		6.2.4	Knowledge transfer to the weakly supervised dataset	107

CONTENTS

	6.3	Exper	${ m iments}$	112
		6.3.1	Dataset and implementation details	112
		6.3.2	Detection results and analysis of discovered part patches .	113
		6.3.3	Classification results	115
		6.3.4	Visualization	117
	6.4	Summ	nary	118
7	Con	clusio	ns	121
	7.1	Thesis	Summarization	121
	7.2	Future	e Work	123
Re	efere	nces		125
Ρι	ıblic	ation		146

List of Figures

1.1	Illustration of unsupervised learning, supervised learning, and weakly	
	supervised learning. A variable within a circle indicates given in-	
	formation, while others indicate hidden variables	3
1.2	Demonstration of the requirement of object-level bounding-box an-	
	notations. The models in the right shows template-HOG results	
	learned by DPM [47] using object-level supervision	4
1.3	The structure of the thesis	9
2.1	Illustration of latent variable models with structured prediction.	
	The three dimensions are: h standing for latent variables, s stand-	
	ing for strong predictions and y standing for weak labels. The axes	
	represent degree of uncertainty over the three dimensions	18
3.1	Illustration for the importance of updating latent assignments when	
	performing line search in CDN. Figure (a)(b) shows the situation	
	where no updating process is performed, while (c)(d) shows the	
	situation after updating latent assignments	39
3.2	L1-norm of the model parameter vectors for different angles learned	
	by MLLR. x-axis stands for angles and y-axis reveals model re-	
	sponses. Although the L1-regularizer is not specified to produce	
	group sparse models, the resulting model parameters follow a sim-	
	ilar pattern	47

3.3	Visualization of the result of MLLR for 3 human actions (cricket-	
	defensive battling, tennis-forehand and croquet). Detected root fil-	
	ters are displayed in red, and part filters are shown in yellow. Note	
	that for the images of the class <i>croquet</i> , people usually have strong	
	interactions with the background, which degrades the performance.	49
3.4	Confusion matrices of MLLR in the task of Mammal dataset (a)	
	and Sports dataset (b)	51
3.5	Visualization of the result of distributed MLLR on the mammal	
	dataset. The first column contains the HOG models trained by	
	non-latent linear SVM. Given the non-latent linear SVM model as	
	the initialization status, MLLR models remove some of the noise	
	data in the models, as shown in the second column. The last five	
	columns visualize typical results of the latent position found by	
	MLLR. The rows show three of the object categories, which are	
	bison, elephant and giraffe respectively	52
3.6	Visualization of how the latent variable (object location) changes	
	during learning. Starting from the full bounding boxes, the al-	
	gorithm iteratively finds the highest scored location of the ob-	
	ject. The numbers underneath indicate the output probabilities	
	of MLLR at various stages	53
3.7	Visualization of the comparison between MLLR (left) and LSVM	
	(right). The text on the bounding box indicates the prediction	
	label and the number shows its probability. We use the sigmoid	
	function to turn the decision values of LSVM into probabilities.	
	Although both algorithms find the same bounding boxes for the	
	classes "elephant" and "rhino", MLLR correctly classifies the ob-	
	ject due to a better calibration process	53

4.1	Schematic illustration of architectural style classification using Multi-	
	nomial Latent Logistic Regression (MLLR). Given a new large-	
	scale architectural style dataset, we model the façade of buildings	
	using deformable part-based models. The resulting classifiers can	
	provide probabilistic analysis along with the standard classification	
	results	57
4.2	Illustration of the architectural style dataset. Each of the 25 styles	
	is represented by a circle with the respective number in the middle,	
	where different colors indicate broad concepts, such as modern	
	architecture and medieval architecture. The styles are arranged	
	according to time order, where newer ones are placed in the right	
	of ancient ones. Various inter-class relationships exist between the	
	styles, $e.g.$, lines between circles stand for following relationships;	
	smaller circles around large ones indicate sub-categories. Typical	
	images of the styles are shown in the background. Better viewed	
	in color	59
4.3	Illustration of the feature pyramid in a DPM. Part filters are placed	
	at twice the spatial resolution than the root filter. Original figure	
	can be found in [47]	61
4.4	Visualization of the use of DPM in architectural style classification.	
	(a)(c)(d) show detection results for different testing images. The	
	trained model for <i>Gothic</i> architectural style is shown in (b)	63
4.5	MLLR maps the classifier results of multiple classes to a unified	
	score function. The resultant scores are directly comparable	68
4.6	Testing results for the ten architectural styles. The first two columns	
	visualize the result root and part filters for each model. From	
	top to bottom: Baroque, Chicago school, Gothic, Greek Revival,	
	Queen Anne, Romanesque and Russian Revival architecture. De-	
	tected root filters are displayed in red, and part filters are shown	
	in yellow. Better viewed in color	69
4.7	Confusion matrix for MLLR on the two experimental settings	70

4.8	An architectural style relationship map generated by the proposed algorithm. The confusion probability between style A and B is obtained by summing the probabilities with regard to B for all images labeled by A. Only links whose weight exceeds a given threshold are	
4.9	shown in the figure. Modern styles, such as <i>Postmodern</i> and <i>International</i> style, are connected, while the links between modern and medieval styles are weak. The figure is drawn using NetDraw [16]. MLLR detects the optimized latent position for each class and outputs a global list of probabilities for each class. (a) Parts shared by different styles. (b) A building that combines several styles. (c)-(f) Typical detection results for the four styles appearing in (a) and (b), i.e., from left to right, <i>Baroque</i> , <i>Russian Revival</i> , <i>Queen Anne</i> and <i>Greek Revival</i>	73 74
5.1	Illustration of the effect of inter-class relationships in fine-grained categorization under weakly supervised settings. In the proposed algorithm, fine-grained categories first act as "friends" in the localization phase against varied backgrounds, then turn back to "foes"	
5.2	in the following classification phase	79
5.3	much smaller region of interest, as shown in $(f),(g)$ Illustration of the proposed method for weakly supervised fine-grained recognition. The first co-localization phase aims to detect foreground regions from the background. We propose a multi-task algorithm to perform co-localization on multiple subcategories simultaneously. The localization results are then employed to initialize a multi-instance learning process to learn the final object	81
	classifiers.	82

5.4	The impact of model parameters μ and λ . In the first figure, λ was	
	fixed as 1, and the second figure set $\mu = 0.1.$	91
5.5	Localization results in different stages. Column 1 to 4: best-scored	
	MCG candidate; results after performing co-localization; results af-	
	ter performing multi-instance classification; best scored bounding	
	box according to SVMs trained using full images	92
5.6	Example localization results for testing images after performing	
	multi-instance learning. The rightmost column shows cases in	
	which the proposed method failed to classify correctly due to mul-	
	tiple objects, uncommon object pose, and background clutter. $\ .$.	94
6.1	Illustration of the proposed semi-supervised method via web data.	
0.1	A strongly supervised dataset is introduced to "teach" web images	
	how to learn properly.	101
6.2	Flowchart of the proposed algorithm. Green lines show modules of	101
0.2	strongly supervised method adopted in our framework, while red	
	lines are additional operations of semi-supervised learning	103
6.3	Detection results on weakly supervised images. Green frames in-	100
0.0	dicate the detected bounding box for part "body". Image labels	
	in the top two rows are correctly classified; the bottom two rows	
	show cases in which classification has failed. Beyond the classifica-	
	tion results, part patches in rows 1 and 3 are associated with high	
	detection scores, while rows 2 and 4 have low detection scores	110
6.4	Examples of detected part patches from web images selected as	110
0.4	valid training patches. From top to bottom: whole object, head,	
	body. The leftmost five columns show top-scoring detections, while	
	the right two columns show patches with the lowest detection scores	114
	the right two columns show pateries with the lowest detection scores	. 114

6.5Visualization of the classification process using the proposed method with a root and two parts: head and body. (a) Test image with a ground-truth label of 80. (b) Activation map for the three detectors. (c) Located part bounding boxes. The top 9 nearest neighbours for the detected parts from the training images are shown in (d)-(f). The original strongly supervised method using training data only misclassified the test image into class 81, as shown in (d). Green boxes demonstrate the image patches of label 80, and red boxes for label 81. After re-fine-tuning part-CNNs with the augmented training set, the new feature representations guaranteed that the test image was correctly classified. (e) Nearest neighbours from the strongly supervised training set only using the new feature representations. (f) Results after putting weakly supervised images into the training set either. Yellow boxes indicate images in the weakly supervised dataset with label 80. (g) and (h) show typical training images from class 80 (Green_Kingfisher)

List of Tables

2.1	Relationship between latent variable models in the view of unified extension model. We use the same representation form as [107].	17
3.1	Prediction accuracies for four digit pairs. N stands for SVM or LR methods without using latent variable models. GD and CDN stand for the two optimization methods in Section 3.2. MLLR-CDN algorithm consistently outperforms two LSSVM-based algorithms.	46
3.2	Average Precision on the PASCAL VOC 2011 Action Classification	
	task	48
3.3	Classification results for the mammal dataset. Linear SVM is trained without latent variables. All algorithms use the same feature extraction method. We show the mean/std of classification accuracies over 10 rounds of experiments	52
4.1	Results on the architectural style classification dataset. MLLR consistently outperforms LSVM. Multiple features (e.g., MLLR+SP) are combined by adopting a late fusion method using the softmax function on classifier outputs	69
5.1	CorLoc results for different co-localization strategies on the CUB-14 dataset. MCG denotes the baseline where boxes with the top objectness scores obtained by MCG were adopted without performing co-localization methods. "@n" denoted the best result among	
	top-n candidates	90

5.2	Localization results for CUB-200-2010, CUB-200-2011 and Stan-
	ford Dogs
5.3	A detailed comparison with baselines of different localization strate-
	gies and classification methods on the CUB-200-2010 dataset. Row
	1-3 show results by training classifiers solely on the detected fore-
	ground regions. Row 4-6 show results by performing a multi-
	instance learning (MIL) approach initialized by the respective lo-
	calization results. The final row presents an upper bound of our
	algorithm by using ground-truth bounding box supervision 95
5.4	Effect of fine-tuning CNNs. We achieved an accuracy of 77.37%
	on the CUB-200-2011 dataset under the weakly supervised scenario. 96
5.5	Performance comparison to the state-of-the-art results in the liter-
	ature with or without the use of ground-truth bounding boxes at
	the training stage
6.1	Part localization accuracy in terms of PCP on the CUB-200-2011
	dataset
6.2	CUB-200-2011 Ablation study of different choices of fine-tuning,
	classifier, detector, and denoising
6.3	Accuracy comparison on the CUB-200-2011 dataset. To conduct
	fair comparison, we only list methods which use no annotation at
	testing time; for all the methods, we report their results using the
	same CNN architecture (AlexNet) if possible
6.4	Accuracy comparison on the Oxford-IIIT Pet Dataset